

I. Introduction & Background

(CS & IT)

- ❖ 1.1 What is Operating System ?
- ❖ 1.2 Function & Goals of Operating System
- ❖ 1.3 Types of Operating system
- ❖ 1.4 Multiprogrammed Operating System
- ❖ ④ 1.5 Architectural requirements for multiprogrammed OS
- ❖ ④ 1.6 Mode Shifting in Multiprogrammed OS
- ❖ ④ 1.7 System Calls
- ❖ ④ 1.8 Fork System Call
- ❖ 1.9 Problem Solving

II. Process Management

30%

□ 2. Process Concepts

❖ 2.1 program Vs Process

❖ 2.2 Process as ADT

❖ * 2.3 Process State Transition Diagram

❖ 2.4 Schedulers & Dispatchers

❖ 2.5 Problem Solving

3.CPU Scheduling ② - 90%

- ❑ 3.1 Need For Scheduling & Scheduling Criteria
- ❑ 3.2 Process Times
- ❑ 3.3 Scheduling Algorithms
 - ❖ 3.3.1 FCFS
 - ❖ 3.3.2 SJF
 - ❖ 3.3.3 SRTF
 - ❖ 3.3.4 LRTF
 - ❖ ~~3.3.4 LRTF~~
 - ❖ 3.3.5 Priority
 - ❖ 3.3.6 Round Robin
 - ❖ 3.3.7 Multilevel Queue Scheduling
- ❑ 3.4 Problem Solving ③

4. Multithreading

- ❑ 4.1 Thread Concept & Benefits
- ❑ 4.2 Types of Threads
- ❑ 4.3 Thread Issues
- ❑ 4.4 Thread Libraries
- ❑ 4.5 Problem Solving

Theoretical

5. Process Synchronization/Coordination

- ❑ 5.1 What is IPC & Synchronization
- ❑ 5.2 Types of Synchronization
- ❑ 5.3 Critical Section Problem
- ❑ 5.4 Requirements of CS Problem

(Analysis)

❑ 5.5 Synchronization Mechanism

- ❖ 5.5.1 Lock Variables
- ❖ 5.5.2 Strict Alternation
- ❖ 5.5.3 Peterson Solution
- ❖ 5.5.4 Synchronization Hardware
- ❖ 5.5.5 Semaphores Intro



❑ 5.6 Classical IPC Problems

- ❖ 5.6.1 Producer Consumer Problem
- ❖ 5.6.2 Reader-Writer Problem
- ❖ 5.6.3 Dining Philosopher Problem

5.7 Monitors

5.8 Concurrency Mechanisms

- ❑ 5.8.1 Parallel Construct
- ❑ 5.8.2 Fork & Join Statement

5.10 Problem Solving



6. Deadlocks

- ❑ 6.1 Concepts of Deadlock
- ❑ 6.2 System Model
- ❑ 6.3 Deadlock Characterizations
 - ❖ 6.3.1 Necessary conditions
 - ❖ 6.3.2 Resource Allocation Graph

6.4 Deadlock Handling Strategies

- ❑ 6.4.1 Prevention
- ❑ 6.4.2 Avoidance
 - ❖ 6.4.2.1 Bankers Algorithm
- ❑ 6.4.3 Detection & Recovery
- ❑ 6.4.4 Deadlock Ignorance
- ❑ 6.5 Problem Solving



III Memory Management

- 7. Abstract View of Memory :
- 8. Loading vs Linking ✓
- 9. Address Binding ✓
- 10. Memory Management Techniques ✓

- ❑ 10.1 Swapping ✓
- ❑ 10.2 Partitioning ✓
 - ❖ 10.2.1 Fixed Partitions
 - ❖ 10.2.2 Variable partitions

❑ Non Contiguous Allocation

- ❖ 11.3.1 Simple Paging
- ❖ 11.3.2 Paging With TLB
- ❖ 11.3.3 Hashed Paging
- ❖ ❖ 11.3.4 Multilevel Paging
- ❖ 11.3.5 Inverted Paging
- ❖ 11.3.6 Shared Paging
- ❖ 11.3.7 Segmentation
- ❖ 11.3.8 Segmented-Paging Architecture

❖

Virtual Memory

→ Concept

→ Implementation

→ Performance Issues

13. Problem Solving

IV. File System & Device Management

14. Physical Structure of Disk

15. Logical Structure of Disk

16. File System Interface

- ❑ 16.1 File & Directory Concept
- ❑ 16.2 File Attributes
- ❑ 16.3 File Operations
- ❑ 16.4 Types of Files
- ❑ 16.5 Directory Structure

17. File System Implementation

✖ ✖

30%

❑ 17.1 Allocation Methods

❑ 17.2 Disk Free Space Management Algorithms

19. IO Scheduling(Disk Scheduling)

90%

❑ 19.1 Need for Disk Scheduling

❑ 19.2 Disk Scheduling Techniques

❖ 19.2.1 FCFS

❖ 19.2.2 SSTF

❖ 19.2.3 SCAN

❖ 19.2.4 LOOK

❖ 19.2.5 C-SCAN

❖ 19.2.6 C-LOOK

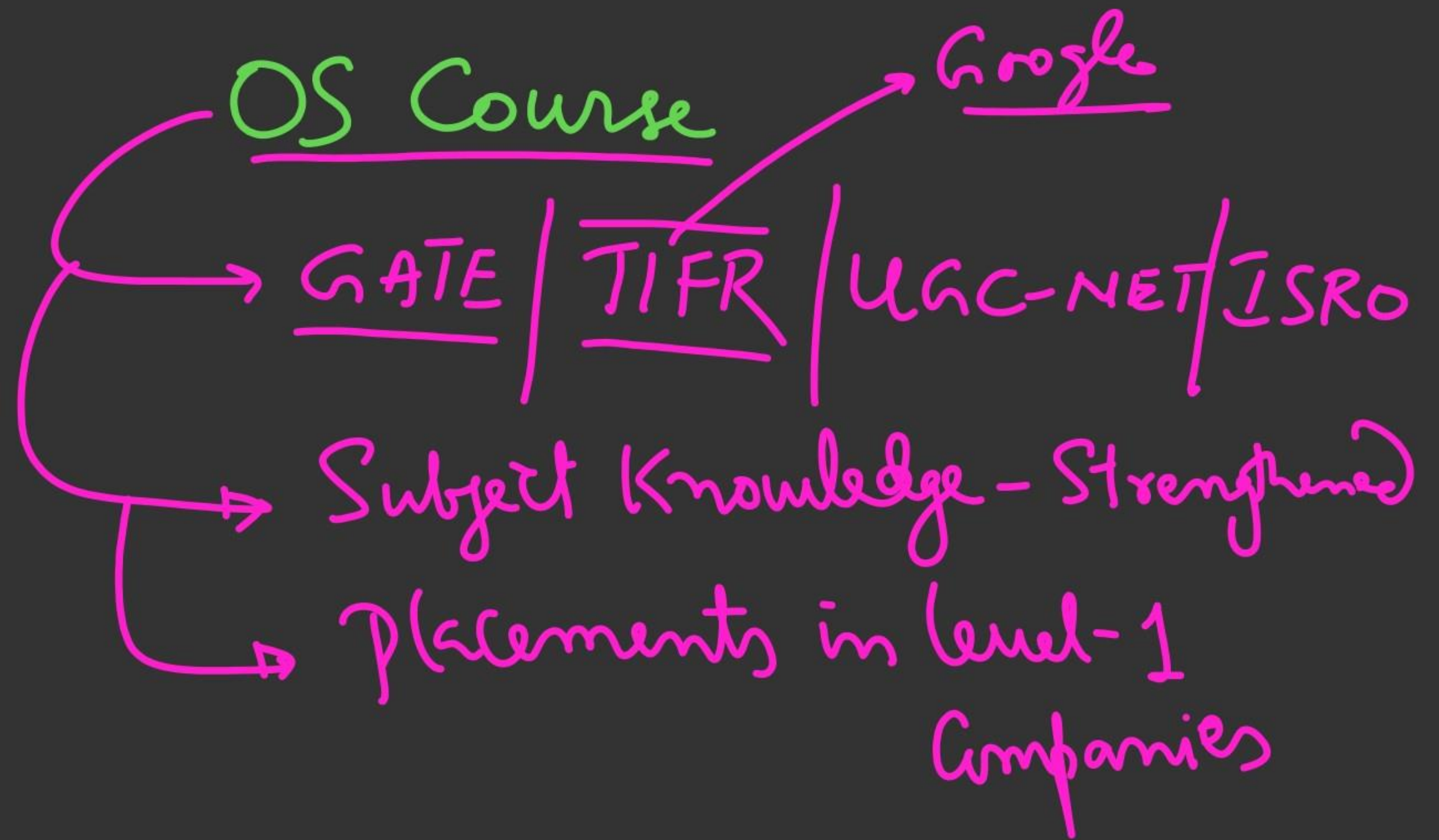
❑ 20. Problem Solving

No. of Hrs: 58-60 hrs

Weightage: 8-10M

(10-12)M

(14)M



Types of Questions

- M.C.Q :
- M.S.Q :
- NAT :

What is O.S: 20 Min

1) Interface between user & Hardware;



$$L = \sum (a \dots z)$$

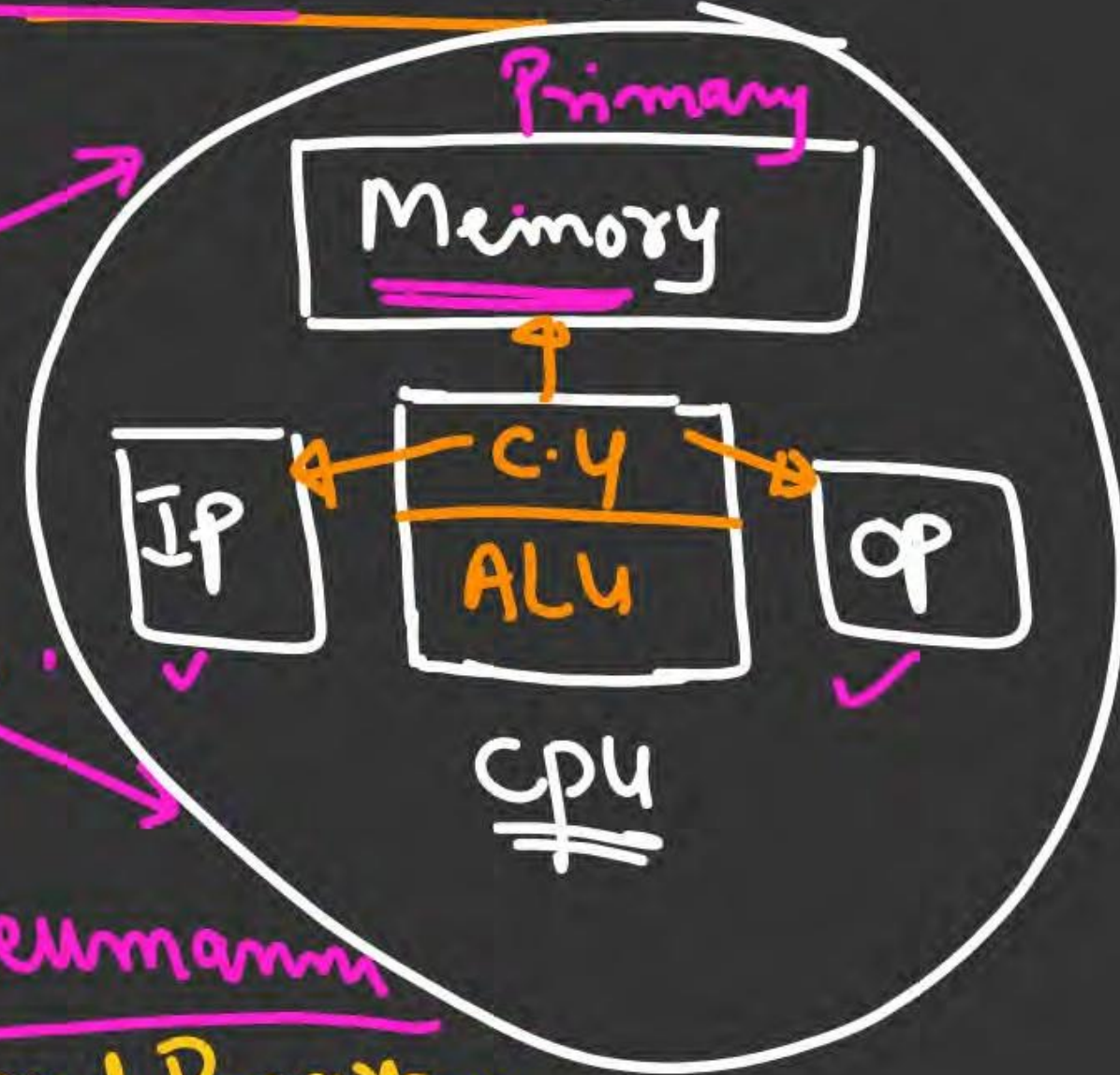
H.L.L



$$L = \sum (0, 1)$$

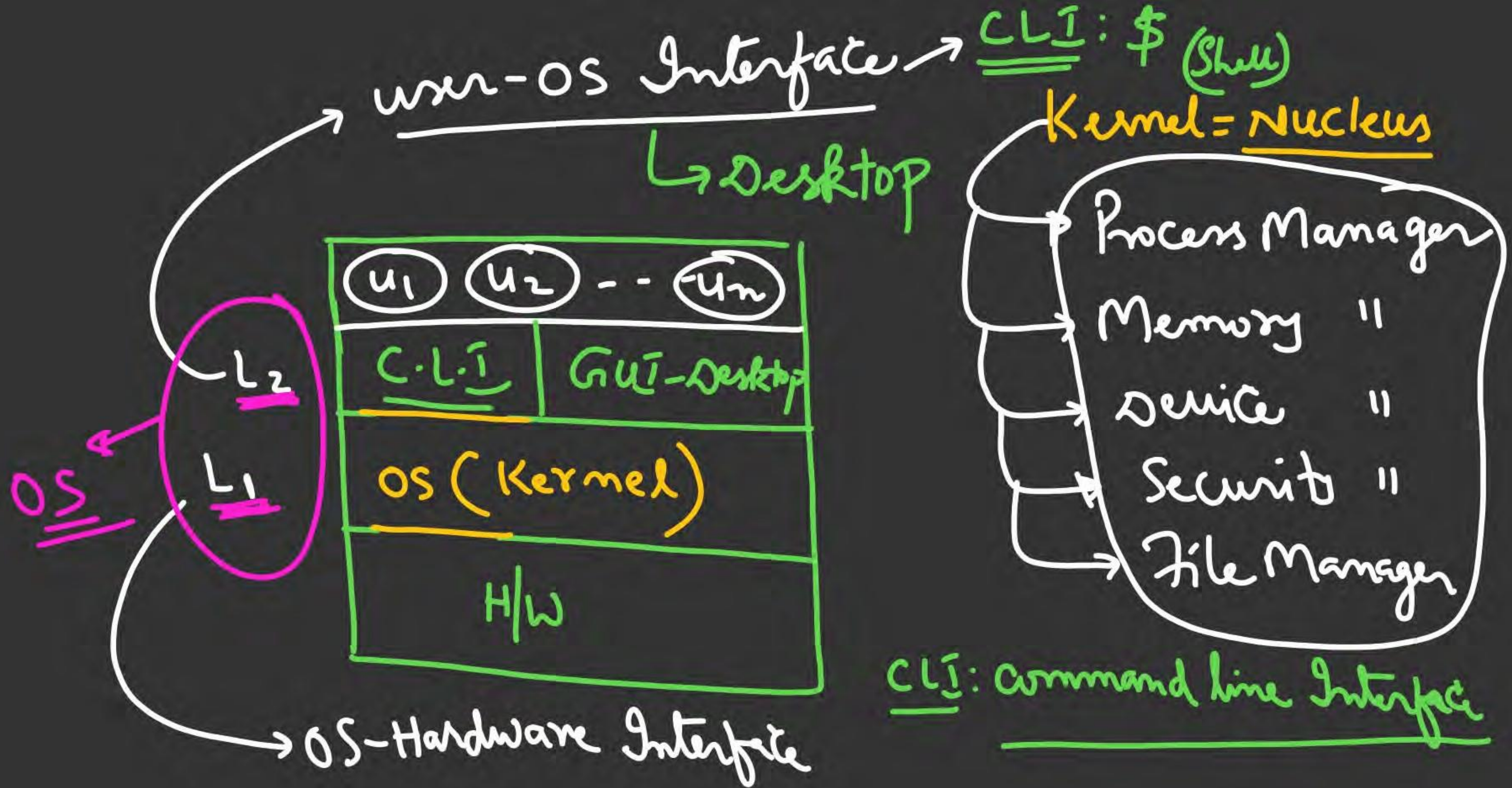


M.L



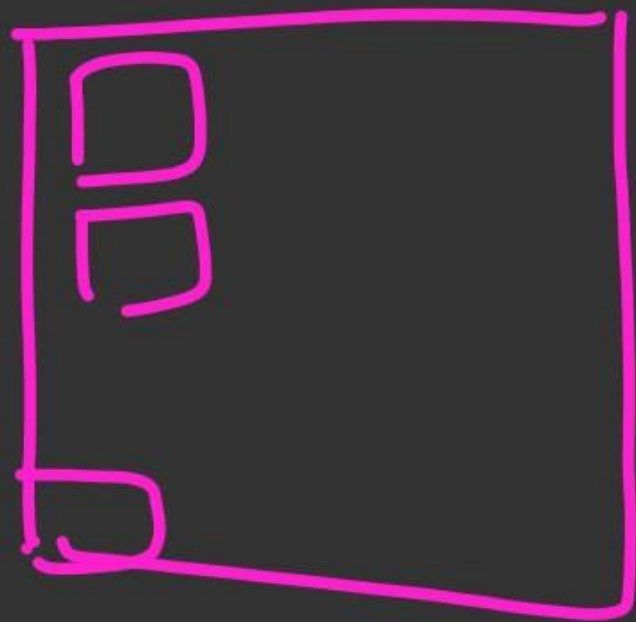
Von-Neumann

Stored Program Concept



WINDOWS:

L2: desktop



UNIX/DOS: Shell

L2 { \$.....
C:>.....

other defns of OS

→ Resource Manager

H/w

cpu
Mem
IO
:

S/w

(Files,
device drivers,
Semaphores
Pipes)

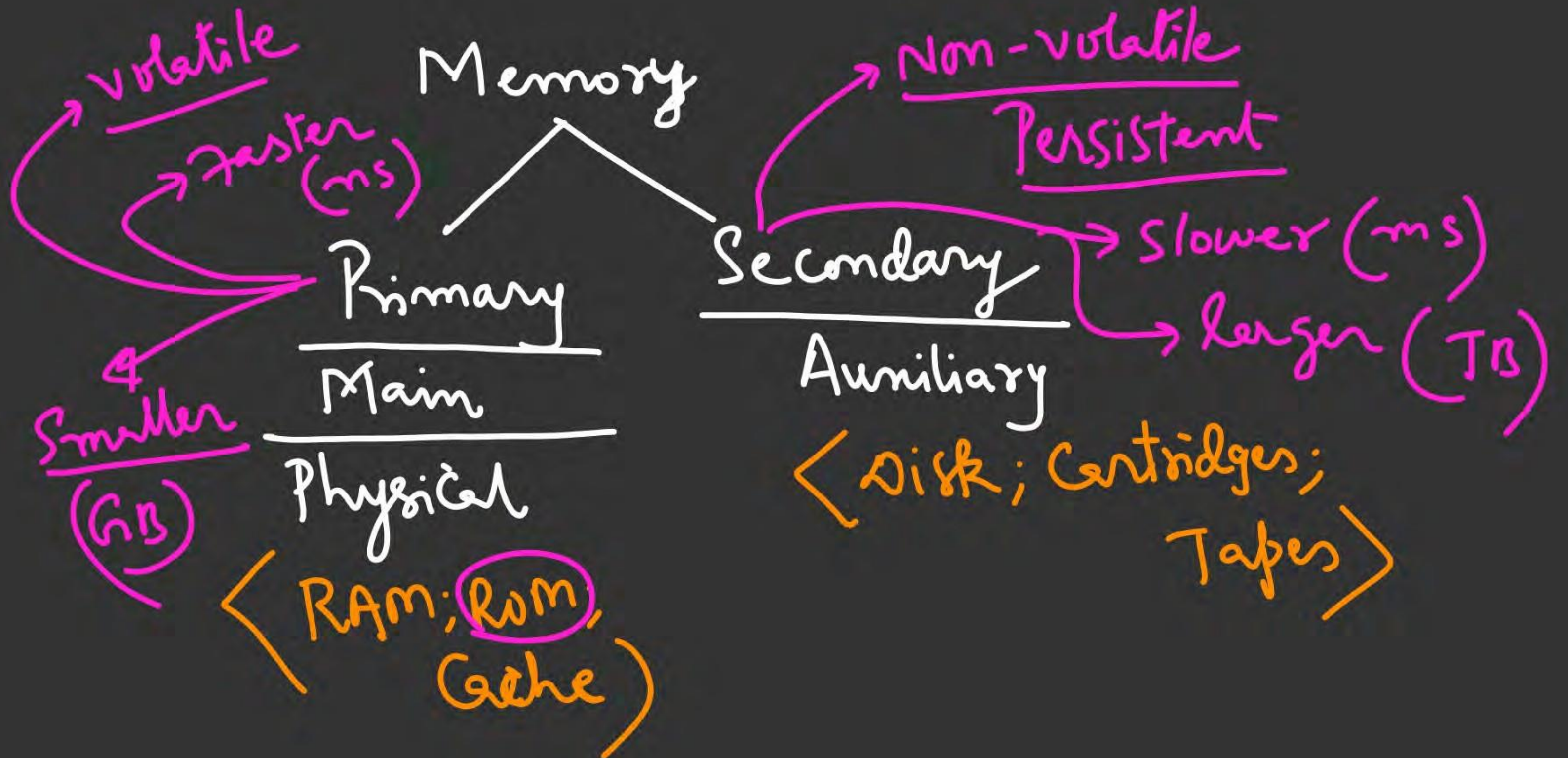
→ Control Program(s)

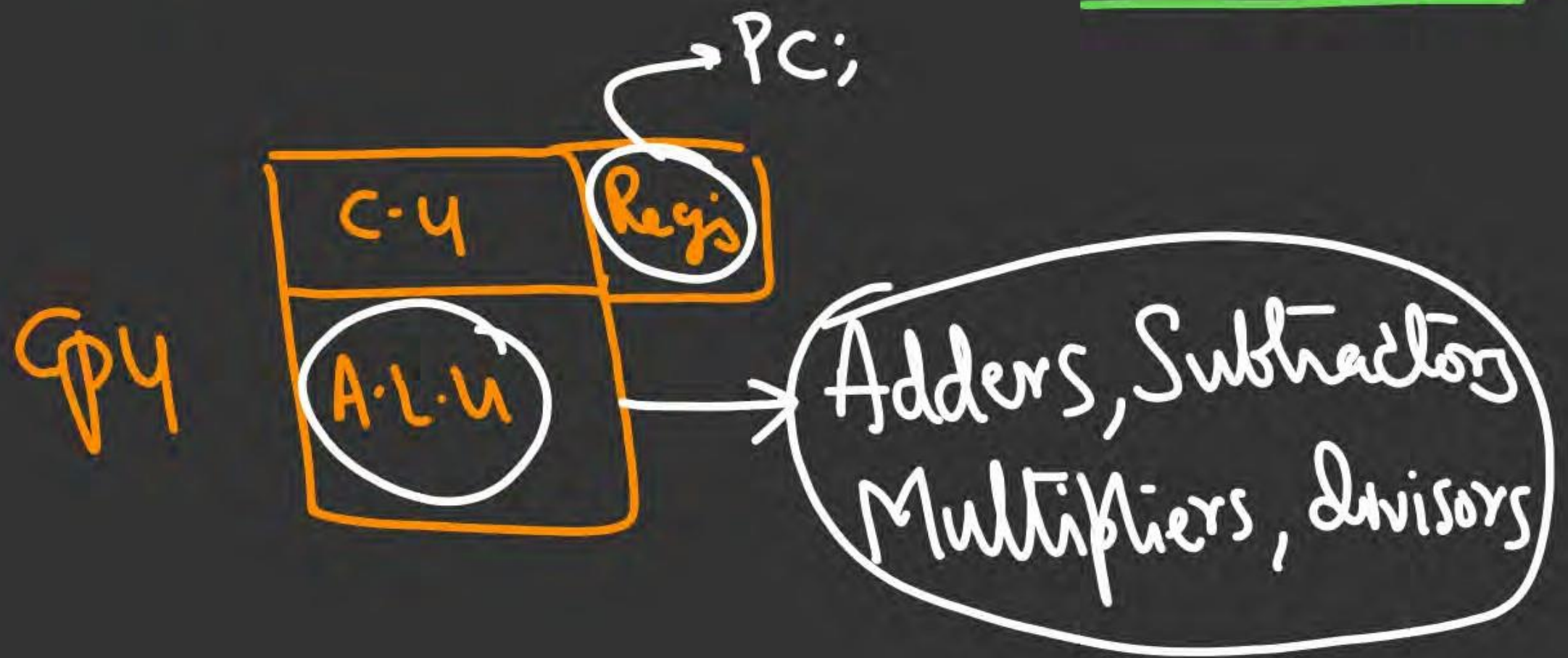
→ Set of utilities to
simplify appl.
development

< Platform/Environment

→ Acts/Functions like a Govt

Functions & Goals





Micro-operations:

Primitive
Atomic

Fundamental

→ operations that are carried out on the Data Stored in registers during one/more

Clock cycles:

$a = b + c;$
HLL

Load R1, b
Load R2, c
Add R1, R2
Store a, R1

Instructions

→ Fetch Cycle
→ Decode Cycle
→ execute "

PC → MAR



