# Video Stabilization using Warping

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#### **Problem Statement**

- Write the code for the recursive Gauss-Newton process yourself.
- Implemente video stabilization using above.

## **Implementation**

- 1. For image warping, work of Lucas-Kanade 20 Years On: A Unifying Framework by Simon Baker and Iain Matthews was referred. Inverse Compositional Image Alignment was implemented.
- 2. For *video stabilization*, we first ask user for a bounding box/object that would be stabilised. Then all subsequent frames are *warped* to a reference frame(it was the *first frame* in our case).

### Tips and Trick

Since the above was implemented in OpenCV using python, following are some tips and tricks for getting Gauss Newton to converge in the aforementioned language.

- 1. Use the *Inverse Compositional Image Alignment Algorithm* as mentioned above. Simple algorithm mentioned in section 2.2 of paper fails to converge.
- 2. Remove the *inverse* in the last step of iterative pseudo code.

- 3. Compute *Hessian Inverse* in pre-computation part for speedy iteration.
- 4. Avoid *for-loops* and compute all operations using in-built numpy functions for performance(Check reference code).
- 5. For video-stabilization, keep an *iteration limit* apart from  $\epsilon$ , so that some frames that does warp(converge) gets handled.

## Assumption

- 1. The stabilizer corrects motion upto a certain waver.
- 2. The object being stabilized does not move out of scene in subsequent frames.
- 3. Inverse of Hessian exists.
- 4. The transformation is affine.

#### Results

Epsilon	Iterations
0.05	1
0.01	290
0.005	297
0.001	315
0.0005	581

- Increasing  $\epsilon$  above a certain value, or decreasing below a threshold is futile. 0.005 appeared optimal.
- Larger resolution Images take *longer time* to converge.
- Sample warped Images and Videos are shown in respective directories.
- The book video has moderate shiver and algorithm successfully tackles it.

 $\bullet$  The kitty video has large camera motions and algorithms produces and  $unstable\ output.$ 

# References

- 1. Paper mentioned in implementation bullet 1.
- 2. Video and Picture Credits: Suyash Agarwal, Saket Dingliwal