view frames Result Recorded at time: 1756042027.847 base_link Broadcaster: /my_gen3/robot_state_publisher Average rate: 40.201 Hz Most recent transform: 1756042027.826 (0.021 sec old) Buffer length: 4.975 sec shoulder_link Broadcaster: /my_gen3/robot state publisher Average rate: 40.201 Hz Most recent transform: 1756042027.826 (0.021 sec old) Buffer length: 4.975 sec half_arm_1_link Broadcaster: /my_gen3/robot state publisher Average rate: 40.201 Hz Most recent transform: 1756042027.826 (0.021 sec old) Buffer length: 4.975 sec half_arm_2_link Broadcaster: /my_gen3/robot_state_publisher Average rate: 40.201 Hz Most recent transform: 1756042027.826 (0.021 sec old) Buffer length: 4.975 sec forearm link Broadcaster: /my_gen3/robot_state_publisher Average rate: 40.201 Hz Most recent transform: 1756042027.826 (0.021 sec old) Buffer length: 4.975 sec spherical_wrist_1_link Broadcaster: /my_gen3/robot state publisher Average rate: 40.201 Hz Most recent transform: 1756042027.826 (0.021 sec old) Buffer length: 4.975 sec spherical_wrist_2_link Broadcaster: /my_gen3/robot state publisher Average rate: 40.201 Hz

Most recent transform: 1756042027.826 (0.021 sec old) Buffer length: 4.975 sec bracelet link Broadcaster: /my_gen3/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1756042027.847 sec old) Buffer length: 0.000 sec end effector link Broadcaster: /my_gen3/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1756042027.847 sec old) / Broadcaster: /my_gen3/robot_state_publisher
Average rate: 10000.000 Hz

Most recent transform: 0.000 (1756042027.847 sec old) Broadcaster: /my_gen3/robot state publisher Broadcaster: /my_gen3/robot_state_publisher Average rate: 10000.000 Hz
\(\text{Most recent transform: 0.000 (1756042027.847 sec old)} \) Buffer length: 0.000 sec robotiq_arg2f_base_link camera_link $camera_depth_frame$ tool_frame camera_color_frame Broadcaster: /my_gen3/robot_state_publisher Broadcaster: /my_gen3/robot_state_publisher Broadcaster: /my_gen3/robot_state_publisher Broadcaster: /my_gen3/robot_state_publisher Average rate: 40.201 Hz

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\(\text{Most recent transform: 1756042027.826 (0.021 sec old)}\) Buffer length: 4.975 sec Buffer length: 4.975 sec Buffer length: 4.975 sec Buffer length: 4.975 sec right_outer_knuckle left_outer_knuckle left_inner_knuckle right_inner_knuckle Broadcaster: /my_gen3/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1756042027.847 sec old) Broadcaster: /my_gen3/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1756042027.847 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec left_outer_finger right_outer_finger Broadcaster: /my_gen3/robot_state_publisher Broadcaster: /my_gen3/robot_state_publisher Average rate: 40.201 Hz

Most recent transform: 1756042027.826 (0.021 sec old) Average rate: 40.201 Hz Most recent transform: 1756042027.826 (0.021 sec old) Buffer length: 4.975 sec Buffer length: 4.975 sec left_inner_finger right_inner_finger Broadcaster: /my_gen3/robot_state_publisher Broadcaster: /my_gen3/robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1756042027.847 sec old) Most recent transform: 0.000 (1756042027.847 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec left inner_finger_pad right inner finger pad