NumPy, short for Numerical Python.

NumPy provides an easy-to-use C API, it is straightforward to pass data to external libraries written in a low-level language and also for external libraries to return data to Python as NumPy arrays. This feature has made Python a language of choice for wrapping legacy C/C++/Fortran codebases and giving them a dynamic and easy-to-use interface.

Data munging, sometimes called data wrangling or data cleaning, is converting and mapping unprocessed data into a different format to improve its suitability and value for various downstream uses, including analytics.

pandas also provides some more domain specific functionality like time series manipulation, which is not present in NumPy.

NumPy internally stores data in a contiguous block of memory, independent of other built-in Python objects. NumPy's library of algorithms written in the C language can operate on this memory without any type checking or other overhead. NumPy arrays also use much less memory than built-in Python sequences.

```
In [1]: import numpy as np
    numpy_array=np.arange(1000000)
    python_list=list(range(1000000))

In [2]: %time for _ in range(10): numpy_array2 = numpy_array *2
    %time for _ in range(10): python_list2 = [x * 2 for x in python_list]

CPU times: user 26 ms, sys: 18.8 ms, total: 44.8 ms
    Wall time: 162 ms
    CPU times: user 1.08 s, sys: 252 ms, total: 1.33 s
    Wall time: 1.97 s
```

NumPy-based algorithms are generally 10 to 100 times faster (or more) than their pure Python counterparts and use significantly less memory.

One of the key features of NumPy is its N-dimensional array object, or ndarray, which is a fast, flexible container for large datasets in Python

```
In [3]:
        d=np.random.randn(2,3)
        array([[-2.05724633, 0.76994867, -0.45824433]
Out[3]:
               [ 1.04091997, 1.61590441, 0.82462728]])
In [4]: d+d
       array([[-4.11449265, 1.53989734, -0.91648865],
Out[4]:
               [ 2.08183994, 3.23180882, 1.64925456]])
In [5]: d*d
       array([[4.23226245, 0.59282095, 0.20998786],
Out[5]:
               [1.08351438, 2.61114706, 0.68001015]])
In [6]: 10*d
Out[6]: array([[-20.57246326,
                               7.6994867 , -4.58244325],
               [ 10.40919969, 16.15904409,
                                             8.24627278]])
```

You are, of course, welcome to put

from numpy import *

in your code to avoid having to write np., but I advise against making a habit of this. The numpy namespace is large and contains a number of functions whose names conflict with built-in Python functions (like min and max).

An idarray is a generic multidimensional container for homogeneous data; that is, all of the elements must be the same type.

Every array has a shape, a tuple indicating the size of each dimension, and a dtype, an object describing the data type of the array

```
In [7]: d.dtype
Out[7]: dtype('float64')
In [8]: d.ndim
Out[8]: 2
In [9]: d.shape
Out[9]: (2, 3)
```

The easiest way to create an array is to use the array function. This accepts any sequence-like object (including other arrays) and produces a new NumPy array containing the passed data. For example, a list is a good candidate for conversion

```
In [10]: a=np.array([[[1,2],[3,4]],[[5,6],[7,8]]])
In [11]: a.shape
           (2, 2, 2)
Out[11]:
In [12]: a.ndim
In [13]: a.dtype
Out[13]: dtype('int64')
In [14]: # dimension 3 means array is divided into 3 parts: no of grids, no of rows in each grid and
           # no of columns in each grid
In [15]: np.array([1,2,3], dtype='int16')
Out[15]: array([1, 2, 3], dtype=int16)
In [16]: np.empty((2,3))
Out[16]: array([[20.57246326, 7.6994867 , 4.58244325], [10.40919969, 16.15904409, 8.24627278]])
In [17]: np.zeros((2,3,4))
Out[17]: array([[[0., 0., 0., 0.],
                    [0., 0., 0., 0.],
                    [0., 0., 0., 0.]],
                   [[0., 0., 0., 0.],
                    [0., 0., 0., 0.],
                   [0., 0., 0., 0.]]])
In [18]: np.zeros((10,))
Out[18]: array([0., 0., 0., 0., 0., 0., 0., 0., 0., 0.])
In [19]: np.ones((2,3))
Out[19]: array([[1., 1., 1.],
                  [1., 1., 1.]])
In [20]: np.identity(3)
Out[20]: array([[1., 0., 0.],
                   [0., 1., 0.],
[0., 0., 1.]])
           asarray ==> Convert input to ndarray, but do not copy if the input is already an ndarray
In [21]: np.asarray?
           asarray(a, dtype=None, order=None, *, device=None, copy=None, like=None)
           Convert the input to an array.
           Parameters
           a : array like
               Input data, in any form that can be converted to an array. This
               includes lists, lists of tuples, tuples, tuples of tuples, tuples
               of lists and ndarrays.
           dtype : data-type, optional
          By default, the data-type is inferred from the input data.

order: {'C', 'F', 'A', 'K'}, optional

Memory layout. 'A' and 'K' depend on the order of input array a.
               'C' row-major (C-style),
               'F' column-major (Fortran-style) memory representation.
'A' (any) means 'F' if `a` is Fortran contiguous, 'C' otherwise
               'K' (keep) preserve input order
               Defaults to 'K'.
           device : str, optional
               The device on which to place the created array. Default: ``None``.
               For Array-API interoperability only, so must be ``"cpu"`` if passed.
               .. versionadded:: 2.0.0
```

```
copy : bool, optional
              If ``True`
              If ``True``, then the object is copied. If ``None`` then the object is copied only if needed, i.e. if ``__array__`` returns a copy, if obj
              is a nested sequence, or if a copy is needed to satisfy any of the other requirements (``dtype``, ``order``, etc.).
              For ``False`` it raises a ``ValueError`` if a copy cannot be avoided.
              Default: ``None``.
               .. versionadded:: 2.0.0
          like : array_like, optional
              Reference object to allow the creation of arrays which are not
              NumPy arrays. If an array-like passed in as ``like`` supports the ``_array_function__`` protocol, the result will be defined
              by it. In this case, it ensures the creation of an array object
              compatible with that passed in via this argument.
               .. versionadded:: 1.20.0
          Returns
          out : ndarrav
              Array interpretation of ``a``. No copy is performed if the input
              is already an ndarray with matching dtype and order. If ``a` \,
              subclass of ndarray, a base class ndarray is returned.
          See Also
          asanyarray : Similar function which passes through subclasses.
          ascontiguousarray : Convert input to a contiguous array.
          asfortranarray: Convert input to an ndarray with column-major
                             memory order.
          asarray chkfinite: Similar function which checks input for NaNs and Infs.
          fromiter : Create an array from an iterator.
          fromfunction : Construct an array by executing a function on grid
                          positions.
          Examples
          Convert a list into an array:
          >>> a = [1, 2]
          >>> import numpy as np
          >>> np.asarray(a)
          array([1, 2])
          Existing arrays are not copied:
          >>> a = np.array([1, 2])
          >>> np.asarray(a) is a
          If `dtype` is set, array is copied only if dtype does not match:
          >>> a = np.array([1, 2], dtype=np.float32)
          >>> np.shares_memory(np.asarray(a, dtype=np.float32), a)
          >>> np.shares_memory(np.asarray(a, dtype=np.float64), a)
          False
          Contrary to `asanyarray`, ndarray subclasses are not passed through:
          >>> issubclass(np.recarray, np.ndarray)
          >>> a = np.array([(1., 2), (3., 4)], dtype='f4,i4').view(np.recarray)
          >>> np.asarray(a) is a
          False
          >>> np.asanyarray(a) is a
          True
                      builtin function or method
          Type:
In [22]: a=(1,2)
          np.asarray(a)
Out[22]: array([1, 2])
          The data type or dtype is a special object containing the information (or metadata, data about data) the ndarray needs
```

The data type or dtype is a special object containing the information (or metadata, data about data) the inderray needs to interpret a chunk of memory as a particular type of data

```
In [23]: arr1 = np.array([1, 2, 3], dtype=np.float64)
arr1

Out[23]: array([1, 2, 3.])

In [24]: arr1 = np.array([1, 2, 3], dtype=np.str_)
arr1
```

```
Out[24]: array(['1', '2', '3'], dtype='<U1')
         int32, uint32 ==> i4, u4 ==> Signed and unsigned 32-bit integer types
         float16 ==> f2 ==> Half-precision floating point
         float32 ==> f4 or f ==> Standard single-precision floating point; compatible with C float
         float64 ==> f8 or d ==> Standard double-precision floating point; compatible with C double
         object ==> O ==> Python object type; a value can be any Python object
         unicode ==> U ==> Fixed-length Unicode type (number of bytes platform specific); same specification semantics as
         string (e.g., 'U10')
In [25]: # You can explicitly convert or cast an array from one dtype to another using ndarray's astype method:
         np.array([1,2,3]).astype(np.float32)
         array([1., 2., 3.], dtype=float32)
In [26]: np.empty(8, dtype='u4')
Out[26]: array([583855524,
                                               0,
                                                           0, 576066000,
                                                                                  Θ,
                 583985056,
                                    0], dtype=uint32)
         Arrays are important because they enable you to express batch operations on data without writing any for loops. NumPy
         users call this vectorization. Any arithmetic operations between equal-size arrays applies the operation element-wise.
In [27]: arr=np.array([1,2,3],dtype=np.float16)
         print(arr*arr,arr**3,1/arr)
         [1. 4. 9.] [ 1. 8. 27.] [1.
                                           0.5
                                                   0.33331
In [28]: # array comparison
         arr1=np.array([3,1,2])
         arr2=np.arange(3)
         print(arr1,arr2,arr1>arr2)
         [3 1 2] [0 1 2] [ True False False]
In [29]: arr=np.arange(12)
         print(arr,arr[5],arr[3:7])
         [ 0 1 2 3 4 5 6 7 8 9 10 11] 5 [3 4 5 6]
In [30]: arr[8:11]=arr[3:6]
         print(arr)
         [0 1 2 3 4 5 6 7 3 4 5 11]
In [31]: arr3d=np.array([[[1,2],[3,4]],[[5,6],[7,8]]])
         arr2d=arr3d[0]
         print(arr3d, '\n\n', arr2d, arr2d.ndim)
         [[[1 2]
           [3 4]]
          [[5 6]
           [7 8]]]
          [[1 2]
          [3 4]] 2
In [32]: print(arr2d[:1,:])
         [[1 2]]
In [33]: arr2d[:1,:]=0
         print(arr2d)
         [[0 0]]
          [3 4]]
         Like arithmetic operations, comparisons (such as ==) with arrays are also vectorized
         names=np.array(['ankit','kiio','summi','soumi','kiio','ankit','summi'])
In [34]:
In [35]:
         names=='kiio'
         array([False, True, False, False, False, False])
Out[35]:
In [36]:
         data=np.random.randn(7,5)
In [37]: data
```

```
Out[37]: array([[ 0.47246008, -0.97230505, -0.88185117, 1.026626 , 0.32148013],
                     [-0.47270189, -1.87421897, -1.7251059, 1.07963034, 0.20243205], [0.81433844, 0.77974422, 1.14522355, -0.88763845, -1.05345061], [-2.32515631, 0.25949492, -0.44071896, 2.79388335, 0.23144792], [-0.35663242, 1.48296132, 0.16217465, 1.27015427, 0.65339976], [0.20411933, 0.46806683, 1.18465655, -1.18838839, -0.69035039], [-2.14149743, -0.81589488, 0.04407909, 1.01297928, -0.81875806]])
In [38]:
            mask=(names=='kiio') | (names=='soumi')
            array([False, True, False, True, True, False, False])
Out[38]:
In [39]: data[mask]
Out[39]: array([[-0.47270189, -1.87421897, -1.7251059 , 1.07963034, 0.20243205],
                     [-2.32515631, 0.25949492, -0.44071896, 2.79388335, 0.23144792], [-0.35663242, 1.48296132, 0.16217465, 1.27015427, 0.65339976]])
            Fancy Indexing: To select out a subset of the rows in a particular order, you can simply pass a list or ndarray of integers
            specifying the desired order
In [40]: arr=np.empty((2,3))
In [41]: arr
Out[41]: array([[1., 1., 1.],
                     [1., 1., 1.]])
In [42]: arr[[1,0]]
Out[42]: array([[1., 1., 1.], [1., 1., 1.]])
In [43]: arr[1:,[1,0,2]]
Out[43]: array([[1., 1., 1.]])
In [44]: arr = np.arange(16).reshape((4, 4))
            print(arr)
            [[ 0 1 2 3]
[ 4 5 6 7]
             [ 8 9 10 11]
             [12 13 14 15]]
In [45]: print(arr[[2,0],[1,3]]) # elements at position (2,1) and (0,3) will be selected but why ?
            [9 3]
            # Transposing Arrays and Swapping Axes
In [46]:
            arr=np.array([[1,2],[3,4]])
            arr
Out[46]: array([[1, 2],
                     [3, 4]])
In [47]: arr.T
            array([[1, 3],
Out[47]:
                     [2, 4]])
In [48]: arr.transpose()
            array([[1, 3],
Out[48]:
                     [2, 4]])
            arr = np.arange(16).reshape((2, 2, 4))
In [49]:
            arr
Out[49]: array([[[ 0, 1, 2, 3],
                      [4, 5, 6, 7]],
                     [[8, 9, 10, 11],
                      [12, 13, 14, 15]])
In [50]: arr.transpose?
```

```
Docstring:
          a.transpose(*axes)
          Returns a view of the array with axes transposed.
          Refer to `numpy.transpose` for full documentation.
          Parameters
          axes : None, tuple of ints, or `n` ints
           * None or no argument: reverses the order of the axes.
          * tuple of ints: `i` in the `j`-th place in the tuple means that the
            array's `i`-th axis becomes the transposed array's `j`-th axis.
          * `n` ints: same as an n-tuple of the same ints (this form is
            intended simply as a "convenience" alternative to the tuple form).
          Returns
          p : ndarray
              View of the array with its axes suitably permuted.
          See Also
          transpose : Equivalent function.
          ndarray.T : Array property returning the array transposed.
          ndarray.reshape : Give a new shape to an array without changing its data.
          Examples
         >>> import numpy as np
         >>> a = np.array([[1, 2], [3, 4]])
          >>> a
         array([[1, 2], [3, 4]])
          >>> a.transpose()
         array([[1, 3],
[2, 4]])
          >>> a.transpose((1, 0))
          array([[1, 3],
                [2, 4]])
          >>> a.transpose(1, 0)
          array([[1, 3],
                [2, 4]])
         >>> a = np.array([1, 2, 3, 4])
          array([1, 2, 3, 4])
          >>> a.transpose()
          array([1, 2, 3, 4])
                    builtin_function_or_method
          Type:
In [51]: arr.transpose((2,1,0))
          # Here, order is 2,1,0 and 2 comes from no. of columns, 1 comes from no of rows and 0 comes from no. of grids
          # so it will show 4 grids, 2 rows and 2 columns and
          # elements will be arranged in the order as column--> row--> grid
Out[51]: array([[[ 0, 8],
                  [ 4, 12]],
                 [[1, 9],
                  [5, 13]],
                 [[ 2, 10],
                  [ 6, 14]],
                 [[ 3, 11],
                  [ 7, 15]]])
In [52]: arr.transpose((1,2,0))
Out[52]: array([[[ 0, 8],
                  [ 1, 9],
[ 2, 10],
                  [ 3, 11]],
                 [[ 4, 12],
                  [ 5, 13],
                  [ 6, 14],
[ 7, 15]]])
```

In [53]: arr.transpose((1,0,2))

```
Out[53]: array([[[ 0, 1, 2, 3],
                 [8, 9, 10, 11]],
                [[ 4, 5, 6, 7], [12, 13, 14, 15]]])
In [54]: arr.strides
Out[54]: (64, 32, 8)
In [55]: arr.dtype
Out[55]: dtype('int64')
In [56]: # So, each element has 4 bytes and from one grid to another grid, it has to cross 8 elements i.e. 32 bytes
          # which is showing in the arr.strides and similary
         # go from one row to another row, it has to cross 4 elements i.e. 16 bytes and from one column to another column
         # it has to cross 4 bytes.
In [57]: arr.transpose((2,1,0)).strides
Out[57]: (8, 32, 64)
In [58]: np.empty((2,2,3))
Out[58]: array([[[0.0e+000, 4.9e-324, 9.9e-324],
                 [1.5e-323, 2.0e-323, 2.5e-323]],
                [[3.0e-323, 3.5e-323, 1.5e-323],
                 [2.0e-323, 2.5e-323, 5.4e-323]]])
In [59]: np.empty((2,2,3)).swapaxes(0,2)
          # here we are swapping axis 0 and axis 2. axis 0 means grid and axis 2 means columns.
         # so we are swapping grids and columns. Initial we has 2 grids so now we have 2 columns
          # and initially we had 3 columns so now we have 3 grids.
         # Accordingly elements will be arranged like elements in columns will go in different grids.
Out[59]: array([[[0.0e+000, 3.0e-323],
                 [1.5e-323, 2.0e-323]],
                 [[4.9e-324, 3.5e-323],
                 [2.0e-323, 2.5e-323]],
                 [[9.9e-324, 1.5e-323],
                 [2.5e-323, 5.4e-323]]])
```

Universal Functions - Fast Element-Wise Array Functions:

A universal function, or ufunc, is a function that performs element-wise operations on data in ndarrays. You can think of them as fast vectorized wrappers for simple functions that take one or more scalar values and produce one or more scalar results. Many ufuncs are simple element-wise transformations, like sqrt or exp.

```
In [60]: arr = np.array([1,2,3])
         np.sqrt(arr)
Out[60]: array([1.
                           , 1.41421356, 1.73205081])
In [61]: np.exp(arr)
Out[61]: array([ 2.71828183, 7.3890561 , 20.08553692])
In [62]: np.log(arr)
                           , 0.69314718, 1.09861229])
         array([0.
In [63]: x=np.array([1,2,3])
         y=np.array([2,3,1])
         np.maximum(x,y)
Out[63]: array([2, 3, 3])
In [64]: arr = np.random.randn(7) * 5
          remainder,whole part=np.modf(arr)
         arr,remainder,whole_part
Out[64]: (array([ 3.18161198, -1.28419106, 3.52870921, 3.41571939, 0.21864495,
          0.85336174, 0.72593577]),
array([ 0.18161198, -0.28419106, 0.52870921, 0.41571939, 0.21864495,
                   0.85336174, 0.72593577]),
          array([ 3., -1., 3., 3., 0., 0., 0.]))
```

Table 4-3. Unary ufuncs

Function --> Description

```
square --> Compute the square of each element (equivalent to arr 2)
          exp --> Compute the exponent ex of each element
          log, log10, log2, log1p --> Natural logarithm (base e), log base 10, log base 2, and <math>log(1 + x), respectively
          sign --> Compute the sign of each element: 1 (positive), 0 (zero), or -1 (negative)
          ceil --> Compute the ceiling of each element (i.e., the smallest integer greater than or equal to that number)
          floor --> Compute the foor of each element (i.e., the largest integer less than or equal to each element)
          rint --> Round elements to the nearest integer, preserving the dtype
          modf --> Return fractional and integral parts of array as a separate array
          isnan --> Return boolean array indicating whether each value is NaN (Not a Number)
          isfinite, isinf --> Return boolean array indicating whether each element is finite (non-inf, non-NaN) or
          infinite, respectively
          cos, cosh, sin, sinh, tan, tanh --> Regular and hyperbolic trigonometric functions
          arccos, arccosh, arcsin, arcsinh, arctanh --> Inverse trigonometric functions
          logical_not --> Compute truth value of not x element-wise (equivalent to \simarr).
In [65]: np.abs(-1.2)
Out[65]: np.float64(1.2)
In [66]: np.fabs([1,1.2,-1.02])
Out[66]: array([1. , 1.2 , 1.02])
In [67]: np.fabs?
          Call signature: np.fabs(*args, **kwargs)
          Type:
                           ufunc
                            <ufunc 'fabs'>
          String form:
                            ~/Desktop/ml/InterviewPreparation/AI-ML-DS/practice env/lib/python3.10/site-packages/numpy/
          File:
          nit .py
          Docstring:
          fabs(x, /, out=None, *, where=True, casting='same\_kind', order='K', dtype=None, subok=True[, signature])
          Compute the absolute values element-wise.
          This function returns the absolute values (positive magnitude) of the
          data in `x`. Complex values are not handled, use `absolute` to find the
          absolute values of complex data.
          Parameters
          x : array like
              The array of numbers for which the absolute values are required. If
               `x` is a scalar, the result `y` will also be a scalar.
          out : ndarray, None, or tuple of ndarray and None, optional A location into which the result is stored. If provided, it must have
              a shape that the inputs broadcast to. If not provided or None,
              a freshly-allocated array is returned. A tuple (possible only as a
              keyword argument) must have length equal to the number of outputs.
          where : array_like, optional
              This condition is broadcast over the input. At locations where the
              condition is True, the `out` array will be set to the ufunc result.
              Elsewhere, the `out` array will retain its original value.
              Note that if an uninitialized `out` array is created via the default
               ``out=None``, locations within it where the condition is False will
              remain uninitialized.
          **kwargs
              For other keyword-only arguments, see the
              :ref:`ufunc docs <ufuncs.kwargs>`.
          Returns
          y : ndarray or scalar
              The absolute values of `x`, the returned values are always floats. This is a scalar if `x` is a scalar.
          See Also
          absolute : Absolute values including `complex` types.
          Examples
          >>> import numpy as np
          >>> np.fabs(-1)
          1.0
          >>> np.fabs([-1.2, 1.2])
          array([ 1.2, 1.2])
          Class docstring:
          Functions that operate element by element on whole arrays.
```

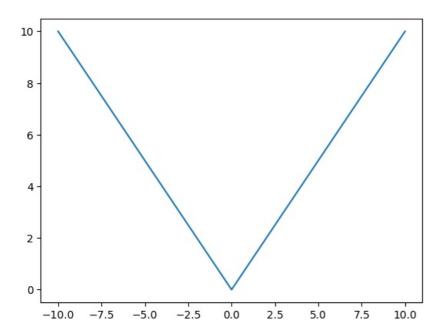
abs, fabs --> Compute the absolute value element-wise for integer, foating-point, or complex values

sqrt --> Compute the square root of each element (equivalent to arr 0.5)

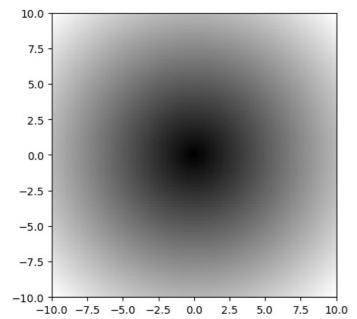
```
To see the documentation for a specific ufunc, use `info`. For example, ``np.info(np.sin)``. Because ufuncs are written in C
          (for speed) and linked into Python with NumPy's ufunc facility,
          Python's help() function finds this page whenever help() is called
          on a ufunc.
          A detailed explanation of ufuncs can be found in the docs for :ref:`ufuncs`.
          **Calling ufuncs:** ``op(*x[, out], where=True, **kwargs)``
          Apply \circ op \circ to the arguments \circ *x elementwise, broadcasting the arguments.
          The broadcasting rules are:
          * Dimensions of length 1 may be prepended to either array.
          * Arrays may be repeated along dimensions of length 1.
          Parameters
          *x : array_like
              Input arrays.
          out : ndarray, None, or tuple of ndarray and None, optional
              Alternate array object(s) in which to put the result; if provided, it
              must have a shape that the inputs broadcast to. A tuple of arrays
              (possible only as a keyword argument) must have length equal to the
              number of outputs; use None for uninitialized outputs to be
              allocated by the ufunc.
          where : array_like, optional
              This condition is broadcast over the input. At locations where the condition is True, the `out` array will be set to the ufunc result.
              Elsewhere, the `out` array will retain its original value.
              Note that if an uninitialized `out` array is created via the default ``out=None``, locations within it where the condition is False will
              remain uninitialized.
          **kwargs
              For other keyword-only arguments, see the :ref:`ufunc docs <ufuncs.kwargs>`.
          Returns
          r : ndarray or tuple of ndarray
                r` will have the shape that the arrays in `x` broadcast to; if `out` is
              provided, it will be returned. If not, `r` will be allocated and
              may contain uninitialized values. If the function has more than one
              output, then the result will be a tuple of arrays.
In [68]: np.absolute?
          Call signature: np.absolute(*args, **kwargs)
          Type:
                             ufunc
          String form:
                             <ufunc 'absolute'>
                             ~/Desktop/ml/InterviewPreparation/AI-ML-DS/practice env/lib/python3.10/site-packages/numpy/
          nit__.py
          Docstring.
          absolute(x, /, out=None, *, where=True, casting='same kind', order='K', dtype=None, subok=True[, signature])
          Calculate the absolute value element-wise.
          ``np.abs`` is a shorthand for this function.
          Parameters
          x : array like
              Input array.
          out : ndarray, None, or tuple of ndarray and None, optional
              A location into which the result is stored. If provided, it must have
              a shape that the inputs broadcast to. If not provided or None,
              a freshly-allocated array is returned. A tuple (possible only as a
              keyword argument) must have length equal to the number of outputs.
          where : array_like, optional
              This condition is broadcast over the input. At locations where the condition is True, the `out` array will be set to the ufunc result.
              Elsewhere, the `out` array will retain its original value.
              Note that if an uninitialized `out` array is created via the default
               ``out=None``, locations within it where the condition is False will
              remain uninitialized.
          **kwargs
              For other keyword-only arguments, see the
              :ref:`ufunc docs <ufuncs.kwargs>`.
          Returns
          absolute : ndarray
              An ndarray containing the absolute value of
              each element in `x`. For complex input, ``a + ib``, the absolute value is :math: \sqrt{ a^2 + b^2 }`.
              This is a scalar if `x` is a scalar.
```

Examples

```
>>> import numpy as np
          >>> x = np.array([-1.2, 1.2])
          >>> np.absolute(x)
          array([ 1.2, 1.2])
          >>> np.absolute(1.2 + 1j)
          1.5620499351813308
          Plot the function over ``[-10, 10]``:
          >>> import matplotlib.pyplot as plt
          >>> x = np.linspace(start=-10, stop=10, num=101)
          >>> plt.plot(x, np.absolute(x))
          >>> plt.show()
          Plot the function over the complex plane:
          >>> xx = x + 1j * x[:, np.newaxis]
          >>> plt.imshow(np.abs(xx), extent=[-10, 10, -10, 10], cmap='gray')
          >>> plt.show()
          The `abs` function can be used as a shorthand for ``np.absolute`` on
          >>> x = np.array([-1.2, 1.2])
          >>> abs(x)
          array([1.2, 1.2])
          Class docstring:
          Functions that operate element by element on whole arrays.
          To see the documentation for a specific ufunc, use `info`. For
          example, ``np.info(np.sin)``. Because ufuncs are written in C
          (for speed) and linked into Python with NumPy's ufunc facility
          Python's help() function finds this page whenever help() is called
          on a ufunc.
          A detailed explanation of ufuncs can be found in the docs for :ref:`ufuncs`.
          **Calling ufuncs:** ``op(*x[, out], where=True, **kwargs)``
          Apply \circp' to the arguments *x elementwise, broadcasting the arguments.
          The broadcasting rules are:
          * Dimensions of length 1 may be prepended to either array.
          * Arrays may be repeated along dimensions of length 1.
          Parameters
          *x : array_like
              Input arrays.
          out : ndarray, None, or tuple of ndarray and None, optional
              Alternate array object(s) in which to put the result; if provided, it
              must have a shape that the inputs broadcast to. A tuple of arrays
              (possible only as a keyword argument) must have length equal to the
              number of outputs; use None for uninitialized outputs to be
              allocated by the ufunc.
          where : array_like, optional
             This condition is broadcast over the input. At locations where the
              condition is True, the `out` array will be set to the ufunc result. Elsewhere, the `out` array will retain its original value.
              Note that if an uninitialized `out` array is created via the default
               ``out=None``
                           , locations within it where the condition is False will
              remain uninitialized.
              For other keyword-only arguments, see the :ref:`ufunc docs <ufuncs.kwargs>`.
          Returns
          r : ndarray or tuple of ndarray
              `r` will have the shape that the arrays in `x` broadcast to; if `out` is provided, it will be returned. If not, `r` will be allocated and
              may contain uninitialized values. If the function has more than one
              output, then the result will be a tuple of arrays.
In [69]: np.absolute(1.2 + 1j)
Out[69]: np.float64(1.5620499351813308)
In [70]: import matplotlib.pyplot as plt
          x = np.linspace(start=-10, stop=10, num=101)
          plt.plot(x, np.absolute(x))
          plt.show()
```



```
In [71]: #Plot the function over the complex plane:
    xx = x + 1j * x[:, np.newaxis]
    plt.imshow(np.abs(xx), extent=[-10, 10, -10, 10], cmap='gray')
    plt.show()
```



```
In [72]: np.log1p(1)
         np.float64(0.6931471805599453)
Out[72]:
In [73]:
         np.ceil(1.2)
         np.float64(2.0)
Out[73]:
In [74]: np.floor(1.2)
         np.float64(1.0)
Out[74]:
In [75]: np.rint(1.2)
         np.float64(1.0)
Out[75]:
In [76]: np.rint(1.5)
         np.float64(2.0)
Out[76]:
In [77]: np.rint(1.6)
         np.float64(2.0)
Out[77]:
In [78]: np.rint(1.4)
```

```
In [79]: np.isnan([1,0,-1,np.nan])
         array([False, False, False, True])
Out[79]:
In [80]: np.arccos(0)
          np.float64(1.5707963267948966)
Out[80]:
In [81]: np.isfinite(np.nan)
          np.False
Out[81]:
In [82]: np.isinf(np.nan)
          np.False
Out[82]:
          Table 4-4. Binary universal functions
          Function --> Description
          add --> Add corresponding elements in arrays
          subtract --> Subtract elements in second array from first array
          multiply --> Multiply array elements
          divide, floor_divide --> Divide or foor divide (truncating the remainder)
          power --> Raise elements in first array to powers indicated in second array
          maximum, fmax --> Element-wise maximum; fmax ignores NaN
          minimum, fmin --> Element-wise minimum; fmin ignores NaN
          mod --> Element-wise modulus (remainder of division)
          copysign --> Copy sign of values in second argument to values in first argument
          greater, greater equal,less, less equal,equal, not equal --> Perform element-wise comparison, yielding boolean array
          (equivalent to infix operators >, >=, <, <=, ==, !=)
          logical and, logical or, logical xor --> Compute element-wise truth value of logical operation (equivalent to infix
          operators & |, ^)
In [83]: np.add?
          Call signature: np.add(*args, **kwargs)
                            ufunc
          Type:
                            <ufunc 'add'>
          String form:
          File:
                            ~/Desktop/ml/InterviewPreparation/AI-ML-DS/practice env/lib/python3.10/site-packages/numpy/ i
          nit__.py
          Docstring:
          add(x1, x2, /, out=None, *, where=True, casting='same kind', order='K', dtype=None, subok=True[, signature])
          Add arguments element-wise.
          Parameters
          x1, x2 : array_like
              The arrays to be added.
                  ``x1.shape != x2.shape``, they must be broadcastable to a common
              shape (which becomes the shape of the output).
          out : ndarray, None, or tuple of ndarray and None, optional
              A location into which the result is stored. If provided, it must have
              a shape that the inputs broadcast to. If not provided or None,
              a freshly-allocated array is returned. A tuple (possible only as a
              keyword argument) must have length equal to the number of outputs.
          where : array_like, optional
              This condition is broadcast over the input. At locations where the
              condition is True, the `out` array will be set to the ufunc result.
              Elsewhere, the `out` array will retain its original value.
              Note that if an uninitialized `out` array is created via the default ``out=None``, locations within it where the condition is False will
              remain uninitialized.
          **kwargs
              For other keyword-only arguments, see the
              :ref:`ufunc docs <ufuncs.kwargs>`
          Returns
          add : ndarray or scalar
              The sum of `x1` and `x2`, element-wise.
This is a scalar if both `x1` and `x2` are scalars.
          Notes
```

Equivalent to `x1` + `x2` in terms of array broadcasting.

Out[78]: np.float64(1.0)

```
Examples
          >>> import numpy as np
          >>> np.add(1.0, 4.0)
          5.0
          >> x1 = np.arange(9.0).reshape((3, 3))
          >>> x2 = np.arange(3.0)
         >>> np.add(x1, x2)
         2.,
                           5., 7.],
                 [ 3.,
                 [ 6.,
                         8., 10.]])
          The ``+`` operator can be used as a shorthand for ``np.add`` on ndarrays.
          >>> x1 = np.arange(9.0).reshape((3, 3))
          >>> x2 = np.arange(3.0)
          >>> x1 + x2
         array([[ 0., 2., 4.], [ 3., 5., 7.], [ 6., 8., 10.]])
          Class docstring:
          Functions that operate element by element on whole arrays.
          To see the documentation for a specific ufunc, use `info`. For
                     `np.info(np.sin)``. Because ufuncs are written in C
          example,
          (for speed) and linked into Python with NumPy's ufunc facility,
          Python's help() function finds this page whenever help() is called
          on a ufunc.
          A detailed explanation of ufuncs can be found in the docs for :ref:`ufuncs`.
          **Calling ufuncs:** ``op(*x[, out], where=True, **kwargs)``
          Apply \circp' to the arguments *x elementwise, broadcasting the arguments.
          The broadcasting rules are:
          st Dimensions of length 1 may be prepended to either array.
          * Arrays may be repeated along dimensions of length 1.
          Parameters
          *x : array like
              Input arrays.
          out : ndarray, None, or tuple of ndarray and None, optional
              Alternate array object(s) in which to put the result; if provided, it
              must have a shape that the inputs broadcast to. A tuple of arrays
              (possible only as a keyword argument) must have length equal to the
              number of outputs; use None for uninitialized outputs to be
              allocated by the ufunc.
          where : array_like, optional
              This condition is broadcast over the input. At locations where the
              condition is True, the `out` array will be set to the ufunc result.
              Elsewhere, the `out` array will retain its original value.
              Note that if an uninitialized `out` array is created via the default ``out=None``, locations within it where the condition is False will
              remain uninitialized.
          **kwargs
              For other keyword-only arguments, see the :ref:`ufunc docs <ufuncs.kwargs>`.
          Returns
          r : ndarray or tuple of ndarray
              `r` will have the shape that the arrays in `x` broadcast to; if `out` is provided, it will be returned. If not, `r` will be allocated and
              may contain uninitialized values. If the function has more than one
              output, then the result will be a tuple of arrays.
In [84]: np.add([1,2,3],[4,5,6])
Out[84]: array([5, 7, 9])
In [85]: np.power([1,2,3],[4,5,3])
Out[85]: array([ 1, 32, 27])
In [86]: np.fmax([1,4,3],[2,1,5])
Out[86]: array([2, 4, 5])
In [87]: np.mod([7,26,3],[2,6,2])
Out[87]: array([1, 2, 1])
In [88]: np.copysign([1,2,3],[-1,-2,1])
```

```
Out[88]: array([-1., -2., 3.])
In [89]: np.greater_equal([1,2,3],[2,2,1])
Out[89]: array([False, True, True])
In [90]: np.logical_xor([1,0,1],[0,0,1])
Out[90]: array([ True, False, False])
In [91]: # computing sqrt(x^2 + y^2) across a regular grid of values:
          x=np.arange(-5,5,0.01)
          y=np.arange(-5,5,0.01)
          xs,ys=np.meshgrid(x,y)
          print(np.sqrt(xs**2+ys**2))
          [7.05693985 7.04985815 7.04278354 ... 7.03571603 7.04278354 7.04985815]
           [7.04988652\ 7.04279774\ 7.03571603\ \dots\ 7.0286414\ \ 7.03571603\ 7.04279774]
           [7.05693985 7.04985815 7.04278354 ... 7.03571603 7.04278354 7.04985815]
           [7.06400028 7.05692568 7.04985815 ... 7.04279774 7.04985815 7.05692568]]
In [92]: x=np.array(['ankit','arpit'])
y=np.array(['kiio','summi'])
          np.where([True,False],x,y)
Out[92]: array(['ankit', 'summi'], dtype='<U5')
In [93]: np.where?
          Call signature: np.where(*args, **kwargs)
                            ArrayFunctionDispatcher
          Type:
                           -
doublet-in function where>
          String form:
          Docstring:
          where(condition, [x, y], /)
          Return elements chosen from `x` or `y` depending on `condition`.
          .. note::
              When only `condition` is provided, this function is a shorthand for ``np.asarray(condition).nonzero()``. Using `nonzero` directly should be
              preferred, as it behaves correctly for subclasses. The rest of this
              documentation covers only the case where all three arguments are
              provided.
          Parameters
          condition : array_like, bool
   Where True, yield `x`, otherwise yield `y`.
          x, y : array_like
              Values from which to choose. `x`, `y` and `condition` need to be
              broadcastable to some shape.
          Returns
          out : ndarray
              An array with elements from `x` where `condition` is True, and elements
              from `y` elsewhere.
          See Also
          choose
          nonzero : The function that is called when x and y are omitted
          Notes
          If all the arrays are 1-D, `where` is equivalent to::
              [xv if c else yv
               for c, xv, yv in zip(condition, x, y)]
          Examples
          >>> import numpy as np
          >>> a = np.arange(10)
          >>> a
          array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9])
         >>> np.where(a < 5, a, 10*a) array([ 0, 1, 2, 3, 4, 50, 60, 70, 80, 90])
          This can be used on multidimensional arrays too:
          >>> np.where([[True, False], [True, True]],
                       [[1, 2], [3, 4]],
```

```
[[9, 8], [7, 6]])
          array([[1, 8],
                 [3, 4]])
          The shapes of x, y, and the condition are broadcast together:
          >>> x, y = np.ogrid[:3, :4]
          >>> np.where(x < y, x, 10 + y) \# both x and 10+y are broadcast
         >>> a = np.array([[0, 1, 2],
                             [0, 2, 4],
          . . .
                             [0, 3, 6]])
          . . .
          >>> np.where(a < 4, a, -1) \# -1 is broadcast
         Class docstring:
          Class to wrap functions with checks for <u>array function</u> overrides.
          All arguments are required, and can only be passed by position.
          Parameters
          dispatcher : function or None
              The dispatcher function that returns a single sequence-like object
              of all arguments relevant. It must have the same signature (except
              the default values) as the actual implementation. If ``None``, this is a ``like=`` dispatcher and the
              first (additional and positional) argument.
          implementation : function
             Function that implements the operation on NumPy arrays without overrides. Arguments passed calling the ``_ArrayFunctionDispatcher`` will be forwarded to this (and the ``dispatcher``) as if using
               `*args, **kwargs``
          Attributes
          implementation : function
             The original implementation passed in.
In [94]: arr=np.random.randn(5)
          print(arr)
          print(np.where(arr>0,2,-3))
          print(np.where(arr>0,2,arr))
          [ 1.03518014  0.26568722  0.3583539  0.15972404 -2.25755302]
          [ 2 2 2 2 -3]
          [ 2.
                                                             -2.25755302]
In [95]: arr = np.array([[1,2,3],[4,5,6]])
Out[95]: array([[1, 2, 3],
                 [4, 5, 6]])
In [96]: arr.mean() # mean of all elements
Out[96]: np.float64(3.5)
In [97]: arr.mean(axis=0) # mean of each column
Out[97]: array([2.5, 3.5, 4.5])
In [98]: arr.mean(axis=1) # mean of each row
Out[98]: array([2., 5.])
In [99]: np.mean(arr)
Out[99]: np.float64(3.5)
In [100... np.mean(arr,axis=0)
Out[100]: array([2.5, 3.5, 4.5])
In [101... np.mean(arr,axis=1)
Out[101]: array([2., 5.])
In [102... arr.cumsum(axis=0)
```

```
Out[102]: array([[1, 2, 3],
                  [5, 7, 9]])
         arr.cumsum(axis=1)
In [103...
          array([[ 1, 3, 6],
Out[103]:
                  [ 4, 9, 15]])
In [104...
          arr.cumsum()
          array([ 1, 3, 6, 10, 15, 21])
Out[104]:
In [105...
          arr.cumprod()
                              6, 24, 120, 720])
          array([ 1,
Out[105]:
In [106...
         arr.cumprod(axis=0)
          array([[ 1, 2, 3],
       [ 4, 10, 18]])
Out[106]:
In [107... arr.cumprod(axis=1)
          array([[ 1,
                        2,
Out[107]:
                  [ 4, 20, 120]])
          Method --> Description
          sum --> Sum of all the elements in the array or along an axis; zero-length arrays have sum 0
          mean --> Arithmetic mean; zero-length arrays have NaN mean
          std, var --> Standard deviation and variance, respectively, with optional degrees of freedom adjustment (default
          denominator n)
          min, max --> Minimum and maximum
          argmin, argmax --> Indices of minimum and maximum elements, respectively
          cumsum --> Cumulative sum of elements starting from 0
          cumprod --> Cumulative product of elements starting from 1
In [108... arr=np.array([])
          arr.mean()
          /tmp/ipykernel_12714/1578359007.py:2: RuntimeWarning: Mean of empty slice.
           arr.mean()
          /home/ankit/Desktop/ml/InterviewPreparation/AI-ML-DS/practice env/lib/python3.10/site-packages/numpy/ core/ met
          hods.py:145: RuntimeWarning: invalid value encountered in scalar divide
           ret = ret.dtype.type(ret / rcount)
          np.float64(nan)
Out[108]:
In [109...
         np.sum((1,2))
          np.int64(3)
Out[109]:
         np.sum([-1,3])
In [110...
          np.int64(2)
Out[110]:
In [111     np.std([[1,2],[4,3]])
Out[111]: np.float64(1.118033988749895)
In [112... np.std?
          Signature:
          np.std(
              axis=None,
              dtype=None,
              out=None,
              ddof=0,
              keepdims=<no value>,
              where=<no value>,
              mean=<no value>,
              correction=<no value>,
          Call signature: np.std(*args, **kwargs)
          Type:
                           ArrayFunctionDispatcher
          String form:
                           <function std at 0x7ec3b85b27a0>
          File:
                           ~/Desktop/ml/InterviewPreparation/AI-ML-DS/practice_env/lib/python3.10/site-packages/numpy/_co
          re/fromnumeric.py
          Docstring:
          Compute the standard deviation along the specified axis.
          Returns the standard deviation, a measure of the spread of a distribution,
```

```
of the array elements. The standard deviation is computed for the
flattened array by default, otherwise over the specified axis.
Parameters
a: array_like
    Calculate the standard deviation of these values.
axis : None or int or tuple of ints, optional
    Axis or axes along which the standard deviation is computed. The
    default is to compute the standard deviation of the flattened array.
    If this is a tuple of ints, a standard deviation is performed over
    multiple axes, instead of a single axis or all the axes as before.
dtype : dtype, optional
    Type to use in computing the standard deviation. For arrays of
    integer type the default is float64, for arrays of float types it is
    the same as the array type.
out : ndarray, optional
    Alternative output array in which to place the result. It must have
    the same shape as the expected output but the type (of the calculated
    values) will be cast if necessary.
    See :ref:`ufuncs-output-type` for more details.
ddof : {int, float}, optional
    Means Delta Degrees of Freedom. The divisor used in calculations is ``N - ddof``, where ``N`` represents the number of elements.

By default `ddof` is zero. See Notes for details about use of `ddof`.
keepdims : bool, optional
    If this is set to True, the axes which are reduced are left
    in the result as dimensions with size one. With this option,
    the result will broadcast correctly against the input array.
    If the default value is passed, then `keepdims` will not be
    passed through to the `std` method of sub-classes of
    `ndarray`, however any non-default value will be. If the sub-class' method does not implement `keepdims` any
    exceptions will be raised.
where : array_like of bool, optional
Elements to include in the standard deviation.
    See `~numpy.ufunc.reduce` for details.
    .. versionadded:: 1.20.0
mean : array_like, optional
    Provide the mean to prevent its recalculation. The mean should have
    a shape as if it was calculated with ``keepdims=True``.
    The axis for the calculation of the mean should be the same as used in
    the call to this std function.
    .. versionadded:: 2.0.0
correction : {int, float}, optional
    Array API compatible name for the ``ddof`` parameter. Only one of them
    can be provided at the same time.
    .. versionadded:: 2.0.0
Returns
standard_deviation : ndarray, see dtype parameter above.
    If `out` is None, return a new array containing the standard deviation,
    otherwise return a reference to the output array.
See Also
var, mean, nanmean, nanstd, nanvar
:ref:`ufuncs-output-type`
There are several common variants of the array standard deviation
calculation. Assuming the input `a` is a one-dimensional NumPy array
and ``mean`` is either provided as an argument or computed as ``a.mean()``, NumPy computes the standard deviation of an array as::
    d2 = abs(a - mean)**2 # abs is for complex `a`
    var = d2.sum() / (N - ddof) # note use of `ddof`
    std = var**0.5
Different values of the argument `ddof` are useful in different
contexts. NumPy's default ``ddof=0`` corresponds with the expression:
.. math::
    \ \frac{\sum_i{|a_i - bar{a}|^2 }}{N}}
which is sometimes called the "population standard deviation" in the field
of statistics because it applies the definition of standard deviation to
```

`a` as if `a` were a complete population of possible observations.

```
Many other libraries define the standard deviation of an array differently, e.g.:  \\
```

```
.. math::
```

```
\ \left(\frac{i}{a_i - \frac{a}{n^2}}\right)^2 }{N - 1}
```

In statistics, the resulting quantity is sometimes called the "sample standard deviation" because if `a` is a random sample from a larger population, this calculation provides the square root of an unbiased estimate of the variance of the population. The use of :math:`N-1` in the denominator is often called "Bessel's correction" because it corrects for bias (toward lower values) in the variance estimate introduced when the sample mean of `a` is used in place of the true mean of the population. The resulting estimate of the standard deviation is still biased, but less than it would have been without the correction. For this quantity, use ``ddof=1``.

Note that, for complex numbers, `std` takes the absolute value before squaring, so that the result is always real and nonnegative.

For floating-point input, the standard deviation is computed using the same precision the input has. Depending on the input data, this can cause the results to be inaccurate, especially for float32 (see example below). Specifying a higher-accuracy accumulator using the `dtype` keyword can alleviate this issue.

```
alleviate this issue.
Examples
>>> import numpy as np
>>> a = np.array([[1, 2], [3, 4]])
>>> np.std(a)
1.1180339887498949 # may vary
>>> np.std(a, axis=0)
array([1., 1.])
>>> np.std(a, axis=1)
array([0.5, 0.5])
In single precision, std() can be inaccurate:
>>> a = np.zeros((2, 512*512), dtype=np.float32)
>>> a[0, :] = 1.0
>>> a[1, :] = 0.1
>>> np.std(a)
np.float32(0.45000005)
Computing the standard deviation in float64 is more accurate:
>>> np.std(a, dtype=np.float64)
0.44999999925494177 # may vary
Specifying a where argument:
>>> a = np.array([[14, 8, 11, 10], [7, 9, 10, 11], [10, 15, 5, 10]])
>>> np.std(a)
2.614064523559687 # may vary
>>> np.std(a, where=[[True], [True], [False]])
Using the mean keyword to save computation time:
>>> import numpy as np
>>> from timeit import timeit
>>> a = np.array([[14, 8, 11, 10], [7, 9, 10, 11], [10, 15, 5, 10]])
>>> mean = np.mean(a, axis=1, keepdims=True)
>>>
>>> g = globals()
>>> n = 10000
>>> t1 = timeit("std = np.std(a, axis=1, mean=mean)", globals=g, number=n)
>>> t2 = timeit("std = np.std(a, axis=1)", globals=g, number=n)
>>> print(f'Percentage execution time saved {100*(t2-t1)/t2:.0f}%')
#doctest: +SKIP
Percentage execution time saved 30%
Class docstring:
Class to wrap functions with checks for __array_function__ overrides.
All arguments are required, and can only be passed by position.
Parameters
dispatcher : function or None
    The dispatcher function that returns a single sequence-like object
    of all arguments relevant. It must have the same signature (except
    the default values) as the actual implementation. If ``None``, this is a ``like=`` dispatcher and the
    ``_ArrayFunctionDispatcher`` must be called with ``like`` as the
    first (additional and positional) argument.
implementation : function
```

Function that implements the operation on NumPy arrays without

```
overrides. Arguments passed calling the ``_ArrayFunctionDispatcher`` will be forwarded to this (and the ``dispatcher``) as if using
                 *args, **kwargs`
          Attributes
           implementation : function
               The original implementation passed in.
In [113...
          np.min([1,4,3])
           np.int64(1)
In [114...
          np.argmax([1,4,3,5,2])
           np.int64(3)
Out[114]:
In [115... np.cumprod((7,2,-0.2))
Out[115]: array([ 7. , 14. , -2.8])
In [116...
          bools=np.array([True,False,True])
          print(bools.sum(),bools.any(),bools.all())
          2 True False
          z=np.array([[2,3,1],[6.1,2,8]])
In [117...
           array([[2. , 3. , 1. ], [6.1, 2. , 8. ]])
In [118...
          z.sort(axis=1)
          print(z)
          [[1. 2. 3.]
           [2. 6.1 8. ]]
In [119...] ints = np.array([3, 3, 3, 2, 2, 1, 1, 4, 4])
          np.unique(ints)
Out[119]: array([1, 2, 3, 4])
          NumPy is able to save and load data to and from disk either in text or binary format.
          np.save and np.load are the two workhorse functions for efficiently saving and loading array data on disk. Arrays are
          saved by default in an uncompressed raw binary format with file extension .npy
In [120...] z=np.arange(16).reshape(4,4)
          np.save('myarray',z)
          y=np.load('myarray.npy')
          [12, 13, 14, 15]])
In [121... # For multiple files:
          a=np.arange(12).reshape(2,2,3)
          b=np.arange(12).reshape(4,3)
          np.savez('myarrays.npz', x=a, y=b)
          loaded=np.load('myarrays.npz')
          loaded['x']
Out[121]: array([[[ 0, 1, 2], [ 3, 4, 5]],
                   [[ 6, 7, 8], [ 9, 10, 11]]])
```

```
[ 3, 4, 5],
[ 6, 7, 8],
[ 9, 10, 11]])
In [123... # for compressed files:
          a=np.arange(12).reshape(2,2,3)
          b=np.arange(12).reshape(4,3)
          np.savez compressed("compressed archived.npz",a=a,b=b)
          arr=np.load("compressed_archived.npz")
          print(arr['a'])
```

In [122... loaded['y']

Out[122]:

array([[0, 1, 2],

```
[[[0 1 2]
            [ 3 4 5]]
           [[6 7 8]
            [ 9 10 11]]]
In [124... print(arr['b'])
          [[01
                   2]
           [ 3
                4 51
           [6 7 8]
           [ 9 10 11]]
          Linear Algebra
In [125...
          a=np.arange(6).reshape(2,3)
          b=np.arange(6).reshape(3,2)
          print(a.dot(b))
          print(np.dot(a,b))
          print(a @ b)
          # The @ symbol (as of Python 3.5) also works as an infix operator that performs matrix multiplication
          [[10 13]
           [28 40]]
          [[10 13]
           [28 40]]
          [[10 13]
           [28 40]]
          numpy.linalg has a standard set of matrix decompositions and things like inverse and determinant. These are
          implemented under the hood via the same industry standard linear algebra libraries used in other languages like
          MATLAB and R, such as BLAS, LAPACK, or possibly (depending on your NumPy build) the proprietary Intel MKL (Math
          Kernel Library)
          diag --> Return the diagonal (or off-diagonal) elements of a square matrix as a 1D array, or convert a 1D array into a
          square matrix with zeros on the off-diagonal
          dot --> Matrix multiplication
          trace --> Compute the sum of the diagonal elements
          det --> Compute the matrix determinant
          eig --> Compute the eigenvalues and eigenvectors of a square matrix
          inv --> Compute the inverse of a square matrix
          pinv --> Compute the Moore-Penrose pseudo-inverse of a matrix
          gr --> Compute the QR decomposition
          svd --> Compute the singular value decomposition (SVD)
          solve --> Solve the linear system Ax = b for x, where A is a square matrix
          Istsq --> Compute the least-squares solution to Ax = b
In [126...
         np.linalg.inv([[1,2],[3,4]])
          array([[-2. , 1. ],
Out[126]:
                  [ 1.5, -0.5]])
In [127...
          np.linalg.det([[1,2],[3,4]])
          np.float64(-2.0000000000000000)
          np.linalg.diagonal([[1,2],[3,4]])
In [128...
          array([1, 4])
Out[128]:
In [129...
          np.diag([1,2,3,4])
          array([[1, 0, 0, 0],
Out[129]:
                  [0, 2, 0, 0],
                  [0, 0, 3, 0],
                  [0, 0, 0, 4]])
In [130...
          np.diag([[1,2],[3,4]])
           array([1, 4])
          np.trace([[1,2],[3,4]])
In [131...
           np.int64(5)
In [132...
          np.linalg.eig([[1,0],[0,1]])
          EigResult(eigenvalues=array([1., 1.]), eigenvectors=array([[1., 0.],
                  [0., 1.]]))
In [133_ np.linalg.pinv([[1,2],[3,4]])
```

```
Out[133]: array([[-2. , 1. ],
                 [ 1.5, -0.5]])
In [134_ np.linalg.pinv([[2,5,9],[4,6,5],[8,4,5]])
In [135... np.linalg.qr([[1,2],[3,4]])
          QRResult(Q=array([[-0.31622777, -0.9486833],
                 [-0.9486833, 0.31622777]]), R=array([[-3.16227766, -4.42718872], [ 0. , -0.63245553]]))
In [136... np.linalg.svd([[1,2],[3,4]])
Out[136]: SVDResult(U=array([[-0.40455358, -0.9145143],
                 [-0.9145143, 0.40455358]]), S=array([5.4649857, 0.36596619]), Vh=array([[-0.57604844, -0.81741556], [0.81741556, -0.57604844]]))
In [137... np.linalg.solve?
         Signature:
                          np.linalg.solve(a, b)
         Call signature: np.linalg.solve(*args, **kwargs)
         Type:
                          ArrayFunctionDispatcher
         String form:
                          <function solve at 0x7ec3b84a2830>
                          ~/Desktop/ml/InterviewPreparation/AI-ML-DS/practice_env/lib/python3.10/site-packages/numpy/lin
         File:
         alg/_linalg.py
         Docstring
         Solve a linear matrix equation, or system of linear scalar equations.
         Computes the "exact" solution, `x`, of the well-determined, i.e., full
         rank, linear matrix equation ax = b.
         Parameters
         a: (..., M, M) array like
             Coefficient matrix.
         b : {(M,), (..., M, K)}, array_like
    Ordinate or "dependent variable" values.
         Returns
         shape (M,) and (\dots, M, K) if b is (\dots, M, K), where the "\dots" part is
             broadcasted between a and b.
         Raises
         LinAlgError
             If `a` is singular or not square.
         See Also
         scipy.linalg.solve : Similar function in SciPy.
         Notes
         Broadcasting rules apply, see the `numpy.linalg` documentation for
         details.
         The solutions are computed using LAPACK routine `` gesv``.
         `a` must be square and of full-rank, i.e., all rows (or, equivalently,
         columns) must be linearly independent; if either is not true, use
          'lstsq' for the least-squares best "solution" of the
         system/equation.
         .. versionchanged:: 2.0
            The b array is only treated as a shape (M,) column vector if it is
            exactly 1-dimensional. In all other instances it is treated as a stack
            of (M, K) matrices. Previously b would be treated as a stack of (M,)
            vectors if b.ndim was equal to a.ndim - 1.
         References
         .. [1] G. Strang, *Linear Algebra and Its Applications*, 2nd Ed., Orlando,
                FL, Academic Press, Inc., 1980, pg. 22.
         Examples
         Solve the system of equations:
          x_0 + 2 * x_1 = 1 and
         ``3 * x0 + 5 * x1 = 2`
         >>> import numpy as np
         >>> a = np.array([[1, 2], [3, 5]])
```

```
>>> b = np.array([1, 2])
           >>> x = np.linalg.solve(a, b)
           >>> X
           array([-1., 1.])
           Check that the solution is correct:
           >>> np.allclose(np.dot(a, x), b)
           True
           Class docstring:
           Class to wrap functions with checks for <u>array function</u> overrides.
           All arguments are required, and can only be passed by position.
           Parameters
           dispatcher: function or None
               The dispatcher function that returns a single sequence-like object
               of all arguments relevant. It must have the same signature (except
               the default values) as the actual implementation.
               If ``None``, this is a ``like=`` dispatcher and the
               `` ArrayFunctionDispatcher`` must be called with ``like`` as the
               first (additional and positional) argument.
           implementation : function
               Function that implements the operation on NumPy arrays without
               overrides. Arguments passed calling the ``_ArrayFunctionDispatcher`` will be forwarded to this (and the ``dispatcher``) as if using
               will be forwarded to this (and the
                 `*arɑs. **kwarɑs`
           Attributes
           implementation : function
               The original implementation passed in.
In [138... import numpy as np
           a = np.array([[1, 2], [3, 5]])
b = np.array([1, 2])
           x = np.linalg.solve(a, b)
           Χ
Out[138]: array([-1., 1.])
In [139_ np.linalg.lstsq?
           Signature:
                              np.linalg.lstsq(a, b, rcond=None)
           Call signature: np.linalg.lstsq(*args, **kwargs)
           Type:
                              ArrayFunctionDispatcher
           String form:
                              <function lstsq at 0x7ec3b84a3a30>
           File:
                              ~/Desktop/ml/InterviewPreparation/AI-ML-DS/practice_env/lib/python3.10/site-packages/numpy/lin
           alg/ linalg.py
           Docstring:
           Return the least-squares solution to a linear matrix equation.
           Computes the vector `x` that approximately solves the equation ``a @ x = b``. The equation may be under-, well-, or over-determined
           (i.e., the number of linearly independent rows of `a` can be less than,
           equal to, or greater than its number of linearly independent columns). If `a` is square and of full rank, then `x` (but for round-off error)
           is the "exact" solution of the equation. Else, `x` minimizes the
           Euclidean 2-norm :math:`||b - ax||`. If there are multiple minimizing
           solutions, the one with the smallest 2-norm :math: `||x||` is returned.
           Parameters
           a : (M, N) array_like
    "Coefficient" matrix.
           b : {(M,), (M, K)} array_like
               Ordinate or "dependent variable" values. If `b` is two-dimensional,
               the least-squares solution is calculated for each of the \ensuremath{^{\backprime}K}\ensuremath{^{\backprime}} columns
               of `b`.
           rcond : float, optional
               Cut-off ratio for small singular values of `a`.
               For the purposes of rank determination, singular values are treated as zero if they are smaller than `rcond` times the largest singular
               value of `a`.
               The default uses the machine precision times ``max(M, N)``. Passing
                      will use machine precision.
                .. versionchanged:: 2.0
                    Previously, the default was ``-1``, but a warning was given that
                    this would change.
           Returns
           x : \{(N,), (N, K)\} ndarray
               Least-squares solution. If `b` is two-dimensional,
               the solutions are in the \K columns of \x.
           residuals : \{(1,), (K,), (0,)\} ndarray
```

```
`b - a @ x`
               If the rank of `a` is < N or M <= N, this is an empty array.
               If `b` is 1-dimensional, this is a (1,) shape array.
               Otherwise the shape is (K,).
          rank : int
              Rank of matrix `a`.
          s : (min(M, N),) ndarray
               Singular values of `a`.
          Raises
          LinAlgError
              If computation does not converge.
          See Also
          scipy.linalq.lstsq : Similar function in SciPy.
          Notes
          If `b` is a matrix, then all array results are returned as matrices.
          Examples
          Fit a line, ``y = mx + c``, through some noisy data-points:
          >>> import numpy as np
          >>> x = np.array([0, 1, 2, 3])
          >>> y = np.array([-1, 0.2, 0.9, 2.1])
          By examining the coefficients, we see that the line should have a
          gradient of roughly 1 and cut the y-axis at, more or less, -1.
          We can rewrite the line equation as ``y = Ap``, where ``A = [[x 1]]``
          and ``p = [[m], [c]]``. Now use `lstsq` to solve for `p`:
          >>> A = np.vstack([x, np.ones(len(x))]).T
          >>> A
          array([[ 0., 1.],
                  [ 1., 1.],
[ 2., 1.],
[ 3., 1.]])
          >>> m, c = np.linalg.lstsq(A, y)[0]
          >>> m, c
          (1.0 - 0.95) # may vary
          Plot the data along with the fitted line:
          >>> import matplotlib.pyplot as plt
          >>> _ = plt.plot(x, y, 'o', label='Original data', markersize=10)
          >>> _ = plt.plot(x, m*x + c, 'r', label='Fitted line')
                = plt.legend()
          >>>
          >>> plt.show()
          Class docstring
          Class to wrap functions with checks for array function overrides.
          All arguments are required, and can only be passed by position.
          Parameters
          dispatcher : function or None
               The dispatcher function that returns a single sequence-like object
               of all arguments relevant. It must have the same signature (except
               the default values) as the actual implementation. If ``None``, this is a ``like=`` dispatcher and the
               ``_ArrayFunctionDispatcher`` must be called with ``like`` as the
               first (additional and positional) argument.
          implementation : function
              Function that implements the operation on NumPy arrays without overrides. Arguments passed calling the ``_ArrayFunctionDispatcher`` will be forwarded to this (and the ``dispatcher``) as if using
                `*args, **kwargs``.
          Attributes
          _implementation : function
              The original implementation passed in.
In [140... x = np.array([0, 1, 2, 3])

y = np.array([-1, 0.2, 0.9, 2.1])
In [141...] A = np.vstack([x, np.ones(len(x))]).T
```

Sums of squared residuals: Squared Euclidean 2-norm for each column in

```
Out[141]: array([[0., 1.],
                 [1., 1.],
                  [2., 1.],
                 [3., 1.]])
In [142... m, c = np.linalg.lstsq(A, y)[0]
Out[142]: (np.float64(0.9999999999999), np.float64(-0.9499999999999))
In [143... from numpy.linalg import inv,qr,svd
         import scipv.linala
         u=np.arange(1,6,1).reshape(5,1)
         M=u.dot(u.T)
         #print("Inverse of M is: ", inv(M)) # M is singular, so inverse does not exist
         #print("matrix q (orthonormal matrix) in qr decomposition is:\n\n",q)
         \#print("\n\nmatrix r (upper triangular) in qr decomposition is:\n\n",r)
         P,L,U=scipy.linalg.lu(M)
         #print("\n\nmatrix P in LU decomposition is:\n\n",P)
         #print("\n\nmatrix L in LU decomposition is:\n\n",L)
         #print("\n\n matrix U in LU decomposition is:\n\n",U)
         U,Sigma,V_transpose=svd(M)
         print("Sum of Singular Values of M is: ", np.sum(Sigma))
         Sum of Singular Values of M is: 55.000000000000001
```

Pseudorandom Number Generation:

The numpy.random module supplements the built-in Python random with functions for efficiently generating whole arrays of sample values from many kinds of probability distributions.

For example, you can get a 4×4 array of samples from the standard normal distribution using normal:

We say that these are pseudorandom numbers because they are generated by an algorithm with deterministic behavior based on the seed of the random number generator. You can change NumPy's random number generation seed using np.random.seed:

Seed is a global pseudo-random generator. However, randomstate is a pseudo-random generator isolated from others, which only impact specific variable.

```
In [145... rng = np.random.RandomState(21212)
         rnq.rand(4)
Out[145]: array([0.8394647 , 0.6312553 , 0.14601055, 0.33653325])
In [146... rng = np.random.RandomState(21212)
         rnq.rand(4)
Out[146]: array([0.8394647 , 0.6312553 , 0.14601055, 0.33653325])
In [147...
         np.random.seed(2)
         np.random.rand(4)
Out[147]: array([0.4359949 , 0.02592623, 0.54966248, 0.43532239])
In [148... np.random.seed(2)
         np.random.rand(4)
Out[148]: array([0.4359949 , 0.02592623, 0.54966248, 0.43532239])
In [149... | np.random.seed(2)
         np.random.rand(4)
Out[149]: array([0.4359949 , 0.02592623, 0.54966248, 0.43532239])
In [150...
         np.random.seed(20)
         np.random.rand(4)
Out[150]: array([0.5881308 , 0.89771373, 0.89153073, 0.81583748])
```

By specifying a seed value, the function ensures that the sequence of random numbers generated remains the same

```
across multiple runs, providing deterministic behavior and allowing reproducibility in random number generation.
In [151...
               in range(3):
             np.random.seed(1)
             s=np.random.normal(size=(2,2))
             print(s)
         [[ 1.62434536 -0.61175641]
          [-0.52817175 -1.07296862]]
         [[ 1.62434536 -0.61175641]
          [-0.52817175 -1.07296862]]
         [[ 1.62434536 -0.61175641]
          [-0.52817175 -1.07296862]]
In [152...
         # random walk
         a=np.random.randint(0,2,size=100)
         a=np.where(a>0,1,-1)
         walk=a.cumsum()
         import matplotlib.pyplot as plt
         plt.plot(walk)
          [<matplotlib.lines.Line2D at 0x7ec385e01570>]
          10.0
            7.5
            5.0
            2.5
            0.0
          -2.5
          -5.0
          -7.5
                  0
                             20
                                                     60
                                                                80
                                                                            100
                                         40
          (np.abs(walk)>10).argmax() # finding the index where walk array has aboslute value 10 "first" time
In [153...
          np.int64(98)
         arr=np.array([1,2,3,4,5,6,7])
In [154...
         print((arr>3),(arr>3).argmax())
         [False False True True True] 3
         The numpy.argmax() function returns indices of the max element of the array in a particular axis.
         np.argmax(np.array([[1,2,5],[5,-1,3]]),axis=0)
In [155...
          array([1, 0, 0])
Out[155]:
        np.random.normal(loc=0, scale=0.25, size=10)
In [156...
seed --> Seed the random number generator
         permutation --> Return a random permutation of a sequence, or return a permuted range
         shuffle --> Randomly permute a sequence in-place
         rand --> Draw samples from a uniform distribution
         randint --> Draw random integers from a given low-to-high range
         randn --> Draw samples from a normal distribution with mean 0 and standard deviation 1 (MATLAB-like interface)
         binomial --> Draw samples from a binomial distribution
         normal --> Draw samples from a normal (Gaussian) distribution
         beta --> Draw samples from a beta distribution
         chisquare --> Draw samples from a chi-square distribution
         gamma --> Draw samples from a gamma distribution
         uniform --> Draw samples from a uniform [0, 1) distribution
```

```
In [157... np.random.seed(42)
        np.random.normal(loc=0, scale=0.25, size=10)
In [158... np.random.permutation(10)
Out[158]: array([6, 2, 8, 7, 9, 5, 1, 3, 0, 4])
In [159... np.random.permutation(10)
Out[159]: array([1, 5, 4, 8, 0, 7, 6, 3, 2, 9])
In [160... np.random.permutation([1,4,9,2,3])
Out[160]: array([2, 4, 9, 1, 3])
In [161... np.random.rand(10)
Out[161]: array([0.94888554, 0.96563203, 0.80839735, 0.30461377, 0.09767211,
               0.68423303, 0.44015249, 0.12203823, 0.49517691, 0.03438852])
In [162... | np.random.randint(1,10)
Out[162]:
In [163... np.random.randint(1,10)
In [164… np.random.randn(10)
In [165... np.random.binomial(10,0.5)
Out[165]: 6
In [166... np.random.normal(loc=0, scale=0.25, size=10)
In [167_ np.random.chisquare( df=2, size=10 )
Out[167]: array([0.64592551, 0.702731 , 0.36128659, 0.03151989, 1.10121812, 1.004662 , 0.69483068, 0.02835977, 0.4433952 , 2.48502504])
In [168_ np.random.beta( a=2.0, b=5.0, size=10 )
Out[168]: array([0.22588393, 0.14591485, 0.25349367, 0.3210881 , 0.21662123,
               0.33971623, 0.73947947, 0.20968991, 0.41613936, 0.19876706])
In [169_ np.random.gamma( shape=2.0, scale=1.0, size=10 )
Out[169]: array([3.24391604, 1.41034735, 2.78711088, 1.35780113, 0.7766732
               1.09442459, 0.61419599, 3.14875069, 2.08672276, 0.40380842])
In [170... np.random.uniform( low=0.0, high=1.0, size=10 )
Out[170]: array([0.25391541, 0.24687606, 0.69630427, 0.71227059, 0.14808693,
               0.99774049, 0.26678101, 0.97661496, 0.41103701, 0.03305073])
 In [ ]:
```