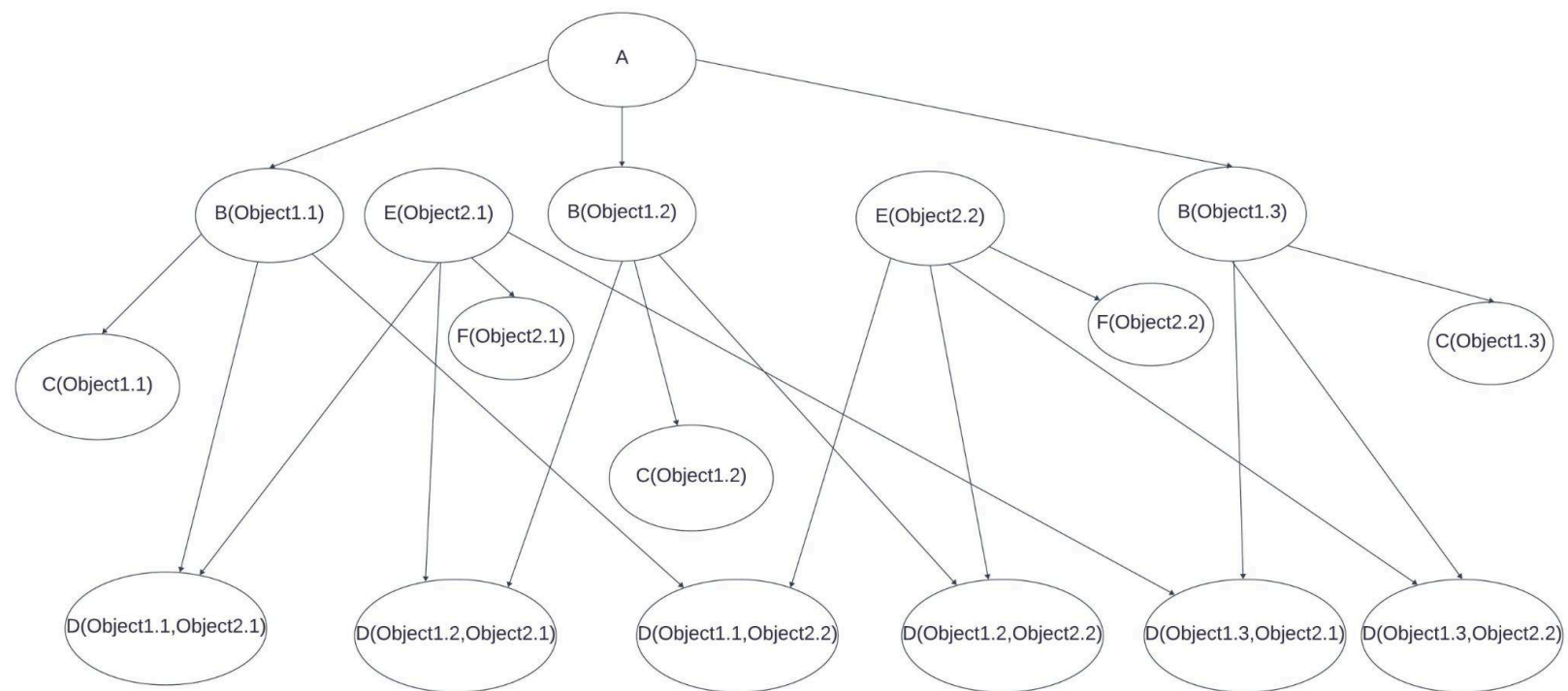


### Problem 1-

Probability distribution -  

$$P(A) \prod_{i=1}^n P(B_i/A) P(C_i/B_i) \prod_{j=1}^m P(E_j) P(F_j/E_j) P(D_{ij}/B_i, E_j)$$
  
 here  $\pi$  is product of probability



### Problem 2.

$$(a) P(C) = \sum P(A) \cdot \sum P(B|A) \cdot P(C|B)$$

Case 1

$$P(C=T) = P(A=T) \cdot [P(B=T|A=T) \cdot P(C=T|B=T)]$$

$$\begin{aligned}
& + P(B=F | A=T).P(C=T | B=F) ] \\
& + P(A=F).[ P(B=T | A=F).P(C=T | B=T) \\
& + P(B=F | A=F).P(C=T | B=F) \\
& ] = 0.4[0.3 \cdot 0.9 + 0.7 \cdot 0.4] + 0.6[0.8 \cdot 0.9 + 0.2 \cdot 0.4] \\
& = 0.4[0.27 + 0.28] + 0.6[0.72 + 0.08] \\
& = 0.4 \cdot 0.55 + 0.6 \cdot 0.8 \\
& = 0.22 + 0.48 \Rightarrow P(C=T) = 0.7 \\
& \text{And } P(C=F) = 1 - P(C=T) = 1 - 0.7 = 0.3
\end{aligned}$$

$$(b) P(C | A=T) = \sum P(B | A=T).P(C | B)$$

For C=T

$$\begin{aligned}
P(C=T | A=T) &= P(B=T | A=T)P(C=T | B=T) + P(B=F | A=T)P(C=T | B=F) \\
&= 0.3 \cdot 0.9 + 0.7 \cdot 0.4 = 0.55
\end{aligned}$$

$$\text{For } C=F: P(C=F | A=T) = 1 - 0.55 = 0.45$$

$$(C) P(C=T | A=T, B=T) = P(C=T | B=T) = 0.9$$

$$P(C=F | A=T, B=T) = 1 - P(C=T | B=T) = 0.1$$

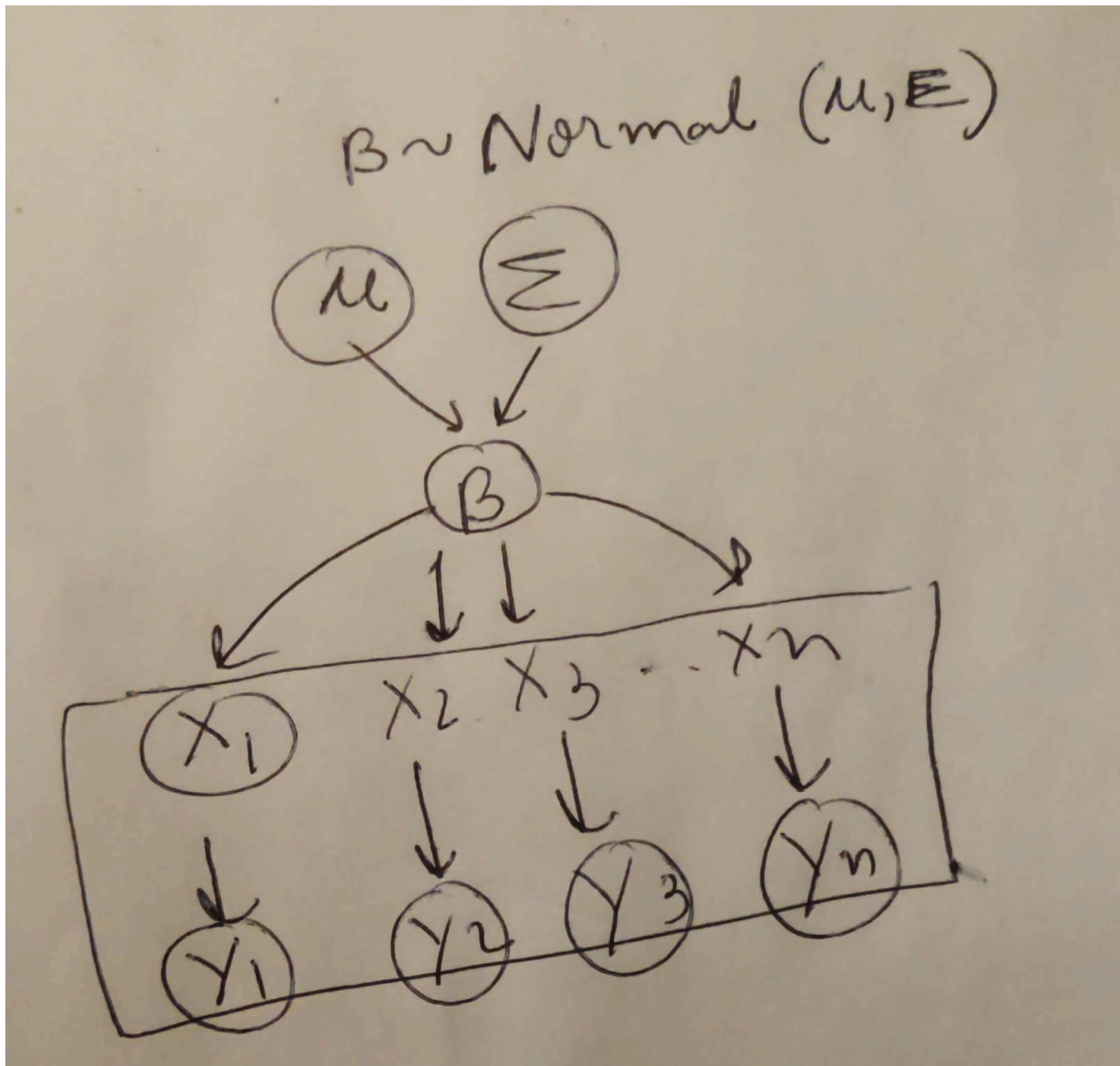
### Problem 3

The plate notation for Bayesian Logistic Regression can be represented as follows:

$$Y_1 \sim \text{Bernoulli}(\text{invLogit}(X_1\beta)) \quad Y_2 \sim \text{Bernoulli}(\text{invLogit}(X_2\beta)) \quad \dots \quad Y_N \sim \text{Bernoulli}(\text{invLogit}(X_N\beta))$$

$$\beta \sim \text{Normal}(\mu, \Sigma).$$

Each box represents a set of variables or data points. The X boxes represent the input vectors. The Y boxes represent the binary outcomes. The arrows from X to Y indicate that each outcome  $Y_n$  depends on its corresponding input vector  $X_n$  through the parameter vector  $\beta$ . The prior distribution of the parameter vector  $\beta$  is represented outside the boxes. In this case, it follows a normal distribution with mean  $\mu$  and covariance matrix  $\Sigma$ .



Problem 4-

Variable	All Factors	Participates	New Factor After *	New Factor After +
A	$P(A), P(B A), P(D), P(C B, D), P(E C)$	$P(A), P(B A)$	$f_1(A, B)$	$t_1(B)$
B	$t_1(B), P(D), P(C B, D), P(E C)$	$t_1(B), P(C B, D)$	$f_2(B, C, D)$	$t_2(C, D)$
D	$P(D), P(E C), t_2(C, D)$	$P(D), t_2(C, D)$	$f_3(C, D)$	$t_3(C)$
C	$P(E C), t_3(C)$	$P(E C), t_3(C)$	$f_4(E, C)$	$t_4(E)$
Normalize	$t_4(E)$			