

ANN { Artificial Neural network }

→ Feature scaling

Interview Question

Q) For which all algorithms feature scaling is required?

ANN ✓

LR ✓

Log R ✓

S. Tree ✗

Random Forest ✗

KNN ✓

or any

Anything distance based  
or  
any kind of optimizer

Tensorflow - Open sourced by google

Pytorch - Facebook

Keras is a wrapper, after 2.0, keras and tensorflow got integrated

Sequential library  
libraries

① Sequential :- Enables to do forward and Backward propagation

② Dense :- Helps to create neurons.

③ Dropout :- Regularisation parameter

Sometimes overfitting happens i.e. Accuracy goes down for output

Black Box Model vs White Box Model  
 can't see internal working vs can see internal working

Explainable AI → Becoming popular

Convolution Neural network

- Images, videos
- ① CNN vs Human brain
  - ② Convolution operation
    - convolution
    - padding
    - strides
    - filter (kernel)

- ③ Max Pooling
- ④ Halling

CNN vs Human Brain

Cerebral cortex :- Visual cortex is responsible for seeing and processing

Convolution :-  $\otimes$  (\*)

Pass the image through a filter / kernel

Min-max scaling :- Divide each value of pixel between

$V_1$  → many digits  
 ↓ → kernel  
 $V_2$  → map the max  
 ↓  
 $V_3$

stride = 1  
 padding place

0	0	0	1	1	1
0	0	0	1	1	1
0	0	0	1	1	1
0	0	0	1	1	1
0	0	0	1	1	1
0	0	0	1	1	1

$$1 \times 0 + 2 \times 0 + 1 \times 0 = 0$$

1	2	1
0	0	0
-1	-2	-1

Horizontal edge detector

10	bits	1	7	1
1	bits	1	7	1

⇒

o/p actual value

0	0	0	0
-4	-4	-4	-4
-4	-4	-4	4
0	0	0	0

now lowest value will become 0 and highest 255, because of min-max scale  
 0 - Black  
 255 - white



$$\lfloor \frac{n-d+1}{p} \rfloor = 0/p$$

filter

all are no. of pixels

Padding:- A pad around the image

$$\lfloor \frac{n+2p-d+1}{p} \rfloor$$

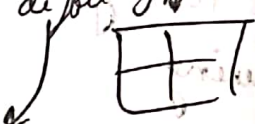
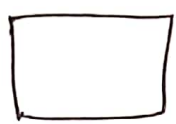
$$\rightarrow \lfloor \frac{n+2p-d+1}{p} \rfloor = 0/p$$

→ the filter is same as the weights, through back propagation we have to update

→ Relu activation on each and every value  
( $\max(0, x)$ )

→ many convolution operation takes place and

## Max Pooling

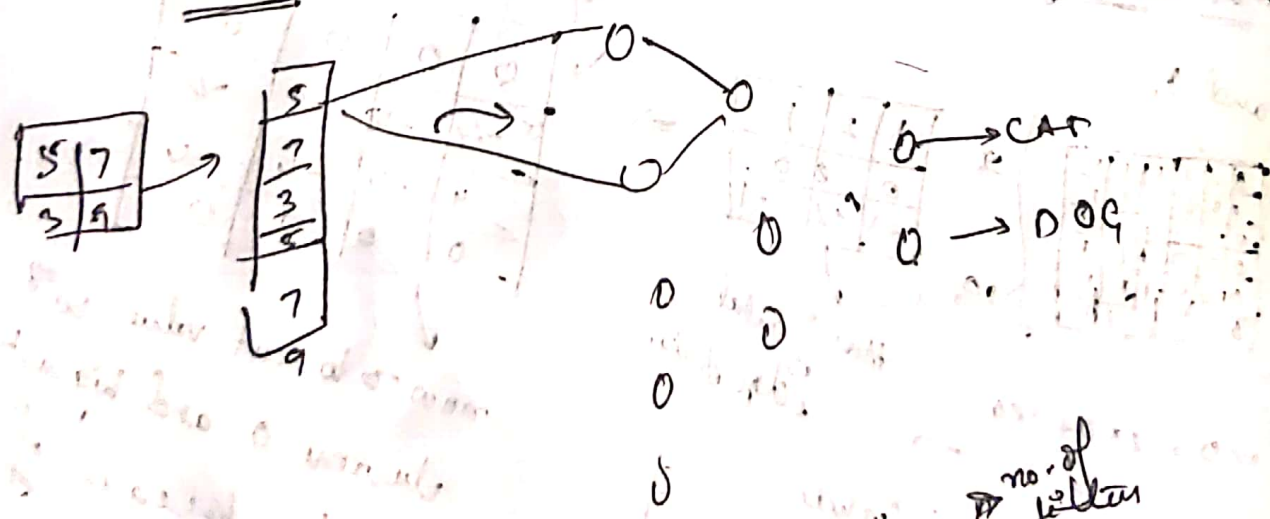


convolution

Relu  
max pooling  
diff bit

Locant invariant:- My object may be put anywhere,  
my CNN should extract most clear object

## Flattening layer



code :- `model.add(layers.Conv2D(32, (3, 3), activation='relu'))`  
no. of filters  
size of each filter