# Chapter\_5\_Resampling\_Methods

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## 0.1 Lab: Cross-Validation and the Bootstrap

In this lab, we explore the resampling techniques covered in this chapter. Some of the commands in this lab may take a while to run on your computer.

We again begin by placing most of our imports at this top level.

```
[2]: import numpy as np
import statsmodels.api as sm
from ISLP import load_data
from ISLP.models import (ModelSpec as MS, summarize, poly)
from sklearn.model_selection import train_test_split
```

There are several new imports needed for this lab.

```
[3]: from functools import partial from sklearn.model_selection import (cross_validate, KFold, ShuffleSplit) from sklearn.base import clone from ISLP.models import sklearn_sm
```

## 0.2 5.3.1 The Validation Set Approach

We explore the use of the validation set approach in order to estimate the test error rates that result from fitting various linear models on the Auto data set.

We use the function train\_test\_split() to split the data into training and validation sets. As there are 392 observations, we split into two equal sets of size 196 using the argument test\_size=196. It is generally a good idea to set a random seed when performing operations like this that contain an element of randomness, so that the results obtained can be reproduced precisely at a later time. We set the random seed of the splitter with the argument random state=0.

```
[4]: Auto = load_data('Auto')
Auto_train, Auto_valid = train_test_split(Auto,test_size=196,random_state=0)
```

Now we can ft a linear regression using only the observations corresponding to the training set Auto\_train.

```
[5]: hp_mm = MS(['horsepower'])
X_train = hp_mm.fit_transform(Auto_train)
y_train = Auto_train['mpg']
model = sm.OLS(y_train, X_train)
```

```
results = model.fit()
```

We now use the predict() method of results evaluated on the model matrix for this model created using the validation data set. We also calculate the validation MSE of our model.

```
[6]: X_valid = hp_mm.transform(Auto_valid)
y_valid = Auto_valid['mpg']
valid_pred = results.predict(X_valid)
np.mean((y_valid - valid_pred)**2)
```

#### [6]: 23.61661706966988

Hence our estimate for the validation MSE of the linear regression ft is 23.62.

We can also estimate the validation error for higher-degree polynomial regressions. We first provide a function evalMSE() that takes a model string as well as a training and test set and returns the MSE on the test set.

Let's use this function to estimate the validation MSE using linear, quadratic and cubic fts. We use the enumerate() function here, which gives both the values and indices of objects as one iterates over a for loop.

```
[8]: MSE = np.zeros(3)
    for idx, degree in enumerate(range(1, 4)):
        MSE[idx] = evalMSE([poly('horsepower', degree)], 'mpg', Auto_train, Auto_valid)
        MSE
```

[8]: array([23.61661707, 18.76303135, 18.79694163])

These error rates are 23.62, 18.76, and 18.80, respectively. If we choose a different training/validation split instead, then we can expect somewhat different errors on the validation set.

```
[9]: Auto_train, Auto_valid = train_test_split(Auto,test_size=196,random_state=3)
    MSE = np.zeros(3)
    for idx, degree in enumerate(range(1, 4)):
        MSE[idx] = evalMSE([poly('horsepower', degree)],'mpg',Auto_train,Auto_valid)
    MSE
```

[9]: array([20.75540796, 16.94510676, 16.97437833])

Using this split of the observations into a training set and a validation set, we find that the validation set error rates for the models with linear, quadratic, and cubic terms are 20.76, 16.95, and 16.97, respectively.

These results are consistent with our previous findings: a model that predicts mpg using a quadratic function of horsepower performs better than a model that involves only a linear function of horsepower, and there is no evidence of an improvement in using a cubic function of horsepower.

#### 0.3 5.3.2 Cross-Validation

In theory, the cross-validation estimate can be computed for any generalized linear model. In practice, however, the simplest way to cross-validate in Python is to use sklearn, which has a different interface or API than statsmodels, the code we have been using to ft GLMs.

This is a problem which often confronts data scientists: "I have a function to do task A, and need to feed it into something that performs task B, so that I can compute B(A(D)), where D is my data." When A and B don't naturally speak to each other, this requires the use of a wrapper.

In the ISLP wrapper package, we provide a wrapper, sklearn\_sm(), that enables us to easily use the cross-validation tools of sklearn with models ft by statsmodels.

The class sklearn\_sm() has as its frst argument a model from statsmodels. It can take two additional optional arguments: model\_str which can be used to specify a formula, and model\_args which should be a dictionary of additional arguments used when ftting the model. For example, to ft a logistic regression model we have to specify a family argument. This is passed as model\_args={'family':sm.families.Binomial()}.

Here is our wrapper in action

```
[10]: hp_model = sklearn_sm(sm.OLS,MS(['horsepower']))
X, Y = Auto.drop(columns=['mpg']), Auto['mpg']
cv_results = cross_validate(hp_model,X,Y,cv=Auto.shape[0])
cv_err = np.mean(cv_results['test_score'])
cv_err
```

## [10]: 24.231513517929212

The arguments to cross\_validate() are as follows: an object with the appropriate fit(), predict(), and score() methods, an array of features X and a response Y. We also included an additional argument cv to cross\_validate(); specifying an integer K results in K-fold cross-validation. We have provided a value corresponding to the total number of observations, which results in leave-one-out cross-validation (LOOCV). The cross\_validate() function produces a dictionary with several components; we simply want the cross-validated test score here (MSE), which is estimated to be 24.23.

We can repeat this procedure for increasingly complex polynomial fts. To automate the process, we again use a for loop which iteratively fts polynomial regressions of degree 1 to 5, computes the associated crossvalidation error, and stores it in the ith element of the vector cv\_error. The variable d in the for loop corresponds to the degree of the polynomial. We begin by initializing the vector. This command may take a couple of seconds to run.

[11]: array([24.23151352, 19.24821312, 19.33498406, 19.42443031, 19.03320428])

As in Figure 5.4, we see a sharp drop in the estimated test MSE between the linear and quadratic fts, but then no clear improvement from using higher-degree polynomials.

Above we introduced the outer() method of the np.power() function. .outer() np.power() The outer() method is applied to an operation that has two arguments, such as add(), min(), or power(). It has two arrays as arguments, and then forms a larger array where the operation is applied to each pair of elements of the two arrays.

```
[12]: A = np.array([3, 5, 9])
B = np.array([2, 4])
np.add.outer(A, B)
```

In the CV example above, we used K = n, but of course we can also use K < n. The code is very similar to the above (and is significantly faster). Here we use KFold() to partition the data into K = 10 random groups. We use random\_state to set a random seed and initialize a vector cv\_error in which we will store the CV errors corresponding to the polynomial fts of degrees one to fve.

[13]: array([24.20766449, 19.18533142, 19.27626666, 19.47848404, 19.13722016])

Notice that the computation time is much shorter than that of LOOCV. (In principle, the computation time for LOOCV for a least squares linear model should be faster than for K-fold CV, due to the availability of the formula (5.2) for LOOCV; however, the generic cross\_validate() function does not make use of this formula.) We still see little evidence that using cubic or higher-degree polynomial terms leads to a lower test error than simply using a quadratic ft.

The cross validate() function is fexible and can take different splitting mechanisms as an argument.

For instance, one can use the ShuffleSplit() funtion to implement the validation set approach just as easily as K-fold cross-validation.

[15]: (23.802232661034164, 1.4218450941091847)

Note that this standard deviation is not a valid estimate of the sampling variability of the mean test score or the individual scores, since the randomly-selected training samples overlap and hence introduce correlations. But it does give an idea of the Monte Carlo variation incurred by picking different random folds.

## 0.4 5.3.3 The Bootstrap

We illustrate the use of the bootstrap in the simple example of Section 5.2, as well as on an example involving estimating the accuracy of the linear regression model on the Auto data set.

#### 0.5 Estimating the Accuracy of a Statistic of Interest

One of the great advantages of the bootstrap approach is that it can be applied in almost all situations. No complicated mathematical calculations are required. While there are several implementations of the bootstrap in Python, its use for estimating standard error is simple enough that we write our own function below for the case when our data is stored in a dataframe.

To illustrate the bootstrap, we start with a simple example. The Portfolio data set in the ISLP package is described in Section 5.2. The goal is to estimate the sampling variance of the parameter given in formula (5.7). We will create a function alpha\_func(), which takes as input a dataframe D assumed to have columns X and Y, as well as a vector idx indicating which observations should be used to estimate . The function then outputs the estimate for based on the selected observations.

```
[16]: Portfolio = load_data('Portfolio')
def alpha_func(D, idx):
    cov_ = np.cov(D[['X','Y']].loc[idx], rowvar=False)
    return ((cov_[1,1] - cov_[0,1]) /(cov_[0,0]+cov_[1,1]-2*cov_[0,1]))
```

This function returns an estimate for based on applying the minimum variance formula (5.7) to the observations indexed by the argument idx. For instance, the following command estimates using all 100 observations.

```
[17]: alpha_func(Portfolio, range(100))
```

#### [17]: 0.57583207459283

Next we randomly select 100 observations from range(100), with replacement. This is equivalent to constructing a new bootstrap data set and recomputing ^ based on the new data set.

```
[18]: rng = np.random.default_rng(0)
alpha_func(Portfolio,rng.choice(100,100,replace=True))
```

#### [18]: 0.6074452469619004

This process can be generalized to create a simple function boot\_SE() for computing the bootstrap standard error for arbitrary functions that take only a data frame as an argument.

```
[19]: def boot_SE(func,D,n=None,B=1000,seed=0):
    rng = np.random.default_rng(seed)
    first_, second_ = 0, 0
    n = n or D.shape[0]
    for _ in range(B):
        idx = rng.choice(D.index,n,replace=True)
        value = func(D, idx)
        first_ += value
        second_ += value**2
    return np.sqrt(second_ / B - (first_ / B)**2)
```

Notice the use of \_ as a loop variable in for \_ in range(B). This is often used if the value of the counter is unimportant and simply makes sure the loop is executed B times.

Let's use our function to evaluate the accuracy of our estimate of using B = 1,000 bootstrap replications.

```
[20]: alpha_SE = boot_SE(alpha_func,Portfolio,B=1000,seed=0) alpha_SE
```

## [20]: 0.09118176521277699

The final output shows that the bootstrap estimate for SE(^) is 0.0912.

## 0.6 Estimating the Accuracy of a Linear Regression Model

The bootstrap approach can be used to assess the variability of the coeffcient estimates and predictions from a statistical learning method. Here we use the bootstrap approach in order to assess the variability of the estimates for 0 and 1, the intercept and slope terms for the linear regression model that uses horsepower to predict mpg in the Auto data set. We will compare the estimates obtained using the bootstrap to those obtained using the formulas for SE( $^{\circ}0$ ) and SE( $^{\circ}1$ ) described in Section 3.1.2.

To use our boot\_SE() function, we must write a function (its frst argument) that takes a data frame D and indices idx as its only arguments. But here we want to bootstrap a specific regression model, specified by a model formula and data. We show how to do this in a few simple steps.

We start by writing a generic function boot\_OLS() for bootstrapping a regression model that takes a formula to define the corresponding regression. We use the clone() function to make a copy of the

formula that can clone() be reft to the new dataframe. This means that any derived features such as those defined by poly() (which we will see shortly), will be re-ft on the resampled data frame.

```
[21]: def boot_OLS(model_matrix, response, D, idx):
    D_ = D.loc[idx]
    Y_ = D_[response]
    X_ = clone(model_matrix).fit_transform(D_)
    return sm.OLS(Y_, X_).fit().params
```

This is not quite what is needed as the frst argument to boot\_SE(). The frst two arguments which specify the model will not change in the bootstrap process, and we would like to freeze them. The function partial() from the functools module does precisely this: it takes a function as an argument, and freezes some of its arguments, starting from the left. We use it to freeze the frst two model-formula arguments of boot OLS().

```
[22]: hp_func = partial(boot_OLS, MS(['horsepower']), 'mpg')
```

Typing hp\_func? will show that it has two arguments D and idx — it is a version of boot\_OLS() with the first two arguments frozen — and hence is ideal as the first argument for boot\_SE().

The hp\_func() function can now be used in order to create bootstrap estimates for the intercept and slope terms by randomly sampling from among the observations with replacement. We first demonstrate its utility on 10 bootstrap samples

```
[23]: rng = np.random.default_rng(0)
np.array([hp_func(Auto,rng.choice(392,392,replace=True)) for _ in range(10)])

[23]: array([[39.88064456, -0.1567849],
```

Next, we use the boot\_SE() function to compute the standard errors of 1,000 bootstrap estimates for the intercept and slope terms.

```
[24]: hp_se = boot_SE(hp_func,Auto,B=1000,seed=10)
hp_se
```

```
[24]: intercept 0.848807
horsepower 0.007352
dtype: float64
```

This indicates that the bootstrap estimate for SE(^0) is 0.85, and that the bootstrap estimate for SE(^1) is 0.0074. As discussed in Section 3.1.2, standard formulas can be used to compute the

standard errors for the regression coefcients in a linear model. These can be obtained using the summarize() function from ISLP.sm.

```
[25]: hp_model.fit(Auto, Auto['mpg'])
model_se = summarize(hp_model.results_)['std err']
model_se
```

[25]: intercept 0.717 horsepower 0.006

Name: std err, dtype: float64

The standard error estimates for ^0 and ^1 obtained using the formulas from Section 3.1.2 are 0.717 for the intercept and 0.006 for the slope. Interestingly, these are somewhat different from the estimates obtained using the bootstrap. Does this indicate a problem with the bootstrap? In fact, it suggests the opposite. Recall that the standard formulas given in Equation 3.8 on page 75 rely on certain assumptions. For example, they depend on the unknown parameter 2, the noise variance. We then estimate 2 using the RSS. Now although the formula for the standard errors do not rely on the linear model being correct, the estimate for 2 does. We see in Figure 3.8 on page 99 that there is a non-linear relationship in the data, and so the residuals from a linear ft will be infated, and so will ^2. Secondly, the standard formulas assume (somewhat unrealistically) that the xi are fxed, and all the variability comes from the variation in the errors "i. The bootstrap approach does not rely on any of these assumptions, and so it is likely giving a more accurate estimate of the standard errors of ^0 and ^1 than the results from sm.OLS.

Below we compute the bootstrap standard error estimates and the standard linear regression estimates that result from fitting the quadratic model to the data. Since this model provides a good ft to the data (Figure 3.8), there is now a better correspondence between the bootstrap estimates and the standard estimates of  $SE(^0)$ ,  $SE(^1)$  and  $SE(^2)$ .

```
[26]: quad_model = MS([poly('horsepower', 2, raw=True)])
   quad_func = partial(boot_OLS,quad_model,'mpg')
   boot_SE(quad_func, Auto, B=1000)
```

We compare the results to the standard errors computed using sm.OLS().

```
[27]: M = sm.OLS(Auto['mpg'],quad_model.fit_transform(Auto))
summarize(M.fit())['std err']
```

```
[27]: intercept 1.800
poly(horsepower, degree=2, raw=True)[0] 0.031
poly(horsepower, degree=2, raw=True)[1] 0.000
Name: std err, dtype: float64
```

```
[]:
```