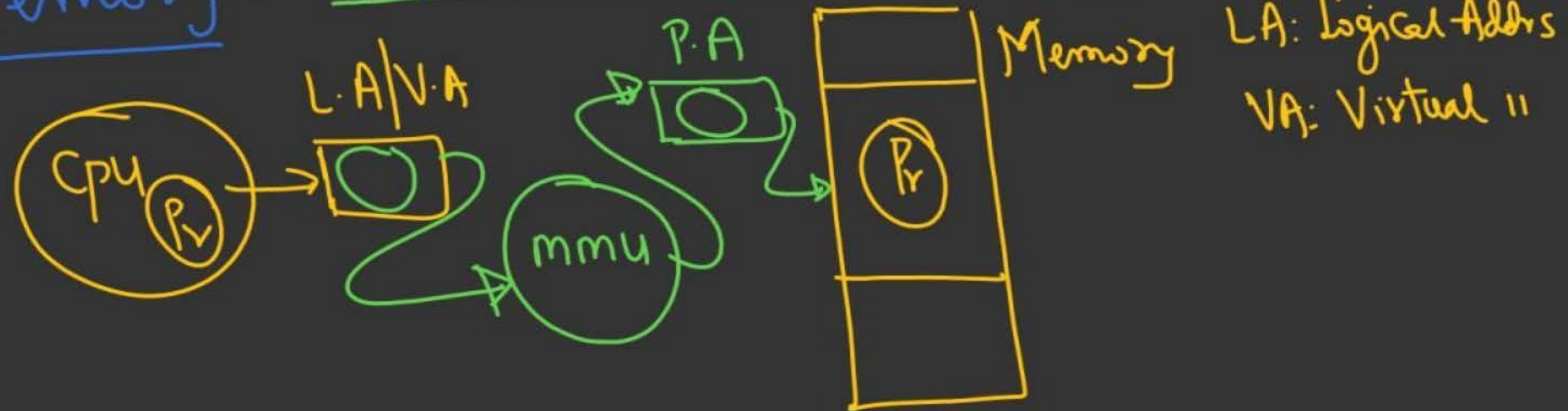


* Architectural Requirement for Implementation of H/W Support a PreEmptive based M.P.v.O.S

1) I/O (Secondary Storage services) : {DMA} (Direct Memory access)
mmu: Mem Mgmt. unit

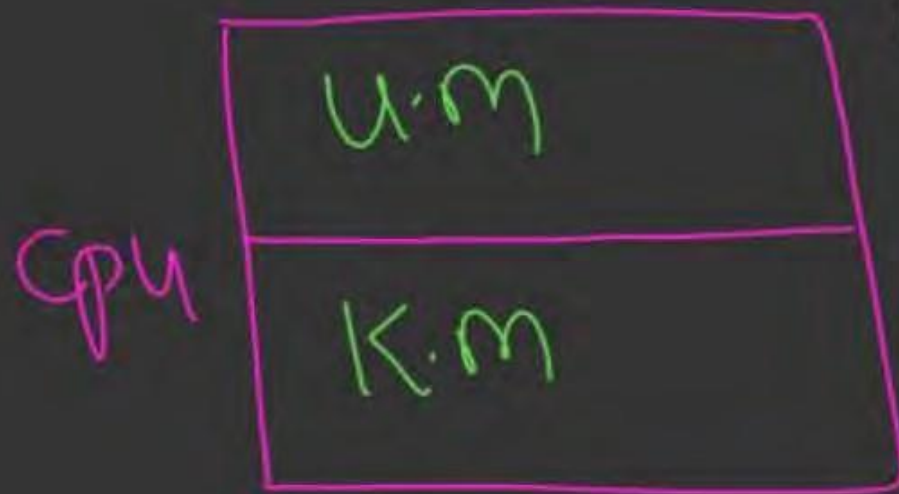
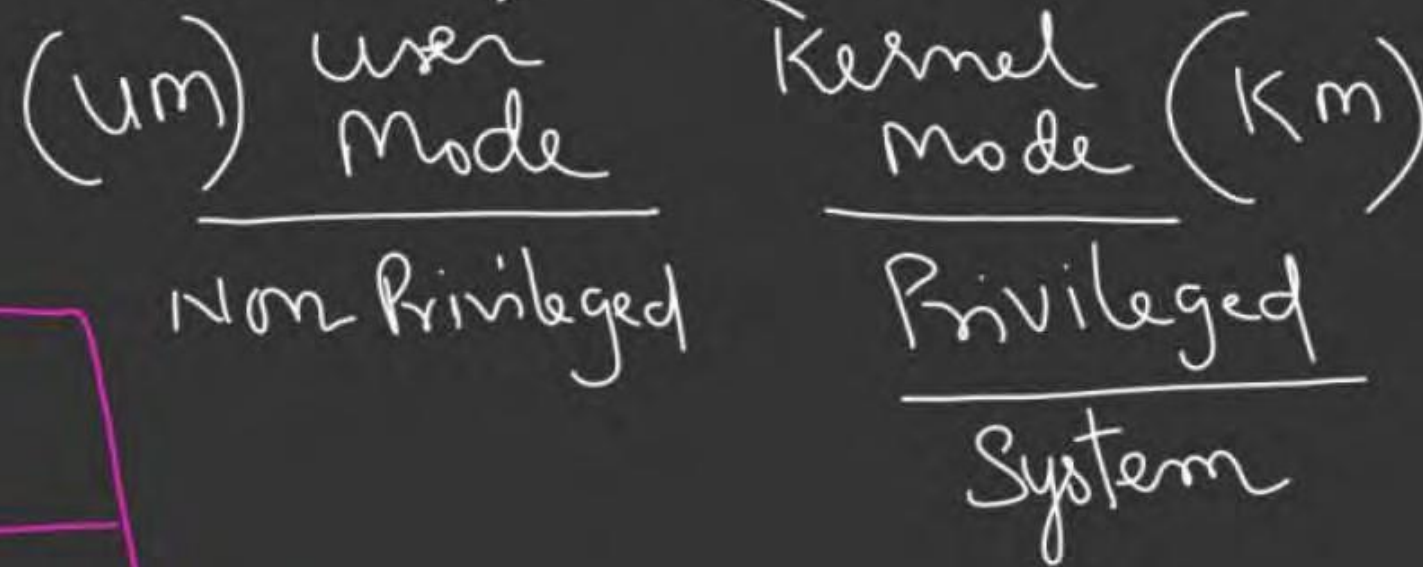
2) Memory : Address Translation Support



3) CPU : Dual Mode operation

CPU: Central processing unit

: Every Processor in a M.P.O.S must support Two Modes (atleast) for ~~m.p.o.s~~

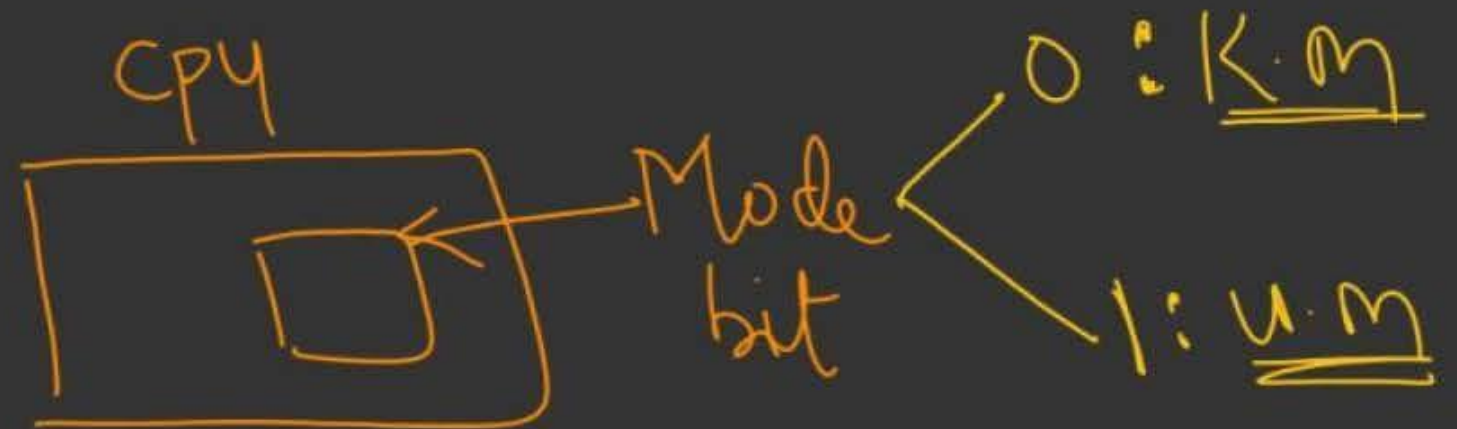


User Mode

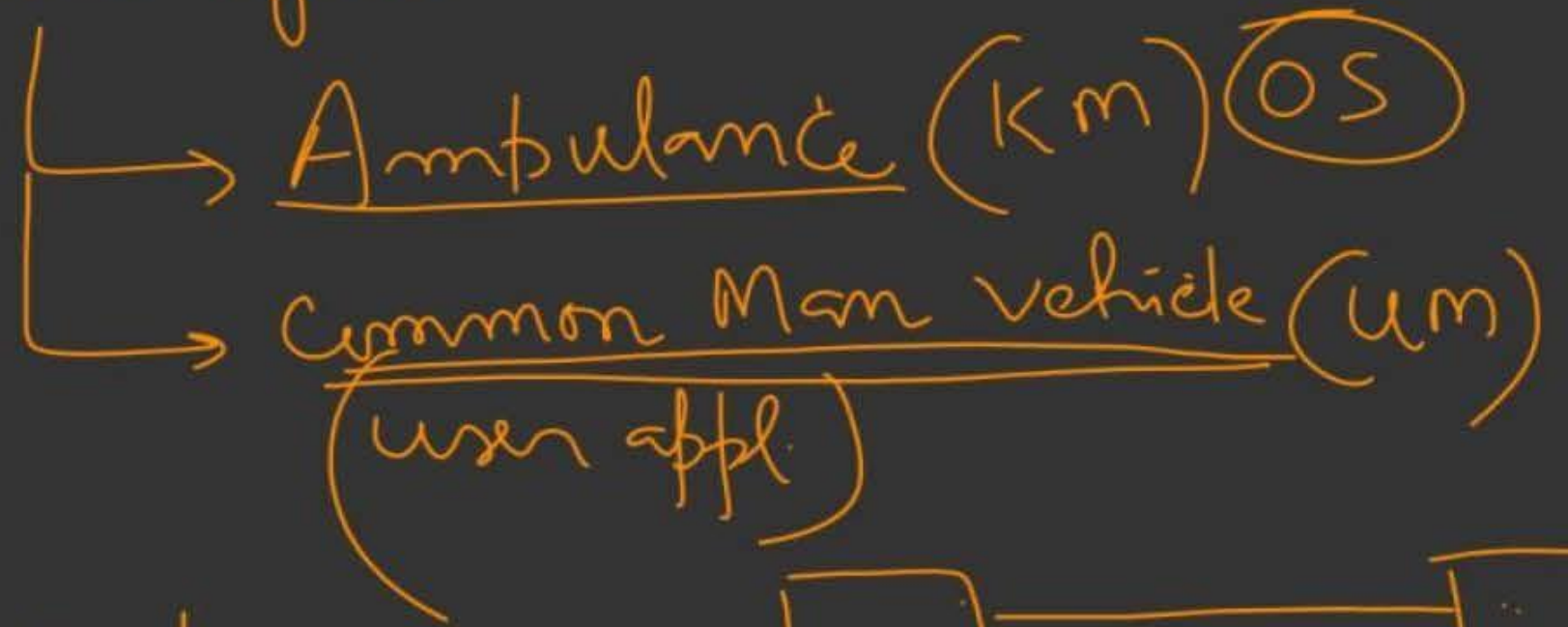
1. User Programs/app's run in User Mode;
2. user mode execution is preemptive (non-atomic)
- 3.

Kernel Mode

- 1) O.S programs/routines run in Kernel Mode;
- 2) Kernel Mode execution of OS programs is Non-Preemptive (atomic)



1. Road Transport-



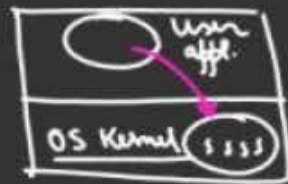
2. Convey of P.M/C.M



② Mode Shifting (MSR)

→ OS is a Service Provider

→ Users & Programmers are Service users



→ Many a times during the execution of user Programs, it is reqd to access/avail OS Service

→ Mode Shifting from UM → KM, whenever an user appl. needs an OS Service;

main() UM
{ int a, b, c;

1. a = 1;
2. b = 2;
3. c = a + b;
4. f(c);
}

User-level Instr's
UM

f(int k)
{

UM printf("%d", k);
}

↓
Predefined
user In-built
Defined Library

→ All user-defined & Predefined fns execute (start) in UM.

Appl - Prog.

```
main()
{
  int a, b, c;
  1. a = 1; um
  2. b = 2; um
  3. c = a + b; um
  4. fork(); km
  5. f(c); um
}
```

```
f(int k)
{
  printf("%d", k);
}
```

→ System Call

→ Create a child Process (OS)

→ (Mode - Shifting)

