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## 4. Estimation Validation and Forecasting

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- Calculation of  $\pi$ -weights and  $\psi$ -weights
- Estimation of parameters
- Forecasting with ARIMA models

**AR and MA polynomials** are defined as:

$$\phi(z) = 1 - \phi_1 z - \cdots - \phi_p z^p, \phi_p \neq 0$$

and

$$\theta(z) = 1 + \theta_1 z - \cdots + \theta_q z^q, \theta_q \neq 0$$

Respectively, where  $z$  is a complex number

An **ARMA(p,q)** model is said to be **causal** if the time series  $\{x_t; t = 0, 1, \dots\}$  can be written as a one-sided linear process:

$$x_t = \sum_{j=0}^{\infty} \psi_j z_{t-j} = \psi(B)z_t$$

Where  $\psi(B) = \sum_{j=0}^{\infty} \psi_j B^j$  and  $\sum_{j=0}^{\infty} |\psi_j| < \infty$ , with  $\psi_0 = 1$

**ARMA(p,q)** model is said to be **invertible** if the time series  $\{x_t; t = 0, 1, \dots\}$  can be written as

$$\pi(B)x_t = \sum_{j=0}^{\infty} \pi_j x_{t-j} = z_t$$

Where,

$\pi(B) = \sum_{j=0}^{\infty} \pi_j B^j$  and  $\sum_{j=0}^{\infty} |\pi_j| < \infty$ , assuming  $\pi_0 = 1$

## AR(2) with Complex Roots example

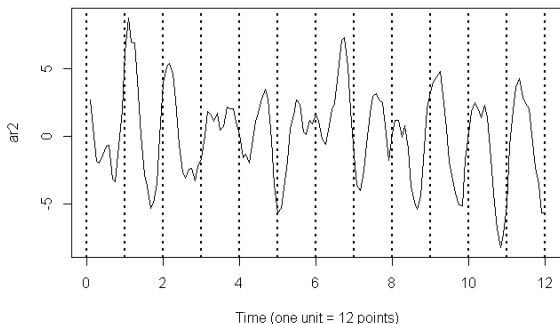
Model:  $x_t = 1.5x_{t-1} - 0.75x_{t-2} + z_t$  with  $\sigma_z^2 = 1$

The **autoregressive polynomial** for this model is:

$$\phi(z) = 1 - 1.5z + 0.75z^2$$

The **roots** of  $\phi(z)$  are  $1 \pm i/\sqrt{3}$  and  $\theta = \tan^{-1}(\frac{1}{\sqrt{3}}) = 2\pi/12$  radians per unit time

**Simulated AR(2) model**,  $n=144$  with  $\phi_1 = 1.5$  and  $\phi_2 = -0.75$ .



```
set.seed(90210)
ar2 = arima.sim(list(order=c(2,0,0), ar=c(1.5,-.75)), n = 144)
plot(1:144/12, ar2, type="l", xlab="Time (one unit = 12 points)")
abline(v=0:12, lty="dotted", lwd=2)
```

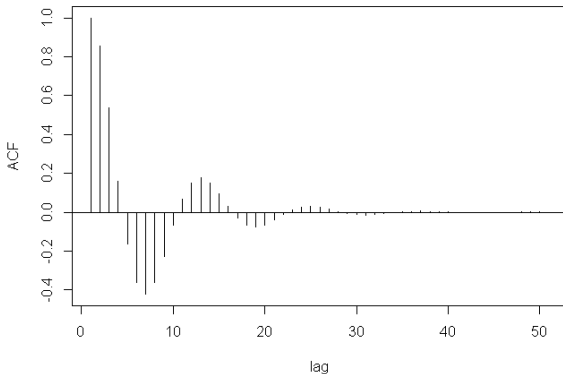
To **calculate the roots of the polynomial and solve** for arg in R:

```
# coefficients of the polynomial
z = c(1,-1.5,0.75)
# print one root:  $1+0.57735i = 1 + i/\sqrt{3}$ 
(a = polyroot(z)[1])
# arg in cycles/pt
arg = Arg(a)/(2*pi)
# = 12, the pseudo period
1/arg
```

## AR(2) model (4/4)

To **calculate** and display the **ACF** for this model:

```
ACF = ARMAacf(ar=c(1.5,-.75), ma=0, 50)  
plot(ACF, type="h", xlab="lag")  
abline(h=0)
```





**ARMA(p,q)** model:  $\psi(B)x_t = \theta(B)w_t$

Any ARMA model can be converted to an **infinite order MA model**:

$$\psi\text{-weights} = \frac{\theta(B)w_t}{\psi(B)}$$

To solve for the  $\psi$ -**weights** in general, we must match the coefficients in  $\phi(z)\psi(z) = \theta(z)$

$$(1 - \phi_1 z - \phi_2 z^2 - \dots)(\psi_0 + \psi_1 z + \psi_2 z^2 + \dots) = (1 + \theta_1 z + \theta_2 z^2 + \dots)$$

The **first few values** are:

$$\psi_0 = 1$$

$$\psi_1 - \phi_1\psi_0 = \theta_1$$

$$\psi_2 - \phi_1\psi_1 - \phi_2\psi_0 = \theta_2$$

$$\psi_3 - \phi_1\psi_2 - \phi_2\psi_1 - \phi_3\psi_0 = \theta_3$$

The  $\psi$ -weights **satisfy the homogeneous difference equation** given by

$$\psi_j - \sum_{k=1}^p \phi_k \psi_{j-k} = 0, j \geq \max(p, q + 1)$$

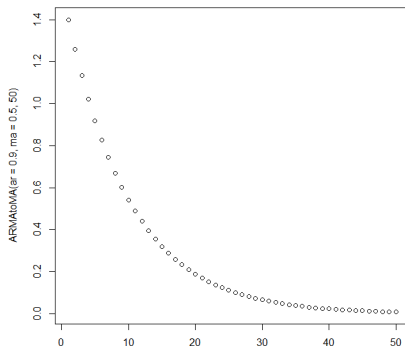
## $\psi$ -weights for an ARMA model (3/3)

To solve for the  $\psi$ -weights **in general**, we must match the coefficients in  $\Phi(z)\Psi(z) = \theta(z)$

First 50  $\psi$ -weights **with R**:

```
ARMAtoMA(ar=.9,ma=.5, 50)
```

```
plot(ARMAtoMA(ar=.9,ma=.5, 50))
```



Let  $X = \{x_t\}_{t=0}^N$  a time series with conditional gaussian distribution

Likelihood of the model:

$$L(\phi, \theta, \sigma_z^2; X) = f_1(x_1) \sum_{i=2}^N f(x_i | x_{i-1}, \dots, x_1)$$

For example, for an AR(1) model:

$$x_i = \phi x_{i-1} + z_t \quad z_t \sim N(0, \sigma_z^2)$$

$$E(x_i | x_{i-1}, \dots, x_1) = \phi x_{i-1}$$

$$V(x_i | x_{i-1}, \dots, x_1) = \sigma_z^2$$

$$L(\phi, \sigma_z^2; X) = f_1(x_1) \sum_{i=2}^N f\left(\frac{x_i - \phi x_{i-1}}{\sigma_z^2}\right)$$

## Maximum likelihood estimation

$$(\hat{\phi}, \hat{\theta}, \hat{\sigma}_z^2) = \operatorname{argmax} L(\phi, \theta, \sigma_z^2; X)$$

Maximum likelihood estimators are **consistent** and **asymptotically efficient and gaussian**

$$\hat{\Theta}_{ML} \approx N(\Theta, I_{\Theta}^{-1})$$

where  $I_{\Theta} = E\left(-\frac{\partial^2 \log L(\Theta; X)}{\partial \Theta^2}\right)$

Given data  $x_1, \dots, x_n$  for forecasting purpose, write the model as

$$x_{n+1} = \phi x_n + z_{n+1} + \theta z_n \quad (1)$$

- **One-step-ahead truncated forecast**

$$\tilde{x}_{n+1}^n = \phi x_n + 0 + \theta \tilde{z}_{n+m-1}^n \quad (2)$$

- **Errors forward in time**

$$\tilde{w}_t^n = x_t - \phi x_{t-1} + \theta \tilde{z}_{t-1}^n, \quad t = 1, \dots, n$$

- The approximate **forecast variance**

$$P_{n+m}^n = \sigma_z^2 \left[ 1 + (\phi + \theta)^2 \sum_{j=1}^{m-1} \phi^{2(j-1)} = \sigma_z^2 \left[ 1 + \frac{(\phi + \theta)^2 (1 - \phi^{2(m-1)})}{(1 - \phi^2)} \right] \right] \quad (3)$$

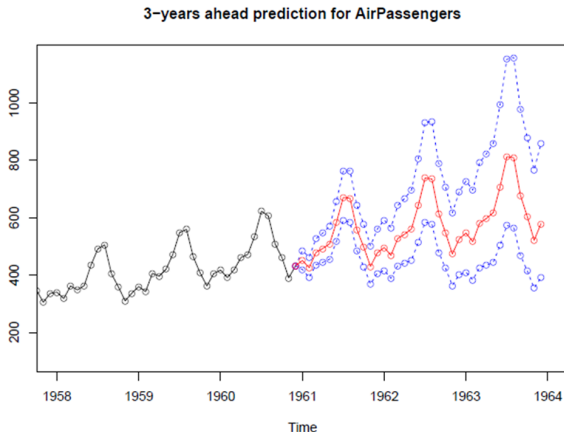
- $(1 - \alpha)$  **prediction interval**

$$x_{n+m}^n \pm c_{\alpha/2} \sqrt{P_{n+m}^n} \quad (4)$$

Where  $c_{\alpha/2}$  is chosen to get the desired degree of confidence.  
*i.e. if the process is Gaussian, choosing  $c_{\alpha/2}$  will yield an approximate 95% prediction interval for  $x_{n+m}$*

# Forecasting and Confidence Interval (1/5)

**ARIMA(0,1,1)(0,1,1)<sub>s</sub>**; period  $s = 12$ ;  $n.ahead = 36$





## Remember:

A times series  $\{x_t; t = 0, \pm 1, \pm 2, \dots\}$  is an **ARMA(p,q)** model if it is **stationary** and

$$x_t = \phi_1 x_{t-1} + \dots + \phi_p x_{t-p} + z_t + \theta_1 z_{t-1} + \dots + \theta_q z_{t-q} \quad (5)$$

with  $\phi_p \neq 0$ ;  $\theta_q \neq 0$  and  $\sigma_z^2 > 0$

**ARMA(p,q)** model can be written in concise form as

$$\Phi(B)x_t = \theta(B)z_t \quad (6)$$

## Objective:

To find the best forecast for  $x_{t+h}$  at time  $t$  using the **h-step-ahead minimum mean square error predictor**, denoted by  $\tilde{X}_{t+h|t}$

## Questions to help the construction process:

- Which is the **forecasting function**?  
i.e., Which are the **values** for  $\tilde{X}_{t+h|t}$  as a function of **h**?
- Which is the **memory of the model**? How are the forecast expressed as a (linear) **function of the previous** (known) observations?
- Which is the **forecasting confidence interval**?

## Three equivalent ARMA(p,q) equations:

- **Previous observations and random noises**

$$x_{t+h} =$$

$$\phi_1 x_{t+h-1} + \cdots + \phi_p x_{t+h-p} + z_{t+h} + \theta_1 z_{t+h-1} + \cdots + \theta_q z_{t+h-q}$$

- **AR process of infinite order**

$$x_{t+h} = -\pi_1 x_{t+h-1} - \pi_2 x_{t+h-2} - \cdots + z_{t+h}$$

- **MA process of infinite order**

$$x_{t+h} = z_{t+h} + \psi_1 z_{t+h-1} + \psi_2 z_{t+h-2} + \cdots$$

## 1-step-ahead-forecast

- **Previous observations and random noises**

$$x_{t+h} =$$

$$\phi_1 x_{t+h-1} + \dots + \phi_p x_t + h - p + z_{t+h} + \theta_1 z_{t+h-1} + \dots + \theta_q z_{t+h-q}$$

- **AR process of infinite order**

$$x_{t+h} = -\pi_1 x_{t+h-1} - \pi_2 x_{t+h-2} - \dots + z_{t+h}$$

- **MA process of infinite order**

$$x_{t+h} = z_{t+h} + \psi_1 z_{t+h-1} + \psi_2 z_{t+h-2} + \dots$$

## Given the model

$$X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + Z_t + \theta_1 Z_{t-1} + \theta_2 Z_{t-2} \quad (7)$$

Suppose that **values of past observations are known**, then

$$Z_t = X_t - \tilde{X}_{t|t-1}; \quad Z_{t-1} = X_{t-1} - \tilde{X}_{t-1|t-2}$$

Substituting

$$\tilde{X}_{t+1|t} = \phi_1 X_t + \phi_2 X_{t-1} + E(Z_{t+1}) + \theta_1 Z_t + \theta_2 Z_{t-1}$$

$$\tilde{X}_{t+2|t} = \phi_1 \tilde{X}_{t+1|t} + \phi_2 X_t + E(Z_{t+2}) + \theta_1 E(Z_{t+1}) + \theta_2 Z_t$$

$$\tilde{X}_{t+3|t} = \phi_1 \tilde{X}_{t+2|t} + \phi_2 \tilde{X}_{t+1|t} + E(Z_{t+3}) + \theta_1 E(Z_{t+2}) + \theta_2 Z_{t+1}$$

...

$$\tilde{X}_{t+h-3|t} = \phi_1 \tilde{X}_{t+h-1|t} + \phi_2 \tilde{X}_{t+h-2|t}, \quad h > 2$$

**In fact,**

Given a general **ARMA(p,q)** model, for  $h > q$ :

**H-step-ahead predictor** is determined by the difference equations for the autocorrelations (which only depend on the autocorrelation characteristic polynomial)

# Non Stationary ARIMA process Forecast. ARIMA(0,1,1)

(1/3)

**Model:**

$$X_t = X_{t-1} + Z_t + \theta Z_{t-1} \quad (8)$$

**also defined by**

$$(1 - B)X_t = (1 - \theta B)Z_t \quad (9)$$

$X_t$  can be expressed as

$$\pi(B) = \frac{1 - B}{1 + \theta B} = 1 - (\theta + 1)B + \theta(\theta + 1)B^2 - \theta^2(\theta + 1)B^3 + \dots \quad (10)$$

# Non Stationary ARIMA process Forecast. ARIMA(0,1,1) (2/3)

**Model:**

$$\tilde{X}_{t+1|t} = (\theta + 1)X_t - \theta(\theta + 1)X_{t-1} + \theta^2(\theta + 1)X_{t-2} - \dots \quad (11)$$

**moving  $\theta$**

$$\tilde{X}_{t+1|t} = (\theta + 1)X_t - \theta\tilde{X}_{t|t-1} \quad (12)$$

**Using the parameter  $\lambda = 1 + \theta$ .** Clearly  $\theta = \lambda - 1 = -(1 - \lambda)$

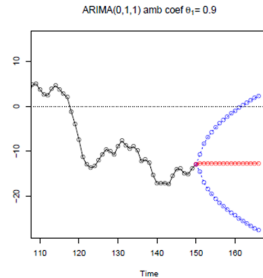
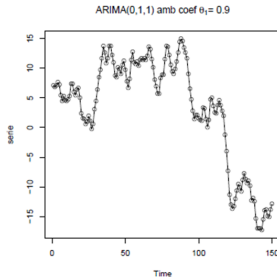
$$\tilde{X}_{t+1|t} = \lambda X_t - (1 - \lambda)\lambda X_{t-1} + (1 - \lambda)^2 \lambda X_{t-2} - \dots = \lambda X_t + (1 - \lambda)\tilde{X}_{t|t-1} \quad (13)$$



# Non Stationary ARIMA process Forecast. ARIMA(0,1,1)

## (3/3)

Hence, the **forecast is the a linear combination** of the last observation and the forecast obtained in the previous step.



## Variance of the 1-step-ahead forecasting error

$$\text{Var}(e_t(1)) = E(X_{t+1} - \tilde{X}_{t+1|t}) = E(Z_{t+1}) = \sigma_Z^2 \quad (14)$$

**H step forecast for h 2 is**

$$\text{Var}(e_t(h)) = \sigma_Z^2(1 + \psi_1^2 + \psi_2^2 + \cdots \psi_{h-1}^2) \quad (15)$$

# Seasonal Processes Forecasting. ARIMA(0,1,1)(0,1,1)<sub>12</sub> (1/4)

**Model:**

$$(1 - B)(1 - B^{12})X_t = (1 + \theta B)(1 + \theta_{12}B^{12})Z_t \quad (16)$$

**also defined by**

$$(X_t - X_{t-12}) - (X_{t-1} - X_{t-13}) = Z_t\theta_1 Z_{t-1} + \theta_1 2Z_{t-12} + \theta_1 \theta_{12} Z_{t-13} \quad (17)$$

**Hence,**

$$X_{t+1} = X_{t-11} + (X_t - X_{t-12} + Z_{t+1} + \theta_1 Z_{t-11} + \theta_1 \theta_{12} Z_{t-12}) \quad (18)$$

**The forecasting function:**

$$\tilde{X}_{t+1|t} = X_{t-11} + (X - X_{t-12}) + \theta_1 Z_t + \theta_1 \theta_{12} Z_{t-11} + \theta_1 \theta_{12} Z_{t-12}$$

$$\tilde{X}_{t+2|t} = X_{t-10} + (\tilde{X}_{t+1|t} - X_{t-11}) + \theta_{12} Z_{t-10} + \theta_1 \theta_{12} Z_{t-11}$$

...

$$\tilde{X}_{t+h|t} = X_{t+h-12} + (\tilde{X}_{t+h-1|t} - X_{t+h-13}) , h > 13$$

# Seasonal Processes Forecasting. ARIMA(0,1,1)(0,1,1)<sub>12</sub>

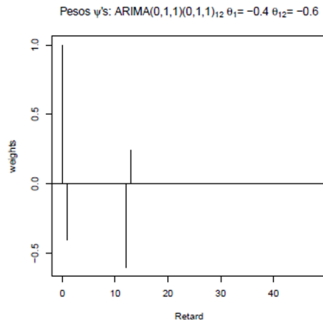
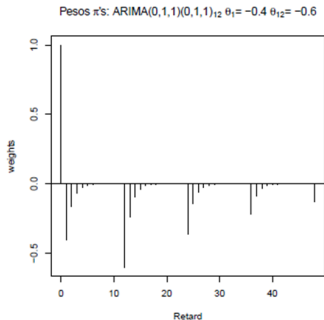
## (3/4)

$$\pi(B) = \pi_0 + \pi_1 B + \pi_2 B^2 + \dots = \frac{1-B}{1+\theta_1 B} \frac{1-B^{12}}{1+\theta_{12} B^{12}} \quad (19)$$

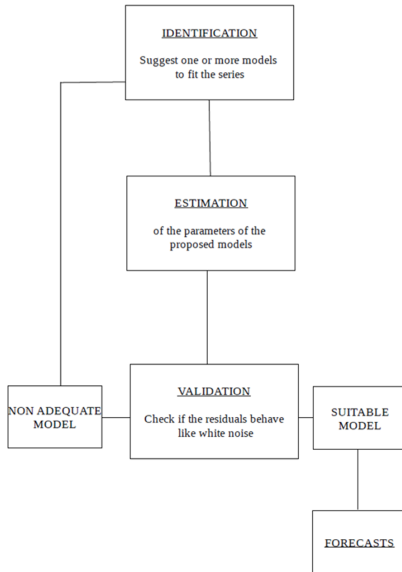
$$\pi_1(B) = \frac{1-B}{1+\theta_1 B} = 1 - (1-\theta_1) + \theta_1(1+\theta_1)B^2 - \theta_1^2(1+\theta_1)B^3 + \dots \quad (20)$$

# Seasonal Processes Forecasting. $ARIMA(0,1,1)(0,1,1)_{12}$

(4/4)



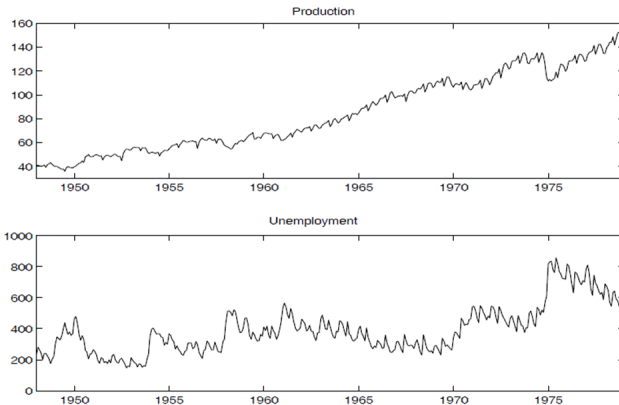
Weights  $Z$  and  $\Psi$  for the model  $ARIMA(0,1,1)(0,1,1)_{12}$  for the parameters above



- The Federal Reserve Board Production Index example

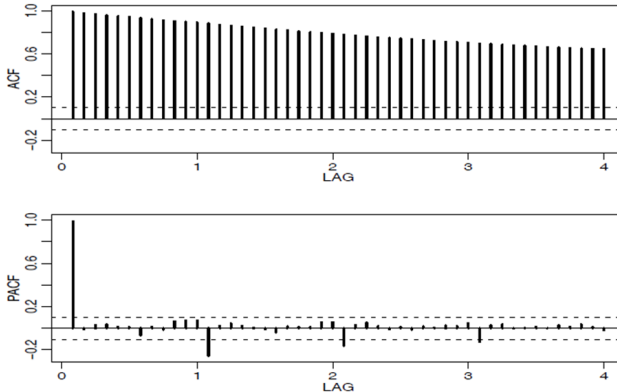


# The Federal Reserve Board Production Index example (1/7)



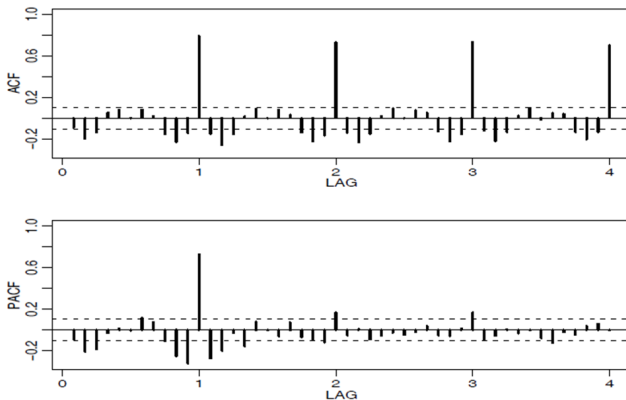
Values of the **Monthly Federal Reserve Board Production Index and Unemployment** (1948-1978,  $n = 372$  months).

# The Federal Reserve Board Production Index example (2/7)



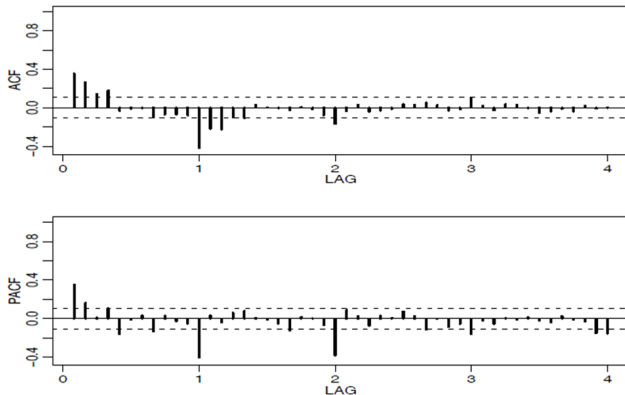
**ACF** and **PACF** of the **production series**

# The Federal Reserve Board Production Index example (3/7)



**ACF** and **PACF** of **differenced production**,  $(1 - B)x_t$

# The Federal Reserve Board Production Index example (4/7)



**ACF and PACF of the first differenced and then seasonally differenced production,  $(1 - B)(1 - B^{12})x_t$**

# The Federal Reserve Board Production Index example (5/7)

Three **models suggested** by these observations:

① **ARIMA(2,1,0) x (0,1,1)<sub>12</sub>**:

AIC= 1.372, BIC= 0.404

② **ARIMA(2,1,0) x (0,1,3)<sub>12</sub>**:

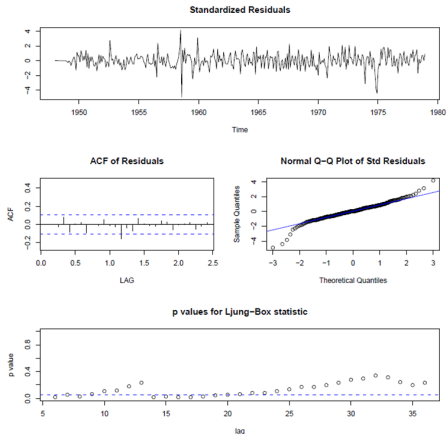
AIC= 1.299, BIC= 0.351

③ **ARIMA(2,1,0) x (2,1,1)<sub>12</sub>**:

AIC= 1.326, BIC= 0.379

**Model that best fits:** ARIMA(2,1,0)x(0,1,3)<sub>12</sub>

# The Federal Reserve Board Production Index example (6/7)



**Diagnostics for the  $ARIMA(2,1,0) \times (0,1,3)_{12}$  on the Production Index.**

## **Residual Analysis**

Homogeneity of variance

Normality

Independence

## **Homogeneity of variance. Tools**

Residuals plot

Square root of absolute values of the residuals with smooth fit

ACF/PACF of square of residuals

## **Homogeneity of variance. Problems**

Outlier observations: Outlier detection and treatment

Volatility: Models for the variance (GARCH)



## **Normality. Tools**

Quantile-Quantile plot

Histogram with theoretical density overlapped

Shapiro-Wilks test

## **Normality. Problems**

Outlier observations: Outlier detection and treatment

Asymmetry or bi-modality: Transformation, outliers or change residuals distribution

Heavy tails (excess of kurtosi): Volatility models or t-distributions for the residuals

## **Independence. Tools**

- ACF/PACF of residuals

- Ljung-Box test

- Durbin-Watson test

## **Independence. Problems**

- Significant lags: Re-identify or add parameters to the model

## Information Criterion

Balance between godness-of-fit and simplicity of the model

Component for the godness-of-fit:  $-2 \log L(\phi, \theta, \sigma^2 | X)$

Component for the simplicity:  $K * p$

$$AIC = -2 \log L(\phi, \theta, \sigma^2 | X) + 2p$$

$$BIC = -2 \log L(\phi, \theta, \sigma^2 | X) + \log(N)p$$