

# Lecture Summary: Linear Transformations and Ordered Bases

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## Key Points

- **Linear Transformations: Recap and Basis Dependency:**

- A linear transformation  $f : V \rightarrow W$  satisfies:

$$f(u + v) = f(u) + f(v), \quad f(c \cdot u) = c \cdot f(u),$$

for  $u, v \in V$  and scalar  $c \in \mathbb{R}$ .

- The action of  $f$  is fully determined by its values on the basis vectors of  $V$ .

- **Isomorphism Using Basis:**

- If  $V$  is an  $n$ -dimensional vector space with basis  $\{v_1, v_2, \dots, v_n\}$ :

1. Define  $f(v_i) = e_i$  (the standard basis for  $\mathbb{R}^n$ ).
2. Extend this mapping linearly to  $V$  by:

$$f\left(\sum_{i=1}^n c_i v_i\right) = \sum_{i=1}^n c_i e_i.$$

- $f$  is an isomorphism, meaning it is both one-to-one and onto.

- **Matrix Representation of Linear Transformations:**

- For  $f : V \rightarrow W$ , let  $\beta = \{v_1, v_2, \dots, v_n\}$  be an ordered basis for  $V$  and  $\gamma = \{w_1, w_2, \dots, w_m\}$  for  $W$ .
- Represent  $f(v_j)$  as a linear combination of  $\{w_1, w_2, \dots, w_m\}$ :

$$f(v_j) = \sum_{i=1}^m a_{ij} w_i.$$

- The coefficients  $a_{ij}$  form the  $i$ th row and  $j$ th column of the matrix representation of  $f$ .

- **Example: Linear Transformation on  $\mathbb{R}^2$ :**

- Define  $f(x, y) = (2x, y)$ .
- With standard basis  $\{(1, 0), (0, 1)\}$ , compute:

$$f(1, 0) = (2, 0), \quad f(0, 1) = (0, 1).$$

- Matrix representation:

$$A = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}.$$

- **Changing Ordered Basis:**

- Changing the basis changes the matrix representation.
- Example: If  $\beta = \{(1, 0), (1, 1)\}$ , then:

$$f(1, 0) = (2, 0), \quad f(1, 1) = (2, 1).$$

- Matrix representation becomes:

$$A = \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix}.$$

- The same linear transformation yields different matrices for different bases.

- **Bijection Between Linear Transformations and Matrices:**

- For fixed ordered bases  $\beta$  and  $\gamma$ , there is a bijection between linear transformations  $f : V \rightarrow W$  and  $m \times n$  matrices.
- The matrix  $A$  encodes the coefficients of  $f(v_j)$  expressed in terms of  $\gamma$ .

## Simplified Explanation

**Example 1: Linear Transformation on  $\mathbb{R}^3$**  Let  $W = \{(x, y, z) \in \mathbb{R}^3 \mid x + y + z = 0\}$  and  $V = \mathbb{R}^2$ :

- Basis for  $W$ :  $\{(-1, 1, 0), (-1, 0, 1)\}$ .
- Define  $f(-1, 1, 0) = (1, 0)$ ,  $f(-1, 0, 1) = (0, 1)$ .
- Matrix representation (standard basis for  $V$ ):

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

## Conclusion

In this lecture, we:

- Explored linear transformations and their dependency on ordered bases.
- Developed matrix representations and analyzed their changes with basis choice.
- Highlighted the bijection between linear transformations and matrices for fixed bases.

This framework unifies the concepts of linear algebra, emphasizing the interplay between transformations, bases, and matrix representations.