Recorded at time: 1742890789.1732132 world Broadcaster: /px100/robot state publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 px100/base link Broadcaster: /px100/robot state publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1742890789.137 Oldest transform: 1742890784.237 px100/shoulder link Broadcaster: /px100/robot state publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1742890789.137 Oldest transform: 1742890784.237 px100/upper_arm_link Broadcaster: /px100/robot state publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1742890789.137 Oldest transform: 1742890784.237 px100/forearm link Broadcaster: /px100/robot state publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1742890789.137 Oldest transform: 1742890784.237 px100/gripper_link Broadcaster: /px100/robot state publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 px100/ee arm link Broadcaster: /px100/robot_state_publisher Broadcaster: /px100/robot state publisher Average rate: 10000.0 Average rate: 10.204 Buffer length: 4.9 Buffer length: 0.0 Most recent transform: 1742890789.137 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 1742890784.237 px100/gripper_bar_link px100/gripper prop link Broadcaster: /px100/robot_state_publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 px100/fingers_link Broadcaster: /px100/robot state publisher Broadcaster: /px100/robot state publisher Broadcaster: /px100/robot state publisher Average rate: 10000.0 Average rate: 10.204 Average rate: 10.204 Buffer length: 0.0 Buffer length: 4.9 Buffer length: 4.9 Most recent transform: 1742890789.137 Most recent transform: 0.0 Most recent transform: 1742890789.137 Oldest transform: 0.0 Oldest transform: 1742890784.237 Oldest transform: 1742890784.237 px100/ee gripper link px100/left finger link px100/right finger link

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