

# MATLAB Tutorial 07

**ENME 303 Computational Methods for Engineers**

**Parham Oveissi**

# Useful Functions

- $d = \det(A)$ 
  - Returns the determinant of square matrix A.
- $Y = \text{inv}(X)$ 
  - Computes the inverse of square matrix X.
  - $X^{-1}$  is equivalent to  $\text{inv}(X)$ .
  - $x = A \backslash b$  is computed differently than  $x = \text{inv}(A) * b$  and is recommended for solving systems of linear equations.
- $k = \text{rank}(A)$ 
  - Returns the rank of matrix A. The rank of a matrix is equal to the number of linearly independent rows/columns in it.
- $R = \text{rref}(A)$ 
  - Returns the reduced row echelon form of A using Gauss-Jordan elimination
- $b = \text{trace}(A)$ 
  - Calculates the sum of the diagonal elements of matrix A.

# Useful Functions

- $n = \text{norm}(v)$ 
  - Returns the Euclidean norm of vector  $v$ . This norm is also called the 2-norm, vector magnitude, or Euclidean length.
- $n = \text{norm}(v, p)$ 
  - Returns the generalized vector  $p$ -norm.
- $[V, D] = \text{eig}(A)$ 
  - Returns diagonal matrix  $D$  of eigenvalues and matrix  $V$  whose columns are the corresponding right eigenvectors, so that  $A \cdot V = V \cdot D$ .
- $tf = \text{issymmetric}(A)$ 
  - Returns logical 1 (true) if  $A$  is a symmetric matrix. Otherwise, it returns logical 0 (false).
  - $tf = \text{issymmetric}(A, \text{skewOption})$  specifies the type of the test. Specify `skewOption` as "skew" to determine if  $A$  is skew-symmetric.
- $B = \text{transpose}(A)$ 
  - Returns the nonconjugate transpose of  $A$  and is an alternate way to execute  $A.'$ .

# Example 1

- Consider Matrix  $A$ :

$$A = \begin{bmatrix} 1 & 2 & -2 \\ 2 & 3 & 1 \\ 3 & 0 & -1 \end{bmatrix}$$

- Find the transpose?
- Is this matrix symmetric?
- Find the determinant?
- Is this Matrix invertible (non-singular?)
- If it is invertible find the inverse?
- Find the Reduced Row Echelon form?
- What is the rank?
- Is this matrix full rank?

## Example 2

- Consider Matrix *Sandwich*\*:

$$\textit{Sandwich} = \begin{bmatrix} 9 & 5 & 24 \\ 7 & 8 & 31 \\ 9 & 4 & 21 \end{bmatrix}$$

- Find the transpose?
- Is this matrix symmetric?
- Find the determinant?
- Is this Matrix invertible (non-singular?)
- If it is invertible find the inverse?
- Find the Reduced Row Echelon form?
- What is the rank?
- Is this matrix full rank?

\* Chosen by Ethan (comments on matrix nomenclature: [ethbow1@umbc.edu](mailto:ethbow1@umbc.edu))

# Create Symbolic Variables Using “sym” Function

- Create Symbolic variables:

```
x = sym('x')
```

---

x = x

- Create Symbolic Vectors:

```
a = sym('a',[1 4])
```

---

a =

[a1, a2, a3, a4]

- Create Symbolic Matrices:

```
A = sym('A',[3 4])
```

---

A =

[A1\_1, A1\_2, A1\_3, A1\_4]  
[A2\_1, A2\_2, A2\_3, A2\_4]  
[A3\_1, A3\_2, A3\_3, A3\_4]

- Create Symbolic Numbers:

```
accurate1 = 1/sym(1234567)
```

---

accurate1 =

$$\frac{1}{1234567}$$

# Create Symbolic Variables Using “syms” Function

- Create Symbolic variables:

```
syms x y
x
x = x
y
y = y
```

- Create Symbolic Vectors:

```
>> syms a b [1 4]
>> a
a =
[a1, a2, a3, a4]
>> b
b =
[b1, b2, b3, b4]
```

- Create Symbolic Matrices:

```
>> syms A B [3 4]
>> A
A =
[A1_1, A1_2, A1_3, A1_4]
[A2_1, A2_2, A2_3, A2_4]
[A3_1, A3_2, A3_3, A3_4]
>> B
B =
[B1_1, B1_2, B1_3, B1_4]
[B2_1, B2_2, B2_3, B2_4]
[B3_1, B3_2, B3_3, B3_4]
```

- Create Symbolic Expressions:

```
>> syms a b c x
>> f = a*x^2 + b*x + c
f =
a*x^2 + b*x + c
```

# Create and Evaluate Symbolic Functions

```
1  clc; clear
2
3  syms f(x,y) g(z)
4
5
6  f(x,y) = x/y;
7  f(1,5)
8
9  g(z) = z^2 + 2*z + 5;
10 g(2)
11
12
```

Command Window

```
ans =
1/5
ans =
13
```

```
1  clc; clear
2
3  syms x y z
4
5
6  f(x,y) = x/y;
7  f(1,5)
8
9  g(z) = z^2 + 2*z + 5;
10 g(2)
11
12
```

Command Window

```
ans =
1/5
ans =
13
```



# Useful Functions for Symbolic Expressions

- **expand**

- Expand expressions

```
1  clc; clear
2  syms x a
3
4  f = (x-a)^3;
5  expand(f)
```

Command Window

```
ans =
- a^3 + 3*a^2*x - 3*a*x^2 + x^3
```

- **factor**

- changes an expression that is a polynomial to a product of polynomials of a lower degree.

```
7  f2 = x^3 + 4*x^2 - 11*x - 30;
8  factor(f2)
9
```

Command Window

```
ans =
[x + 5, x - 3, x + 2]
```

- **simplify**

- Algebraic simplification

```
10 f3 = -2*tan(x)/(tan(x)^2 - 1);
11 simplify(f3)
12
```

Command Window

```
ans =
tan(2*x)
```

- **collect**

- collects the terms in the expression that have the variable with the same power.

```
13 f4 = (x + x^2)*(x^3 + 1)*x;
14 collect(f4)
15
```

Command Window

```
ans =
x^6 + x^5 + x^3 + x^2
```

# “subs” and “double” Functions

- **subs:**

- `snew = subs(s,old,new)` returns a copy of `s`, replacing all occurrences of `old` with `new`, and then evaluates `s`.

```

1  clc; clear
2
3  syms x y
4
5  f1 = (x + x^2)*(x^3 + 1)*x;
6  subs(f1,x,2)
7
8  f2 = x/y;
9  subs(f2,[x,y],[1,5])

```

Command Window

```

ans =

108

ans =

1/5

```

- **double:**

- `d = double(s)` converts the symbolic values `s` to double precision.

```

1  clc; clear
2
3  syms x y
4
5  f1 = (x + x/4)*(x^3 + 1)*x/4 + sin(x);
6  f1_assigned = subs(f1,x,pi/2);
7  f1_double = double(f1_assigned)
8
9  f2 = x/y;
10 f2_assigned = subs(f2,[x,y],[1,5]);
11 f2_double = double(f2_assigned)

```

Command Window

```

f1_double =

4.7595

f2_double =

0.2000

```

# Solving Equations and System of Equations

```
1  clc; clear
2
3  syms a b c x
4  eqn = a*x^2 + b*x + c == 0;
5  S = solve(eqn)
```

Command Window

S =

```
-(b + (b^2 - 4*a*c)^(1/2))/(2*a)
-(b - (b^2 - 4*a*c)^(1/2))/(2*a)
```

```
1  clc; clear
2  syms u v
3
4  eqns = [2*u + v == 0, u - v == 1];
5  S = solve(eqns,[u v])
```

Command Window

S =

struct with fields:

```
u: 1/3
v: -2/3
```

# Differentiation and Integration

```
1  clc; clear
2
3  syms x
4  expr1 = -2*x/(1+x^2)^2;
5
6  F1 = int(expr1)
7
8  expr2 = x*log(1+x);
9  F2 = int(expr2,[0 1])
```

Command Window

F1 =

$1/(x^2 + 1)$

F2 =

$1/4$

```
1  clc; clear
2
3  syms x t
4
5  expr1 = (1-4*x)^3;
6  diff(expr1)
7  diff(expr1,2)
8
9  expr2 = (sin(t)-4*x)^3;
10 diff(expr2,t)
```

Command Window

ans =

$-12*(4*x - 1)^2$

ans =

$96 - 384*x$

ans =

$3*\cos(t)*(4*x - \sin(t))^2$

Thanks!