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AI20MTECH14010

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Abstract—This document aims to identify subspaces of a given vector space.

Download all latex-tikz codes from

https://github.com/anjanavasudevan/ grad_schoolwork/tree/master/EE5609/ Assignment8

1 Question

Which of the following are subspaces of the vector space \mathbb{R}^3 ?

- 1) (x, y, z) : x + y = 0
- 2) (x, y, z) : x y = 0
- 3) (x, y, z) : x + y = 1
- 4) (x, y, z) : x y = 1

2 Answer

A subspace S of a vector space is defined as a non-empty subset that is closed under addition and scalar multiplication, i.e

- 1) All possible linear combinations of the vectors in **S** lie in the subspace.
- 2) Any vector in S scaled by a scalar c lies in the subspace.

Using the above definition,:

2.1 *Option* 1:

Let
$$\mathbf{A} = \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix}$$
 and $\mathbf{B} = \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} \in \mathbf{S}$, and k_1 and k_2 be

some scalars.

The linear combination of **A** and **B** is:

$$k_{1}\mathbf{A} + k_{2}\mathbf{B} = k_{1} \begin{pmatrix} x_{1} \\ y_{1} \\ z_{1} \end{pmatrix} + k_{2} \begin{pmatrix} x_{2} \\ y_{2} \\ z_{2} \end{pmatrix} = \begin{pmatrix} k_{1}x_{1} + k_{2}x_{2} \\ k_{1}y_{1} + k_{2}y_{2} \\ k_{1}z_{1} + k_{2}z_{2} \end{pmatrix}$$
(2.1.1)

Verifying the property of the subspace:

$$\begin{pmatrix} 1 & 1 \end{pmatrix} \{ k_1 \mathbf{x_1} + k_2 \mathbf{x_2} \} = \begin{pmatrix} 1 & 1 \end{pmatrix} \left\{ k_1 \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} + k_2 \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} \right\}$$
(2.1.2)

$$\Longrightarrow = \begin{pmatrix} 1 & 1 \end{pmatrix} k_1 \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} + \begin{pmatrix} 1 & 1 \end{pmatrix} k_2 \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} \quad (2.1.3)$$

$$\implies k_1 \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} + k_2 \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = 0 \quad (2.1.4)$$

As

$$\begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 0$$
(2.1.5)

It is also evident from above that

$$c\mathbf{A} = \begin{pmatrix} cx_1 \\ cy_1 \\ cz_1 \end{pmatrix} \tag{2.1.6}$$

$$\implies \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} cx \\ cy \end{pmatrix} = 0 \tag{2.1.7}$$

for some scalar c. Therefore, option 1 is a subspace of \mathbb{R}^3 .

It can also be proven that option 2 is also a valid subspace of \mathbb{R}^3 as:

$$c\mathbf{A} = \begin{pmatrix} cx_1 \\ cy_1 \\ cz_1 \end{pmatrix} \tag{2.1.8}$$

$$\implies \begin{pmatrix} 1 & -1 \end{pmatrix} \begin{pmatrix} cx_1 \\ cy_1 \end{pmatrix} = \begin{pmatrix} 1 & -1 \end{pmatrix} c \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} =$$

$$c \begin{pmatrix} 1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = 0$$
(2.1.9)

$$\implies k_1 \mathbf{A} + k_2 \mathbf{B} = \begin{pmatrix} k_1 x_1 + k_2 x_2 \\ k_1 y_1 + k_2 y_2 \\ k_1 z_1 + k_2 z_2 \end{pmatrix}$$
 (2.1.10)

$$\implies \begin{pmatrix} 1 & -1 \end{pmatrix} \begin{pmatrix} k_1 x_1 + k_2 x_2 \\ k_1 y_1 + k_2 y_2 \end{pmatrix} =$$

$$\begin{pmatrix} 1 & -1 \end{pmatrix} \begin{pmatrix} k_1 x_1 \\ k_1 y_1 \end{pmatrix} + \begin{pmatrix} 1 & -1 \end{pmatrix} \begin{pmatrix} k_2 x_2 \\ k_2 y_2 \end{pmatrix} = 0 \in \mathbf{S} \quad (2.1.11)$$

for some scalars c, k_1 and k_2 and vectors **A** and **B** \in **S**.

2.2 *Option 3*:

Option 3 is not a valid subspace of \mathbb{R}^3 as:

$$k_1 \mathbf{A} + k_2 \mathbf{B} = \begin{pmatrix} k_1 x_1 + k_2 x_2 \\ k_1 y_1 + k_2 y_2 \\ k_1 z_1 + k_2 z_2 \end{pmatrix}$$
(2.2.1)

$$\implies \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} k_1 x_1 + k_2 x_2 \\ k_1 y_1 + k_2 y_2 \end{pmatrix} =$$

$$\begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} k_1 x_1 \\ k_1 y_1 \end{pmatrix} + \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} k_2 x_2 \\ k_2 y_2 \end{pmatrix} =$$

$$k_1 \begin{pmatrix} 1 & 1 \end{pmatrix} \mathbf{x_1} + k_2 \begin{pmatrix} 1 & 1 \end{pmatrix} \mathbf{x_2} = k_1 + k_2 \neq 1 \quad (2.2.2)$$

For some scalars k_1 and k_2 , **A** and **B** \in **S** in the option.

Similarly option 4 is also not a valid subspace of \mathbb{R}^3 as it can be be shown in similar manner that

$$k_1 \mathbf{A} + k_2 \mathbf{B} = \begin{pmatrix} k_1 x_1 + k_2 x_2 \\ k_1 y_1 + k_2 y_2 \\ k_1 z_1 + k_2 z_2 \end{pmatrix}$$
(2.2.3)

$$\implies \begin{pmatrix} 1 & -1 \end{pmatrix} \begin{pmatrix} k_1 x_1 + k_2 x_2 \\ k_1 y_1 + k_2 y_2 \end{pmatrix} =$$

$$\begin{pmatrix} 1 & -1 \end{pmatrix} \begin{pmatrix} k_1 x_1 \\ k_1 y_1 \end{pmatrix} + \begin{pmatrix} 1 & -1 \end{pmatrix} \begin{pmatrix} k_2 x_2 \\ k_2 y_2 \end{pmatrix} =$$

$$k_1 \begin{pmatrix} 1 & -1 \end{pmatrix} \mathbf{x_1} + k_2 \begin{pmatrix} 1 & -1 \end{pmatrix} \mathbf{x_2} = k_1 + k_2 \neq 1 \quad (2.2.4)$$

Therefore, Options 1 and 2 are valid subspces of the vector space \mathbb{R}^3