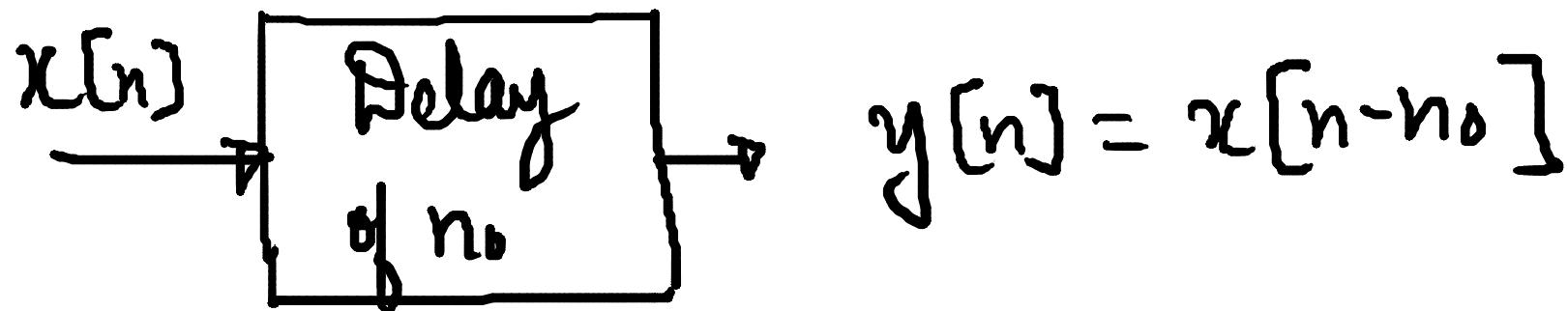


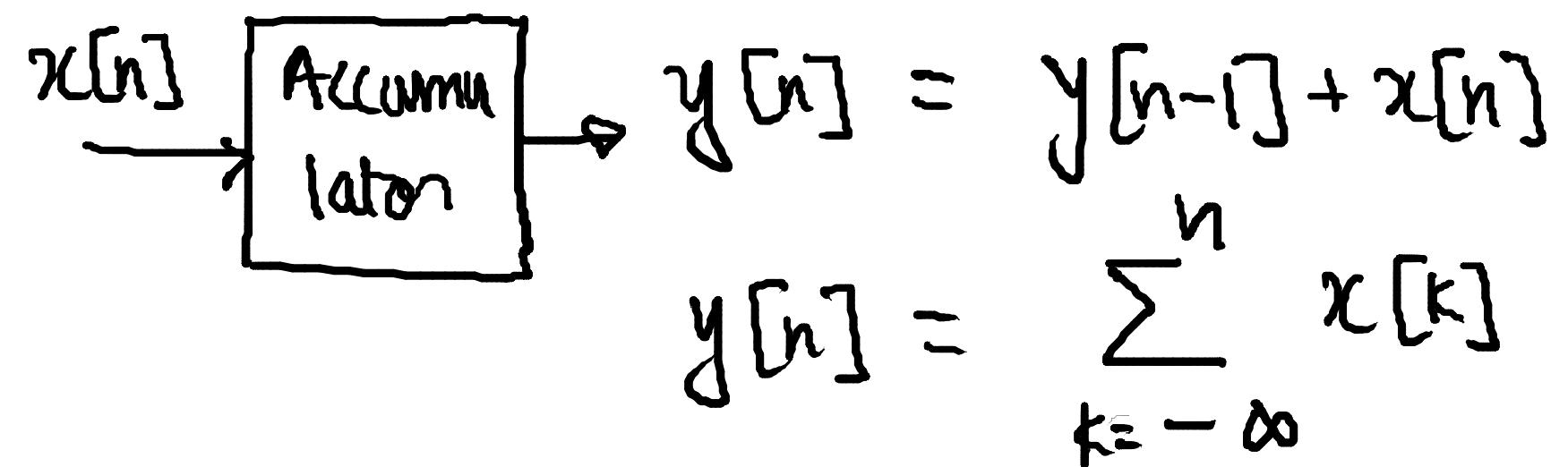
e.g

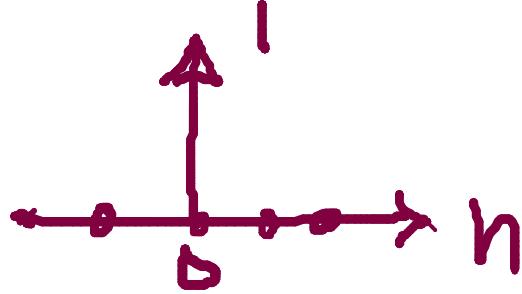


$$x[n] = \delta[n] \rightarrow y[n] = \delta[n-n_0]$$

e.g

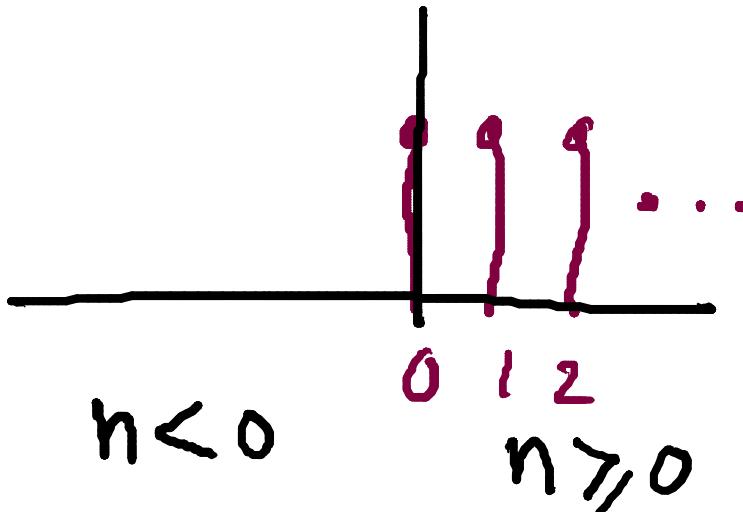
Accumulator





$$\delta[n] \rightarrow h[n] = \sum_{k=-\infty}^n \delta[k]$$

$$h[n] = u[n]$$



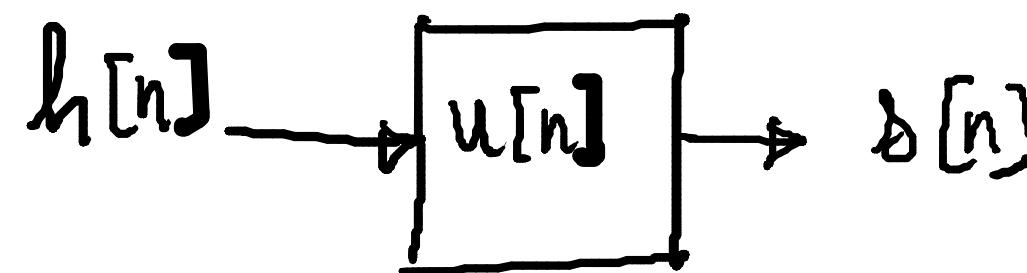
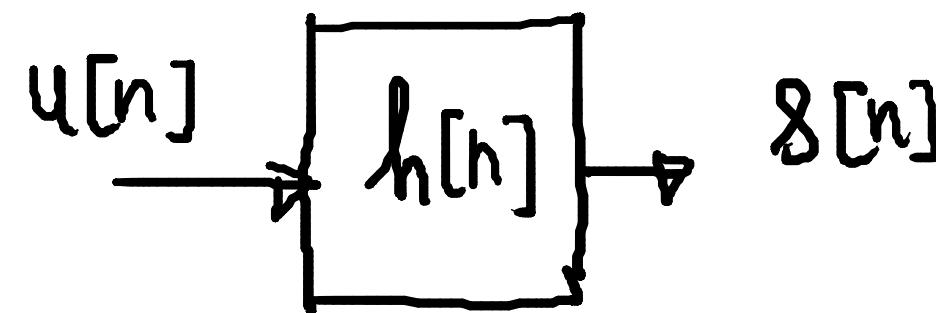
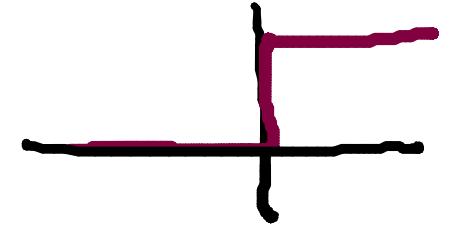
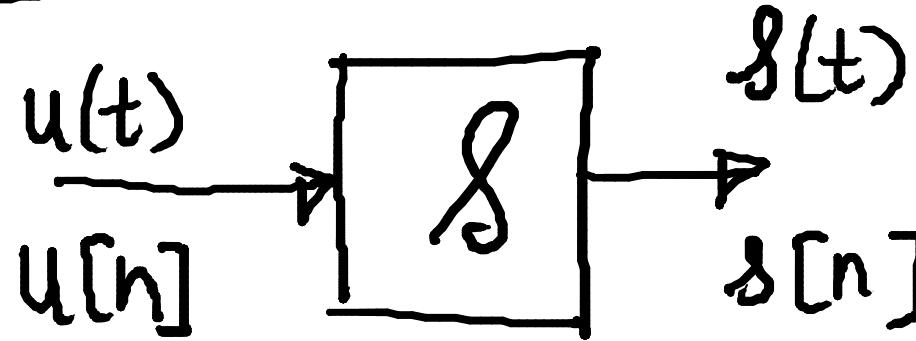
$$y[n] = y[n-1] + x[n]$$

$$y[n] - y[n-1] = x[n]$$

$$x[n] \quad 1, 2, 3 \\ \uparrow$$

$$y[n] \quad 1, 3, 6 \dots$$

Step Response :

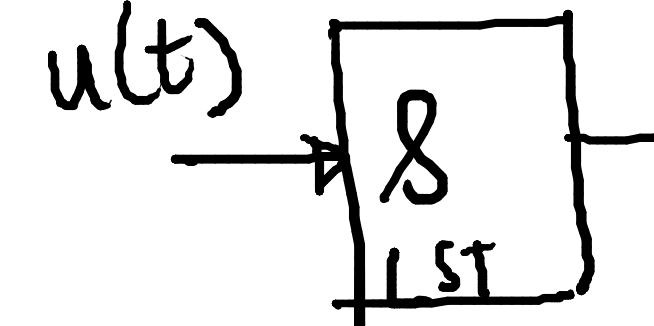


$$\delta[n] = h[n] * u[n]$$

$$\delta[n] = \sum_{k=-\infty}^n h[k]$$

Step response

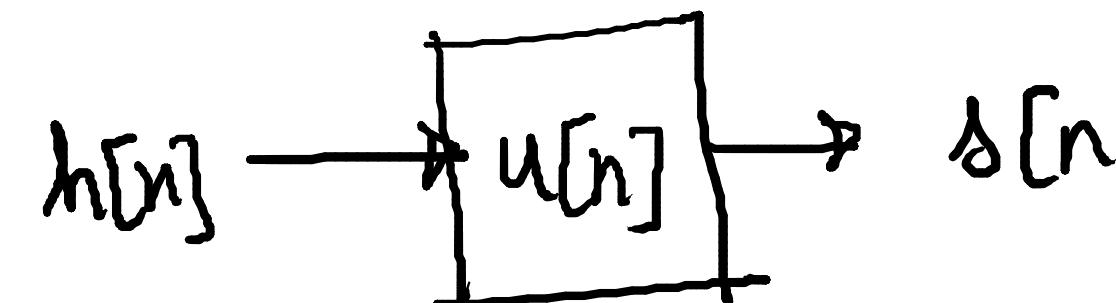
x
y
1, 2, 3, 4, ...
 ① 3, 6, 10, ...
 1, 2, 3, 4, ...



$$s(t) = u(t) * h(t)$$

$$s[n] = u[n] * h[n]$$

$$= h[n] * u[n]$$



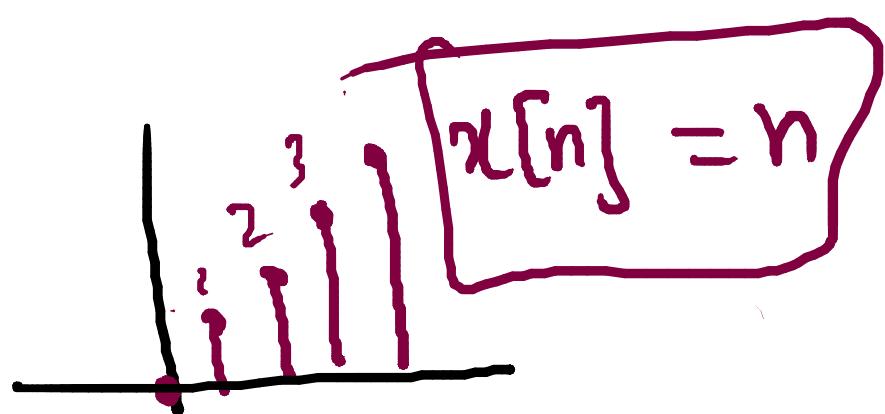
Step response is
running sum / result of accumulation

of impulse response

$$s[n] = \sum_{k=-\infty}^n h[k]$$

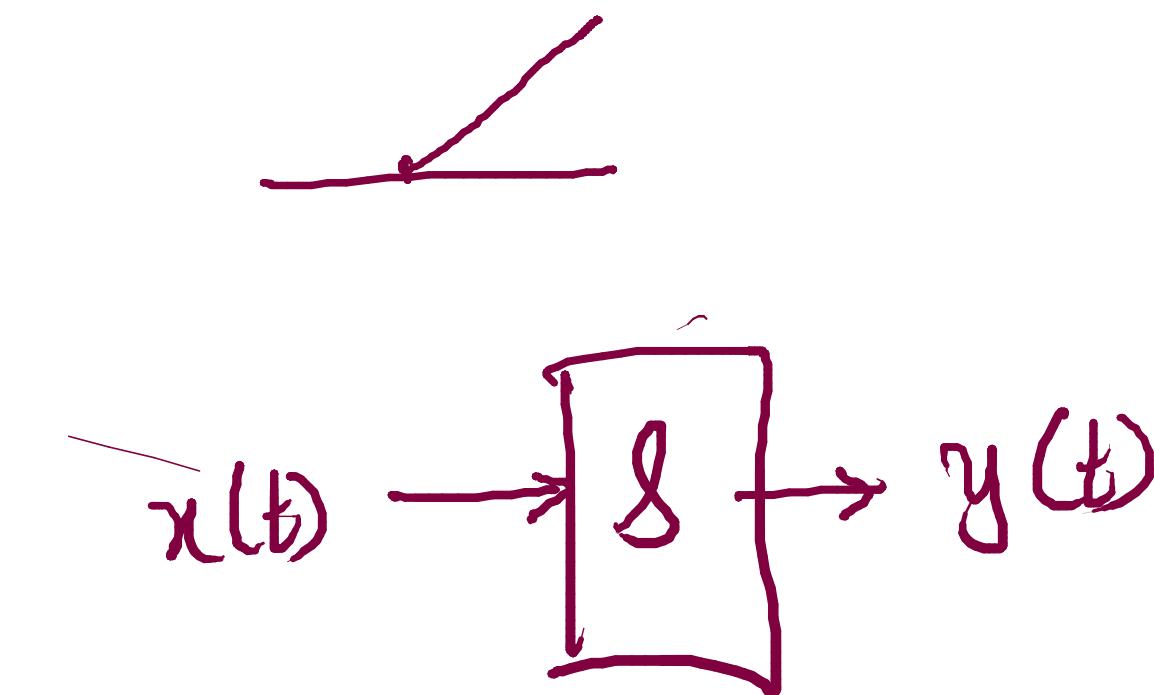
$$h[n] = s[n] - s[n-1]$$

Impulse response can be obtained from step response
by simply taking first difference of step response



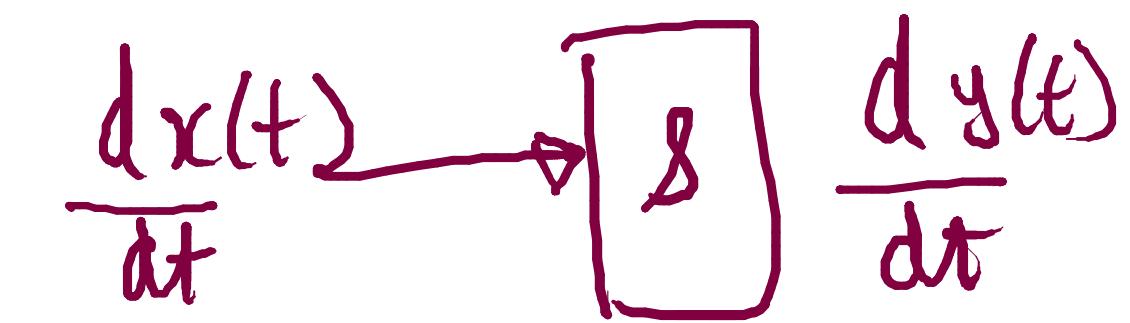
$x[n]$	1	2	3	4
$u[n]$	1	1	1	1
$\delta[n]$	1	0	0	0

n



$$\frac{dx(t)}{dt} = \lim_{t_0 \rightarrow 0} \frac{x(t) - x(t-t_0)}{t_0}$$

$$= \lim_{t_0 \rightarrow 0} \frac{x(t) - x(t+t_0)}{t_0}$$



$$y[n] = x[n] + x[n-1]$$

$$y[n] = x[n] + x[n+1]$$

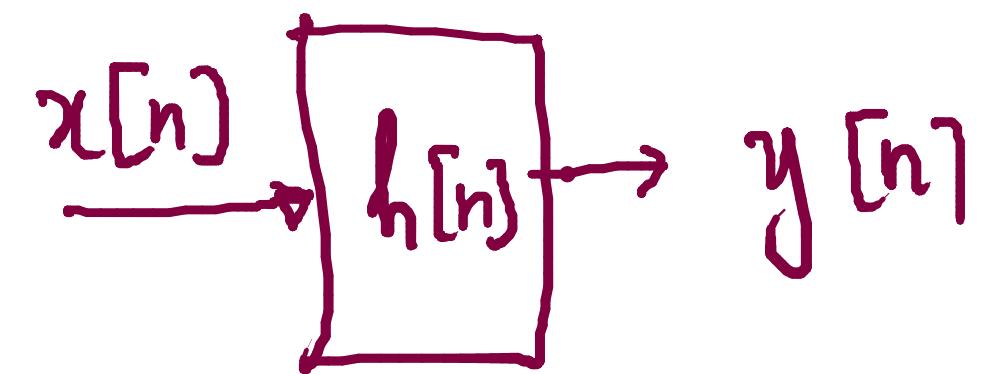
e.g

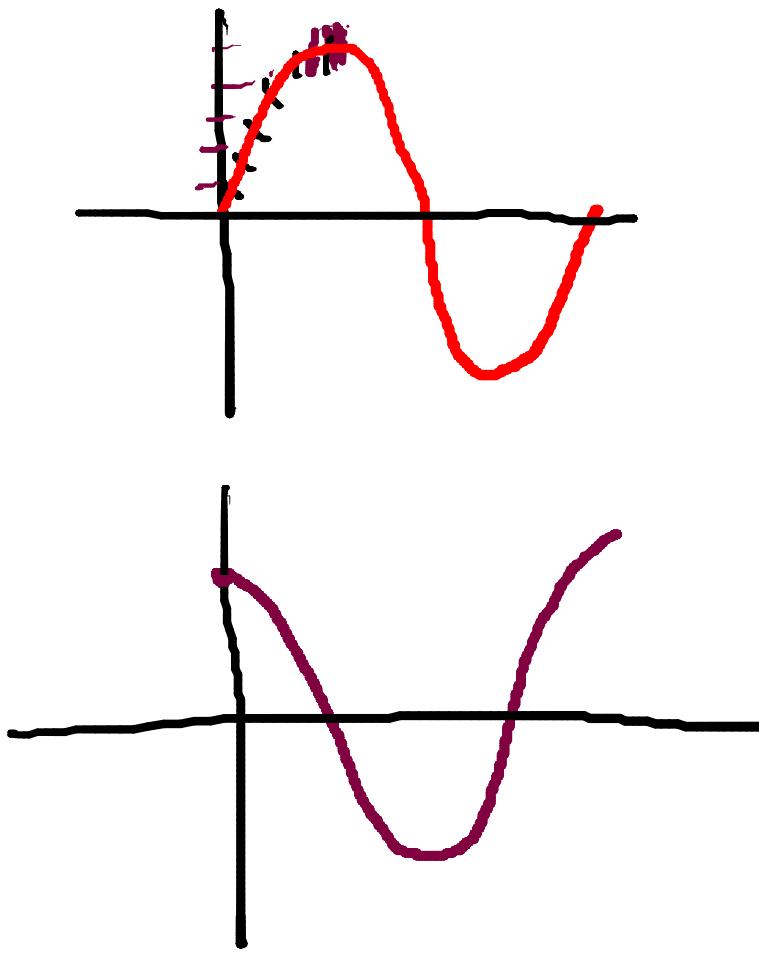
$$s(t) = 8 \sin(2t)$$

$$\delta(t) = 2 \cos(2t)$$

2, 4, 6, 8,
|
|

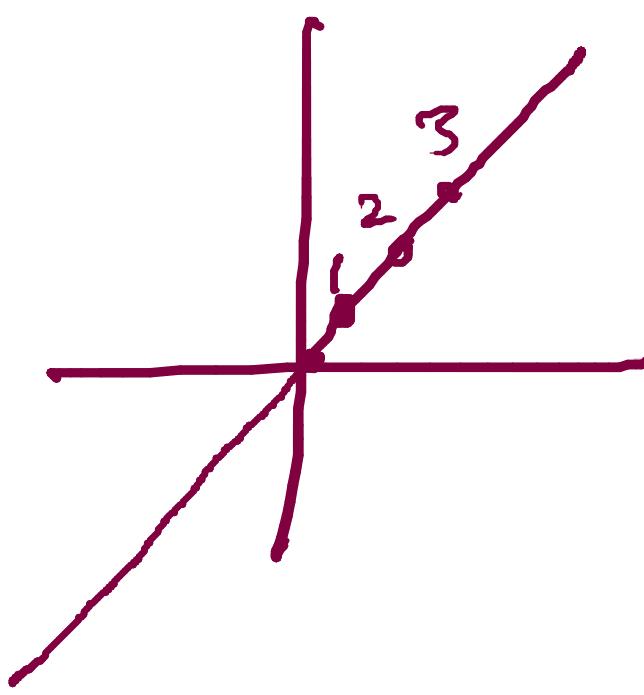
$$h(t) = \frac{d s(t)}{dt}$$
$$s(t) = \int_{-\infty}^t h(\tau) d\tau$$





$$t$$
$$2t$$
$$2x$$

$$x(t) = t$$

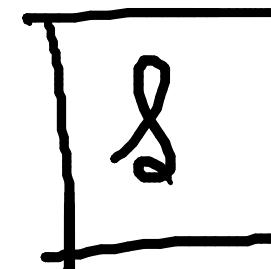


Stability of LSI System

$$x[n]$$

[] [] []

$$h[n] = \{1, 2, 3\}$$



$$h[n] = u[n]$$

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k] = \sum_{k=-\infty}^{\infty} h[k] x[n-k]$$

$$0 < |x[n]| < \infty$$

$$|x[n]| < B$$

$$\begin{aligned}
 |y[n]| &= \left| \sum_{k=-\infty}^{\infty} h[k] x[n-k] \right| \leq \sum_{k=-\infty}^{\infty} |h[k]| |x[n-k]| \\
 &= \sum_{k=-\infty}^{\infty} |h[k]| |x[n-k]| \leq \sum_{k=-\infty}^{\infty} |h[k]| B
 \end{aligned}$$

$|y[n]| \leq B \sum_{k=-\infty}^{\infty} |h[k]|$