

stepper motor Interface to rotate clockwise by N steps, Introduce suitable delay.

```
#include <stdio.h>
#include <reg51.h>
char *data_port = 0x803;
char *data_port = 0x800;
char *data_acc = 0x8030;
delay ()
{
    int j;
    for (j = 0; j < 800; j++)
    {
        void main ()
        {
            port = 0x80;
            while (1)
            {
                acc = 0x88;
                port = acc;
                delay ();
                acc = 0x44;
                port = acc;
                delay ();
                acc = 0x22;
```

```
porta = acc;  
delay();  
acc = 0x11  
porta = acc;  
delay();  
}
```