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OpenCL

Crash Course

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Sources + slides

http://github.com/anirul/OpenCL_Crash_Course.git

- Known to work on Linux/OSX:
 - a C++ compiler (g++/clang++)
 - the OpenCL Header + libs cmake / OpenCV / Boost / GL / GLU / glut
 - Based on (Simple & Floyd-Warshall & Video): http://github.com/anirul/OpenCL_PA_2012.git

 http://github.com/anirul/OpenCL_Video.git
 - Warning! The Nvidia drivers on linux only support OpenCL 1.1!

Plan

- General overview (GPGPU -> OpenCL)
- Code dive (various examples)
- Conclusion (Optimisation tips)

General Overview

- GPGPU Technology overview
- OpenCL
 - Language and API
 - Device Model
 - Objects

GPGPU

General Purpose GPU

- Using Graphical Processing Unit to compute.
 - Shader languages (GLSL / DirectX)
 - CUDA (Nvidia proprietary)
 - DirectCompute (Windows)
 - OpenACC (no free compiler support yet)

heterogeneous computing platforms

- Khronos (OpenGL, Vulkan, COLLADA, etc...)
 - Intel, QUALCOMM, AMD, Altera Corporation, Vivante Corporation, Xilinx, Inc., MediaTek Inc, ARM Limited, Imagination Technologies, Apple, Inc., STMicroelectronics International NV, ARM, IBM Corporation, Creative Labs, NVIDIA, Samsung Electronics.
- Work on CPU / GPU / DSP / FPGA ...
- Open Standard

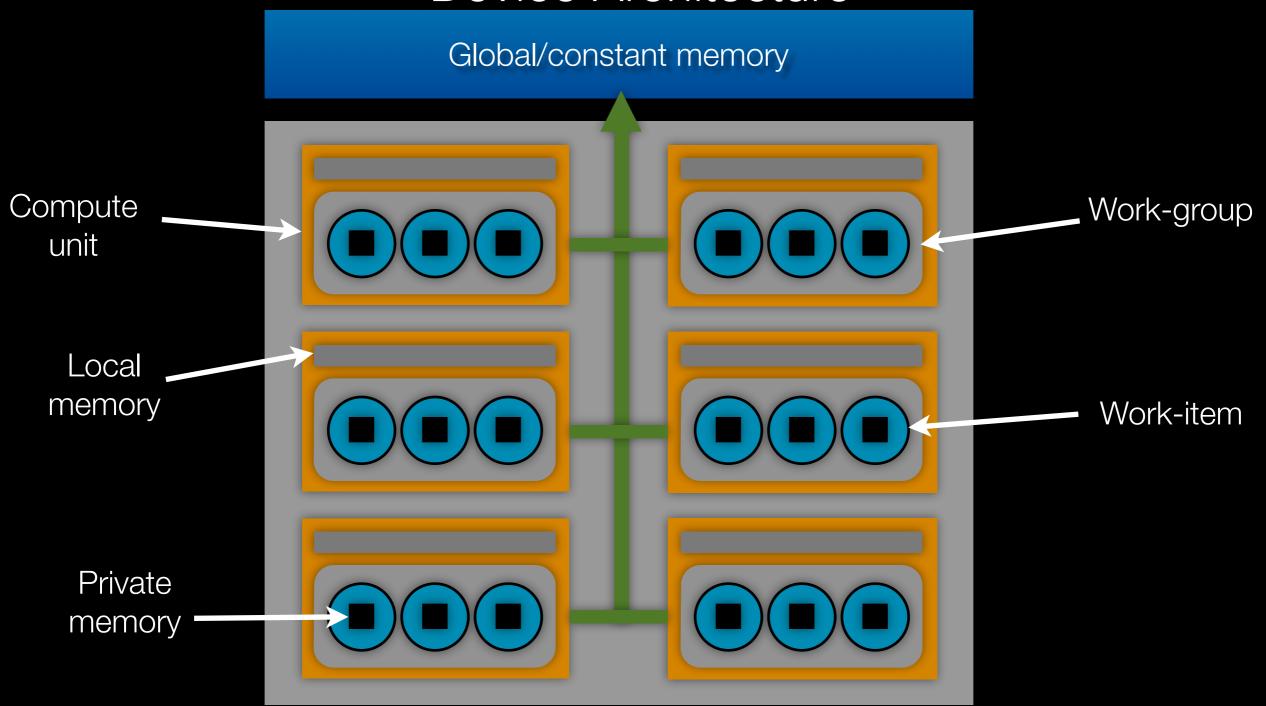
Language and API

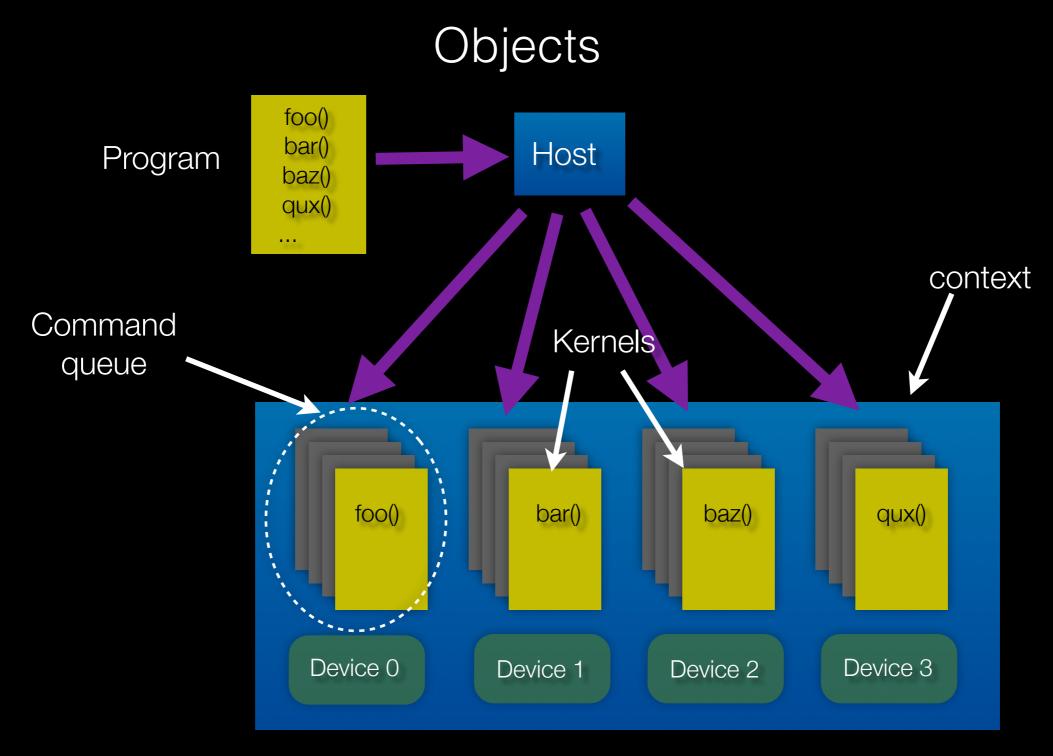
CPU

- An API (run on the Host)
 - in C but with interface to many other languages
- A language (run on the Device)
 - vector oriented
 - \sim C99 inspired (2.1 -> C++14)

GPU

Device Architecture





Things to keep in mind

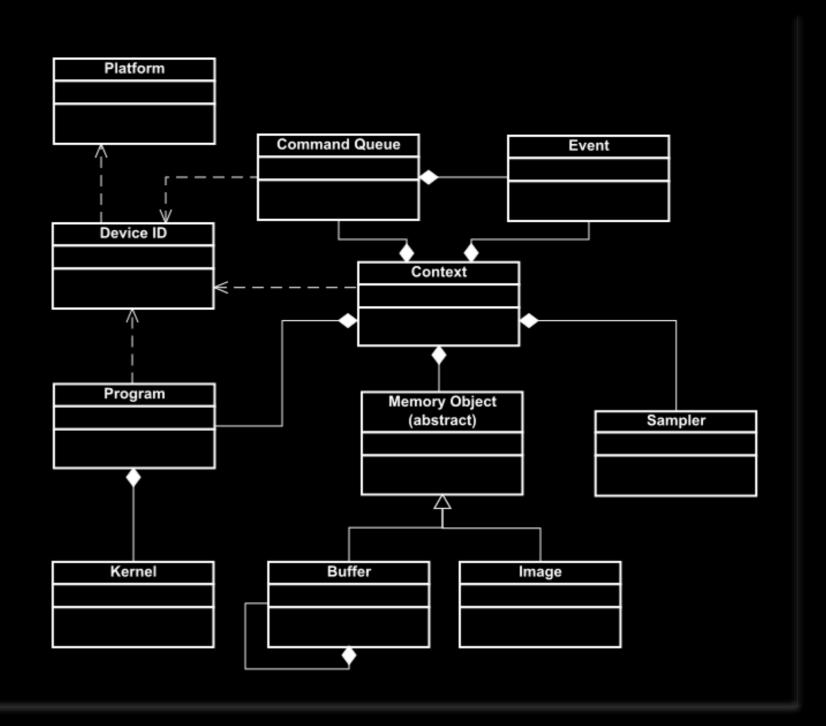
- Forget about memory protection (no MMU)
- No recursion!
- memory limited (no swap)
- local memory bottleneck (64k typically)

Code Dive

- Khronos C++ wrapper
- Simple (as it can be!)
- Floyd-Warshall (memory coalescing)
- Histogram (reduce, local memory)
- Video (the full stack)

Khronos C++ wrapper

- Officially published by Khronos
- Template based
- Header only
- 100% portable
- Object Oriented



Simple

- Very simple example using the C++ wrapper
- Compute the product of 2 vectors
- Single file only OpenCL dependent
 - simple.cpp
- Not a practical example!

Device code

```
// very simple kernel

kernel void simple(
    global read_only float* in1,
    global read_only float* in2,
    global write_only float* out)

{
    const uint pos = get_global_id(0);
    out[pos] = in1[pos] * in2[pos];
}
```

Simple product of two vectors

Host code (1)

Add exception support to OpenCL

```
#define __CL_ENABLE_EXCEPTIONS
#include <CL/cl.hpp>
```

Get Platform and device

Host code (2)

Generate a context

```
cl_context_properties properties[] = {
    CL_CONTEXT_PLATFORM,
    (cl_context_properties) (platforms[platform_id]) (),
    0
};
cl::Context context_ = cl::Context(CL_DEVICE_TYPE_ALL, properties);
cl::CommandQueue queue_(context_, devices_[device_id], 0 , nullptr);
```

Get the source build and select a kernel

```
cl::Program::Sources source(
    1,
    std::make_pair(
        kernel_source.c_str(),
        kernel_source.size()));
cl::Program program_(context_, source);
program_.build(devices_);
cl::Kernel kernel_(program_, "simple");
```

Host code (3)

Create a buffer from a STL vector

```
cl::Buffer buf_in1_ = cl::Buffer(
    context_,
    CL_MEM_READ_ONLY | CL_MEM_COPY_HOST_PTR,
    sizeof(cl_float) * in1.size(),
    (void*)&in1[0]);
```

Set the arguments of the kernel

```
kernel_.setArg(0, buf_in1_);
    kernel_.setArg(1, buf_in2_);
    kernel_.setArg(2, buf_out_);
```

Host code (4)

Execute the kernel

```
queue_.enqueueNDRangeKernel(
    kernel_,
    cl::NullRange,
    cl::NDRange(vector_size),
    cl::NullRange);
```

Get the result

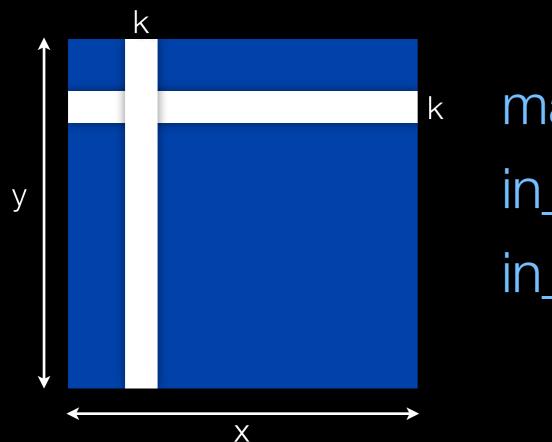
```
queue_.enqueueReadBuffer(
   buf_out_,
   CL_TRUE,
   0,
   vector_size * sizeof(float),
   &out[0]);
```

Floyd Warshall

For each values of k (in 0..N -1)

The Matrix

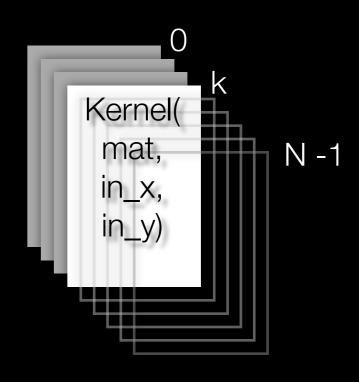
The Kernel Stack



mat (whole)

$$in_x = y[k]$$

$$in_y = x[k]$$



Device code

```
// mat the matrix
// in x column
// in y line
kernel void floyd warshall buffer (
      global float* mat,
      global float* in x,
     global float* in y)
   const int2 d = (int2)(get global id(0), get global id(1));
   const int2 m = (int2)(get global size(0), get global size(1));
   int position = d.y * m.x + d.x;
   float val1 = mat[position];
   float val2 = in x[d.x] + in y[d.y];
   mat[position] = (val1 < val2) ? val1 : val2;</pre>
```

Host code

```
for (int i = 0; i < mdx; ++i) {
                                          Iterate on the stack
   [...]
   queue .enqueueCopyBufferRect(
      cl buffer mat ,
                                        Copy Column X into buffer
      cl buffer in x ,
      [...]);
   [...]
   queue .enqueueCopyBuffer(
      cl buffer mat ,
                                        Copy line Y into buffer
      cl_buffer_in_y_,
      [...]);
   err = queue .enqueueNDRangeKernel(
      kernel ,
      cl::NullRange,
      cl::NDRange(mdx_, mdy_),
                                        Execute kernel
      cl::NullRange,
      NULL,
      &event );
   [...]
```

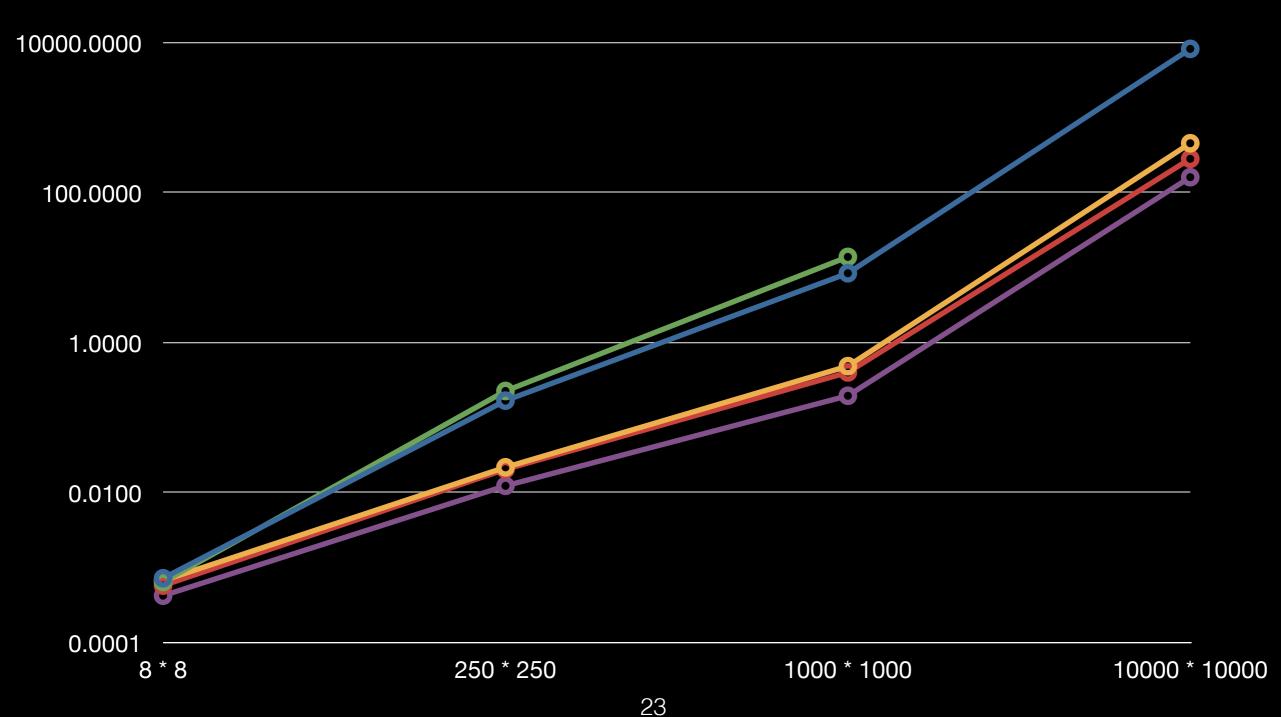
Remarks

- Memory coalescing
- Loop on kernel
- local memory is typically 64k (on Nvidia)

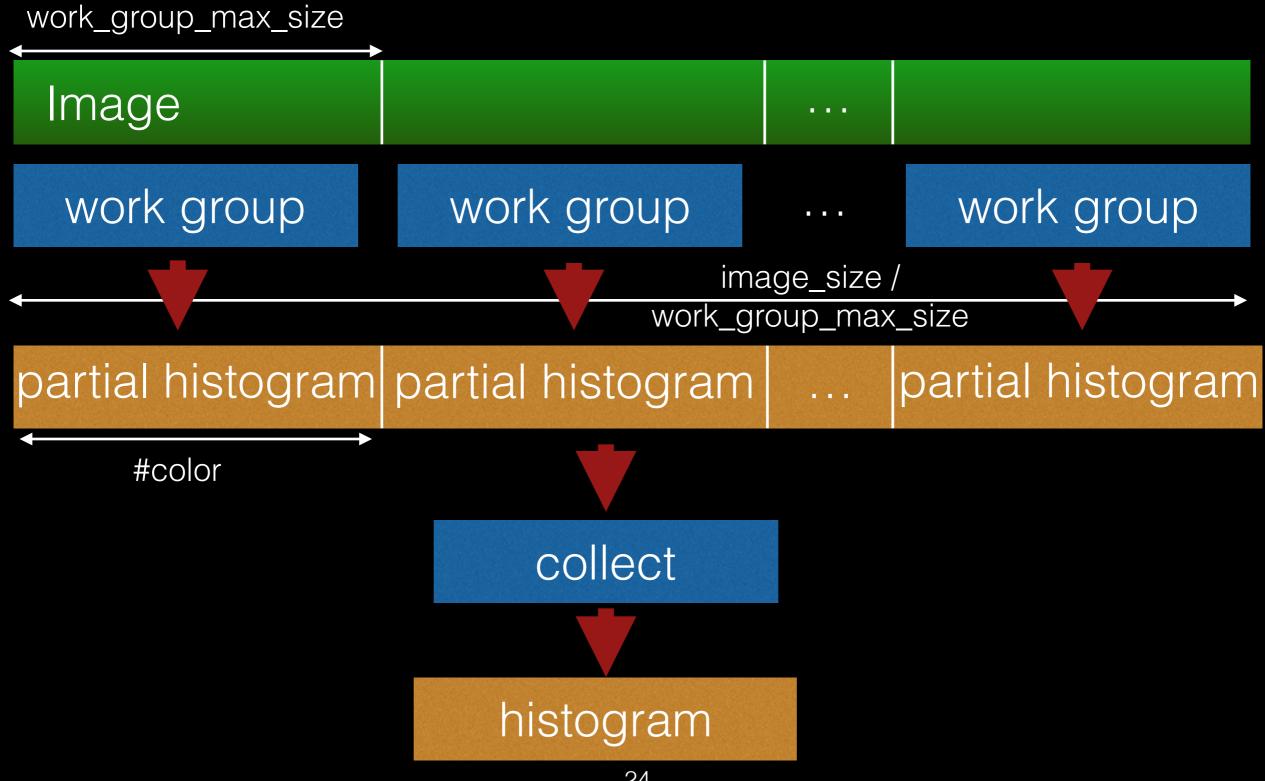
- Could be computed by bloc
- Could use local memory (per bloc)

Performances

- Core 2 Duo
- nVidia (Quadro NVS 295)
- nVidia (TESLA 1060C)
- nVidia (GTX 285)
- nVidia (GTX 560)



Histogram



Histogram

- Split into 4 kernels:
 - compute luminosity (on image2d)
 - clean the partial histogram buffer
 - partial histogram (to avoid atomic hell)
 - collect all partial histogram (could be split more if needed)

Device code (1)

```
constant sampler t format =
   CLK NORMALIZED COORDS FALSE |
   CLK FILTER NEAREST |
   CLK ADDRESS CLAMP;
static float luminosity from color(const float4 col)
   return 0.21f * col.x + 0.72f * col.y + 0.07f * col.z;
kernel void pixel luminosity(
   read only image2d t img,
   global uchar* luminosity)
   int2 d = (int2)(get global id(0), get global id(1));
   int 1 = get global id(0) + get global id(1) * get global size(0);
   float4 col = read imagef(img, format, d);
   float lum = luminosity from color(col);
   luminosity[1] = convert uchar sat(min(lum, 1.0f) * 255.0f);
```

Device code (2)

```
kernel void histogram_partial(
    global const uchar* luminosity,
    global uint* partial_histogram)
{
    int image_len = get_global_size(0) * get_global_size(1);
    int group_indx = get_global_id(1) * NB_COLOR;
    int linear_index = get_global_id(1) * get_global_size(0) +
get_global_id(0);

if (linear_index < image_len) {
    uchar col_indx = luminosity[linear_index];
    atomic_inc(&partial_histogram[group_indx + col_indx]);
}</pre>
```

Device code (3)

```
kernel void histogram reduce (
   global const uint *partial histogram,
   const int num groups,
   global uint *histogram)
   int tid = (int)get global id(0);
   int group indx;
   int n = num groups;
   int tid histogram = 0;
   for (int i = 0; i < num groups * NB COLOR; i += NB COLOR)
      tid histogram += partial histogram[i + tid];
   // cumulative histogram
   histogram[tid] = tid histogram;
```

Host code (1)

Create the different kernel from the same program

```
kernel_luminosity_ = cl::Kernel(program_, "histogram_luminosity");
kernel_init_ = cl::Kernel(program_, "histogram_init");
kernel_partial_ = cl::Kernel(program_, "histogram_partial");
kernel_reduce_ = cl::Kernel(program_, "histogram_reduce");
```

Host code (2)

Create an image2d from a pointer

Remarks

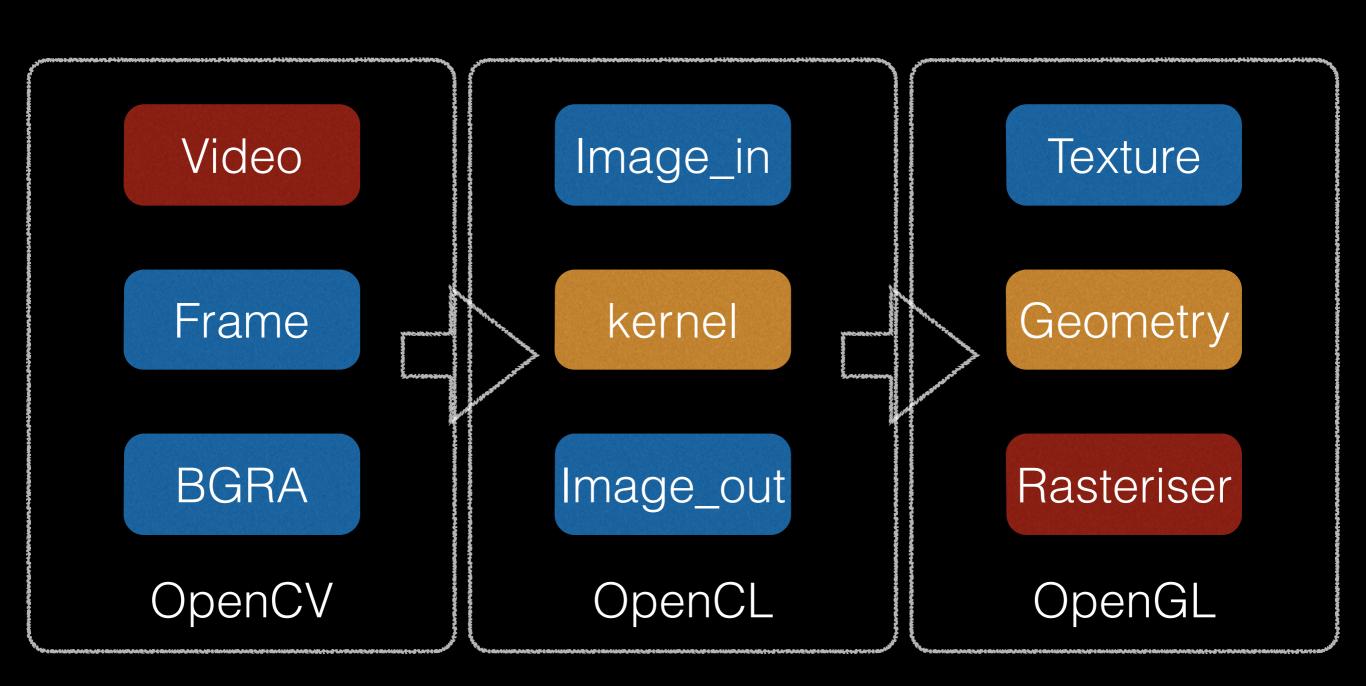
- multiple kernel in a single program
- usage of image2d!
- map and collect technique
- atomic (warning atomic only work on int!)
 (there is ways to make it work with float)
 - only work on image if: (image_size % WORK_GROUP_MAX_SIZE == 0) easy way around this
 - collect could be divided in many more step to improve performances

Performances

Computed on a full HD image (1080p)

Device	Time [s]
i7-3720QM CPU	0.004870
i7-4930K CPU	0.016011
HD Graphics 4000	0.057108
GeForce GT 650M	0.014480
GeForce GTX TITAN	0.000512

Video



Video

- OpenCV to capture video
- OpenCL to modify it
 - copy to OpenGL could be avoided with OpenCL interop (OS / Hardware dependent)
- OpenGL to draw it

Device code

simple code to copy from image_in to image_out

Remarks

- Kernel can be swap from the command line
- Direct feed back from the window

- Could improve the copying of the video to the OpenCL image2D (1 less copy)
- Could use OpenGL interop to directly bind the out image to the OpenGL texture (2 less copies)

Conclusion

- Third part (conclusion)
 - Optimisation tips
 - OpenGL <-> OpenCL interop
 - Vulkan / OpenCL 2.1 / OpenACC / boost::compute
 - Questions?

Optimisation Tips (1)

From Nvidia

- Overall
 - Maximizing parallel execution
 - Optimizing memory usage to achieve maximum memory bandwidth
 - Optimizing instruction usage to achieve maximum instruction throughput

Optimisation Tips (2)

From Me

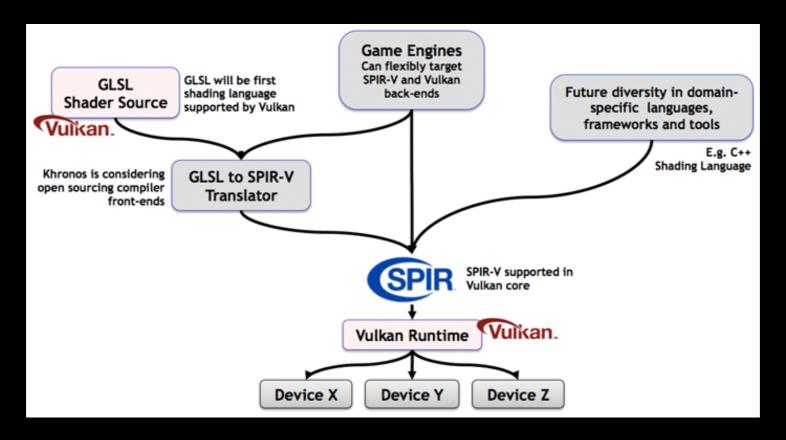
- Don't trust, test!
- Sometime using image is faster than using buffers
- Use barrier([memory type]) to synchronize inside a kernel
- Local memory don't exist on CPU!
- The compiler is sometime (too) clever
- Watch out, branching can kill you (or not)
- For b power of 2 -> a % b -> a & (b -1)

OpenCL / OpenGL

Interoperation

- very platform dependent
- still a moving target
- usually drawing to the screen won't be your bottleneck

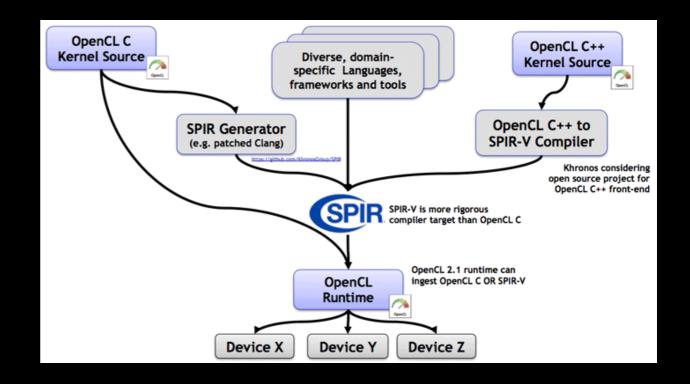
Vulkan



- Vulkan is the fusion between OpenCL and OpenGL
 - access to the full pipeline in raw mode
 - OpenCL will compile to vulkan (SPIR-V)

OpenCL 2.1

- OpenCL 2.1 build on top of Vulkan (SPIR-V)
 - subset of the C++14 language
 - still compatible with C99 syntax



OpenACC

- OpenMP type optimisation (#pragma acc)
 - Should be supported in gcc 5

```
[...]
#pragma acc data copy(a0[0:sz*sz*sz]), create(a1[0:sz*sz*sz],
i,j,k,iter), copyin(sz,fac,n) {
    for (iter = 0; iter < ITERATIONS; iter++) {
#pragma acc parallel loop
        for (i = 1; i < n+1; i++) {
#pragma acc loop
        for (j = 1; j < n+1; j++) {
#pragma acc loop
        for (k = 1; k < n+1; k++) { [...]</pre>
```

boost::compute

- A boost library for GPU programming?
 - Still under heavy development

```
#include <iostream>
#include <boost/compute/core.hpp>

namespace compute = boost::compute;

int main()
{
    // get the default device
    compute::device device = compute::system::default_device();
    // print the device's name
    std::cout << "hello from " << device.name() << std::endl;
    return 0;
}</pre>
```

Questions?