

Uncertainty-Aware Carbon Flux Estimation from Multispectral Landsat Imagery Using Mixture Density Networks



Climate Change Al

Anish Dulal¹; Jake Searcy²

¹Department of Computer Science, ²Department of Data Science, ^{1,2}University of Oregon

Abstract

Accurately quantifying carbon fluxes across ecosystems is essential for monitoring and validating natural climate solutions (NCS) which promise to mitigate climate change. Measurement methods, such as eddy covariance towers, provide ground truth data at high temporal resolution but suffer from limited spatial coverage. Upscaling these measurements to ecosystem scales is performed with machine learning methods based on environmental drivers and satellite data. However, correctly quantifying uncertainty in these predictions remains a challenge, which limits its use in carbon markets. We propose an uncertainty-aware carbon flux estimation framework that integrates multispectral Landsat imagery, EC flux measurements, and ancillary environmental variables using Mixture Density Networks. Our framework provides estimates of both aleatoric and epistemic uncertainties that enhance the reliability and scalability of carbon monitoring efforts.

Introduction

- Natural Climate Solutions (NCS) like reforestation and conservation are vital for climate change mitigation, policy decisions, and integrity of carbon markets.
- Ground methods like eddy covariance towers offer precision but lack spatial coverage.
- Remote sensing + ML enable upscaling, but most traditional models provide point estimates with no uncertainty.
- Mixture Density Networks (MDNs) offer a solution: We explore MDNs for uncertainty-aware carbon flux estimation using Landsat imagery + environmental data.
- Accurate carbon-flux estimates with quantified uncertainty are critical: larger uncertainty leads to steeper discounts on the carbon credits projects can claim.

Methodology

- **Data Collection & Preprocessing**
 - EC Flux Towers: 209 AmeriFlux sites (filtered from 393) with half-hourly carbon flux (FC) measurements and meteorological variables.
 - Landsat 8/9 Imagery: 11 spectral/thermal bands, averaged over a 2×2 window at each tower's location. Solar & sensor azimuth / zenith included.
 - Data Cleaning: Removed sites lacking key variables (e.g., wind direction, tower height), outliers (<0.5th or >99.5th percentile), and physically implausible values (e.g., negative solar radiation, nighttime drawdown).
- Model Architecture
 - Dense Neural Network: Transforms raw inputs (Landsat + meteorological data) into high-level features. Each Dense (fully-connected) layer learns high-level representations, capturing complex, nonlinear relationships between environmental drivers, imagery, and carbon flux.
 - Mixture Density Network (MDN): Final layer outputs parameters $\{\alpha_k, \mu_k, \sigma_k^2\}$ of a Gaussian mixture model:
 - Mixing coefficients (α_k): The probability that each Gaussian coefficient k explains the flux at input x.
 - Means(μ_k): The predicted carbon flux values for each Gaussian component k.
 - Variances (σ_k^2) : Measure the uncertainty or variability within each Gaussian component k.

$$p(y \mid x) = \sum_{k=1}^K lpha_k(x) \, \mathcal{N}ig(y \mid \mu_k(x), \sigma_k^2(x)ig).$$

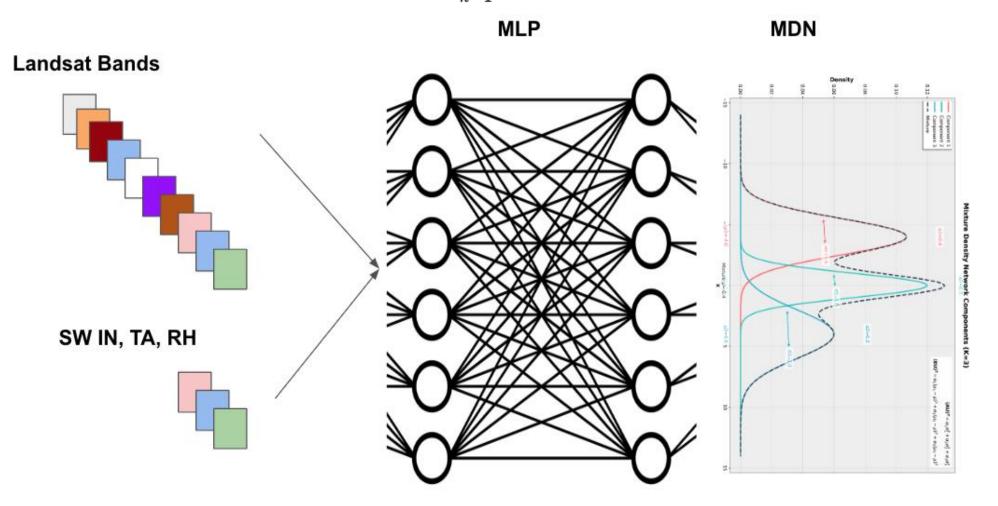


Figure 1: MDN-based architecture combining Landsat and meteorological inputs for carbon flux prediction and uncertainty estimation.

Full Paper



Acknowledgement

This material is based upon work supported by the National Science Foundation under Grant No. 2319597.

I acknowledge the support of the Frank Vignola Scholarship Fund and the Eugene-Kathmandu Sister City Association (EKSCA) for covering travel expenses to attend ICLR 2025.

3. Uncertainty Quantification

- Aleatoric Uncertainty: Noise inherent in the data (modeled via σ^2 within each Gaussian component).
- Epistemic Uncertainty: Model uncertainty captured by dispersion among mixture components (μ_k).
- Single Forward Pass approach (no expensive Monte Carlo sampling) to efficiently estimate both uncertainties:

$$\sigma_{ ext{total}}^2(x) = \underbrace{\sum_{k=1}^K lpha_k \sigma_k^2}_{ ext{aleatoric}} + \underbrace{\sum_{k=1}^K lpha_k \left(\mu_k - \sum_{j=1}^K lpha_j \mu_j
ight)^2}_{ ext{opistomic}}$$

4. Training Objective

Negative Log-Likelihood of observed flux values. Encourages the MDN to learn multi-modal distributions and heteroscedastic noise for uncertainty-aware flux prediction.

Results

The model achieves R² values of 0.7958, 0.7363, 0.7239, and 0.5829 on the training, validation, future test(withheld data from the last year of each training site), and site test set(withheld sites), respectively.

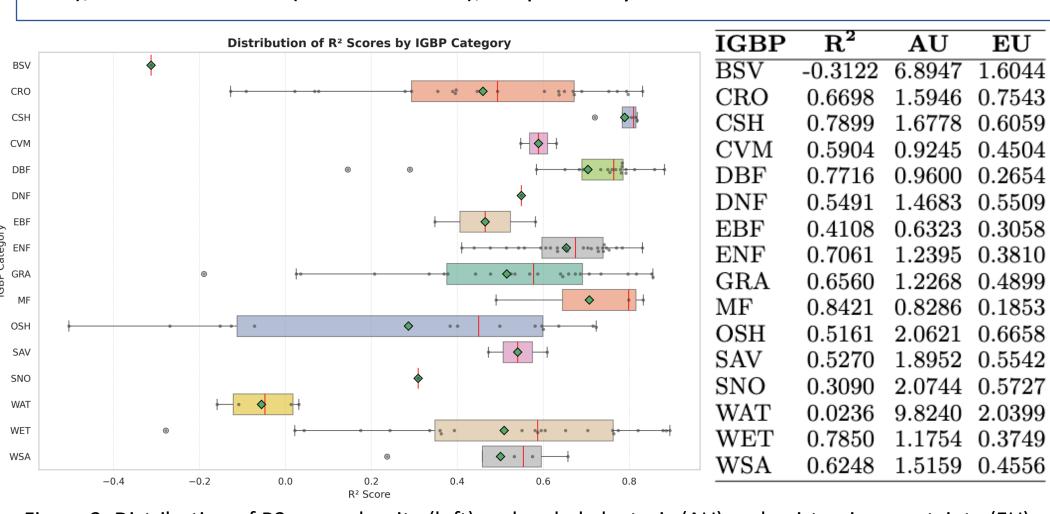


Figure 2: Distribution of R2 scores by site (left) and scaled aleatoric (AU) and epistemic uncertainty (EU) summary (right) across IGBP categories for the future test set. AU and EU are scaled by the predicted mean to allow comparison across categories.

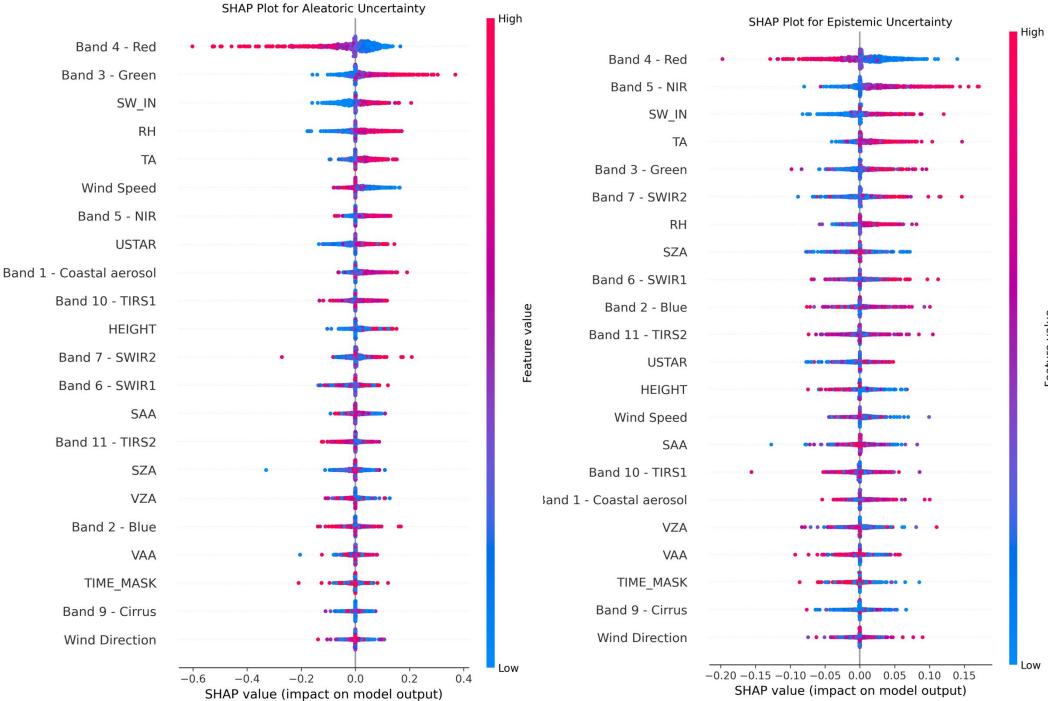


Figure 3: SHAP plots for aleatoric uncertainty (left) and epistemic uncertainty (right)

Conclusions

- Uncertainty-aware MDN: Combines Landsat imagery, eddy-covariance fluxes, and meteorological drivers, outputting carbon-flux predictions with separate aleatoric + epistemic uncertainty.
- Performance: R^2 0.74 (val) \rightarrow 0.72 (temporal test) shows strong time-generalization; drop to 0.58 on unseen sites pinpoints the spatial gap.
- Key insights: Water & Barren land exhibit the largest uncertainties; solar radiation, air temperature and Landsat Bands 3, 4 & 5 dominate both flux and uncertainty (SHAP).
- Uncertainty quantification improves prediction reliability, directly informs data acquisition priorities, strengthens Natural Climate Solutions validation, and supports robust climate policy and carbon market integrity.

References

- 1. B. W. Griscom et al. Natural climate solutions. Proceedings of the National Academy of Sciences, 114(44):11645–11650, 2017.
- 2. N. Seddon et al. Understanding the value and limits of nature-based solutions to climate change and other global challenges. Philosophical Transactions of the Royal Society B, 375(1794):20190120, 2020.
- 3. D. Baldocchi et al. Measuring fluxes of trace gases and energy between ecosystems and the atmosphere—the state and future of the eddy
- covariance method. Global Change Biology, 20(12):3600-3609, 2014. 4. G. Pastorello et al. The fluxnet2015 dataset and the oneflux processing pipeline for eddy covariance data. Scientific Data, 7:225, 2020
 - C. M. Bishop. Mixture density networks. Number NCRG/4288. 1994.
- International Conference on Computer Vision (ICCV), pages 10247–10256, 2021. 7. Ameriflux base data, n.d. Available at https://ameriflux.lbl.gov/data/. 8. Sungjoon Choi, Kyungjae Lee, Sungbin Lim, and Songhwai Oh. Uncertainty-aware learning from demonstration using mixture density networks

6. J. Choi, Z. Deng, X. Yu, and M. Chandraker. Active learning for deep object detection via probabilistic modeling. In Proceedings of the IEEE/CVF

with sampling-free variance modeling. 2018 IEEE International Conference on Robotics and Automation (ICRA), pages 6915–6922, 2017. 9. Scott M Lundberg and Su-In Lee. A unified approach to interpreting model predictions. In I. Guyon, U. Von Luxburg, S. Bengio, H. Wallach, R.

Fergus, S. Vishwanathan, and R. Garnett, editors, Advances in Neural Information Processing Systems, volume 30. Curran Associates, Inc., 2017.