

$$1. \quad a. \quad \bar{T}_1 = a\bar{X} + (1-a)c_{\bar{x}}S$$

$$E(\bar{T}_1) = aE(\bar{X}) + (1-a)E(c_{\bar{x}}S)$$

$$E(\bar{X}) = E(c_{\bar{x}}S) = \gamma$$

$$\therefore E(\bar{T}_1) = a\gamma + (1-a)\gamma$$

$$= a\gamma + \gamma - a\gamma$$

$$= \gamma$$

$\therefore E(\bar{T}_1)$ is unbiased for
any constant a .

$$b. \text{MSE}(T_1) = E\{(T_1 - \gamma)^2\}$$

$$= E\{T_1 - E(T_1)\}^2 + \{E(T_1) - \gamma\}^2$$

$$= \text{Var}(T_1) + \text{Bias}(T_1)$$

T_1 is unbiased, so

$$= \text{Var}(T_1)$$

$$= \text{Var}(a\bar{X} + (1-a)c_x S)$$

$$= a^2 \text{Var}(\bar{X}) + (1-a)^2 \text{Var}(c_x S)$$

$$= a^2 \frac{\gamma^2}{n} + (1-a)^2 (c_x^2 (E(S^2) - E(S)^2))$$

$$= a^2 \frac{\gamma^2}{n} + (1-a)^2 (c_x^2 (\gamma^2 - \frac{\gamma^2}{c_x^2}))$$

$$= a^2 \frac{\gamma^2}{n} + \gamma^2 (1-a)^2 (c_x^2 - 1)$$

$$\text{let } f(a) = a^2 \frac{\gamma^2}{n} + \gamma^2 (1-a)^2 (c_x^2 - 1)$$

$$f'(a) = 2a \frac{\gamma^2}{n} - 2\gamma^2 (1-a)(c_x^2 - 1)$$

since S^2 is unbiased,

$$\hookrightarrow E(S^2) = \gamma^2$$

since $c_x S$ is unbiased,

$$\hookrightarrow E(c_x S) = \gamma$$

$$E(S) = \frac{\gamma}{c_x}$$

$$0 \stackrel{!}{=} 2u \frac{\gamma^2}{n} - 2\gamma^2 (1-u)(c_*^2 - 1)$$

$$\frac{u}{n} = (c_*^2 - 1)(1-u)$$

$$u = \frac{u(c_*^2 - 1)}{u(c_*^2 - 1) + 1}$$

$$\therefore T_1^* = \frac{u(c_*^2 - 1)}{u(c_*^2 - 1) + 1} \bar{X} + \frac{1}{u(c_*^2 + 1)} c_* S$$

$$c. T_2 = a_1 \bar{X} + a_2 (c_* S)$$

$$MSE(T_2) = E((T_2 - \gamma)^2)$$

$$= \text{Var}(T_2) + (E(T_2) - \gamma)^2$$

consider $\text{Var}(T_2)$:

$$\text{Var}(T_2) = \text{Var}(a_1 \bar{X} + a_2 (c_* S))$$

$$= a_1^2 \text{Var}(\bar{X}) + a_2^2 \text{Var}(c_* S)$$

from (b),

$$= a_1^2 \frac{\gamma^2}{n} + a_2^2 \gamma^2 (c_*^2 - 1)$$

consider $(E(T_2) - \gamma)^2$

$$= (E(a_1 \bar{X} + a_2 c_* S) - \gamma)^2$$

$$= (a_1 E(\bar{X}) + a_2 E(c_* S) - \gamma)^2$$

from (b),

$$= (a_1 \gamma + a_2 \gamma - \gamma)^2$$

$$= (a_1 + a_2 - 1)^2 \gamma^2$$

$$\therefore \text{MSE}(T_2) = a_1^2 \frac{\gamma^2}{n} + a_2^2 \gamma^2 (C_x^2 - 1) + (a_1 + a_2 - 1)^2 \gamma^2$$

$$\frac{\partial f}{\partial a_1} = 2a_1 \frac{\gamma^2}{n} + 2(a_1 + a_2 - 1) \gamma^2$$

$$0 = 2a_1 \frac{\gamma^2}{n} + 2(a_1 + a_2 - 1) \gamma^2$$

$$0 = \frac{a_1}{n} + a_1 + a_2 - 1$$

$$n = (n+1)a_1 + na_2$$

$$\frac{\partial f}{\partial a_2} = 2a_2 \gamma^2 (C_x^2 - 1) + 2(a_1 + a_2 - 1) \gamma^2$$

$$0 = 2a_2 \gamma^2 (C_x^2 - 1) + 2(a_1 + a_2 - 1) \gamma^2 \quad (2)$$

$$0 = a_2 (C_x^2 - 1) + a_1 + a_2 - 1$$

$$1 = C_x^2 a_2 + a_1 \quad (2)$$

① and ②:

$$\left(\begin{array}{cc|c} 1 & c_k^2 & 1 \\ n+1 & n & n \end{array} \right)$$

$$R_2 \rightarrow R_2 - (n+1)R_1$$

$$\left(\begin{array}{cc|c} 1 & c_k^2 & 1 \\ 0 & n - n c_k^2 - c_k^2 & -1 \end{array} \right)$$

$$R_2 \rightarrow \frac{R_2}{n - n c_k^2 - c_k^2}$$

$$\left(\begin{array}{cc|c} 1 & c_k^2 & 1 \\ 0 & 1 & \frac{1}{n(c_k^2 - 1) + c_k^2} \end{array} \right)$$

$$R_1 \rightarrow R_1 - \frac{c_k^2}{n(c_k^2 - 1) + c_k^2} R_2$$

$$\left(\begin{array}{cc|c} 1 & 0 & 1 - \frac{c_k^2}{n(c_k^2 - 1) + c_k^2} \\ 0 & 1 & \frac{1}{n(c_k^2 - 1) + c_k^2} \end{array} \right)$$

$$a_1 = 1 - \frac{c_x^2}{n(c_x^2 - 1) + c_x^2}$$

$$a_2 = \frac{1}{n(c_x^2 - 1) + c_x^2}$$

$$A. \text{MSE}(T_2) = \frac{\gamma^2}{n} a_1^2 + \gamma^2 (c_x^2 - 1) a_2^2 + \gamma (a_1 + a_2 - 1)^2$$

$$= \frac{\gamma^2}{n} \left(\frac{n(c_x^2 - 1)}{n(c_x^2 - 1) + c_x^2} \right) + \gamma^2 (c_x^2 - 1) \left(\frac{1}{n(c_x^2 - 1) + c_x^2} \right)^2 + \gamma \left(\frac{n(c_x^2 - 1) + 1}{n(c_x^2 - 1) + c_x^2} - 1 \right)^2$$

Let $n(c_x^2 - 1) + c_x^2 = A$

$$= \gamma^2 \left(\frac{c_x^2 - 1}{A} \right) + \gamma^2 \left(\frac{c_x^2 - 1}{A^2} \right) + \gamma \left(\left(\frac{n(c_x^2 - 1) + 1}{A} \right) - 1 \right)^2$$

Let $c_x^2 - 1 = B$

$$= \gamma^2 \frac{B}{A} + \gamma^2 \frac{B}{A^2} + \gamma \frac{nB^2 + 1}{A^2} - 2 \frac{B}{A} + 1$$

$$= \gamma^2 \frac{B}{A} + \gamma^2 \frac{B}{A^2} + n^2 \gamma \frac{B^2}{A^2} + 2n \frac{B}{A^2} + \frac{1}{A^2} - 2 \frac{B}{A} + 1$$

$$= \frac{\gamma^2 (c_x^2 - 1)}{n(c_x^2 - 1) + c_x^2}$$

$$\text{MSE}(T_1) = \frac{\gamma^2 (c_x^2 - 1)}{n(c_x^2 - 1) + 1}$$

Since $c_x^2 > 1$

$$n(c_x^2 - 1) + c_x^2 > n(c_x^2 - 1) + 1$$

$$\therefore \text{MSE}(T_2) = \frac{\gamma^2 (c_x^2 - 1)}{n(c_x^2 - 1) + c_x^2} < \frac{\gamma^2 (c_x^2 - 1)}{n(c_x^2 - 1) + 1} = \text{MSE}(T_1)$$

$$e. \quad \text{MSE}(V_+) = E[(\max(0, T_2^*) - \gamma)^2]$$

$$\text{MSE}(T_2^*) = E[(T_2^* - \gamma)^2]$$

$$\text{If } T_2^* \geq 0,$$

$$\max(0, T_2^*) = T_2^*$$

$$\therefore E[(\max(0, T_2^*) - \gamma)^2] = E[(T_2^* - \gamma)^2]$$

$$\text{If } T_2^* < 0,$$

$$\max(0, T_2^*) = 0$$

$$1. \quad E[(\max(0, T_2^*) - \gamma)^2] = E(\gamma^2)$$

$$\therefore \text{ in both cases, } E[(\max(0, T_2^*) - \gamma)^2] \leq E[(T_2^* - \gamma)^2]$$

$$\text{So } \text{MSE}(V_+) \leq \text{MSE}(T_2^*)$$

$$f. T_3 = a_1 \bar{x} + a_2 c_x S + a_3$$

1

T_3 is unbiased, so

$$MSE(T_3) = Var(T_3)$$

$$= Var(a_1 \bar{x} + a_2 c_x S + a_3)$$

$$= a_1^2 Var(\bar{x}) + a_2^2 Var(c_x S)$$

$$= a_1^2 \frac{\gamma^2}{n^2} + a_2^2 \gamma^2 (c_x^2 - 1)$$

$$Let \quad f(a_1, a_2) = a_1^2 \frac{\gamma^2}{n^2} + a_2^2 \gamma^2 (c_x^2 - 1)$$

$$\frac{\partial f}{\partial a_1} = 2a_1 \frac{\gamma^2}{n^2}$$

$$0 = 2a_1 \frac{\gamma^2}{n^2}$$

$$a_1 = 0$$

$$\frac{\partial f}{\partial a_2} = 2a_2 \gamma^2 (c_{*}^{2-1})$$

$$0 = 2a_2 \gamma^2 (c_{*}^{2-1})$$

$$a_2 = 0$$

we know T_3 is unbiased.

$$\therefore E(T_3) = \gamma$$

$$E(a_1 \bar{x} + a_2 c_{*} s + a_3) = \gamma$$

$$E(a_3) = \gamma$$

$$a_3 = \gamma$$

2.

a.

$$l(y, \hat{y}) = \frac{1}{2} (y - \hat{y})^2$$

$$\text{Show: } r_{t,i} = y_i - f_{t-1}(x_i)$$

GC1:

$$r_{t,i} = - \frac{\partial}{\partial f(x_i)} \sum_{j=1}^n \frac{1}{2} (y_j - f(x_j))^2 \Big|_{f=f_{t-1}}$$

$$= - \sum_{j=1}^n (y_j - f_{t-1}(x_j)) \delta_{ij}$$

$$= y_i - f_{t-1}(x_i)$$

GC2:

$$h_t = \arg \min_{u \in F} \sum_{i=1}^n \frac{1}{2} (r_{t,i} - u(x_i))^2$$

$$b. \quad \alpha_t = \arg \min_{\alpha} \sum_{i=1}^n \frac{1}{2} (y_i - (f_{t-1}(x_i) + \alpha h_t(x_i)))^2$$

$$\frac{d}{d\alpha} = \sum_{i=1}^n (y_i - f_{t-1}(x_i) - \alpha h_t(x_i)) (-h_t(x_i))$$

$$= \sum_{i=1}^n (r_{t,i} - \alpha h_t(x_i)) h_t(x_i)$$

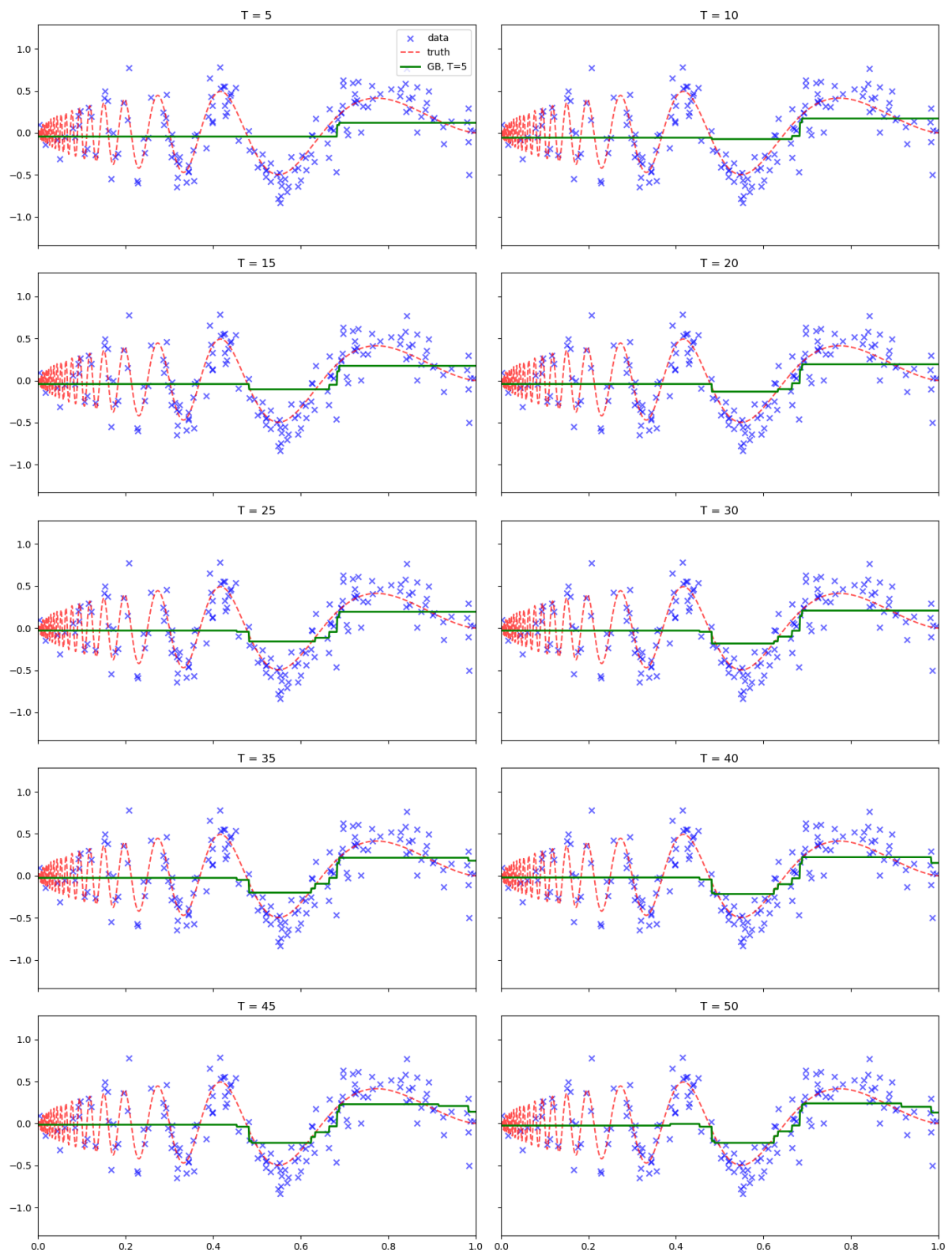
$$\frac{d}{d\alpha} = 0$$

$$0 = \sum_{i=1}^n (r_{t,i} - \alpha h_t(x_i)) h_t(x_i)$$

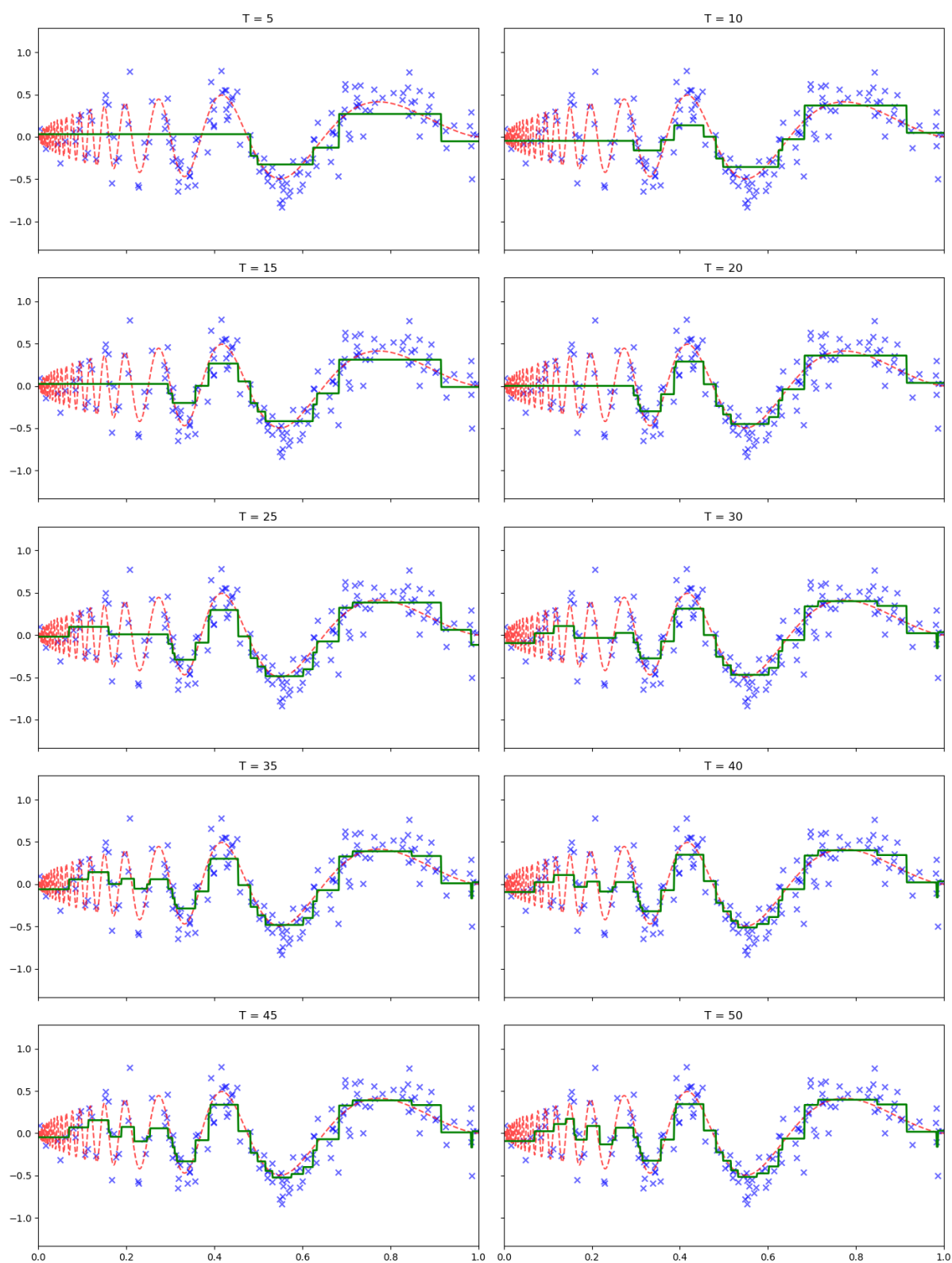
$$\alpha_t = \frac{\sum_{i=1}^n r_{t,i} h_t(x_i)}{\sum_{i=1}^n h_t(x_i)^2} = \frac{\sum_{i=1}^n (y_i - f_{t-1}(x_i)) h_t(x_i)}{\sum_{i=1}^n h_t(x_i)^2}$$

c.

Gradient-Combination with decision stumps, step="fixed"



Gradient-Combination with decision stumps, step="adaptive"



With the fixed step size, it underfits significantly, even at high T . The adaptive step size converges much faster and also fits the data much better.

```

yy_true = f(xx.flatten())

def gradient_combination(X, y, xx, T, max_depth, step='fixed', alpha_fixed=0.1):
    n = X.shape[0]
    f_pred = np.zeros(n)
    f_grid = np.zeros_like(xx.flatten())
    models = []
    alphas = []

    for t in range(T):
        r = y - f_pred

        stump = DecisionTreeRegressor(max_depth=max_depth)
        stump.fit(X, r)
        h_train = stump.predict(X)
        h_grid = stump.predict(xx.reshape(-1, 1))

        if step == 'fixed':
            alpha = alpha_fixed
        else:
            alpha = np.dot(r, h_train) / np.dot(h_train, h_train)

        f_pred += alpha * h_train
        f_grid += alpha * h_grid

        models.append(stump)
        alphas.append(alpha)

    return f_grid

T_list = [5, 10, 15, 20, 25, 30, 35, 40, 45, 50]

for step in ['fixed', 'adaptive']:
    fig, axes = plt.subplots(5, 2, figsize=(14, 20), sharex=True, sharey=True)
    fig.suptitle(f'Gradient Combination with decision stumps, step="{step}"', fontsize=16)

    for ax, T in zip(axes.flat, T_list):
        yb = gradient_combination(X, y, xx, T=T, max_depth=1,
                                  step=step, alpha_fixed=0.1)

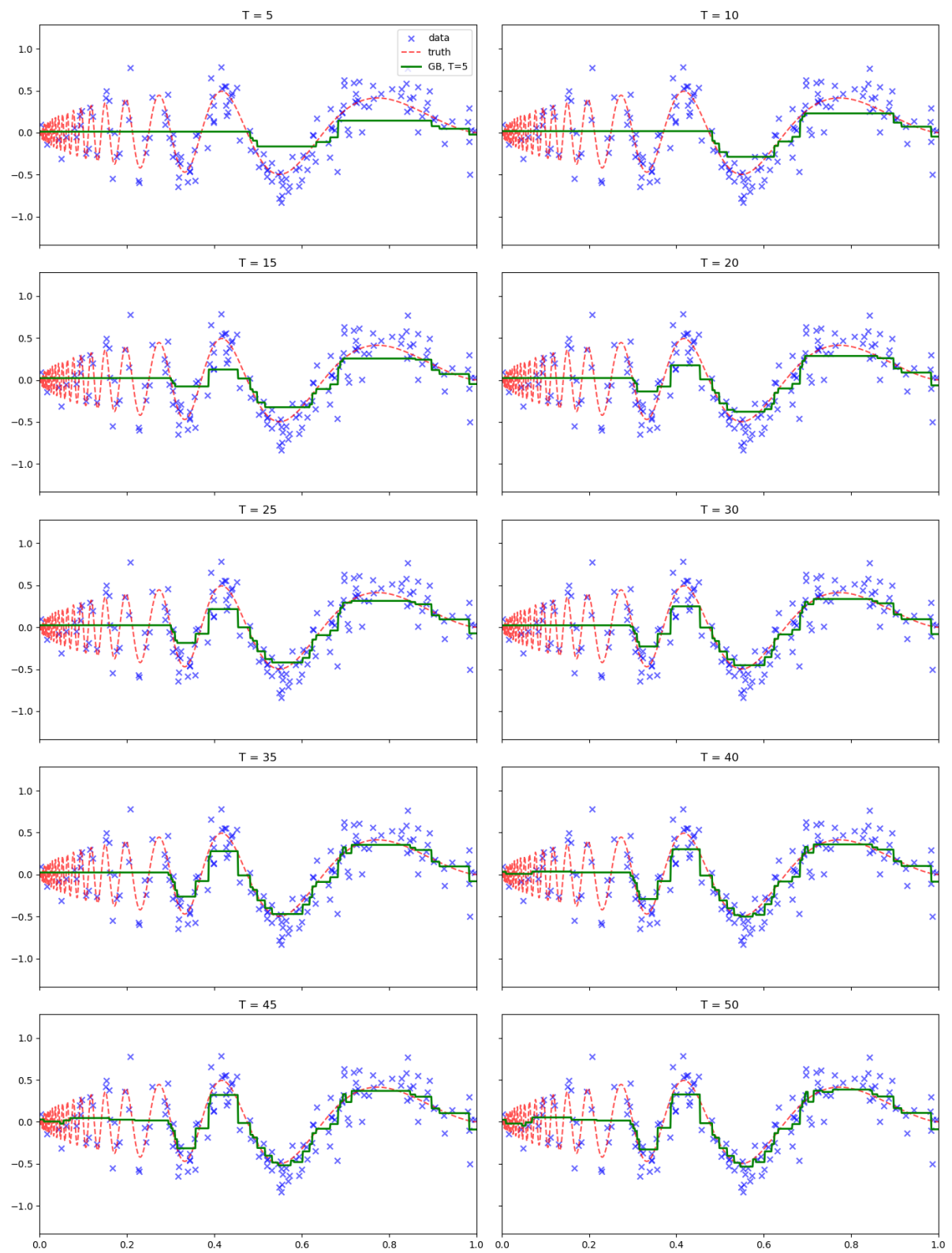
        ax.scatter(X, y, marker='x', color='blue', alpha=0.6, label='data')
        ax.plot(xx, yy_true, 'r--', alpha=0.7, label='truth')
        ax.plot(xx, yb, 'g-', lw=2, label=f'GB, T={T}')
        ax.set_xlim(0, 1)
        ax.set_ylim(np.min(y) - 0.5, np.max(y) + 0.5)
        ax.set_title(f'T = {T}')
        if (T == T_list[0] and step=='fixed'):
            ax.legend(loc='upper right')

    plt.tight_layout(rect=[0, 0.03, 1, 0.97])
    plt.show()

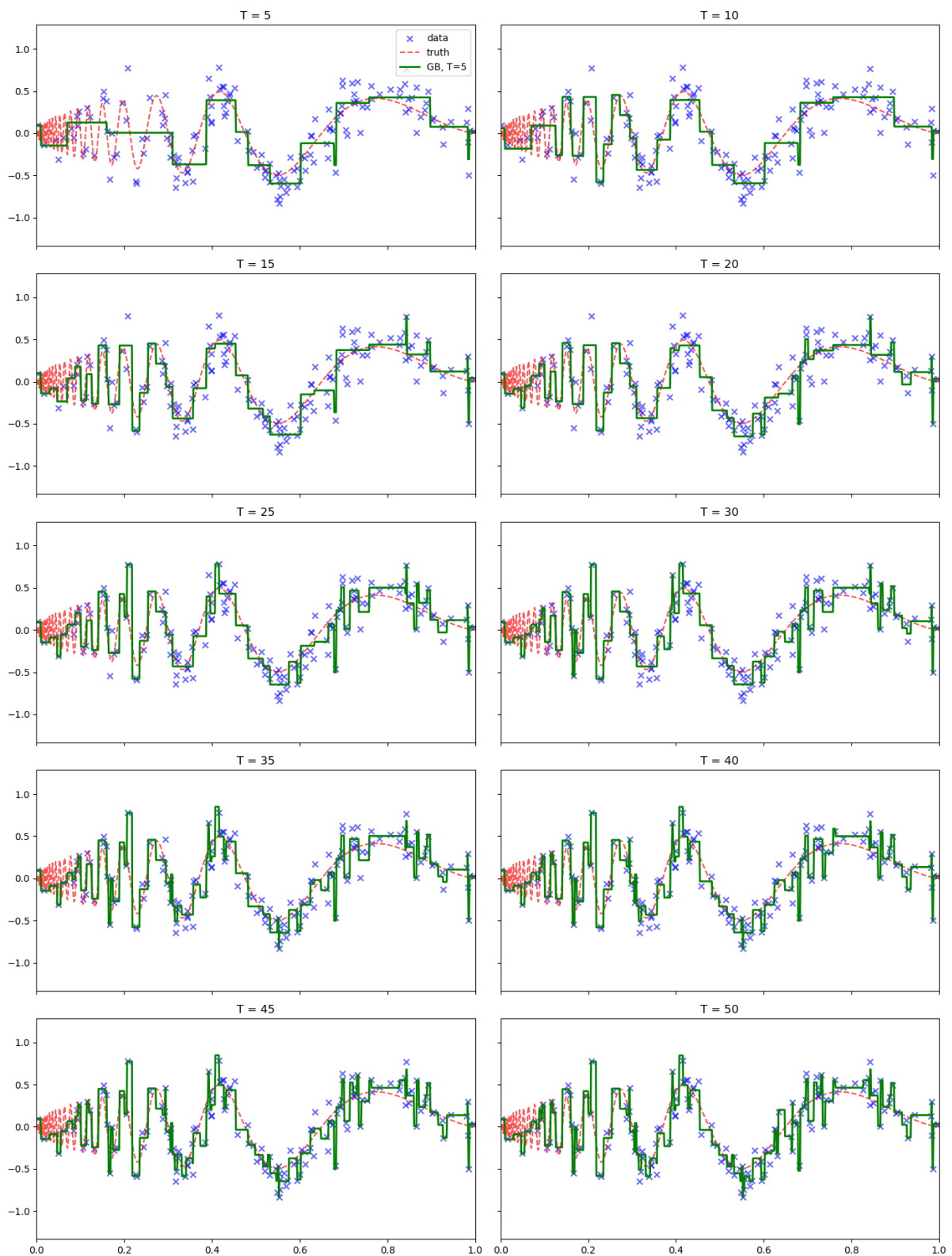
```

d.

Depth-2 Trees, step="fixed"



Depth-2 Trees, step="adaptive"



for a fixed $\alpha = 0.1$, fit is piecewise constant but tracks the curvature well. adaptive α : each tree is stronger, so adaptive boosting zooms in on residuals very quickly. therefore, it ends up overfitting the data.

```

T_list = [5, 10, 15, 20, 25, 30, 35, 40, 45, 50]

for step in ['fixed', 'adaptive']:
    fig, axes = plt.subplots(5, 2, figsize=(14, 20), sharex=True, sharey=True)
    fig.suptitle(f'Depth-2 Trees, step="{step}"', fontsize=16)

    for ax, T in zip(axes.flat, T_list):
        yb = gradient_combination(X, y, xx, T=T, max_depth=2,
                                step=step, alpha_fixed=0.1)
        ax.scatter(X, y, marker='x', color='blue', alpha=0.6, label='data')
        ax.plot(xx.flatten(), yy_true, 'r--', alpha=0.7, label='truth')
        ax.plot(xx.flatten(), yb, 'g-', lw=2, label=f'GB, T={T}')
        ax.set_xlim(0, 1)
        ax.set_ylim(np.min(y) - 0.5, np.max(y) + 0.5)
        ax.set_title(f'T = {T}')
        if T == T_list[0]:
            ax.legend(loc='upper right')

plt.tight_layout(rect=[0, 0.03, 1, 0.97])
plt.show()

```

$$c. \ell(y, \hat{y}) = \log(1 + e^{-y\hat{y}}) \quad y \in \{-1, 1\}$$

$$v_{f,i} = -\frac{\partial}{\partial f(x_i)} \sum_{j=1}^n \log(1 + e^{-y_j f(x_j)})_{f=f_{t-1}} = -\left(-\frac{y_i e^{-y_i f_{t-1}(x_i)}}{1 + e^{-y_i f_{t-1}(x_i)}} \right) = \frac{y_i}{1 + e^{-y_i f_{t-1}(x_i)}}$$

not F

$$n_f = \underset{n \in F}{\operatorname{argmin}} \sum_{i=1}^n \log(1 + e^{-v_{f,i}^T u(x_i)})$$

choose:

$$f_t \quad \alpha_t = \arg \min_{\alpha} \sum_{i=1}^n \log(1 + \exp(-y_i(f_{t-1}(x_i) + \alpha h_t(x_i))))$$

derivative and set to zero:

$$0 = \sum_{i=1}^n \frac{-y_i h_t(x_i) e^{-y_i(f_{t-1}(x_i) + \alpha h_t(x_i))}}{1 + e^{-y_i(f_{t-1}(x_i) + \alpha h_t(x_i))}}$$

so in α ,

$$\sum_i y_i h_t(x_i) \cdot \frac{1}{1 + e^{y_i(f_{t-1}(x_i) + \alpha h_t(x_i))}} = 0$$

No closed form exists because the logistic loss terms for different i couple α in separate exponentials.

g. we can't solve for θ directly.

but we can approximate it using \nearrow cost of $O(Kn)$
a 1D line search with booting rounds \nearrow extra per round.

\hookrightarrow Backtracking line search \rightarrow Armijo's rule

\hookrightarrow Brent's method or golden section search

$$- \phi(\alpha) = \sum_i \ell(y_i, f_{t-1}(x_i) + \alpha h_t(x_i))$$

- use univariate optimizer to find

minimum on $\alpha \in [0, A]$

\hookrightarrow Newton Raphson on $\phi'(\alpha) = 0$

$$- \text{iterate } \alpha_{h+1} = \alpha_h - \frac{\phi'(\alpha_h)}{\phi''(\alpha_h)}$$