Gwinnett School of Math, Science, and Technology

Multivariable Calculus Yearlong Notes

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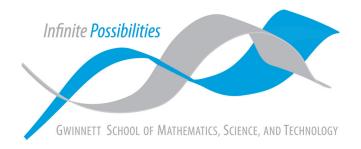


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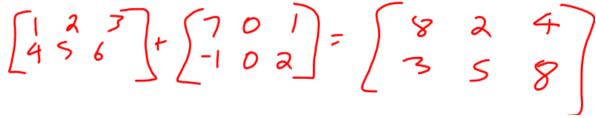
1 Chapter 1: Systems of Linear Equations and Matrices

1.1 Matrix Operations

- Matrix operations are given as: rows x columns
- Two matrices are equal
 ⇔ they have the same dimensions and values

1.1.1 Addition & Subtraction

Two matrices can be added/subtracted \iff they have the same dimensions.



1.1.2 Scalar Multiplication

• Scalar multiplication is defined as multiplying each element of a matrix by a number

$$3\begin{bmatrix} 2 & 1 \\ 5 & 2 \end{bmatrix} = \begin{bmatrix} 6 & 3 \\ 15 & 6 \end{bmatrix}$$

1.1.3 Matrix Multiplication

- We can **only** multiply an (m x n) by (n x p) matrix.
- The resulting matrix will be (m x p)

1.1.4 Properties of Matrix Arithmetic

(a) A + B = B + A (Commutative law for addition)

(b) A + (B + C) = (A + B) + C (Associative law for addition)

(c) A(BC) = (AB)C (Associative law for multiplication)

(d) A(B + C) = AB + AC (Left distributive law)

(e) (B + C)A = BA + CA (Right distributive law)

(f) A(B-C) = AB - AC

(g) (B-C)A = BA - CA

(h) a(B+C) = aB + aC

(i) a(B-C) = aB - aC

(j) (a+b)C = aC + bC

(k) (a-b)C = aC - bC

(I) a(bC) = (ab)C

(m) a(BC) = (aB)C = B(aC)

1.1.5 Examples

1.

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \cdot 1 + 2 \cdot 3 & 1 \cdot 2 + 2 \cdot 4 \\ 3 \cdot 1 + 4 \cdot 3 & 3 \cdot 2 + 4 \cdot 4 \end{bmatrix}$$

$$= \begin{bmatrix} 7 & 10 \\ 15 & 22 \end{bmatrix}$$

2.

$$\begin{bmatrix} 2 & -3 \\ 5 & 0 \\ -2 & 4 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

$$= \begin{bmatrix} 2 \cdot (-1) + (-3) \cdot 3 \\ 5 \cdot (-1) + 0 \cdot 3 \\ -2 \cdot (-1) + 4 \cdot 3 \\ 1 \cdot (-1) + 2 \cdot 3 \end{bmatrix}$$

$$= \begin{bmatrix} -11 \\ -5 \\ 14 \\ 5 \end{bmatrix}$$

3.

$$\begin{bmatrix} 4 & 5 & -1 \end{bmatrix} \begin{bmatrix} 8 \\ 0 \\ 2 \end{bmatrix}$$
$$= \begin{bmatrix} 4 \cdot 8 + 5 \cdot 0 + (-1) \cdot 2 \end{bmatrix}$$
$$= \begin{bmatrix} 30 \end{bmatrix}$$

1.2 Transpose of a Matrix

The transpose of an (m x n) matrix is the (n x m) matrix where the rows and columns are swapped.

If
$$B = \begin{bmatrix} 4 & 2 \\ -1 & 0 \\ 3 & 5 \end{bmatrix}$$
, $B^T = \begin{bmatrix} 4 & -1 & 3 \\ 2 & 0 & 5 \end{bmatrix}$

$$B \cdot B^{T} = \begin{bmatrix} 4 & 2 \\ -1 & 0 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} 4 & -1 & 3 \\ 2 & 0 & 5 \end{bmatrix}$$

$$= \begin{bmatrix} 4 \cdot 4 + 2 \cdot 2 & 4 \cdot (-1) + 2 \cdot 0 & 4 \cdot 3 + 2 \cdot 5 \\ (-1) \cdot 4 + 0 \cdot 2 & (-1) \cdot (-1) + 0 \cdot 0 & (-1) \cdot 3 + 0 \cdot 5 \\ 3 \cdot 4 + 5 \cdot 2 & 3 \cdot (-1) + 5 \cdot 0 & 3 \cdot 3 + 5 \cdot 5 \end{bmatrix}$$

$$= \begin{bmatrix} 20 & -4 & 22 \\ -4 & 1 & -3 \\ 22 & -3 & 34 \end{bmatrix}$$

- The transpose of a matrix is **always** multiplicative with the original.
- There is also a main diagonal that is the diagonal from the top left to the bottom right, but only square matrices have these.
- The **trace** of a square matrix A is equal to the sum of all the elements on the main diagonal: tr(A)

1.2.1 Transpose Matrix Properties

- $(A^T)^T = A$
- $(A + B)^T = A^T + B^T$ $(A B)^T = A^T B^T$ $(kA)^T = kA^T$ $(AB)^T = B^T A^T$

1.3 Homework — "Matrix Stuff" (08/03/2023)

1.3.1 Suppose that A, B, C, D and E are matrices with the following sizes:

A B C D E
$$(3 \times 2)$$
 (2×3) (3×3) (3×2) (2×3)

For each matrix operation, sort them into undefined if the operation can't be done, or defined if it can along with the correct dimensions of the outcome.

Undefined	Defined; (4 × 2)	Defined; (5 × 5)	Defined; (5 × 2)
BA AB + B E ^T A AE + B	AC + D	E(A + B)	$(A^T + E)D$ E(AC)

1.3.2 Consider the matrices

$$A = \begin{bmatrix} 3 & 0 \\ -1 & 2 \\ 1 & 1 \end{bmatrix}, B = \begin{bmatrix} 4 & -1 \\ 0 & 2 \end{bmatrix}, C = \begin{bmatrix} 1 & 4 & 2 \\ 3 & 1 & 5 \end{bmatrix}, D = \begin{bmatrix} 1 & 5 & 2 \\ -1 & 0 & 1 \\ 3 & 2 & 4 \end{bmatrix}, E = \begin{bmatrix} 6 & 1 & 3 \\ -1 & 1 & 2 \\ 4 & 1 & 3 \end{bmatrix}$$

In each part, compute the given expression (where possible).

2. **2A^T + C**

$$2A^{T} + C = 2\begin{bmatrix} 3 & 0 \\ -1 & 2 \\ 1 & 1 \end{bmatrix}^{T} + \begin{bmatrix} 1 & 4 & 2 \\ 3 & 1 & 5 \end{bmatrix}$$
$$= 2\begin{bmatrix} 3 & -1 & 1 \\ 0 & 2 & 1 \end{bmatrix} + \begin{bmatrix} 1 & 4 & 2 \\ 3 & 1 & 5 \end{bmatrix}$$
$$= \begin{bmatrix} 6 & -2 & 2 \\ 0 & 4 & 2 \end{bmatrix} + \begin{bmatrix} 1 & 4 & 2 \\ 3 & 1 & 5 \end{bmatrix}$$
$$= \begin{bmatrix} 7 & 2 & 4 \\ 3 & 5 & 7 \end{bmatrix}$$

3. $B^{T} + 5C^{T}$

$$B^{T} + 5C^{T} = \begin{bmatrix} 4 & -1 \\ 0 & 2 \end{bmatrix}^{T} + 5\begin{bmatrix} 1 & 4 & 2 \\ 3 & 1 & 5 \end{bmatrix}^{T}$$
$$= \begin{bmatrix} 4 & 0 \\ -1 & 2 \end{bmatrix} + 5\begin{bmatrix} 1 & 3 \\ 4 & 1 \\ 2 & 5 \end{bmatrix}$$
$$= \begin{bmatrix} 4 & 0 \\ -1 & 2 \end{bmatrix} + \begin{bmatrix} 5 & 15 \\ 20 & 5 \\ 10 & 25 \end{bmatrix}$$

= Undefined

4. $2E^{T} - 3D^{T}$

$$2E^{T} - 3D^{T} = 2\begin{bmatrix} 6 & 1 & 3 \\ -1 & 1 & 2 \\ 4 & 1 & 3 \end{bmatrix}^{T} - 3\begin{bmatrix} 1 & 5 & 2 \\ -1 & 0 & 1 \\ 3 & 2 & 4 \end{bmatrix}^{T}$$

$$= 2\begin{bmatrix} 6 & -1 & 4 \\ 1 & 1 & 1 \\ 3 & 2 & 3 \end{bmatrix} - 3\begin{bmatrix} 1 & -1 & 3 \\ 5 & 0 & 2 \\ 2 & 1 & 4 \end{bmatrix}$$

$$= \begin{bmatrix} 12 & -2 & 8 \\ 2 & 2 & 2 \\ 6 & 4 & 6 \end{bmatrix} - \begin{bmatrix} 3 & -3 & 9 \\ 15 & 0 & 6 \\ 6 & 3 & 12 \end{bmatrix}$$

$$= \begin{bmatrix} 9 & -5 & -1 \\ -13 & 2 & -4 \\ 0 & 1 & -6 \end{bmatrix}$$

5. tr(**DE**)

$$tr(DE) = tr\left(\begin{bmatrix} 1 & 5 & 2 \\ -1 & 0 & 1 \\ 3 & 2 & 4 \end{bmatrix} \begin{bmatrix} 6 & 1 & 3 \\ -1 & 1 & 2 \\ 4 & 1 & 3 \end{bmatrix}\right)$$

$$= tr\left(\begin{bmatrix} 1 \cdot 6 + 5 \cdot (-1) + 2 \cdot 4 & 1 \cdot 1 + 5 \cdot 1 + 2 \cdot 1 & 1 \cdot 3 + 5 \cdot 2 + 2 \cdot 3 \\ (-1) \cdot 6 + 0 \cdot (-1) + 1 \cdot 4 & (-1) \cdot 1 + 0 \cdot 1 + 1 \cdot 1 & (-1) \cdot 3 + 0 \cdot 2 + 1 \cdot 3 \\ 3 \cdot 6 + 2 \cdot (-1) + 4 \cdot 4 & 3 \cdot 1 + 2 \cdot 1 + 4 \cdot 1 & 3 \cdot 3 + 2 \cdot 2 + 4 \cdot 3 \end{bmatrix}\right)$$

$$= tr\left(\begin{bmatrix} 9 & 8 & 19 \\ -2 & 0 & 0 \\ 32 & 9 & 25 \end{bmatrix}\right)$$

$$= 34$$

2 Intro to Systems

What are we looking for?

Lines: How many possible solutions?

- · Infinite solutions
- · One solution
- No solutions

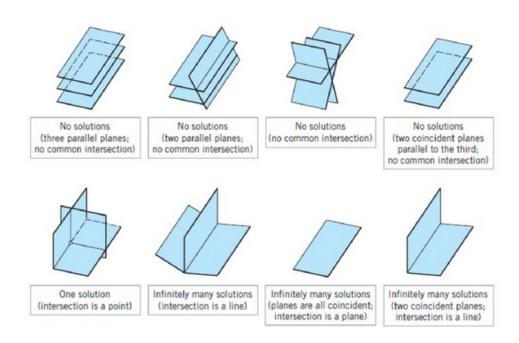
Planes: How many possible solutions?

- · Infinite solutions
- No solutions

What does linear actually mean?

- The word linear really means that you've got equations with variables and **all** of the variables are degree one.
- This means that there is no limit to the number of dimensions in a linear system.

Linear Systems in Three Unknowns



2.1 Review: Solve the following systems

1.
$$\begin{cases} 2x + y = 10 \\ 3x - y = 5 \end{cases}$$

$$5x = 15$$

$$x = 3$$

$$2(3) + y = 10$$

$$6 + y = 10$$

$$y = 4$$

2.
$$\begin{cases} 2x + y = 10 \\ 6x + 3y = 10 \end{cases}$$

$$y = 10 - 2x$$

 $6x + 3(10 - 2x) = 10$
 $6x + 30 - 6x = 10$
 $30 = 10$: no solution

3.
$$\begin{cases} 5x - 2y = 4 \\ 15x - 6y = 12 \end{cases}$$

$$0 = 0$$

12 = 12.: infinite solutions

2.1.2 Inconsistent

2.1.1 Consistent

- A system of equations is **consistent** if it has at least one solution.
- A system of equations is inconsistent if it has no solutions.

2.2 The Augmented Matrix

$$\begin{cases} x - y + 2z = 5 \\ 2x - 2y + 4z = 10 \longrightarrow \begin{bmatrix} 1 & -1 & 2 & 5 \\ 2 & -2 & 4 & 10 \\ 3 & -3 & 6 & 15 \end{bmatrix}$$

2.3 Elementary Row Operations

- 1. Interchange 2 rows
- 2. Multiply a row by a non-zero constant
- 3. Add/substract a multiple of one row to/from another row

Doing these things changes the matrix, but it's the same system!

2.3.1 Example 1... again

$$\begin{cases} 2x + y = 10 \\ 3x - y = 5 \end{cases}$$

$$\begin{bmatrix} 2 & 1 & 10 \\ 3 & -1 & 5 \end{bmatrix} \xrightarrow{\frac{1}{2}R_1} \begin{bmatrix} 1 & \frac{1}{2} & 5 \\ 3 & -1 & 5 \end{bmatrix} \xrightarrow{R_2 - 3R_1} \begin{bmatrix} 1 & \frac{1}{2} & 5 \\ 0 & -\frac{5}{2} & -10 \end{bmatrix}$$

$$\xrightarrow{-\frac{2}{5}R_2} \begin{bmatrix} 1 & \frac{1}{2} & 5 \\ 0 & 1 & 4 \end{bmatrix} \xrightarrow{R_1 - \frac{1}{2}R_2} \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 4 \end{bmatrix}$$

And so... x = 3 and y = 4!

2.4 Connection to Matrices

If we can make a system's matrix look like

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & c_1 \\ 0 & 1 & 0 & c_2 \\ 0 & 0 & 1 & c_3 \end{array}\right],$$

then the solution to the system will be the ordered triple (c_1, c_2, c_3) .

2.4.1 Example 2: again

$$\begin{cases} 2x + y = 10 \\ 6x + 3y = 10 \end{cases}$$

$$\begin{bmatrix} 2 & 1 & | & 10 \\ 6 & 3 & | & 10 \end{bmatrix} \xrightarrow{\frac{1}{2}R1} \begin{bmatrix} 1 & \frac{1}{2} & | & 5 \\ 6 & 3 & | & 10 \end{bmatrix} \xrightarrow{R2-6R1} \begin{bmatrix} 1 & \frac{1}{2} & | & 5 \\ 0 & 0 & | & -20 \end{bmatrix}$$

This is inconsistent, so there is no solution.

2.4.2 Example 3: again

$$\begin{cases} 5x - 2y = 4 \\ 15x - 6y = 12 \end{cases}$$

$$\begin{bmatrix} 5 & -2 & | & 4 \\ 15 & -6 & | & 12 \end{bmatrix} \xrightarrow{\frac{1}{5}R1} \begin{bmatrix} 1 & -\frac{2}{5} & | & \frac{4}{5} \\ 15 & -6 & | & 12 \end{bmatrix} \xrightarrow{R2-15R1} \begin{bmatrix} 1 & -\frac{2}{5} & | & \frac{4}{5} \\ 0 & 0 & | & 0 \end{bmatrix}$$

Since 0 = 0, there are infinitely many solutions.

2.4.3 Example 4: Solve the following system

$$\begin{cases} x_1 - 2x_2 + x_3 = 0 \\ 2x_2 - 8x_3 = 8 \\ -4x_1 + 5x_2 + 9x_3 = -9 \end{cases}$$

$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ -4 & 5 & 9 & -9 \end{bmatrix} \xrightarrow{R3+4R1} \begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ 0 & -3 & 13 & -9 \end{bmatrix} \xrightarrow{R3+\frac{3}{2}R2} \begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ 0 & 0 & -1 & 3 \end{bmatrix}$$

$$\xrightarrow{\frac{1}{2}R_2} \begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 1 & -4 & 4 \\ 0 & -3 & 13 & -9 \end{bmatrix} \xrightarrow{R_1+2R_2} \begin{bmatrix} 1 & 0 & -7 & 8 \\ 0 & 1 & -4 & 4 \\ 0 & 0 & 1 & 3 \end{bmatrix} \xrightarrow{R_1+7R_3} \begin{bmatrix} 1 & 0 & 0 & 29 \\ 0 & 1 & 0 & 16 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

Therefore the solution to (x_1, x_2, x_3) is (29, 16, 3).

2.4.4 Elementary Row Operations & REF Homework Problem (08/08/2023)

$$\begin{cases} x + y + 2z = 8 \\ -x - 2y + 3z = 1 \\ 3x - 7y + 4z = 10 \end{cases}$$

$$\begin{bmatrix} 1 & 1 & 2 & 8 \\ -1 & -2 & 3 & 1 \\ 3 & -7 & 4 & 10 \end{bmatrix} \xrightarrow{R_2+R_1} \begin{bmatrix} 1 & 1 & 2 & 8 \\ 0 & -1 & 5 & 9 \\ 0 & -10 & -2 & -14 \end{bmatrix} \xrightarrow{R_2-R_3} \begin{bmatrix} 1 & 1 & 2 & 8 \\ 0 & 1 & -5 & -9 \\ 0 & 10 & 2 & 14 \end{bmatrix}$$

$$\xrightarrow{R_1-R_2} \begin{bmatrix} 1 & 0 & 7 & 17 \\ 0 & 1 & -5 & -9 \\ 0 & 0 & 52 & 104 \end{bmatrix} \xrightarrow{\frac{1}{52}R_3} \begin{bmatrix} 1 & 0 & 7 & 17 \\ 0 & 1 & -5 & -9 \\ 0 & 0 & 1 & 2 \end{bmatrix} \xrightarrow{R_1-7R_3} \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

Therefore, the solution to (x, y, z) is (3, 1, 2).

2.5 Gaussian Elimination

Vocabulary: A matrix is in Row Echelon Form (REF) if:

- (a) Any rows of all zeroes are placed at the bottom of the matrix
- (b) All other rows have a leading 1 ("pivot")
- (c) As we move down the matrix, each leading 1 is further to the right than the 1 above it

A matrix is in Row Reduced Echelon Form if the three above conditions are met in adition to:

(d) Each column with a leading 1 has all other entries in the column as a 0. ("pivot column")

2.5.1 Examples

2.6 Gaussian Elimination With Back-Substitution

2.6.1 Goal:

To get the augmented matrix in REF

Solve:
$$\begin{cases} x_1 - 2x_2 + 3x_3 = 9 \\ -x_1 + 3x_2 = -4 \\ 2x_1 - 5x_2 + 5x_3 = 17 \end{cases}$$

$$\begin{bmatrix} 1 & -2 & 3 & 9 \\ -1 & 3 & 0 & -4 \\ 2 & -5 & 5 & 17 \end{bmatrix} \xrightarrow{\xrightarrow{R_2 + R_1}} \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & -1 & -1 & -1 \end{bmatrix} \xrightarrow{\xrightarrow{R_1 + 2R_2}} \begin{bmatrix} 1 & 0 & 9 & 19 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 2 & 4 \end{bmatrix}$$

$$\xrightarrow{\frac{1}{2}R_3} \begin{bmatrix} 1 & 0 & 9 & 19 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

$$x + 9z = 19$$

$$y + 3z = 5$$

$$z = 2$$

$$\therefore z = 2, y = 5 - 3z, x = 19 - 9z$$

$$z = 2, y = 5 - 3(2), x = 19 - 9(2)$$

$$z = 2, y = -1, x = 1$$

Therefore, the solution (x_1, x_2, x_3) is (1, -1, 2).

2.6.2 Gaussian Elimination Homework Problem (08/09/2023)

$$\begin{cases}
-2w & + y + z = -3 \\
x + 2y - z = 2 \\
-3w + 2x + 4y + z = -2 \\
-w + x - 4y - 7z = -19
\end{cases}$$

$$\begin{bmatrix} -2 & 0 & 1 & 1 & | & -3 \\ 0 & 1 & 2 & -1 & | & 2 \\ -3 & 2 & 4 & 1 & | & -2 \\ -1 & 1 & -4 & -7 & | & -19 \end{bmatrix} \xrightarrow{R_4} \begin{bmatrix} -1 & 1 & -4 & -7 & | & -19 \\ 0 & 1 & 2 & -1 & | & 2 \\ -3 & 2 & 4 & 1 & | & -2 \\ -3 & 2 & 4 & 1 & | & -2 \end{bmatrix} \xrightarrow{R_1 + R_2} \begin{bmatrix} 1 & -1 & 4 & 7 & | & 19 \\ 0 & 1 & 2 & -1 & | & 2 \\ -3 & 2 & 4 & 1 & | & -2 \\ -3 & 2 & 4 & 1 & | & -2 \end{bmatrix} \xrightarrow{R_3 + 3R_1} \begin{bmatrix} 1 & -1 & 4 & 7 & | & 19 \\ 0 & 1 & 2 & -1 & | & 2 \\ 0 & -1 & 16 & 22 & | & 55 \end{bmatrix} \xrightarrow{R_3 + R_2} \xrightarrow{R_4 + 2R_2} \begin{bmatrix} 1 & 0 & 6 & 6 & | & 21 \\ 0 & 1 & 2 & -1 & | & 2 \\ 0 & 0 & 18 & 21 & | & 57 \\ 0 & 0 & 13 & 13 & | & 39 \end{bmatrix} \xrightarrow{\frac{13}{18}R_3} \begin{bmatrix} 1 & 0 & 6 & 6 & | & 21 \\ 0 & 1 & 2 & -1 & | & 2 \\ 0 & 0 & 1 & | & \frac{7}{6} & | & \frac{19}{6} \\ 0 & 0 & 13 & | & 13 & | & \frac{19}{6} \end{bmatrix} \xrightarrow{R_4 - 13R_3} \xrightarrow{R_4 - 13R_3} \begin{bmatrix} 1 & 0 & 0 & -1 & | & 2 \\ 0 & 1 & 0 & -\frac{10}{3} & | & \frac{19}{6} \\ 0 & 0 & 0 & 1 & | & \frac{19}{6} & | & \frac{13}{3} \\ 0 & 0 & 1 & 0 & | & \frac{13}{6} & | & \frac{13}{6} & | & \frac{13}{6} \end{bmatrix} \xrightarrow{\frac{6}{13}R_4} \begin{bmatrix} 1 & 0 & 0 & -1 & | & 2 \\ 0 & 1 & 0 & -\frac{10}{6} & | & -\frac{13}{3} \\ 0 & 0 & 1 & 0 & | & \frac{19}{6} & | & \frac{13}{6} & | & \frac{19}{6} \\ 0 & 0 & 0 & 1 & | & 1 \end{bmatrix} \Longrightarrow \begin{cases} W = 3 \\ X = -1 \\ y = 2 \\ z = 1 \end{cases}$$

2.7 Gauss-Jordan Elimination

2.7.1 Goal:

To get the matrix into RREF

Solve:
$$\begin{cases} x_1 & -3x_3 = -2 \\ 3x_1 + x_2 - 2x_3 = 5 \\ 2x_1 + 2x_2 + x_3 = 4 \end{cases}$$

$$\begin{bmatrix} 1 & 0 & -3 & | & -2 \\ 3 & 1 & -2 & | & 5 \\ 2 & 2 & 1 & | & 4 \end{bmatrix} \xrightarrow{R_2 - 3R_1} \begin{bmatrix} 1 & 0 & -3 & | & -2 \\ 0 & 1 & 7 & | & 11 \\ 0 & 2 & 7 & | & 8 \end{bmatrix} \xrightarrow{R_3 - 2R_2} \begin{bmatrix} 1 & 0 & -3 & | & -2 \\ 0 & 1 & 7 & | & 11 \\ 0 & 0 & -7 & | & -14 \end{bmatrix}$$

$$\xrightarrow{\frac{-1}{7}R_3} \begin{bmatrix} 1 & 0 & -3 & | & -2 \\ 0 & 1 & 7 & | & 11 \\ 0 & 0 & 1 & | & 2 \end{bmatrix} \xrightarrow{\frac{R_1 + 3R_3}{R_2 - 7R_3}} \begin{bmatrix} 1 & 0 & 0 & | & 4 \\ 0 & 1 & 0 & | & -3 \\ 0 & 0 & 1 & | & 2 \end{bmatrix} \Longrightarrow \begin{cases} x_1 = 4 \\ x_2 = -3 \\ x_3 = 2 \end{cases}$$

2.8 Matrix Properties, Equations, and Inverses

2.8.1 With Real Numbers

- If ab = bc, then a = c, if $b \neq 0$
- If ab = 0, then a = 0 or b = 0, or both

2.8.2 With Matrices

- If AB = AC, then B = C, if A is invertible
- If AB = [0], then A = [0] or B = [0], or both

2.8.2.1 Multiply:

$$\begin{bmatrix} 2 & 3 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} 5 & -3 \\ -3 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 2(5) + 3(-3) & 2(-3) + 3(2) \\ 3(5) + 5(-3) & 3(-3) + 5(2) \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

2.8.3 Matrix Inverses

- If a matrix has an inverse, it is said to be invertible or non-singular.
- If a matrix does not have an inverse, it is said to be singular.
- Every square matrix has a "special number" associated with it called the determinant.
- For the 2 × 2 matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, the determinant is ad bc
- $A^{-1} = \frac{1}{\det A} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$
- When det A = 0, the matrix is singular and has no inverse (since you cannot divide by zero)

Find the inverse of $A = \begin{bmatrix} 4 & 3 \\ 1 & 2 \end{bmatrix}$

$$\begin{bmatrix} 4 & 3 \\ 1 & 2 \end{bmatrix}^{-1} = \frac{1}{\det A} \begin{bmatrix} 2 & -3 \\ -1 & 4 \end{bmatrix}$$

$$= \frac{1}{(4)(2) - (3)(1)} \begin{bmatrix} 2 & -3 \\ -1 & 4 \end{bmatrix}$$

$$= \frac{1}{5} \begin{bmatrix} 2 & -3 \\ -1 & 4 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{2}{5} & -\frac{3}{5} \\ -\frac{1}{5} & \frac{4}{5} \end{bmatrix}$$

3 Chapter 2: Determinants

3.1 Prior Knowledge:

$$\begin{bmatrix} 10 & -4 \\ -3 & -5 \end{bmatrix} = -50 - = -62$$

$$\begin{bmatrix} 2 & 4 & 3 \\ -1 & 2 & 3 \\ 3 & 0 & -2 \end{bmatrix}$$

$$= ((2 \cdot 2 \cdot -2) + (4 \cdot 3 \cdot 3) + (3 \cdot -1 \cdot 0)) - ((3 \cdot 2 \cdot 3) + (0 \cdot 3 \cdot 2) + (-2 \cdot -1 \cdot 4))$$

$$= (-8 + 36 + 0) - (18 + 0 + 8)$$

$$= 28 - 26$$

$$= 2$$

3.2 Minors & Cofactors

Given a square matrix A, the $\underline{\text{minor}}$ of matrix element a_{ij} , (M_{ij}) is the determinant of the matrix formed by removing the i^{th} row and j^{th} column from matrix A.

The <u>cofactor</u> of matrix element a_{ij} , $C_{ij} = (-1)^{i+j} \cdot M_{ij}$

3.2.1 Example

Let
$$\det \begin{bmatrix} 2 & 4 & 3 \\ -1 & 2 & 3 \\ 3 & 0 & -2 \end{bmatrix}$$
. What is the cofactor of element (1, 1)?

$$M_{11} = \begin{vmatrix} 2 & 3 \\ 0 & -2 \end{vmatrix} = -4$$

$$C_{11} = 1 \cdot -4 = -4$$

Find the minor and cofactor of: \ a) $a_{21} = -1$

$$M_{21} = \begin{vmatrix} 4 & 3 \\ 0 & -2 \end{vmatrix} = -8$$
$$C_{21} = 8$$

b)
$$a_{33} = -2$$

$$M_{33} = \begin{vmatrix} 2 & 4 \\ -1 & 2 \end{vmatrix} = 8$$

$$C_{33} = 8$$

3.3 Cofactor Expansion

- 1) Pick a row or column
- 2) Multiply every entry in that row or column by it's corresponding cofactor
- 3) Add those together. That's it

$$A = \begin{bmatrix} 6 & 7 & -1 \\ 0 & 4 & 1 \\ 2 & 5 & -3 \end{bmatrix}$$

$$det(A) = 6 \begin{pmatrix} 4 & 1 \\ 5 & -3 \end{pmatrix} + 7 \begin{pmatrix} - \begin{pmatrix} 0 & 1 \\ 2 & -3 \end{pmatrix} \end{pmatrix} + -1 \begin{pmatrix} \begin{pmatrix} 0 & 4 \\ 2 & 5 \end{pmatrix} \end{pmatrix}$$
$$= 6(-17) + 7(2) + (-1(-8))$$
$$= -102 + 14 + 8$$
$$= -80$$

3.3.1 Example

$$A = \begin{bmatrix} 6 & 4 & 2 \\ 5 & -6 & 1 \\ 0 & 3 & 0 \end{bmatrix}$$

$$6\begin{vmatrix} -6 & 1 \\ 3 & 0 \end{vmatrix} + 4\begin{pmatrix} -\begin{vmatrix} 5 & 1 \\ 0 & 0 \end{vmatrix} \end{pmatrix} + 2\begin{vmatrix} 5 & -6 \\ 0 & 3 \end{vmatrix}$$

$$= 6(-3) + 0 + 2(15)$$

$$= -18 + 30$$

$$= 12$$

3.3.2 Does the method generalize to 2×2 matrices?

The determinant of a 1×1 matrix is... itself!

3.3.3 Find the determinant of a 4×4

$$A = \begin{bmatrix} -3 & 2 & 0 & 8 \\ 2 & 1 & 0 & -4 \\ 5 & -2 & 1 & 5 \\ 2 & 3 & 0 & 6 \end{bmatrix}$$

$$= 0 + 0 + \begin{vmatrix} -3 & 2 & 8 \\ 2 & 1 & -4 \\ 2 & 3 & 6 \end{vmatrix} + 0$$

$$= -2 \begin{vmatrix} 2 & 8 \\ 3 & 6 \end{vmatrix} + \begin{vmatrix} -3 & 8 \\ 2 & 6 \end{vmatrix} - \left(-4 \begin{vmatrix} -3 & 2 \\ 2 & 3 \end{vmatrix} \right)$$

$$= 24 - 34 - 52$$

$$= -62$$

3.4 Theorem

If A is an $n \times n$ matrix, then regardless of which row or column of A is chosen, the number obtained by multiplying the elements in that row or column by their corresponding cofactors is **always the same** and is called the determinant of A.

3.4.1 Example

Find the determinant of
$$A = \begin{bmatrix} 1 & 0 & 0 & -1 \\ 3 & 1 & 2 & 2 \\ 1 & 0 & -2 & 1 \\ 2 & 0 & 0 & 1 \end{bmatrix}$$

$$1 \cdot \begin{vmatrix} 1 & 0 & -1 \\ 1 & -2 & 1 \\ 2 & 0 & 1 \end{vmatrix}$$

$$= \begin{pmatrix} -2 \begin{vmatrix} 1 & -1 \\ 2 & 1 \end{vmatrix} \end{pmatrix}$$

$$= -6$$

3.5 Triangular Matrices

Find the determinant of
$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 2 & 2 & 2 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 4 \end{bmatrix}$$

$$\begin{vmatrix} 2 & 2 & 2 \\ 0 & 3 & 3 \\ 0 & 0 & 4 \end{vmatrix}$$

$$= 2 \begin{vmatrix} 3 & 3 \\ 0 & 4 \end{vmatrix}$$

$$= 2(3 \cdot 4)$$

$$= 2 \cdot 12$$

$$= 24$$

If A is an $n \times n$ triangular matrix, then det(A) is equal to the product of the elements along the main diagonal.

3.6 An Important Definition

Elementary Matrix a matrix that can be obtanied from the $n \times n$ identity matrix by performing a single row operation. \

Are the following matrices elementary? 1) $\begin{bmatrix} 1 & 0 \\ -5 & 1 \end{bmatrix}$ + $(R_3 + 5R_1)$ yes 2) $\begin{bmatrix} -5 & 1 \\ 1 & 0 \end{bmatrix}$ + $(R_1 + 5R_2)$...

3.7 A Pair of Theorems

3.7.1 Theorem: If a square matrix A has a row of column of zeros, then det(A) = 0

3.7.2 Theorem: If A is a square matrix, then $det(A) = det(A^T)$

3.8 Unit 1 & 2 Homework Problems

3.8.1 "Gaussian Elimination" (08/11/2023)

3.8.1.1 Solve this system using Gaussian Elimination

$$\begin{cases} x_1 + x_2 + 2x_3 = 8 \\ -x_1 - 2x_2 + 3x_3 = 1 \\ 3x_1 - 7x_2 + 4x_3 = 10 \end{cases}$$

$$\Rightarrow \begin{bmatrix} 1 & 1 & 2 & 8 \\ -1 & -2 & 3 & 1 \\ 3 & -7 & 4 & 10 \end{bmatrix} \xrightarrow{\stackrel{R_2 + R_1}{R_3 - 3R_1}} \begin{bmatrix} 1 & 1 & 2 & 8 \\ 0 & -1 & 5 & 9 \\ 0 & -10 & -2 & -14 \end{bmatrix} \xrightarrow{\stackrel{R_2}{\longrightarrow}} \begin{bmatrix} 1 & 1 & 2 & 8 \\ 0 & 1 & -5 & -9 \\ 0 & -10 & -2 & -14 \end{bmatrix}$$

$$\xrightarrow{\stackrel{R_3 + 10R_2}{\longrightarrow}} \begin{bmatrix} 1 & 1 & 2 & 8 \\ 0 & 1 & -5 & -9 \\ 0 & 0 & -52 & -104 \end{bmatrix} \xrightarrow{\stackrel{-1}{52}R_3} \begin{bmatrix} 1 & 1 & 2 & 8 \\ 0 & 1 & -5 & -9 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

$$\therefore \begin{cases} x_1 + x_2 + 2x_3 = 8 \\ x_2 - 5x_3 = -9 \Rightarrow \begin{cases} x_1 = 3 \\ x_2 = 1 \\ x_3 = 2 \end{cases}$$

3.8.1.2 Solve this system using Gaussian Elimination

$$\begin{cases} x_1 - 2x_2 + 3x_3 = 0 \\ -2x_1 - 3x_2 - 4x_3 = 0 \\ 2x_1 - 4x_2 + 4x_3 = 0 \end{cases}$$

$$\Rightarrow \begin{bmatrix} 1 & -2 & 3 & 0 \\ -2 & -3 & -4 & 0 \\ 2 & -4 & 4 & 0 \end{bmatrix} \xrightarrow{\frac{R_2 + 2R_1}{R_3 - 2R_1}} \begin{bmatrix} 1 & -2 & 3 & 0 \\ 0 & -7 & 2 & 0 \\ 0 & 0 & -2 & 0 \end{bmatrix} \xrightarrow{\frac{-1}{7}R_2} \begin{bmatrix} 1 & -2 & 3 & 0 \\ 0 & 1 & \frac{2}{7} & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\therefore \begin{cases} x_1 - 2x_2 + 3x_3 = 0 \\ x_2 + \frac{2}{7}x_3 = 0 \Rightarrow 1 \neq 0 \therefore \text{ no solution} \\ x_3 = 0 \end{cases}$$

3.8.2 "Inverses and Determinants" (08/14)

3.8.2.1 Find the determinants of the following:

$$1) \begin{bmatrix} 2 & -3 \\ 4 & 4 \end{bmatrix}$$

$$\begin{vmatrix} 2 & -3 \\ 4 & 4 \end{vmatrix} = 2(4) - (-3)(4) = 8 + 12 = 20$$

$$2) \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$$

$$\begin{vmatrix} 2 & 0 \\ 0 & 3 \end{vmatrix} = 2(3) - 0(0) = 6$$

3)
$$\begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

$$\begin{vmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{vmatrix} = \cos^2 \theta + \sin^2 \theta = 1$$

3.8.2.2 Find the INVERSES of those matrices:

1)
$$\begin{bmatrix} 2 & -3 \\ 4 & 4 \end{bmatrix}$$

$$\begin{bmatrix} 2 & -3 \\ 4 & 4 \end{bmatrix}^{-1} = \frac{1}{20} \begin{bmatrix} 4 & 3 \\ -4 & 2 \end{bmatrix} = \begin{bmatrix} \frac{1}{5} & \frac{3}{20} \\ -\frac{1}{5} & \frac{1}{10} \end{bmatrix}$$

$$2) \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}^{-1} = \frac{1}{6} \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{3} \end{bmatrix}$$

3)
$$\begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

$$\begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}^{-1} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

3.8.3 Inverses and Determinants (08/15)

3.8.3.1 Use a matrix equation to solve the following problems:

1)
$$\begin{cases} 3x_1 - 2x_2 = 1 \\ 4x_1 + 5x_2 = 3 \end{cases}$$

$$\Rightarrow \begin{bmatrix} 3 & -2 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$
$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 & -2 \\ 4 & 5 \end{bmatrix}^{-1} \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$
$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \frac{1}{23} \begin{bmatrix} 5 & 2 \\ -4 & 3 \end{bmatrix} \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$
$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \frac{1}{23} \begin{bmatrix} -1 \\ 9 \end{bmatrix}$$
$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -\frac{1}{23} \\ \frac{9}{23} \end{bmatrix}$$

2)
$$\begin{cases} 6x_1 + x_2 = 0 \\ 4x_1 - 3x_2 = -2 \end{cases}$$

$$\Rightarrow \begin{bmatrix} 6 & 1 \\ 4 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 6 & 1 \\ 4 & -3 \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \frac{1}{-22} \begin{bmatrix} -3 & -1 \\ -4 & 6 \end{bmatrix} \begin{bmatrix} 0 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \frac{1}{-22} \begin{bmatrix} 2 \\ 8 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -\frac{1}{11} \\ -\frac{4}{11} \end{bmatrix}$$

3.8.4 Consistent Systems (08/21)

3.8.4.1 Solve the linear systems together by reducing the appropriate augmented matrix.

$$\begin{cases} x_1 - 5x_2 = b_1 \\ 3x_1 + 2x_2 = b_2 \end{cases}$$

1)
$$b_1 = 1$$
, $b_2 = 4$
2) $b_1 = -2$, $b_2 = 5$

First, let's solve it for the general case:

$$\begin{bmatrix} 1 & -5 & b_1 \\ 3 & 2 & b_2 \end{bmatrix} \xrightarrow{R_2 - 3R_1} \begin{bmatrix} 1 & -5 & b_1 \\ 0 & 17 & b_2 - 3b_1 \end{bmatrix} \xrightarrow{\frac{1}{17}R_2} \begin{bmatrix} 1 & -5 & b_1 \\ 0 & 1 & \frac{b_2 - 3b_1}{17} \end{bmatrix} \xrightarrow{\frac{R_1 + 5R_2}{17}} \begin{bmatrix} 1 & 0 & \frac{2b_1 + 5b_2}{17} \\ 0 & 1 & \frac{-3b_1 + b_2}{17} \end{bmatrix}$$

Therefore, the solution to the general case is $(x_1, x_2) = (\frac{2b_1 + 5b_2}{17}, \frac{-3b_1 + b_2}{17})$

And so, for the specific cases:

1)
$$(x_1, x_2) = \left(\frac{2(1)+5(4)}{17}, \frac{-3(1)+4}{17}\right) = \left(\frac{13}{17}, \frac{1}{17}\right)$$

2) $(x_1, x_2) = \left(\frac{2(-2)+5(5)}{17}, \frac{-3(-2)+5}{17}\right) = \left(\frac{16}{17}, \frac{11}{17}\right)$

2)
$$(x_1, x_2) = \left(\frac{2(-2)+5(5)}{17}, \frac{-3(-2)+5}{17}\right) = \left(\frac{16}{17}, \frac{11}{17}\right)$$

3.8.4.2 Determine the conditions on b, if any, in order to guarantee that the linear system is consistent.

$$\begin{cases} x_1 + 3x_2 = b_1 \\ -2x_1 + x_2 = b_2 \end{cases}$$

$$\begin{bmatrix} 1 & 3 & b_1 \\ -2 & 1 & b_2 \end{bmatrix} \xrightarrow{R_2 + 2R_1} \begin{bmatrix} 1 & 3 & b_1 \\ 0 & 7 & b_2 + 2b_1 \end{bmatrix} \xrightarrow{\frac{1}{7}R_2} \begin{bmatrix} 1 & 3 & b_1 \\ 0 & 1 & \frac{b_2 + 2b_1}{7} \end{bmatrix} \xrightarrow{\frac{R_1 - 3R_2}{7}} \begin{bmatrix} 1 & 0 & \frac{b_1 - 3b_2}{7} \\ 0 & 1 & \frac{b_2 + 2b_1}{7} \end{bmatrix}$$

There are no conditions. The system is consistent for all values of b_1 and b_2 .

3.8.5 Another "determining the conditions" problem:

$$\begin{cases} x_1 - 2x_2 - x_3 = b_1 \\ -4x_1 + 5x_2 + 2x_3 = b_2 \\ -4x_1 + 7x_2 + 4x_3 = b_3 \end{cases}$$

$$\begin{bmatrix} 1 & -2 & -1 & b_{1} \\ -4 & 5 & 2 & b_{2} \\ -4 & 7 & 4 & b_{3} \end{bmatrix} \xrightarrow{R_{2}+4R_{1} \atop R_{3}+4R_{1}} \begin{bmatrix} 1 & -2 & -1 & b_{1} \\ 0 & -3 & -2 & b_{2}+4b_{1} \\ 0 & -1 & 0 & b_{3}+4b_{1} \end{bmatrix} \xrightarrow{-\frac{1}{3}R_{2}} \begin{bmatrix} 1 & -2 & -1 & b_{1} \\ 0 & 1 & \frac{2}{3} & \frac{-b_{2}-4b_{1}}{3} \\ 0 & 0 & -\frac{2}{3} & \frac{b_{3}+4b_{1}}{3} \end{bmatrix}$$

$$\xrightarrow{-\frac{3}{2}R_{3}} \begin{bmatrix} 1 & -2 & -1 & b_{1} \\ 0 & 1 & \frac{2}{3} & \frac{-b_{2}-4b_{1}}{3} \\ 0 & 0 & 1 & \frac{-b_{2}-4b_{1}}{3} \end{bmatrix}$$

Therefore, the system is consistent for all values of b_1 , b_2 , and b_3 .

3.8.6 Triangular and Diagonal Matrices

3.8.6.1 Find A^2

1)
$$A = \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix}$$

$$A^{2} = \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix}$$
$$= \begin{bmatrix} 1(1) + 0(0) & 1(0) + 0(-2) \\ 0(1) + (-2)(0) & 0(0) + (-2)(-2) \end{bmatrix}$$
$$= \begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix}$$

$$A^{2} = \begin{bmatrix} -6 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix} \begin{bmatrix} -6 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

$$= \begin{bmatrix} (-6)(-6) + (0)(0) + (0)(0) & (-6)(0) + (0)(3) + (0)(0) & (-6)(0) + (0)(0) + (0)(5) \\ (0)(-6) + (3)(0) + (0)(0) & (0)(0) + (3)(3) + (0)(0) & (0)(0) + (3)(0) + (0)(5) \\ (0)(-6) + (0)(0) + (5)(0) & (0)(0) + (0)(3) + (5)(0) & (0)(0) + (0)(0) + (5)(5) \end{bmatrix}$$

$$= \begin{bmatrix} 36 & 0 & 0 \\ 0 & 9 & 0 \\ 0 & 0 & 25 \end{bmatrix}$$

3.8.6.2 Find A^{-k} , such that k is some nonzero constant

$$A = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & -4 & 0 & 0 \\ 0 & 0 & -3 & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$

$$A^{-k} = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & -4 & 0 & 0 \\ 0 & 0 & -3 & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix}^{-k}$$

$$= \begin{bmatrix} 2^{-k} & 0 & 0 & 0 \\ 0 & (-4)^{-k} & 0 & 0 \\ 0 & 0 & (-3)^{-k} & 0 \\ 0 & 0 & 0 & 2^{-k} \end{bmatrix}$$

4. Determine whether each matrix is symmetric or not.

 $\mathbf{\#} \begin{bmatrix} -8 & -8 \\ 0 & 0 \end{bmatrix}$

 $\mathbf{ii} \quad \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}$

 $\mathbf{ii} \begin{bmatrix} 3 & 4 \\ 4 & 0 \end{bmatrix}$

 $\mathbf{II} \begin{bmatrix} 2 & -1 & 3 \\ -1 & 5 & 1 \\ 3 & 1 & 7 \end{bmatrix}$

Symmetric

 $\begin{bmatrix} 0 & -7 \\ -7 & 7 \end{bmatrix}$

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 $\begin{bmatrix} 3 & 4 \\ 4 & 0 \end{bmatrix}$

 $\begin{bmatrix} 2 & -1 & 3 \\ -1 & 5 & 1 \\ 3 & 1 & 7 \end{bmatrix}$

Not symmetric

 $\begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}$

 $\begin{bmatrix} -8 & -8 \\ 0 & 0 \end{bmatrix}$

 $\begin{bmatrix} 0 & 1 & 2 \\ 1 & 5 & -6 \\ 2 & 6 & 6 \end{bmatrix}$

 $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 2 & 0 \\ 3 & 0 & 0 \end{bmatrix}$

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3.8.6.3 Find a diagonal matrix A that satisfies the given condition

1)
$$A^5 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}^{\frac{1}{5}}$$

$$= \begin{bmatrix} 1^{\frac{1}{5}} & 0 & 0 \\ 0 & (-1)^{\frac{1}{5}} & 0 \\ 0 & 0 & (-1)^{\frac{1}{5}} \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

2)
$$A^{-2} = \begin{bmatrix} 9 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 9 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-\frac{1}{2}}$$

$$= \begin{bmatrix} 9^{-\frac{1}{2}} & 0 & 0 \\ 0 & 4^{-\frac{1}{2}} & 0 \\ 0 & 0 & 1^{-\frac{1}{2}} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{3} & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

3.8.7 Determinants and Triangular Matrices (08/29)

3.8.7.1 What is C_{32}

$$A = \begin{bmatrix} 2 & 3 & -1 & 1 \\ -3 & 2 & 0 & 3 \\ 3 & -2 & 1 & 0 \\ 3 & -2 & 1 & 4 \end{bmatrix}$$

$$C_{32} = (-1)^{3+2} \begin{vmatrix} 2 & -1 & 1 \\ -3 & 0 & 3 \\ 3 & 1 & 0 \end{vmatrix}$$

$$= - \begin{vmatrix} 2 & -1 & 1 \\ -3 & 0 & 3 \\ 3 & 1 & 0 \end{vmatrix}$$

$$= - \left(2 \begin{vmatrix} 0 & 3 \\ 1 & 0 \end{vmatrix} - (-1) \begin{vmatrix} -3 & 3 \\ 3 & 0 \end{vmatrix} + 1 \begin{vmatrix} -3 & 0 \\ 3 & 1 \end{vmatrix} \right)$$

$$= - (2(-3) - (-1)(-9) + 1(-3))$$

$$= - (-6 + 9 - 3)$$

3.8.7.2 Find all values of λ such that |A| = 0

$$A = \begin{bmatrix} \lambda - 2 & 1 \\ -5 & \lambda + 4 \end{bmatrix}$$

$$det(A) = (\lambda - 2)(\lambda + 4) - (-5)(1)$$

$$= \lambda^2 + 2\lambda - 8 + 5$$

$$= \lambda^2 + 2\lambda - 3$$

$$= (\lambda + 3)(\lambda - 1)$$

$$= 0$$

Therefore, $\lambda = -3, 1$

3.8.7.3 For the matrix $\begin{bmatrix} 3 & 0 & 0 \\ 2 & -1 & 5 \\ 1 & 9 & -4 \end{bmatrix}$ find the determinant 3 different ways with cofactor expansion. Pick different rows and columns each time.

$$det(A) = 3 \begin{vmatrix} -1 & 5 \\ 9 & -4 \end{vmatrix} - 0 \begin{vmatrix} 2 & 5 \\ 1 & -4 \end{vmatrix} + 0 \begin{vmatrix} 2 & -1 \\ 1 & 9 \end{vmatrix}$$

$$= 3(-1(-4) - 5(9)) - 0(2(-4) - 5(1)) + 0(2(9) - (-1)(1))$$

$$= 3(4 - 45) - 0(-8 - 5) + 0(18 + 1)$$

$$= 3(-41) - 0(-13) + 0(19)$$

$$= 36$$

$$det(A) = 0 \begin{vmatrix} 2 & 5 \\ 9 & -4 \end{vmatrix} - 3 \begin{vmatrix} 3 & 0 \\ 1 & -4 \end{vmatrix} + 0 \begin{vmatrix} 3 & 0 \\ 2 & 5 \end{vmatrix}$$

$$= 0(2(-4) - 5(9)) - 3(3(-4) - 0(1)) + 0(3(5) - 0(2))$$

$$= 0(-8 - 45) - 3(-12 - 0) + 0(15 - 0)$$

$$= 0(-53) - 3(-12)$$

$$= 36$$

$$det(A) = 0 \begin{vmatrix} 2 & -1 \\ 9 & -4 \end{vmatrix} - 0 \begin{vmatrix} 3 & 0 \\ 1 & -4 \end{vmatrix} + 3 \begin{vmatrix} 3 & 0 \\ 2 & -1 \end{vmatrix}$$

$$= 0(2(-4) - (-1)(9)) - 0(3(-4) - 0(1)) + 3(3(-1) - 0(2))$$

$$= 0(-8 + 9) - 0(-12 - 0) + 3(-3 - 0)$$

$$= 0(1) - 0(-12) + 3(-3)$$

$$= 0 + 0 - 9$$

$$= 36$$

3.8.7.4 Evaluate det(A) by a cofactor expansion along a row or column of your choice

$$A = \begin{bmatrix} 1 & k & k^2 \\ 1 & k & k^2 \\ 1 & k & k^2 \end{bmatrix}$$

$$\det(A) = 1 \begin{vmatrix} k & k^2 \\ k & k^2 \end{vmatrix} - k \begin{vmatrix} 1 & k^2 \\ 1 & k^2 \end{vmatrix} + k^2 \begin{vmatrix} 1 & k \\ 1 & k \end{vmatrix}$$
$$= 1(k^2 - k^2) - k(1(k^2) - k^2(1)) + k^2(1(k) - k(1))$$
$$= 0$$

3.8.7.5 Evaluate the determinant of the following matrices by just looking at them.

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$det(A) = 1(-1)(1) = -1$$

$$A = \begin{bmatrix} 1 & 2 & 7 & -3 \\ 0 & 1 & -4 & 1 \\ 0 & 0 & 2 & 7 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$

$$det(A) = 1(1)(2)(3) = 6$$

3.8.7.6 Show that the value of the determinant is independent of θ

$$A = \begin{vmatrix} \sin \theta & \cos \theta & 0 \\ -\cos \theta & \sin \theta & 0 \\ \sin \theta - \cos \theta & \sin \theta + \cos \theta & 1 \end{vmatrix}$$

$$\det(A) = \sin\theta \begin{vmatrix} \sin\theta & 0 \\ \sin\theta + \cos\theta & 1 \end{vmatrix} - \cos\theta \begin{vmatrix} \cos\theta & 0 \\ \sin\theta + \cos\theta & 1 \end{vmatrix} + 0 \begin{vmatrix} \cos\theta & \sin\theta \\ \sin\theta + \cos\theta & \sin\theta \end{vmatrix}$$

$$+0$$
 $\begin{vmatrix} \cos \theta & \sin \theta \\ \sin \theta + \cos \theta & \sin \theta \end{vmatrix}$

$$=\sin\theta\left(\sin\theta(1)-0(\sin\theta+\cos\theta)\right)-\cos\theta\left(\cos\theta(1)-0(\sin\theta+\cos\theta)\right)$$

+0 (cos θ (sin θ) – sin θ (sin θ + cos θ))

$$= \sin^2 \theta - \cos^2 \theta$$

3.8.8 Row operations and Determinants (08/31)

3.8.8.1 Find the determinant of $\begin{bmatrix} 1 & -3 & 0 \\ -2 & 4 & 1 \\ 5 & -2 & 2 \end{bmatrix}$ WITHOUT using cofactor expansion

$$det(A) = \begin{vmatrix} 1 & -3 & 0 \\ -2 & 4 & 1 \\ 5 & -2 & 2 \end{vmatrix}$$
$$= \begin{vmatrix} 1 & -3 & 0 \\ 0 & -2 & 1 \\ 0 & 13 & 2 \end{vmatrix}$$
$$= \begin{vmatrix} 1 & -3 & 0 \\ 0 & -2 & 1 \\ 0 & 0 & \frac{28}{2} \end{vmatrix}$$
$$= 1(-2)\left(\frac{28}{2}\right)$$
$$= -28$$

3.8.8.2 Find the determinant of $\begin{bmatrix} 2 & 1 & 3 & 1 \\ 1 & 0 & 1 & 1 \\ 0 & 2 & 1 & 0 \\ 0 & 1 & 2 & 3 \end{bmatrix}$

$$det(A) = \begin{vmatrix} 2 & 1 & 3 & 1 \\ 1 & 0 & 1 & 1 \\ 0 & 2 & 1 & 0 \\ 0 & 1 & 2 & 3 \end{vmatrix}$$
$$= \begin{vmatrix} 2 & 1 & 3 & 1 \\ 0 & -2 & -5 & -1 \\ 0 & 2 & 1 & 0 \\ 0 & 1 & 2 & 3 \end{vmatrix}$$
$$= \begin{vmatrix} 2 & 1 & 3 & 1 \\ 0 & -2 & -5 & -1 \\ 0 & 0 & -4 & -1 \\ 0 & 0 & -3 & 2 \end{vmatrix}$$
$$= 2(-2)(-4)(2)$$
$$= 64$$

3.8.9 Adjoints and Cramer's Rule (09/05)

3.8.9.1 Find the inverse of $A = \begin{bmatrix} 2 & 5 & 5 \\ -1 & -1 & 0 \\ 2 & 4 & 3 \end{bmatrix}$ using the adjoint method

$$\det(A) = 2 \begin{vmatrix} -1 & 0 \\ 4 & 3 \end{vmatrix} - 5 \begin{vmatrix} -1 & 0 \\ 2 & 3 \end{vmatrix} + 5 \begin{vmatrix} -1 & -1 \\ 2 & 4 \end{vmatrix}$$

$$= 2(-3) - 5(-3) + 5(-2)$$

$$= -6 + 15 - 10$$

$$= -1$$

$$\det(A) = \begin{bmatrix} (-1)^{1+1} \begin{vmatrix} -1 & 0 \\ 4 & 3 \end{vmatrix} & (-1)^{1+2} \begin{vmatrix} -1 & 0 \\ 2 & 3 \end{vmatrix} & (-1)^{1+3} \begin{vmatrix} -1 & -1 \\ 2 & 4 \end{vmatrix}$$

$$(-1)^{2+1} \begin{vmatrix} 5 & 5 \\ 4 & 3 \end{vmatrix} & (-1)^{2+2} \begin{vmatrix} 2 & 5 \\ 2 & 3 \end{vmatrix} & (-1)^{2+3} \begin{vmatrix} 2 & 5 \\ 2 & 4 \end{vmatrix}$$

$$(-1)^{3+1} \begin{vmatrix} 5 & 5 \\ -1 & 0 \end{vmatrix} & (-1)^{3+2} \begin{vmatrix} 2 & 5 \\ -1 & 0 \end{vmatrix} & (-1)^{3+3} \begin{vmatrix} 2 & 5 \\ -1 & 0 \end{vmatrix}$$

$$= \begin{bmatrix} (-1)(3) & -(-1)(3) & -4 + 2 \\ -(15 - 20) & 6 - 10 & -(8 - 10) \\ 5 & -5 & -2 + 5 \end{bmatrix}^{T}$$

$$= \begin{bmatrix} -3 & 3 & -2 \\ 5 & -4 & 2 \\ 5 & -5 & 3 \end{bmatrix}^{T}$$

$$= \begin{bmatrix} -3 & 5 & 5 \\ 3 & -4 & -5 \\ -2 & 2 & 3 \end{bmatrix}$$

$$\therefore A^{-1} = -\begin{bmatrix} -3 & 5 & 5 \\ 3 & -4 & -5 \\ -2 & 2 & 3 \end{bmatrix}$$

$$= \begin{bmatrix} 3 & -5 & -5 \\ -3 & 4 & 5 \\ 2 & -2 & -3 \end{bmatrix}$$

3.8.9.2 Solve the following system of equations using Cramer's Rule

$$\begin{cases} 4x + 5y &= 2 \\ 11x + y + 2z = 3 & \longrightarrow \begin{vmatrix} 4 & 5 & 0 \\ 11 & 1 & 2 \\ x + 5y + 2z = 1 \end{vmatrix} \longrightarrow 4 \begin{vmatrix} 1 & 2 \\ 5 & 2 \end{vmatrix} - 5 \begin{vmatrix} 11 & 2 \\ 1 & 2 \end{vmatrix} = -132$$

$$\det(x) = \begin{vmatrix} 2 & 5 & 0 \\ 3 & 1 & 2 \\ 1 & 5 & 2 \end{vmatrix}$$

$$= 2 \begin{vmatrix} 1 & 2 \\ 5 & 2 \end{vmatrix} - 5 \begin{vmatrix} 3 & 2 \\ 1 & 2 \end{vmatrix}$$

$$= 2(2 - 10) - 5(6 - 2)$$

$$= -16 - 20$$

$$= -36$$

$$\det(y) = \begin{vmatrix} 4 & 2 & 0 \\ 11 & 3 & 2 \\ 1 & 1 & 2 \end{vmatrix}$$

$$= 4 \begin{vmatrix} 3 & 2 \\ 1 & 2 \end{vmatrix} - 2 \begin{vmatrix} 11 & 2 \\ 1 & 2 \end{vmatrix}$$

$$= 4(6 - 2) - 2(22 - 2)$$

$$= 16 - 40$$

$$= -24$$

$$\det(z) = \begin{vmatrix} 4 & 5 & 2 \\ 11 & 1 & 3 \\ 1 & 5 & 1 \end{vmatrix}$$

$$= 4 \begin{vmatrix} 1 & 3 \\ 5 & 1 \end{vmatrix} - 5 \begin{vmatrix} 11 & 3 \\ 1 & 3 \end{vmatrix} + 2 \begin{vmatrix} 11 & 1 \\ 1 & 5 \end{vmatrix}$$

$$= 4(1 - 15) - 5(33 - 3) + 2(55 - 1)$$

$$= -56 - 150 + 108$$

$$= -98$$

Therefore, the solution $(x, y, z) = (\frac{3}{11}, \frac{2}{11}, -\frac{49}{66})$

4 Chapter 5: Eigenvectors and Eigenvalues

4.1 Eigenvalues and Eigenvectors (11/06)

If A is an $n \times n$ matrix, then a non-zero vector \mathbf{x} , in R^n , is called an <u>eigenvector</u> of A if $A\mathbf{x}$ is a scalar multiple of \mathbf{x} ; that is $A\mathbf{x} = \lambda \mathbf{x}$ for some scalar λ . This scalar λ is called an eigenvalue of A and \mathbf{x} is said to be an eigenvector corresponding to λ .

See, normally, multiplying a vector by a square matrix changes both the magnitude and the direction of the vector. Really screws it up.

Some examples:

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 5 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 5 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 7 & 8 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 23 \\ 4 \end{bmatrix}$$

However, there are some ways to get consistent results.

4.1.1 Examples

4.1.1.1
$$\vec{x} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$
 is an eigenvector of $A = \begin{bmatrix} 3 & -2 \\ 1 & 0 \end{bmatrix}$ because

$$A\vec{x} = \begin{bmatrix} 3 & -2 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 \end{bmatrix} = 2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} = 2\vec{x} : \lambda = 2$$

4.1.1.2 Let
$$A = \begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix}$$
, $\vec{u} = \begin{bmatrix} 6 \\ -5 \end{bmatrix}$, $\vec{v} = \begin{bmatrix} 3 \\ -2 \end{bmatrix}$. Are \vec{u} and \vec{v} eigenvectors of \vec{A} ?

$$A\vec{u} = \begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix} \begin{bmatrix} 6 \\ -5 \end{bmatrix} = \begin{bmatrix} 1(6) + 6(-5) \\ 5(6) + 2(-5) \end{bmatrix} = \begin{bmatrix} -24 \\ 20 \end{bmatrix} = -4 \begin{bmatrix} 6 \\ -5 \end{bmatrix} \therefore \lambda = -4$$

$$A\vec{v} = \begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix} \begin{bmatrix} 3 \\ -2 \end{bmatrix} = \begin{bmatrix} 1(3) + 6(-2) \\ 5(3) + 2(-2) \end{bmatrix} = \begin{bmatrix} -9 \\ 11 \end{bmatrix} \neq \lambda \vec{v}$$

4.2 Eigenvector Homework Problem (11/06)

Confirm by multiplication that ${\bf x}$ is an eigenvector of ${\bf A}$, and find the corresponding eigenvalue.

4.2.1
$$A = \begin{bmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ 1 & 0 & 4 \end{bmatrix}$$
; $\mathbf{x} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$

$$A\mathbf{x} = \begin{bmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ 1 & 0 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 4(1) + 0(2) + 1(1) \\ 2(1) + 3(2) + 2(1) \\ 1(1) + 0(2) + 4(1) \end{bmatrix} = \begin{bmatrix} 5 \\ 10 \\ 5 \end{bmatrix} = 5 \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \therefore \lambda = 5$$

4.3 Finding Eigenvalues and Eigenvectors (11/07)

Essential question:

If we know an $n \times n$ matrix A, can we find its λ ?

If $A\vec{x} = \lambda \vec{x}$, then:

$$A\vec{x} = \lambda \vec{x}$$
$$A\vec{x} - \lambda \vec{x} = \vec{0}$$

$$(A - \lambda I)\vec{x} = \vec{0}$$

This equation is familiar. It's the homogeneous system of equations $A\vec{x} = \vec{0}$, the solution of which is the nullspace of $A - \lambda I$. Therefore, \vec{x} is an eigenvector of $A \iff \vec{x}$ is in the nullspace of $A - \lambda I$.

In this situation, what do we know about that matrix?

Everything in the equivalent statements is false because \vec{x} cannot be the zero vector. Therefore, we can see that $\det(A - \lambda I)$ OR $\det(\lambda I - A)$ MUST be 0.

Big Idea: If A is an $n \times n$ matrix, then λ is an eigenvalue of $A \iff \det(\lambda I - A) = 0$. This is called the characteristic equation of A.

4.3.1 Find the characteristic equation and the eigenvalues of $A = \begin{bmatrix} 3 & 0 & 5 \\ \frac{1}{5} & -1 & 0 \\ 1 & 1 & -2 \end{bmatrix}$

$$\det(\lambda I - A) = 0$$

$$\begin{vmatrix} \lambda - 3 & 0 & 5 \\ -\frac{1}{5} & \lambda + 1 & 0 \\ -1 & -1 & \lambda + 2 \end{vmatrix} = 0$$

$$0 = (\lambda - 3)((\lambda + 1)(\lambda + 2)) + 5(\frac{1}{5} + \lambda + 1)$$

$$0 = (\lambda - 3)(\lambda^2 + 3\lambda + 2)$$

$$0 = \lambda(\lambda^2 - 2)\lambda$$

$$0 = \lambda(\lambda^2 - 2)\lambda$$

$$= 0, \pm \sqrt{2}$$

4.3.2 Find the characteristic equation and the eigenvalues of $A = \begin{bmatrix} -1 & 0 & 1 \\ -1 & 3 & 0 \\ -4 & 13 & -1 \end{bmatrix}$

$$\begin{vmatrix} -1 - \lambda & 0 & 1 \\ -1 & 3 - \lambda & 0 \\ -4 & 13 & -\lambda \end{vmatrix} = 0$$

$$(-1 - \lambda)((3 - \lambda)(-\lambda) - 0(13)) + (-1(13) - (3 - \lambda)(-4)) = 0$$

$$(-1 - \lambda)(\lambda^2 - 3\lambda) + (-13 - 4\lambda + 12) = 0$$

$$(-1 - \lambda)(\lambda^2 - 3\lambda) + (-4\lambda - 1) = 0$$

$$-\lambda^3 + 3\lambda^2 + 2 = 0$$

$$(-\lambda + 2)(-\lambda^2 - \lambda - 1) = 0$$

$$(-\lambda + 2)(-\lambda - 1)(-\lambda + 1) = 0$$

$$\lambda = 2$$

4.3.3 Find the eigenvalues of
$$A = \begin{bmatrix} 2 & 0 & 0 \\ 6 & 3 & 0 \\ 1 & 4 & 5 \end{bmatrix}$$

$$\begin{vmatrix} \lambda - 2 & 0 & 0 \\ 6 & \lambda - 3 & 0 \\ 1 & 4 & \lambda - 5 \end{vmatrix} = 0$$
$$(\lambda - 2)(\lambda - 3)(\lambda - 5) = 0$$
$$\lambda = 2, 3, 5$$

Theorem 1: For a triangular matrix, the eigenvalues are the elements on the main diagonal.

4.3.4 Find the eigenvalues of
$$A^3$$
 if $A = \begin{bmatrix} \frac{1}{2} & 4 & 5 & -2 \\ 0 & -1 & 3 & -8 \\ 0 & 0 & 2 & 6 \\ 0 & 0 & 0 & 4 \end{bmatrix}$

$$\lambda_A = \frac{1}{2}, -1, 2, 4$$

$$\lambda_{A^3} = \frac{1}{8}, -1, 8, 64$$

Theorem 2: The eigenvalues of A^k are $\lambda_1^k, \lambda_2^k, ...$

4.3.5 Give me a matrix with eigenvalues $\lambda = 0, 2, 5$

$$A = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 2 & 0 \\ 2 & 2 & 5 \end{bmatrix}$$

Theorem 3: A square matrix A is invertible $\iff \lambda \neq 0$ (which also means its determinant is 0).

4.3.6 Finding eigenvectors!

Find the nontrivial eigenvectors of:

$$A = \begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix}$$

$$\begin{vmatrix} \lambda - 1 & -6 \\ -5 & \lambda - 2 \end{vmatrix} = 0$$

$$(\lambda - 1)(\lambda - 2) - (-6)(-5) = 0$$

$$\lambda^2 - 3\lambda - 28 = 0$$

$$(\lambda - 7)(\lambda + 4) = 0$$

$$\lambda = 7, -4$$

Substitute each λ , one at a time into the λI – A matrix and find the null space.

For $\lambda = -4$:

$$\begin{pmatrix} -5 & -6 & 0 \\ -5 & -6 & 0 \end{pmatrix}$$
$$\begin{pmatrix} -5 & -6 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$
$$\langle -\frac{6}{5}t, t \rangle$$
$$\vec{x} = \{ \langle -6, 5 \rangle \}$$

For $\lambda = 7$:

$$\begin{pmatrix} 6 & -6 & | & 0 \\ -5 & 5 & | & 0 \end{pmatrix}$$
$$\begin{pmatrix} 6 & -6 & | & 0 \\ 0 & 0 & | & 0 \end{pmatrix}$$
$$\langle t, t \rangle$$
$$\vec{x} = \{ \langle 6, 6 \rangle \}$$

Therefore, the eigen space is: $\{\langle -6, 5 \rangle, \langle 6, 6 \rangle\}$