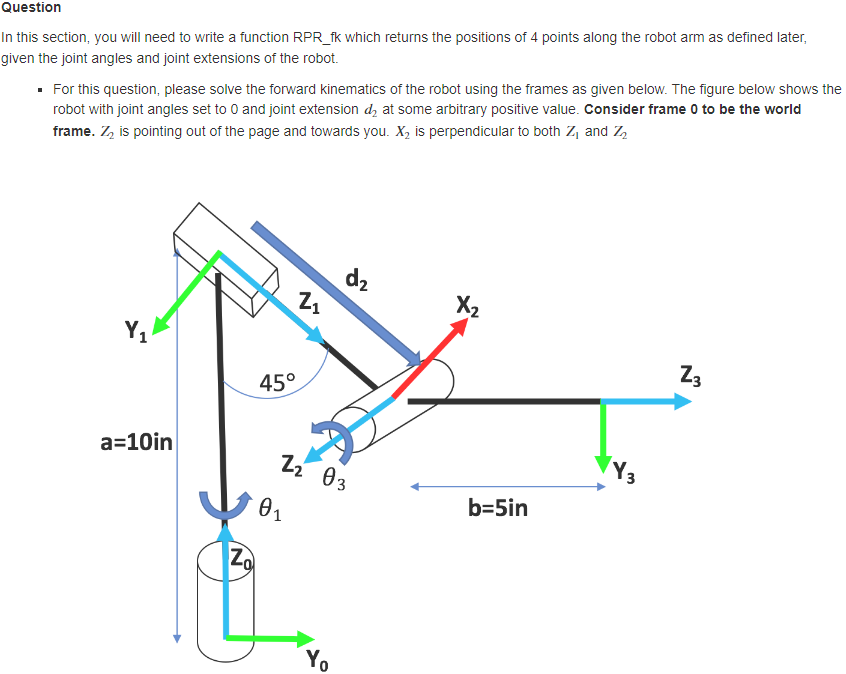
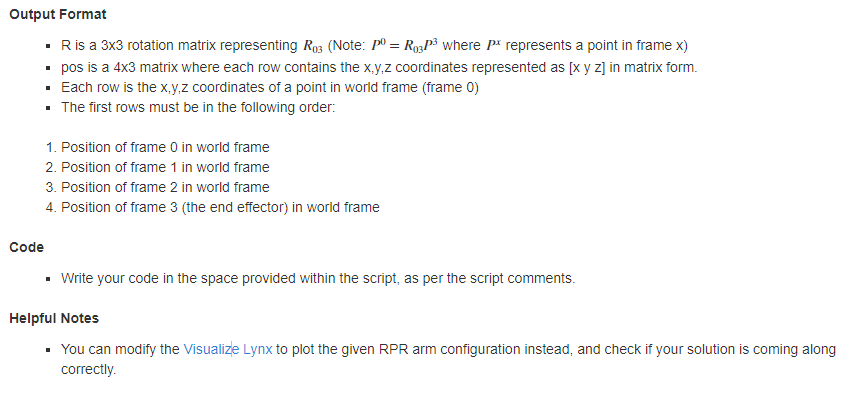
## Write a Function for Forward & Inverse Kinematics of the RPR Robot





**Inverse Kinematics: -**

