ANKIT DHALL

adhall@ethz.ch | ankitdhall.github.io

EDUCATION

ETH-Zürich, Switzerland 2017 - present

Master of Science in Robotics, Systems & Control

Computer Vision, Machine Learning and Robotics

Vellore Institute of Technology, Chennai, India

2013 - 2017

Bachelor of Technology in Computer Science & Engineering

CGPA: 9.7/10, ranked 2nd out of 147 students in department Teaching Assistant - *Data Structures and Algorithms*, *Fall 2015*

St. George's College, Mussoorie, India

2004 - 2013

Class 12, 95.50% in Indian School Certificate Examination(ISC) 2013

Class 10, 94.16% in Indian Certificate of Secondary Education Examination(ICSE) 2011

EXPERIENCE

Learning and Adaptive Systems Group, ETH Zurich

Master thesis

Advisors: Prof. Andreas Krause, Anastasia Makarova, Octavian Eugen-Ganea

March 2019 - present

• Learning representations for images with hierarchical labels.

NuTonomy, Singapore [7]

Autonomous Vehicle Intern

Computer Vision and Machine Learning

September 2018 - February 2019

Deployable safety-critical perception system using deep learning and exploiting map priors.

Head of Perception

Formula Student Driverless 2019

November 2018 - present

• Head of Perception. Technically lead and manage the Perception team.

Academic Motorsports Association of Zurich (AMZ)

Formula Student Driverless 2018

Computer Vision

November 2017 - present

• Working on developing a customized vision pipeline for robust detection and accurate localization of cones (upto 15 meters) in 3D for Formula Student Driverless 2018 season for FS Germany and FS-Italy races. Developing real-time key-point regression with novel priors for pose estimation with mono camera. Competition video

Robotics Research Center, IIIT-Hyderabad C

Researcher/Bachelor's thesis

Advisor: Prof. K. Madhava Krishna

January 2017 - May 2017

• Proposed a novel pipeline and experimental setup to find accurate rigid-body transformation for extrinsically calibrating a low-resolution LiDAR (VLP-16) and camera(s) using 3D-3D correspondences. The ROS package has been forked widely and usage can be found at: https://github.com/ankitdhall/lidar_camera_calibration ...

Autonome Intelligente Systeme, University of Freiburg C

Researcher

Advisors: Prof. Wolfram Burgard, Abhinav Valada

June 2016 - August 2016

 Created a Mixture of Deep CNN Experts for robust semantic segmentation by adaptively fusing complementary modalities (RGB and depth, for instance). Implemented segmentation on NVIDIA TX1 and generated way-points for an all-terrain vehicle that autonomously navigated ~4.5km of rough, forested terrain.
Project page: https://deepscene.cs.uni-freiburg.de ♂

Microsoft Corporation - Campus Connect

Software Developer

Mentor: Akanksha Gupta

June 2015 - September 2015

 Created a music discovery engine using Flask that fetches queries and visualizes the data through D3.js. Judged as the winning idea and implementation at Microsoft Campus Connect and Most-Popular vote at Yahoo! Accenture Innovation Jockeys 4.

University of California, Santa Cruz + Stanford Research

Researcher

Advisors: Prof. James Davis, Dr. Rajan Vaish

January 2015 - June 2015

• Collaborated to improve vision algorithms by introducing crowdsourced human cognition in the pipeline. Reordered images for human workers based on confidence scores to improve system accuracy.

PUBLICATIONS

 Ankit Dhall, Dengxin Dai, Luc Van Gool Real-time 3D Traffic Cone Detection for Autonomous Driving IEEE Intelligent Vehicles (IV), Paris 2019.

• Abhinav Valada, Johan Vertens, Ankit Dhall, Wolfram Burgard

AdapNet: Adaptive Semantic Segmentation in Adverse Environmental Conditions

http://ais.informatik.uni-freiburg.de/publications/papers/valada17icra.pdf IEEE International Conference on Robotics and Automation (ICRA), Singapore, 2017.

 Ankit Dhall, Kunal Chelani, Vishnu Radhakrishnan, K.M. Krishna LiDAR-Camera Calibration using 3D-3D point correspondences

http://arxiv.org/abs/1705.09785 ℃

Bachelor thesis and Research internship, May 2017

• Abhinav Valada*, Ankit Dhall*, Wolfram Burgard

Convoluted Mixture of Deep Experts for Robust Semantic Segmentation

http://ais.informatik.uni-freiburg.de/publications/papers/valada16irosws.pdf 12 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) Workshop, Daejeon, Korea, 2016.

Andreas Veit, Michael Wilber, Rajan Vaish, Serge Belongie, James Davis, Ankit Dhall et al.

On Optimizing Human-Machine Task Assignments

http://arxiv.org/abs/1509.07543 [2]

WiP at AAAI Conference on Human Computation & Crowdsourcing (HCOMP), San Diego, USA, 2015.

LANGUAGE SKILLS

Hindi Mother tongue

English Bilingual proficiency (TOEFLiBT: L:30 R:30 W:30 S:26 = 114/120)

German Elementary proficiency (Basic-German Level A1.1 - DEUTSCH-UNI ONLINE ☑)

Italian Elementary proficiency

TECHNICAL SKILLS

Programming Languages Python, C++, MATLAB

Libraries, Frameworks & APIs PyTorch, OpenCV, basic ROS, basic Caffe **Miscellaneous** Adobe Photoshop, NVIDIA TX1, Latex

MOOCS AND OTHER COURSES

- Introduction to Probability The Science of Uncertainty 6.041x, edX Honor Code Certificate MITX 🖸
- Machine Learning, Coursera Honor Code Certificate STANFORD UNIVERSITY
- Artificial Intelligence CS188x audited online and on edX UNIVERSITY OF CALIFORNIA, BERKELEY
- Discrete Optimization audited on Coursera UNIVERSITY OF MELBOURNE

ACADEMIC AWARDS AND ACHIEVEMENTS

- DAAD-WISE Scholarship 2016 to pursue research in Germany; one of the 160 students from all over India
- Awarded for academic excellence for 2013-14, 2014-15, 2015-16 and 2016-17
- Voted most popular project at Yahoo! and Accenture's Innovation Jockeys 4 and one of the 10 finalists out of more than 2500+ teams across India and invited to Bangalore to present our idea
- Music Discovery engine judged as the winning idea and implementation at Microsoft Campus Connect 2015.
- On-site Finalist at ACM ICPC, Asia Regional, 2014 and 10th in GRIET Code, 2015 coding competitions
- Awarded for excellence in Computer Science and Physics in high school (ISC)
- School topper in the ICSE examinations and awarded scholarship for 2011 and 2012

^{*} These authors contributed equally