

```
In [1]: 1 # For this task, again consider, dependent variable is "Price of the flat (
2 # i.e "Size of the flat in square ft(x)" & "number of bedrooms in the flat(
3 # let  $z = ax+by+c$  is a hyperplane which is nearest to the points given in t
4 # Here, I will use gradient descent method
5 # I will consider the sum of squared error function as loss function to cal
```

```
In [2]: 1 #Importing libraries
2 import numpy as np
```

```
In [3]: 1 dataset = [[1600,3,8.2],
2             [1260,2,6.6],
3             [1800,4,10.3],
4             [600,1,1.7],
5             [850,2,3.6],
6             [920,2,4.4],
7             [1090,2,5.4],
8             [890,2,4.8],
9             [1340,3,10.5],
10            [1650,2,7.4]]
11 # For each sublist of list dataset, 1st entry shows x value, 2nd entry show
```

```
In [4]: 1 #To take separate values of both features in lists x and y
2 x1=[]
3 y1=[]
4 z1=[]
5 for i in range(10):
6     x1.append(dataset[i][0])
7 for i in range(10):
8     y1.append(dataset[i][1])
9 for i in range(10):
10     z1.append(dataset[i][2])
11
12 # To normalize the data to put it on same scale
13 norm = np.linalg.norm(x1)
14 x=x1/norm
15 norm1 = np.linalg.norm(y1)
16 y=y1/norm1
17 norm2 = np.linalg.norm(z1)
18 z=z1/norm2
19
20
21
22 print(x)
23 print(y)
24 print(z) #actual value of z in  $Z=ax+by + c$ 
```

[0.40233529 0.31683904 0.4526272 0.15087573 0.21374062 0.23134279  
0.27409092 0.22379901 0.33695581 0.41490827]  
[0.39056673 0.26037782 0.52075564 0.13018891 0.26037782 0.26037782  
0.26037782 0.26037782 0.39056673 0.26037782]  
[0.37851574 0.30465901 0.4754527 0.07847278 0.16617764 0.20310601  
0.24926647 0.22157019 0.48468479 0.34158738]

```
In [5]: 1 # Applying Gradient Descent algorithm
2
3 a=0.45
4 b=0.35
5 c=0.33 # initializing unknown parameters which we have to find with some ra
6
7 l = 0.001 # assigning learning rate as 0.0001 for good accuracy
8
9 iterations = 1000 # initializaing number of iterations
10
11 n= 10 # total number of datapoints
12
```

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13 # Here, error function is sum of squared error function which is  $E = 1/2 \sum (z[i] - z_{pred})^2$ 
14 # where  $z_{pred}$  is  $ax_i + by_i + c$ 
15
16
17
18
19 for p in range(iterations):
20     sum1=0
21     D_a=0
22     D_b=0
23     D_c=0
24     for i in range(10):
25         z_pred = a*x[i]+b*y[i]+c
26         #print(z_pred)
27         sum1 += (z[i]-z_pred)**2 # Calculating total sum of squared error(s)
28         #print(sum1)
29     sse = sum1/2
30     #print(sse)
31     if sse < 0.02: # considering 0.02 is close to zero
32         break
33     for i in range(10):
34         z_pred = a*x[i]+b*y[i]+c
35         #print(z_pred)
36         D_a += (-1)*x[i]*(z[i] - z_pred) #partial derivative of error fu
37         #print(D_a)
38         D_b += (-1)*y[i]*(z[i] - z_pred) #partial derivative of error fu
39         #print(D_b)
40         D_c += (-1)*(z[i] - z_pred) #partial derivative of error fu
41         #print(D_c)
42
43     # Adjust the weights with the gradients to reach the optimal values whe
44
45     a = a - l*D_a
46     b = b - l*D_b
47     c = c - l*D_c
48     #print(a,b,c)
49     # we will use these updated value for next iteration and we do this unt
50     print("At iteration %d, The value of sse is: %2.5f " %(p,sse))
51 print("final sum of squared error using gradient descent : ", sse)
52 print("Final values of a,b,c are: ", a,b,c)

```

At iteration 0, The value of sse is: 0.41189  
 At iteration 1, The value of sse is: 0.40280  
 At iteration 2, The value of sse is: 0.39393  
 At iteration 3, The value of sse is: 0.38526  
 At iteration 4, The value of sse is: 0.37680  
 At iteration 5, The value of sse is: 0.36854  
 At iteration 6, The value of sse is: 0.36047  
 At iteration 7, The value of sse is: 0.35259  
 At iteration 8, The value of sse is: 0.34490  
 At iteration 9, The value of sse is: 0.33739  
 At iteration 10, The value of sse is: 0.33005  
 At iteration 11, The value of sse is: 0.32289  
 At iteration 12, The value of sse is: 0.31590  
 At iteration 13, The value of sse is: 0.30907  
 At iteration 14, The value of sse is: 0.30240  
 At iteration 15, The value of sse is: 0.29588  
 At iteration 16, The value of sse is: 0.28952  
 At iteration 17, The value of sse is: 0.28331  
 At iteration 18, The value of sse is: 0.27725  
 At iteration 19, The value of sse is: 0.27133

```

In [6]: 1 print("final sum of squared error using gradient descent : ", sse)
        2 print("Final values of a,b,c are: ", a,b,c)

```

```

final sum of squared error using gradient descent : 0.021821776978798908
Final values of a,b,c are: 0.4171638121446569 0.32211296484688473 0.0703519441
3069641

```

As we can see here, after each iteration, value of sse(sum of squared error)

is decreasing and converging to zero.

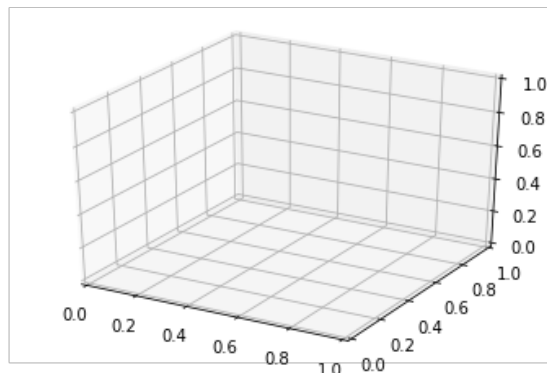
After 1000 iteration, values of a,b and c are 0.4171638121446569  
0.32211296484688473 0.07035194413069641

**So, by using Gradient Descent, Best fit hyperplane for given data is  $z=0.41x + 0.32y + 0.07$  for normalized data. If data is not normalized then it would be different because after normalization, data points will be in range 0 to 1.**

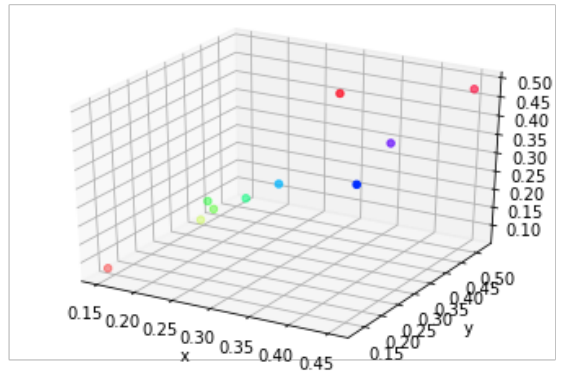
## Task 2.2.c

```
In [7]: 1 #Now we will plot the 3d points for the given normalized data
        2 #For 3D plotting, I didn't know anything, so, I referred this article http
```

```
In [8]: 1 #Importing libraries
        2 from mpl_toolkits import mplot3d
        3
        4 import numpy as np
        5 import matplotlib.pyplot as plt
        6
        7 fig = plt.figure()
        8 ax = plt.axes(projection="3d")
        9
        10 plt.show()
```



```
In [9]: 1 #Now that our axes are created we can start plotting in 3D.
2 fig = plt.figure()
3 ax = plt.axes(projection="3d")
4
5 z_points = z
6 x_points = x
7 y_points = y
8 ax.scatter3D(x_points, y_points, z_points, c=z_points, cmap='hsv');
9
10 ax.set_xlabel('x')
11 ax.set_ylabel('y')
12 ax.set_zlabel('z')
13
14 plt.show()
15 #here, z points are colored
```

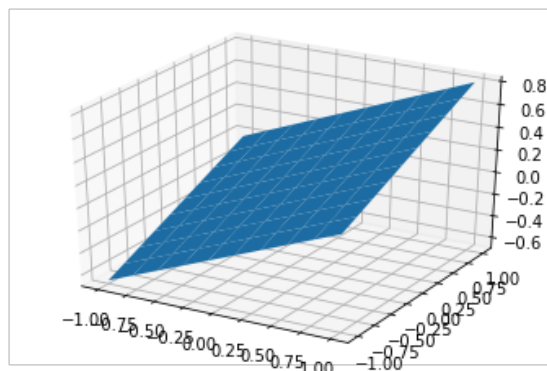
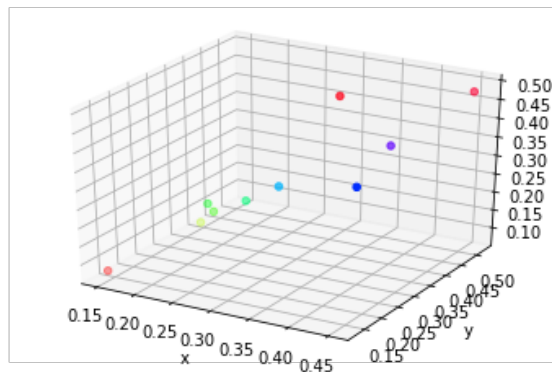


```
In [10]: 1 # To draw a plane, I have referred this link https://stackoverflow.com/questions/11594407/how-to-draw-a-plane-in-matplotlib
```

```

In [11]: 1 from mpl_toolkits.mplot3d import Axes3D
          2
          3 x1 = np.linspace(-1,1,10)
          4 y1 = np.linspace(-1,1,10)
          5
          6 fig = plt.figure()
          7 ax = plt.axes(projection="3d")
          8
          9 z_points = z
         10 x_points = x
         11 y_points = y
         12 ax.scatter3D(x_points, y_points, z_points, c=z_points, cmap='hsv');
         13
         14 ax.set_xlabel('x')
         15 ax.set_ylabel('y')
         16 ax.set_zlabel('z')
         17
         18
         19 X,Y = np.meshgrid(x1,y1)
         20 Z= 0.4171638121446569*X + 0.32211296484688473*Y + 0.07035194413069641
         21
         22 fig = plt.figure()
         23 ax = fig.gca(projection='3d')
         24
         25 surf = ax.plot_surface(X, Y, Z)
         26 plt.show()

```



```

In [12]: 1 # plot of hyperplane which I got using least method will be :
          2 import numpy as np
          3 import matplotlib.pyplot as plt
          4 from mpl_toolkits.mplot3d import Axes3D
          5
          6 x = np.linspace(-1,1,10)
          7 y = np.linspace(-1,1,10)
          8
          9 X,Y = np.meshgrid(x,y)
         10 Z=0.00362953*X + 1.67818099*Y-1.9252501
         11
         12 fig = plt.figure()

```

```
13 ax = fig.gca(projection='3d')  
14  
15 surf = ax.plot_surface(X, Y, Z)
```

