

```
when Right.TouchUp
do call BluetoothClient1.SendText
   text "Z"

when Up.TouchUp
do call BluetoothClient1.SendText
   text "Z"

when Down.TouchDown
do call BluetoothClient1.SendText
   text "D"

when Left.TouchDown
do call BluetoothClient1.SendText
   text "L"

when Happy.Click
do call BluetoothClient1.SendText
   text "H"

when Love.Click
do call BluetoothClient1.SendText
   text "B"

when Clock1.Timer
do if BluetoothClient1.IsConnected
   then set Label2.Text to "CONNECTED"
        set Label2.BackgroundColor to green
   if not BluetoothClient1.IsConnected
   then set Label2.Text to "NOT CONNECTED"
        set Label2.BackgroundColor to red

when Sendmessage.Click
do set Terminal.Text to Terminal.Text
   call BluetoothClient1.Send1ByteNumber
      number 255
   call BluetoothClient1.SendText
      text Terminal.Text
   call BluetoothClient1.Send1ByteNumber
      number 0
```

```
when Right.TouchDown
do call BluetoothClient1.SendText
   text "R"

when Up.TouchDown
do call BluetoothClient1.SendText
   text "U"

when Down.TouchUp
do call BluetoothClient1.SendText
   text "Z"

when Left.TouchUp
do call BluetoothClient1.SendText
   text "Z"

when Neutral.Click
do call BluetoothClient1.SendText
   text "N"

when Angry.Click
do call BluetoothClient1.SendText
   text "A"

when Connect.AfterPicking
do evaluate but ignore result call BluetoothClient1.Connect
   address Connect.Selection

when Screen1.Initialize
do set Connect.Elements to BluetoothClient1.AddressesAndNames

when Clear.Click
do set Terminal.Text to ""

when Disconnect.Click
do call BluetoothClient1.Disconnect
```

Robot Controls

Bluetooth Module Controls

Connect

Disconnect

CONNECTED

Display a message

...

Clear Terminal

Send to WALL-E

WALL-E ROBOT CONTROLS

HEAD UP

TURN LEFT

TURN RIGHT

HEAD DOWN

WALL-E MODES

Angry

Happy

Love

Neutral