

Class Test - 1

Anish Sachdeva

DTU / 2016 / MC / 13

Class Form	
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Q1) i) (d) None

ii) (a) xlabel()

iii) (b) Matrix Laboratory

iv) ~~(a) clear~~ (b) clear

v) (b) %

Q2) Program For Linear Fit for given data?

% Fitting a linear curve using polyfit

clc;

clear;

close all;

% Creating The discrete data

X = [-10:20]

Y = X.^2;

% Using The polyfit function to fit a linear
% curve to the data

[theta, _] = polyfit(X, Y, 1);

% Creating a Linear Function Using Points

% Obtained

Syms f(t);

~~f(t) = theta(1)*t + theta(2);~~

f(t) = theta(1)*t + theta(2);

```
% Plotting the Function
p1 = fplot(f);
title("Linear Curve Fitted To Data");
xlabel("x");
ylabel("Fitted Curve;  $y'(x)$ ");
```

```
% Plotting The Original Discrete data
hold on;
p2 = plot(X, y, '-o');
legend([p1, p2], 'Fitted Curve', 'Original Data');
```

Q3) Write a program for ODE?

```
% Solving the Non-linear ODE for Hooke's Law
```

```
clc;
clear;
close all;
```

```
% Creating the function
syms x(t);
```

```
% Declaring the mass and spring constant
m = 1/16;
K = 4;
```

```
% Declaring the second order non-linear ODE
```

```
Dy = diff(x);  
ode = m * diff(x, t, 2) + k * x == 0;
```

```
% Providing initial value conditions  
condition1 = x(0) == 0;  
condition2 = Dy(0) == 1;
```

```
% We solve the equation and add the initial  
% value condition  
x(t) = dsolve(ode, [condition1, condition2]);
```

```
% We plot the obtained Function
```

```
fplot(x);  
title('Object attached at End of Spring -  
Obeying Hooke's Law');  
xlabel('Time: t');  
ylabel('Position of Object: ' + string(x));  
legend;
```