

INSTRUCTIONS:
Fill out the hazard analysis and risk assessment below.
HA-001 should be for the lane departure warning function as discussed in the lecture
HA-002 should be for the lane keeping assistance function as discussed in the lecture
Then come up with your own situations and hazards for the other functions.
When finished, export your spreadsheet as a pdf file so I can see it.

Hazard ID		
	Operational Mode	Operational Scenario
HA-001	OM03 - Normal driving	OS04 – Highway
HA-002	OM03 - Normal driving	OS04 – Highway
HA-003	OM03 - Normal driving	OS04 – Highway
HA-004	OM03 - Normal driving	OS04 – Highway

ssed in the lecture.

ussed in the lecture.

**the lane assistance system. Fill in the HA-003 and HA-004 rows.
that a reviewer can easily see your work.**

Situational Analysis		
Environmental Details	Situation Details	Other Details (optional)
EN02 - Sun blares (degraded view)	SD02 - High speed	Lane Markings not clearly marked
EN02 - Sun blares (degraded view)		Lane Markings not clearly marked
EN01 - Normal conditions		Lane Markings clearly detected
EN01 - Normal conditions		Lane Markings clearly detected

Item Usage (function)	Situation Description
IU01 - Correctly used	Normal driving on a Highway under Sun blares driving with high speed and lane marking not clearly marked
IU01 - Correctly used	Normal driving on a Highway under Sun blares driving with high speed and lane marking not clearly marked
IU02 - Incorrectly used	Normal driving on a highway under normal lighting conditions with high speed and lane markings correctly visible
IU02 - Incorrectly used	Normal driving on a highway under normal lighting conditions with high speed and lane markings correctly visible

Haza		
Function	Deviation	Deviation Details
Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver with haptic feedback	DV19 - Sensor detection is wrong	Sensor detection is wrong due to bad lighting conditions
Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane	DV19 - Sensor detection is wrong	Sensor detection is wrong due to bad lighting conditions
Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver with haptic feedback	DV04 - Actor effect is too much	Actor applies too much torque to change the lane
Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane	DV11 - Actor effect is wrong	Actor treats the lane keeping function as an autonomous function to driver autonomously

rd Identification

Hazardous Event (resulting effect)	Event Details
EV-02 - Side collision with other traffic	Possible injury to the driver
EV-02 - Side collision with other traffic	Possible injury to the driver
EV-02 - Side collision with other traffic	Possible injury to the driver
EV00 - Collision with other vehicle	Possible injury to the driver

Hazardo

Hazardous Event Description	Exposure (of situation)	Rationale (for exposure)	Severity (of potential harm)
Possible bad lane detection fals to warn the driver about deviating lane and possible	E4 - High probability	Highway driving is a common occurance and possible high sun flares with bad lane markings due	S3 - Life-threatening or fatal injuries
Possible bad lane detection fals to warn the driver about deviating lane and possible	E4 - High probability	Highway driving is a common occurance and possible high sun flares with bad lane markings due	S3 - Life-threatening or fatal injuries
driver causes the car to loose control and spin out of control and collide with vehicles in	E4 - High probability	Highway driving under normal conditions is a common occurance	S3 - Life-threatening or fatal injuries
Possible mistreating the LKA function as an autonomous function	E4 - High probability	Highway driving under normal conditions is a common occurance	S3 - Life-threatening or fatal injuries

us Event Classification

Rationale (for severity)	Controllability (of hazardous event)	Rationale (for controllability)
High Speed driving on highways	C2 - Normally controllable	If system warns driver in advance about bad lighting and bad lane markings, Driver could be notified to take over the wheel
High Speed driving on highways	C2 - Normally controllable	If system warns driver in advance about bad lighting and bad lane markings, Driver could be notified to take over the wheel
High Speed driving on highways	C3 - Difficult to control or uncontrollable	High Torque by the actor could make the vehicle go spinning
High Speed driving on highways	C2 - Normally controllable	If system warns the driver of not taking control on the vehicle, when the LKA function as autonomous

Determination of ASIL and Safety Goals	
ASIL Determination	Safety Goal
ASIL C	Bad lighting conditions would be notified and bad lane marking detections would be notified well in advance to the driver
ASIL C	Bad lighting conditions would be notified and bad lane marking detections would be notified well in advance to the driver
ASIL D	Warn the Driver of excessive applied torque on the steering wheel and ignore the steering inputs from the driver
ASIL B	Warn the driver to take control of the wheel

EXAMPLE DISCUSSED IN THE PROJECT INSTRUCTIONS -

Hazard ID	
	Operational Mode
HA-001	Normal Driving

MORE EXAMPLES - Headlamp System

Hazard ID	
	Operational Mode
HA-001	OM03 - Normal Driving
HA-002	OM03 - Normal Driving
HA-003	OM03 - Normal Driving
HA-004	OM03 - Normal Driving
HA-005	OM03 - Normal Driving

Headlamp System

Situ	
Operational Scenario	Environmental Details
City Road	Normal Conditions

Situ	
Operational Scenario	Environmental Details
OS01 - City Road	EN01 - Normal conditions
OS01 - City Road	EN04 - Snowfall (degraded view)
OS03 - Highway	EN04 - Snowfall (degraded view)
OS02 - Country Road	EN01 - Normal conditions
OS02 - Country Road	EN04 - Snowfall (degraded view)

Situational Analysis		
Situation Details (optional)	Other Details (optional)	Item Usage (function)
Low Speed	Night time + Obstacle on the road	Correctly Used

Situational Analysis		
Situation Details (optional)	Other Details (optional)	Item Usage (function)
SD03 - Low speed	Night time + Obstacle on the road	IU01 - Correctly used
SD03 - Low speed	the road and no other	IU01 - Correctly used
SD03 - High speed	the road or upcoming	IU01 - Correctly used
SD02 - High speed	Night time + Oncoming vehicle	IU01 - Correctly used
SD04 - High speed	the road and no other	IU01 - Correctly used

Situation Description	Function
Conditions at Low Speed at Night with an	Low beam illuminates the roadway in the dark

Situation Description	Function
conditions with Low speed (Night time + (degraded view) with Low speed (Night time + Obstacle on the road and no other illumination	Low beam illuminates the roadway in the dark
(degraded view) with High speed (Night time +	Low beam illuminates the roadway in the dark
conditions with High speed (Night time + Snowfall (degraded view) with High speed	Low beam illuminates the roadway in the dark
(Night time + Obstacle on the road and no	Low beam illuminates the roadway in the dark

Hazard Id	
Deviation	Deviation Details
Function not activated	Both headlights stop working

Hazard Id	
Deviation	Deviation Details
DV01 - Function not activated	Both headlights stop working
DV01 - Function not activated	Both headlights stop working
DV01 - Function not activated	Both headlights stop working
DV01 - Function not activated	Both headlights stop working
DV01 - Function not activated	Both headlights stop working

Identification		
Hazardous Event (resulting effect)	Event Details	Hazardous Event Description
Front collision with obstacle	the obstacle with injury	

Identification		
Hazardous Event (resulting effect)	Event Details	Hazardous Event Description
EV04 - Front collision with obstacle	the obstacle with injury	total loss or tow
EV04 - Front collision with obstacle	the obstacle with injury	total loss or tow
EV04 - Front collision with obstacle	infrastructure with	total loss or tow
EV08 - Collision with other vehicle	the oncoming vechile	total loss or tow
EV04 - Front collision with obstacle	infrastructure with	total loss or tow

Exposure (of situation)	Rationale (for exposure)
E4 - High probability	night driving in the city is a regular activity

Exposure (of situation)	Rationale (for exposure)
E4 - High probability	night driving in the city is a regular activity
E1 - Very low probability	completely unilluminated roads
E2 - Low probability	driving, however, heavy snow
E4 - High probability	country driving is part of regular driving
E2 - Low probability	driving, however, heavy snow

Hazardous Event Classification	
Severity (of potential harm)	Rationale (for severity)
S1 - Light and moderate injuries	In city traffiic, speed of vehicle is expected to be low

Hazardous Event Classification	
Severity (of potential harm)	Rationale (for severity)
S1 - Light and moderate injuries	In city traffiic, speed of vehicle is expected to be low
S1 - Light and moderate injuries	In city traffiic, speed of vehicle is expected to be low
S3 - Life-threatening or fatal injuries	On highway speed of vehicle is expected to be high
S3 - Life-threatening or fatal injuries	On country roads speed of vehicle is expected to be high
S3 - Life-threatening or fatal injuries	On country roads speed of vehicle is expected to be high

Controllability (of hazardous event)	Rationale (for controllability)
C0 - Controllable in general	control the situation by applying brakes and there is additional illumination on

Controllability (of hazardous event)	Rationale (for controllability)
C0 - Controllable in general	control the situation by applying brakes and there is additional illumination on
C1 - Simply controllable	drivers usually drive at lower end of city illumination on road and hence >90% drivers are able to brake and control the
C2 - Normally controllable	road, it will be difficult for the average
C1 - Simply controllable	road, it will be difficult for the average
C3 - Difficult to control or uncontrollable	road, it will be difficult for the average

Determination of ASIL and Safety Goals	
ASIL	Safety Goal
Determination	
QM	total LOSS of Beam shall be prevented

Determination of ASIL and Safety Goals	
ASIL	Safety Goal
Determination	
QM	total LOSS of low beam shall be prevented
QM	total LOSS of low beam shall be prevented
A	total LOSS of low beam shall be prevented
B	total LOSS of low beam shall be prevented
B	total LOSS of low beam shall be prevented

Hazard & Risk Analysis Defi

Operational Mode

ID	Mode
OM01	Parked
OM02	Ignition on
OM03	Normal driving
OM04	Backward driving
OM05	Degraded driving
OM06	Towing (active)
OM07	Towing (passive)
OM08	Service
OM09	N/A

Operational Scenario

ID	Scenario
OS01	Any Road
OS02	City Road
OS03	Country Road
OS04	Highway
OS05	Mountain Pass
OS06	Off Road
OS07	Road with gradient
OS08	Road with bump
OS09	Road tunnel
OS10	Road with construction site
OS11	N/A

Situation Details

ID	Scenario
SD01	Low speed
SD02	High speed
SD03	Normal acceleration
SD04	High acceleration
SD05	Normal braking
SD06	High braking
SD07	N/A

Item Usage

ID	Mode
IU01	Correctly used
IU02	Incorrectly used
IU03	N/A

Environmental Details

ID	Scenario
EN01	Normal conditions
EN02	Sun blares (degraded view)
EN03	Fog (degraded view)
EN04	Snowfall (degraded view)

EN05	Cross-wind (lateral force)
EN06	Rain (slippery road)
EN07	Snow (slippery road)
EN08	Glacé (slippery road)
EN09	N/A

itions

Remarks
Car is parked, ignition is off
Car is parked, ignition is on
Car is driving
Car is driving
Limp home mode
Towing another car
Beeing towed by another car
Vehicle is in repair garage
not applicable or not relevant

Remarks
road type
road type
road type
road type
road type
road type
road attribute
road attribute
road attribute
road attribute
not applicable or not relevant

Remarks
driving attribute
driving attribute
driving attribute
driving attribute
driving attribute
driving attribute
not applicable or not relevant

Remarks
Intended usage
Unintended usage (foreseeable)
not applicable or not relevant

Remarks
weather attribute
weather attribute
weather attribute
weather attribute

weather attribute
road attribute
road attribute
road attribute
not applicable or not relevant

Reference
OM01 - Parked
OM02 - Ignition on
OM03 - Normal driving
OM04 - Backward driving
OM05 - Degraded driving
OM06 - Towing (active)
OM07 - Towing (passive)
OM08 - Service
OM09 - N/A

Reference
OS01 - Any Road
OS02 - City Road
OS03 - Country Road
OS04 - Highway
OS05 - Mountain Pass
OS06 - Off Road
OS07 - Road with gradient
OS08 - Road with bump
OS09 - Road tunnel
OS10 - Road with construction site
OS11 - N/A

Reference
SD01 - Low speed
SD02 - High speed
SD03 - Normal acceleration
SD04 - High acceleration
SD05 - Normal braking
SD06 - High braking
SD07 - N/A

Reference
IU01 - Correctly used
IU02 - Incorrectly used
IU03 - N/A

Reference
EN01 - Normal conditions
EN02 - Sun blares (degraded view)
EN03 - Fog (degraded view)
EN04 - Snowfall (degraded view)

EN05 - Cross-wind (lateral force)
EN06 - Rain (slippery road)
EN07 - Snow (slippery road)
EN08 - Glace (slippery road)
EN09 - N/A

Deviation

ID	Deviation (Guideword)	Remarks
DV01	Function not activated	Activation error
DV02	Function unexpectedly activated	Activation error
DV03	Function always activated	Activation error
DV04	Actor effect is too much	Quantitative error
DV05	Actor effect is too less	Quantitative error
DV06	Actor action too early	Timing error
DV07	Actor action too late	Timing error
DV08	Actor action before	Sequence error
DV09	Actor action after	Sequence error
DV10	Actor effect is reverse	Logical error
DV11	Actor effect is wrong	Logical error
DV12	Sensor sensitivity is too high	Quantitative error
DV13	Sensor sensitivity is too low	Quantitative error
DV14	Sensor detection too early	Timing error
DV15	Sensor detection too late	Timing error
DV16	Sensor detection before	Sequence error
DV17	Sensor detection after	Sequence error
DV18	Sensor detection is reverse	Logical error
DV19	Sensor detection is wrong	Logical error
DV20	N/A	not applicable or not relevant

Hazardous Events (possible effects)

ID	Hazardous Event	Remarks
EV-07	None	
EV-06	Front collision with oncoming traffic	
EV-05	Front collision with ahead traffic	
EV-04	Front collision with obstacle	
EV-03	Rear collision with trailing traffic	
EV-02	Side collision with other traffic	
EV-01	Side collision with obstacle	
EV00	Collision with other vehicle	
EV01	Collision with train	
EV02	Collision with pedestrian	
EV03	Car spins out of control	
EV04	Car comes off the road	
EV05	Car catches fire	
EV06	N/A	

Reference
DV01 - Function not activated
DV02 - Function unexpectedly activated
DV03 - Function always activated
DV04 - Actor effect is too much
DV05 - Actor effect is too less
DV06 - Actor action too early
DV07 - Actor action too late
DV08 - Actor action before
DV09 - Actor action after
DV10 - Actor effect is reverse
DV11 - Actor effect is wrong
DV12 - Sensor sensitivity is too high
DV13 - Sensor sensitivity is too low
DV14 - Sensor detection too early
DV15 - Sensor detection too late
DV16 - Sensor detection before
DV17 - Sensor detection after
DV18 - Sensor detection is reverse
DV19 - Sensor detection is wrong
DV20 - N/A

Reference
EV-07 - None
EV-06 - Front collision with oncoming traffic
EV-05 - Front collision with ahead traffic
EV-04 - Front collision with obstacle
EV-03 - Rear collision with trailing traffic
EV-02 - Side collision with other traffic
EV-01 - Side collision with obstacle
EV00 - Collision with other vehicle
EV01 - Collision with train
EV02 - Collision with pedestrian
EV03 - Car spins out of control
EV04 - Car comes off the road
EV05 - Car catches fire
EV06 - N/A

Exposure

ID	Description
E0	Incredible
E1	Very low probability
E2	Low probability
E3	Medium probability
E4	High probability

Severity

ID	Description
S0	No injuries
S1	Light and moderate injuries
S2	Severe and life-threatening injuries
S3	Life-threatening or fatal injuries

Controllability

ID	Description
C0	Controllable in general
C1	Simply controllable
C2	Normally controllable
C3	Difficult to control or uncontrollable

Duration (of situation)
Not specified
<1 % of average operating time
1 % to 10 % of average operating time
>10 % of average operating time

Remarks
No injuries
Light and moderate injuries
Severe and life-threatening injuries (survival probable)
Life-threatening injuries (survival uncertain), fatal injuries

Remarks
Controllable in general
99 % or more of all drivers or other traffic participants are usually
90 % or more of all drivers or other traffic participants are usually
Less than 90 % of all drivers or other traffic participants are usually

Frequency (of situation)	Reference
	E0 - Incredible
Occurs less often than once a year for the great majority of drivers	E1 - Very low probability
Occurs a few times a year for the great majority of drivers	E2 - Low probability
Occurs once a month or more often for an average driver	E3 - Medium probability
Occurs during almost every drive on average	E4 - High probability

Probability of Injuries	Reference
AIS 0 and less than 10 % probability of AIS 1-6	S0 - No injuries
More than 10 % probability of AIS 1-6 (and not S2 or S3)	S1 - Light and moderate injuries
More than 10 % probability of AIS 3-6 (and not S3)	S2 - Severe and life-threatening injuries
More than 10 % probability of AIS 5-6	S3 - Life-threatening or fatal injuries

	Reference
	C0 - Controllable in general
Very able to avoid harm	C1 - Simply controllable
Usually able to avoid harm	C2 - Normally controllable
Not usually able, or barely able, to avoid harm	C3 - Difficult to control or uncontrollable

Controllability	Exposure	Severity		
		S0	S1	S2
C1	E1	QM	QM	QM
	E2	QM	QM	QM
	E3	QM	QM	QM
	E4	QM	QM	A
C2	E1	QM	QM	QM
	E2	QM	QM	QM
	E3	QM	QM	A
	E4	QM	A	B
C3	E1	QM	QM	QM
	E2	QM	QM	A
	E3	QM	A	B
	E4	QM	B	C

S3
QM
QM
A
B
QM
A
B
C
A
B
C
D