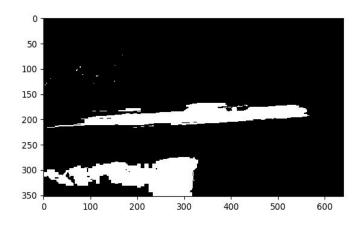
## Task:

To detect the defect in the rod from the given video.

## Algorithm 1:

- 1. Initially, the whole video is being converted into frames. Total number of frames being 132.
- 2. Now, Binary thresholding using the OpenCV library in Python has been implemented on the images.



Frame 45-after Binary Thresholding

(Note: Defect on the rod is at approximate location (450,250) in the above image)

When applied other thresholdings on the frame:

Original Image
BINARY
BINARY\_INV

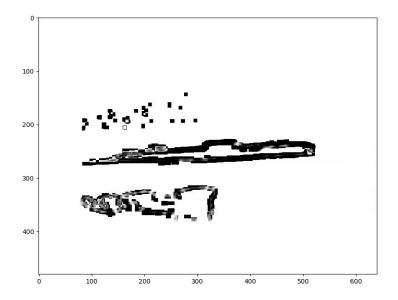
TRUNC
TOZERO
TOZERO\_INV

So, among all the above, chose Binary Thresholding for better results.

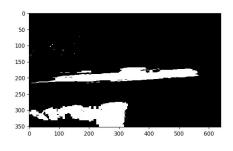
- 3. Then, converted the image into 2D (Gray image). Used OpenCv function to convert colored image to gray.
- 4. Now, I have chosen, the middle frame (approx)-Frame number 45, as my base image and compared other frames wrt this base frame. (Note: chose this frame randomly and was given better visible result when compared to the first frame)
- 5. Used Structural similarity Index to compare any two images. Used compare\_ssim function from the skimage library.

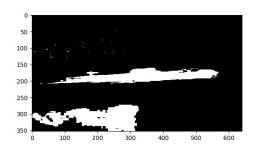
6.compare\_ssim has two return values. One being diff (a 2D matrix of differences between two images given in the argument), and other being score(it is given on the scale of [-1,1], where 1 indicates perfect match)

7. The part of gray color shows the area of defect.

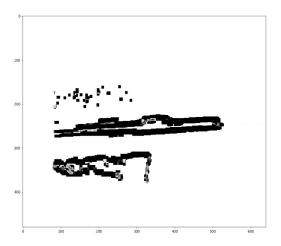


Difference between frames 45 and 32

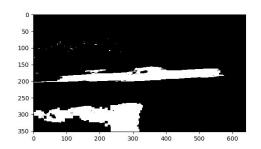


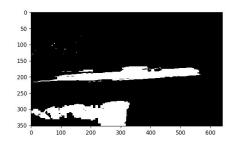


Frame 45 Frame 32



Diff between frame 45 and 62





Frame 62 Frame 45