

Assignment - I

18AV63

- i) Design a helical spring to operate for range of force 90N to 135N. The deflection of spring for load range is 7.5mm. Take $C=10$ & FOS=2.

Ans Given:-
Max load $F_a = 135\text{ N}$, Min load $F_i = 90\text{ N}$.

$$y' = 7.5\text{ mm}$$

$$C = 10$$

$$\text{FOS} = 2$$

Let us assume the materials as chrome vanadium.

From table 20.10.

$$\sigma_y = 690 \text{ MPa}$$

$$G = 79.34 \text{ GPa}$$

$$\therefore \tau = \frac{\sigma_y}{\text{FOS}} = \frac{690}{2} = 345 \text{ N/mm}^2$$

Formula 20.31 DDAB

$$\text{max deflection } y = \frac{y' F_a}{F_a - F_i} = \frac{7.5 \times 135}{135 - 90} = 22.5 \text{ mm}$$

i) Diameter of wire

$$\text{Shear stress } \tau = \frac{8 F_a D R}{\pi d^3} \quad \text{20.22 DDAB}$$

$$\text{Stress factor } K = \frac{4C-1}{4C-4} + \frac{0.615}{C}$$

$$= \frac{4 \times 10 - 1}{4 \times 10 - 4} + \frac{0.615}{10} = 1.1448$$

$$\text{Spring index } C = \frac{D}{d} \quad \therefore D = cd = 10d$$

$$\therefore 345 = \frac{8 \times 135 \times 10d \times 1.1448}{\pi d^3}$$

$$\therefore d = 3.37 \text{ mm/mm}$$

From table ~~20.8~~ 20.8

$$d = 3.4 \text{ mm/mm}$$

ii) Diameter of coil

$$\text{mean dia of coil } D = cd = 10 \times 3.4 = 34 \text{ mm/mm}$$

$$\text{Outer dia of coil } D_o = D + d = 34 + 3.4 = 37.4 \text{ mm/mm}$$

$$\text{Inner dia of coil } D_i = D - d = 34 - 3.4 = 30.6 \text{ mm/mm}$$

iii) Number of coils

$$y_1 = \frac{8F_o D^3 i}{d^4 h} \quad \text{from table 20.29,}$$

$$22.5 = \frac{8 \times 135 \times 34^3 \times i}{3.4^4 \times 79340}$$

$$\therefore i = 5.62$$

Thus we consider $i = 6 \Rightarrow$ no. of active coils.

iv) Free length.

From formula 20.53 (DDHB)

$$l_0 \geq (i+n)d + y + a$$

$$a = 25\% \text{ of max deflection} = \frac{25}{100} \times 24.022 = \underline{\underline{6 \text{ mm}}}$$

~~Actual~~ Actual max deflection ϕ

$$y = \frac{8 \times 135 \times 34^3 \times 6}{3.44 \times 79340} = \underline{\underline{24.022 \text{ mm}}}$$

Assuming square & ground end ϕ .

The number of additional coil $n=2$.

$$\therefore l_0 \geq (6+2) \times 3.4 + 24.022 + 6 \\ \geq 57.22 \text{ mm} \quad //$$

v) Pitch

from table 20.14

$$P = \frac{l_0 - 2d}{i} = \frac{57.22 - 2 \times 3.4}{6} = 8.4 \text{ mm} \quad //$$

vi) Required stiffness

From formulae 20.30 (CDNB)

$$F_o = \frac{F_{\text{max}}}{c} = \frac{135}{22.5} = 6 \text{ N/mm}^2$$

$$\text{or } \frac{1}{k} (w + \delta) \leq 1$$

vii) Actual stiffness

From formulae

$$F_o = \frac{d^4 h}{8 i^3 D} = \frac{3.44 \times 79340}{8.6 \times 341^3}$$

$$\text{or } \frac{1}{k} (w + \delta) \leq 8.62 \text{ N/mm}^2$$

viii) Total length of wire.

$$l = \pi D i' \quad i' = i + n$$

$i = \text{no. of coil turns}$

$$\therefore l = 3.14 \times 34 \times 8$$

$$= 854.513 \text{ mm} // \text{S.F.}$$

2) Design a helical spring to operate for range of Force 100 N to 160 N. The deflection of spring for load range is 7.5 mm. Take $C=8$ & FOS = 1.5

Ans

Given:-

Max load $F_2 = 160 \text{ N}$, Min load $F_1 = 100 \text{ N}$

$$y' = 7.5 \text{ mm}$$

$$C = 8$$

$$\text{FOS} = 1.5$$

lets assume the material as chrome vanadium.
from table no. 10.

$$Z_y = 690 \text{ MPa} = 690 \text{ N/mm}^2$$

$$G = 79340 \text{ MPa}$$

$$\therefore Z_{\text{eff}} = \frac{Z_y}{\text{FOS}} = \frac{690}{8} = 345 \text{ MPa}$$

Formula no. 31 DDKAB

$$\text{Max deflection } y = \frac{y' F_2}{F_2 - F_1} = \frac{7.5 \times 160}{160 - 100} = 20 \text{ mm}$$

i) Diameter of wire 20 mm DDKAB

$$\text{Shear stress } \tau = \frac{8 F_2 D k}{\pi d^3} =$$

$$\text{Stress factor } k = \frac{4c-1}{4c-4} + \frac{0.615}{c}$$

$$= \frac{4 \times 10 - 1}{4 \times 10 - 4} + \frac{0.615}{10} \geq 1.1448$$

$$\text{Spunnd index } c = \frac{D}{d} \therefore D = cd = 8d$$

$$\therefore 345 = \frac{8 \times 160 \times 8d \times 1.1448}{\pi \times d^3}$$

$$\therefore d = 10.81$$

$$d = 3.28 \text{ mm} \approx 3.3 \text{ mm}$$

ii) Dia of coil

$$\text{mean dia of coil } D = cd = 10 \times 3.3 = 33 \text{ mm}$$

$$\text{Outer dia of coil } D_o = D+d = 33+3.3 = 36.3 \text{ mm}$$

$$\text{Inner " " " } D_i = D-d = 33-3.3 = 29.7 \text{ mm}$$

iii) Number of coils

$$y_2 = \frac{8F_d D^3 i}{\pi^2 L^2}$$

$$20 = \frac{8 \times 160 \times 33^3 \times i}{\pi^2 \times 79340}$$

$$\therefore i = 4.090$$

Thus we consider $i = 5$

iv) Free length 20.53 DDB

$$l_0 \geq (i+n)d + y + a$$

$$a = 15\% \text{ of max def} = \frac{20}{100} \times 29.33 = 5.86 \text{ mm}$$

Actual ~~at~~ max deflection

$$y = \frac{8 \times 160 \times 33^3 \times 6}{3.34 \times 79340} = 29.33 \text{ mm}$$

Assuming square end ground end

the no of additional coil $n = 2$

$$\therefore l_0 \geq (6+2) \times 3.34 + 29.33 + 5.86$$

$$\geq 61.59 \text{ mm}$$

v) Pitch

Table 20.14 DDB

$$P = \frac{l_0 - ad}{i} = \frac{61.59 - 2 \times 3.34}{6} = 9.16 \text{ mm}$$

vi) Required stiffness

20.30 (DDB)

$$F_0 = \frac{F_{max}}{c} = \frac{160}{40} = 40 \text{ N/mm}$$

vii) Actual deflection stiffness.

$$F_0 = \frac{d^4 G}{81 D^3} \Rightarrow \frac{3.34 \times 79340}{8 \times 5 \times 33^3} = 654 \text{ N/mm}$$

viii) Total length of wire.

$$l = \pi D i' \quad i' = i + n$$

$$l = \pi \times 33 \times 7$$

$$= 725.70 \text{ mm}$$

3) Derive the equation for stress in helical spring of circular wire.

Ans.

Consider a helical compression spring made of circular wire and subjected to an axial load F .

Let, D = Mean dia of coil

d = dia of spring wire

i = number of spring active coils.

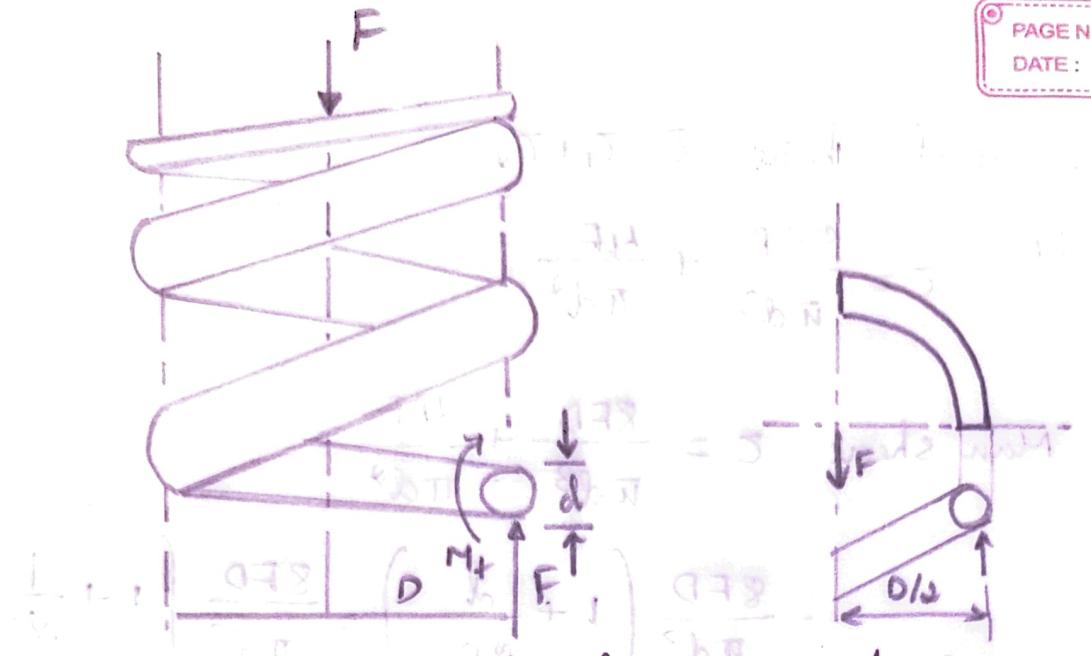
G = Modulus of rigidity.

F = Axial load on the spring.

τ = Max shear stress on the spring.

C = Spring Index.

y = Deflection of the spring.



Now consider a quadrant of a coil of a coiled wire spring. The load 'F' acting along the axis of the spring which has a mean diameter 'D' produces a torsional moment T_f or M_f .

$$\therefore M_f \text{ or } T = F \cdot \frac{D}{2}$$

This torsional moment is also equal to $\frac{\pi}{16} \tau_1 d^3$

$$\therefore T = \frac{FD}{2} = \frac{\pi}{16} \tau_1 d^3$$

$$\therefore \text{Shear stress, } \tau_1 = \frac{8FD}{\pi d^3} = \text{Poisson's ratio, } \mu = \frac{G}{E}$$

In addition there are 2 stresses acting.

i) Direct stress due to load 'F'

$$\sigma_{\text{direct}} = \frac{\text{load}}{\text{C/S Area of wire.}}$$

$$\tau_2 = \frac{F}{\frac{\pi}{4} d^2}$$

$$\therefore \tau_2 = \frac{4F}{\pi d^3}$$

Resultant shear $\tau = \tau_r + \tau_s$

$$\text{i.e., } \tau = \frac{8FD}{\pi d^3} + \frac{4F}{\pi d^2}$$

$$\text{Max shear } \tau = \frac{8FD}{\pi d^3} + \frac{4F}{\pi d^2}$$

$$= \frac{8FD}{\pi d^3} \left(1 + \frac{d}{2d} \right) = \frac{8FD}{\pi d^3} \left(1 + \frac{1}{2c} \right)$$

$$\therefore \tau = \frac{8FD}{\pi d^3} \cdot k_s \quad \left(\because c = \frac{D}{d} \right)$$

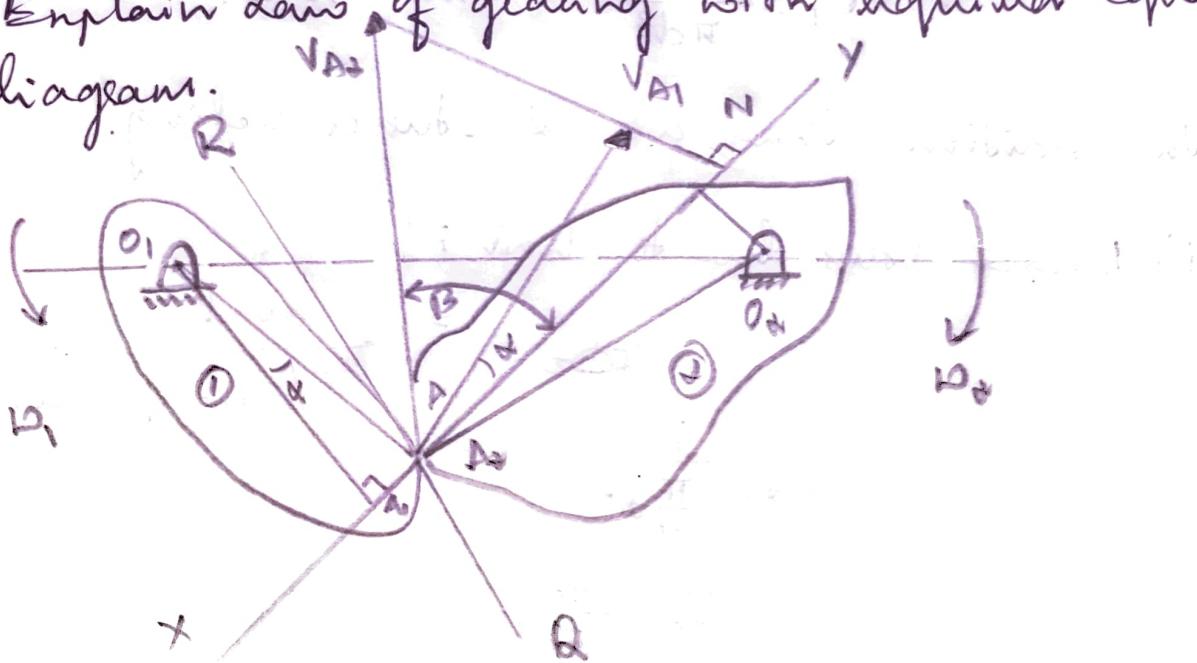
$$k_s = 1 + \frac{1}{2c} = \text{Shear stress factor.}$$

\therefore Max shear stress induced in the

$$\text{width } \tau = \frac{8FD}{\pi d^3} \cdot k$$

$$\text{where } k = \frac{4c-1}{4c-4} + \frac{0.615}{c}$$

- 4) Explain laws of gearing with required equations and diagrams.



When the tooth profiles are shaped, and if they produce a constant angular velocity ratio during meshing, then they are said to have conjugate action.

Fairwhale tooth profile is one of them which gives conjugate action.

Now let us consider two curved bodies 1 & 2 rotating about centres O_1 & O_2 which is in contact at A.

A_1 and A_2 are two coincident points. A_1 lying on body 1 and A_2 lying on body 2.

θ_1 and θ_2 are common tangent and common normal

at the point of contact respectively.

ω_1 and ω_2 are the angular velocities of A_1 and A_2 respectively.

The linear velocities at the point of contact at the instant be V_{A_1} and V_{A_2} .

The directions of these are \perp to the line joining O_1 to A_1 and O_2 to A_2 respectively.

Let the normal to the intersection of the line joining the centres of rotation 1 & 2 be P.

* Let $O_2 N$ be a perpendicular to the common normal from O_2 and $O_1 M$ be a perpendicular to the common normal from O_1 .

* If two bodies remain in contact then the linear velocities of A_1 & A_2 along the normal must be equal.

$$V_{A_1} \cdot \cos \alpha = V_{A_2} \cdot \cos \beta$$

$$\omega_1 \cdot O_1 A_1 \cos \alpha = \omega_2 \cdot O_2 A_2 \cdot \cos \beta$$

$$\therefore \frac{\omega_1 \cdot O_1 A_1}{O_1 A_1} \cdot \frac{O_2 N}{O_2 A_2} = \omega_2 \cdot O_2 A_2 \cdot \frac{O_2 N}{O_2 A_2}$$

$$\therefore \frac{\omega_1}{\omega_2} = \frac{O_2 N}{O_1 M} = \text{velocity ratio of rotation}$$

also triangles $O_1 MP$ and $O_2 NP$ are similar.

$$\therefore \frac{O_2 N}{O_1 P}$$

$$\therefore \text{Velocity ratio} = \frac{\omega_1}{\omega_2} = \frac{O_2 P}{O_1 P}$$

Thus far constant angular velocity ratio of gears, the normal at the point of contact divides the line joining the contact centres of rotation in the inverse ratio of the angular velocities.

Thus law of gearing states that for constant angular velocity ratio of the two gears, the common normal at the point of contact of the two meshing teeth must pass through a fixed point on the line joining the centre of rotation.

- 5) Design a spur gear to transmit power of 15kW at 1000 rpm. Check suitability and safety. Suggest suitable BHN, Take $i = 3.5$.

Ans

Given:-

$$P = 15 \text{ kW}, N_1 = 1000 \text{ rpm}, \text{ safety} = ? \quad \text{BHN} = ? \quad i = 3.5$$

Transmission ratio $i = 3.5$.

Calculating no of teeth $\dots (23.6) \text{ DDMB}$

assuming profile as 20° FDI $\therefore z_1 > 14$

lets take $z_1 = 20$

$$\text{WKT}; z_2 = i z_1 \quad \therefore z_2 = 3.5 \times 20 = 70$$

$$\therefore z_1 = 20 \quad \& \quad z_2 = 70$$

$$\left| \begin{array}{l} n_1 = 1000 \text{ rpm} \\ i = \frac{n_1}{n_2} \\ 3.5 = \frac{1000}{n_2} \\ \therefore n_2 = 285.71 \text{ rpm} \end{array} \right.$$

allow form Factor.

$$\text{For } 20^\circ \text{ FDI} \quad y = 0.154 - \frac{0.912}{2} \quad 23.116 \text{ DDMB}$$

Material \Rightarrow SAE 2320 for both gears and pinion

$$\therefore \tau = 345 \text{ MPa}$$

23.18 DDMB

$$\text{Power} = y_1 = 0.154 - \frac{0.812}{20} = 0.1084.$$

$$\text{Gear} = y_2 = 0.154 - \frac{0.912}{70} = 0.1409.$$

Particulars	σ	y	$(\omega \times y)$	Remarks
* Pinion	345	0.1084	37.39	Wearer.
* Gearing	345	0.1409	48.63	

"Pinion is weaker member hence design will be based on pinion".

Tangential load. --- 23.97 (DDKB)

$$F_t = \frac{9550 \times 1000 \times P \times C_v}{1000 \times m \times d}, \left[\alpha = \frac{m_2}{2} \right] \left[C_o = 1.5 \right]$$

$$= \frac{9550 \times 1000 \times 15 \times 1.5 \times 2}{1000 \times 10 \times 20}$$

$$\left[\because \alpha_1 = \frac{m_2}{\alpha} \right]$$

$$\therefore F_t = 11.487 \times w^3 / m^2 \rightarrow \textcircled{1} \quad \textcircled{2}$$

Lewis tangential tooth load,

$$F_t = \Gamma \times b \times y \times P \times C_v \quad (y = y_1)$$

$$= 345 \times 10 \times 10 \times 0.1084 \times \pi \times m$$

$$b = 9.5m - 12.5m$$

$$\therefore b = 10m$$

$$\Gamma = \pi \times m$$

$$F_t = 1.174 \times w^3 \times m^2 \times C_v \rightarrow \textcircled{2}$$

Equating $\textcircled{1} = \textcircled{2}$

$$\frac{11.487 \times 10^3}{m} = 1.174 \times w^3 \times m^2 \times C_v$$

$$\therefore w^3 C_v = 18.302 \rightarrow \textcircled{3}$$

~~Ans~~ Mean velocity

$$V_m = \frac{\pi \times d_1 \times n_1}{60 \times 1000} = \frac{\pi \times m_2 \times n_1}{60 \times 1000} = \frac{\pi \times m \times 1000}{360 \times 1000}$$

$$\therefore V_m = 1.047 \text{ m/s}$$

~~Ans~~ Table 23.3 DDHB

Teeth ① $m = 4 \text{ mm}$

$$V_m = 1.047 \times 4 = 4.188 \text{ m/s} < 7.5 \text{ m/s.}$$

$$\therefore C_r = \frac{3}{3 + V_m} = \frac{3}{3 + 4.188} = 0.4173. \quad \text{Q3.13(a)}$$

DDHB

$$② \Rightarrow m^3 C_r > 18.302$$

$$4^3 \times 0.417 > 18.302$$

$$\Rightarrow 64 > 18.302$$

\therefore It passes the requirement.

From T(23.1) DDHB

Addendum $\Rightarrow 1 \times m = 1 \times 4 = 4 \text{ mm.}$

Dedendum $\Rightarrow 1.25 \times m = 1.25 \times 4 = 5 \text{ mm.}$

Working depth $\Rightarrow 2 \times m = 2 \times 4 = 8 \text{ mm.}$

Total depth $\Rightarrow 2.25 \times m = 2.25 \times 4 = 9 \text{ mm.}$

Tooth thickness $\Rightarrow (\pi/4) \times m = (\pi/4) \times 4 = 6.28 \text{ mm.}$

minimum

$$\text{Clearance} \Rightarrow 0.25 \times m = 0.25 \times 4 = 1\text{mm}.$$

$$\text{Appox fillet radius} \rightarrow 0.3 \times m = 0.3 \times 4 = 1.2\text{mm}.$$

$$\text{Backlash} \Rightarrow 0\text{mm}$$

Pitch dia

$$\Rightarrow \text{Pinion} \Rightarrow 2.2m = 20 \times 4 = 80\text{mm}.$$

$$\Rightarrow \text{Gear} \Rightarrow 2.2m = 70 \times 4 = 140\text{mm}.$$

Outside dia

$$\Rightarrow \text{Pinion} \Rightarrow (2.4m) = (80+2) \times 4 = 88\text{mm}.$$

$$\Rightarrow \text{Gear} \Rightarrow (2.4m) = (140-2) \times 4 = 138\text{mm}.$$

Check for stress

$$\text{Allow stress; } \sigma_{\text{allow}} = \sigma \times C_v = 345 \times 0.4173$$

$$= 143.96 \text{ MPa}$$

$$\text{Induced stress; } \sigma_{\text{ind}} = \frac{F_t}{\text{by} \times P_{\text{inv}}} = \frac{(1.48 \times 10^3 / 4)}{10 \times 4 \times 0.1084 \times \pi \times 4}$$

$$\therefore \sigma_{\text{ind}} = 98.58 \text{ MPa}$$

∴ $\tau_{\text{allow}} > \tau_{\text{ind}}$ and thus the design is safe.

Check for factor of safety.

WKT;

$$n = \frac{\tau_{\text{allow}}}{\tau_{\text{ind}}} = \frac{143.96}{98.58} = 1.460$$

BHN = (23.37B) DDHB -

Having (shear) value of 345 MPa or 413.98 MPa

BHN of pinion = 200

BHN of gear = 150

- 6) Design a spur gear to transmit power of 10kW at 1500 rpm. Check suitability and safety.
- ② Suggest suitable BHN; back i=4.

Data

$P = 20 \text{ kW}$, $N_1 = 1500 \text{ rpm}$, softening = ? BHN = ?

$$i = 4$$

$$\therefore i = 4$$

from 23.6 DDFHB

assuming $\alpha = 20^\circ$

$$z_1 = 14$$

$$i = \frac{n_1}{n_2}$$

$$n_2 = \frac{n_1}{i} = \frac{1500}{4}$$

$$n_2 = 375 \text{ rpm}$$

Let's take $z_1 = 20$

wkf,

$$z_2 = i z_1 \therefore z_2 = 4 \times 20 = 80$$

$$z_1 = 20 \& z_2 = 80$$

Devise form factor.

for 20° FDI $y = 0.154 - \frac{0.912}{2}$

from 23.116 DDFHB.

natural \Rightarrow SAE 2320 form

both gear & pinion

$$\therefore \tau = 345 \text{ MPa} \xrightarrow{\text{23.18 DDFHB}}$$

$$\text{Pinion} = y_1 = 0.154 - \frac{0.912}{20} = 0.1084 \text{ N/mm}$$

$$\text{Gear} = y_2 = 0.154 - \frac{0.912}{80} = 0.1426 \text{ N/mm}$$

Particular $m = 0.5$ $\text{Pitch } 10\text{ mm}$ (5×5)

$$\text{Pinion} \quad 345 \quad 0.1084 \quad 37.39 \rightarrow \text{weak}$$

$$\text{Gear} \quad 345 \quad 0.1426 \quad 0.1429 \rightarrow \text{strong}$$

Thus pinion is weaker number.

Design

Tangential load.

$$F_t = \frac{9550 \times 1000 \times P \times C_s}{1000 \times m \times d_i} \left\{ \begin{array}{l} d_i = \frac{m^2}{\alpha} \\ (C_s = 1.5) \end{array} \right\} \therefore \left(d_i = \frac{m^2}{\alpha} \right)$$

$$F_t = \frac{9550 \times 1000 \times 20 \times 1.5}{1500 \times m \times 20} \times 2 = \frac{m^2 d_i}{\alpha}$$

$$\therefore F_t = \frac{19100}{m}$$

$$\therefore F_t = 19.10 \times 10^3 \text{ N/m} \rightarrow ①$$

Lini's Tangential tooth load.

$$F_t = \tau \times b \times y \times P \times C_v$$

$$= 345 \times 10 \times m \times 0.1084 \times \pi \times m \times C_v$$

$$\therefore F_t = 1.174 \times 10^3 \text{ m}^2 C_v \rightarrow ②$$

converting ① = ②

$$\frac{19.100 \times 10^3}{m} = 1.174 \times 10^3 \text{ m}^2 C_v$$

$$\therefore m^3 C_v = 16.269 \rightarrow ③$$

mean velocity

$$V_m = \frac{\pi \times d_1 \times m}{60 \times 1000}$$

$$= \frac{\pi \times m_2 \times n_1}{60 \times 1000}$$

$$= \frac{\pi \times m \times 20 \times 1500}{60 \times 1000}$$

$$\therefore V_m = 1.570 \text{ m/s}$$

DOB
23/9/3
D = 10m
P = 10pm

From Table 23.3 DDBB

trial ①. $m = 4 \text{ mm}$

$$\cancel{m = 10 \times 1.5 = 15.1}$$

$$= 1.57$$

$$V_m = 1.570 \times 4 = 6.28 \text{ & } 7.5 \text{ m/s.}$$

$$② \Rightarrow m^3 C_r -$$

$$C_r = \frac{3}{3 + 6.28} \geq 0.323 \rightarrow 23.18 \text{ m/s.}$$

$$m^3 C_r > 18.30$$

$$m^3 \times 0.323 > 18.30$$

$$= 20.3672 > 18.30$$

\therefore it passes the requirement.

From Table 23.1 DDBB.

$$\text{Addendum} \Rightarrow 1 \times m = 1 \times 4 = 4 \text{ mm}$$

$$\text{Bedendum} \Rightarrow 1.25 \times m = 1.25 \times 4 = 5 \text{ mm}$$

$$\text{work depth} \Rightarrow 1.25 \times m = 1.25 \times 4 = 8 \text{ mm.}$$

$$\text{total depth} \Rightarrow 2.25 \times m = 2.25 \times 4 = 9 \text{ mm.}$$

$$\text{Tooth thickness} \Rightarrow (\pi/4) \times m = (\pi/4) \times 4 = 6.28 \text{ mm}$$

minimum clearance $\Rightarrow 0.25 \times m = 0.25 \times 4 = 1\text{mm}$

Approach tilt
racks $\Rightarrow 0.3 \times m = 0.3 \times 4 = 1.2\text{mm}$

Backlash $\Rightarrow 0\text{mm}$

Pitch dia

$\Rightarrow \text{Pitch dia} \Rightarrow 2, \text{mm} = 10 \times 4 = 80\text{mm}$

$\Rightarrow \text{Gear} \Rightarrow 2 \times m = 80 \times 4 = 320\text{mm}$

Outside dia

$\Rightarrow \text{Pitch dia} + 2 \times 2 = (20 + 2) \times 4 = 88\text{mm}$

Gear $= (2, + 2)m = (80 + 2) \times 4 = 328\text{mm}$

Stress

$\sigma_{\text{allow}} = \sigma \times C_v = 345 \times 0.323 = 111.435 \text{ MPa}$

Induced

shear stress $\tau_{\text{ind}} = \frac{F_t}{b \times P} = \frac{(19.100 \times 10^3 / 4)}{10 \times 4 \times 0.1084 \times \pi \times 4}$

$\tau_{\text{ind}} > 87.63 \text{ MPa}$

$\therefore \sigma_{\text{allow}} > \sigma_{\text{find}}$ \therefore Design is safe.

~~Step 8:-~~ ϕ

Factor of safety.

$$\text{WKT } h = \frac{\sigma_{\text{allow}}}{\sigma_{\text{find}}} = \frac{111.435}{87.63} = 1.27$$

BHN \rightarrow 23378 DDU B.

having shear value of 345 MPa
 $\approx 413.95 \text{ MPa}$

BHN of pinion = 200

BHN of gear = 150