# Lecture Summary: Errors in Parameter Estimation

### Lecture: 9.3 - Errors in Parameter Estimation

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### **Key Points**

#### • The Parameter Estimation Problem:

- Estimation involves deriving an unknown parameter  $\theta$  from iid samples  $X_1, X_2, \ldots, X_n$ .
- The parameter  $\theta$  is fixed, but the estimator  $\hat{\theta}$  is a random variable with its own distribution.
- A good estimator produces errors that are small and close to zero.

#### • Error in Estimation:

- Error is defined as:

Error = 
$$\hat{\theta}(X_1, \dots, X_n) - \theta$$
.

- The error is a random variable, and its absolute value should ideally remain small.
- A mathematical approach to controlling error:

 $P(|\text{Error}| > \delta)$  should be small, where  $\delta$  is a threshold.

- The choice of  $\delta$  is context-dependent and often relative to the magnitude of  $\theta$ .

#### • Relative Error Thresholds:

- Errors should be characterized as a fraction of the parameter being estimated.
- For example:
  - \* For Bernoulli(p):  $|\text{Error}| \le p/10$  (10% error relative to p).
  - \* For Normal( $\mu, \sigma^2$ ): Error relative to  $\mu$  varies with scale.

#### • Comparing Estimators:

- Three estimators for p in Bernoulli trials were evaluated:
  - 1.  $\hat{p}_1 = 0.5$  (fixed).
  - 2.  $\hat{p}_2 = \frac{X_1 + X_2}{2}$  (uses only the first two samples).
  - 3.  $\hat{p}_3 = \frac{\sum_{i=1}^n X_i}{n}$  (sample mean).
- Observations:
  - \*  $\hat{p}_1$  is constant and does not adapt to p.
  - \*  $\hat{p}_2$  adapts but has high variability.
  - \*  $\hat{p}_3$  uses all samples, balances adaptability and stability, and shows the best performance.

#### • Chebyshev's Inequality in Estimation:

- Chebyshev's bound on error:

$$P(|\text{Error}| > \delta) \le \frac{\text{Var}(\text{Error})}{\delta^2}.$$

- For  $\hat{p}_3$ :
  - \*  $\mathbb{E}[\text{Error}] = 0$  (unbiased).
  - \*  $Var(Error) = \frac{p(1-p)}{n}$ .
  - \* Probability bound for |Error| > p/10:

$$P(|\text{Error}| > p/10) \le \frac{100(1-p)}{np}.$$

– As  $n \to \infty$ ,  $P(|\text{Error}| > \delta) \to 0$ , demonstrating the estimator's performance improvement with more samples.

#### • Key Insights:

- Good estimators adapt to the parameter and leverage all available data.
- Increasing the sample size reduces error variance and improves reliability.
- Concentration results like Chebyshev's and Chernoff bounds highlight how probabilities of large errors diminish with more samples.

## Simplified Explanation

Key Idea: Errors in parameter estimation should be small and decrease as the sample size increases.

Comparison of Estimators: -  $\hat{p}_3$  (sample mean) is effective because it uses all samples, adapts to p, and reduces error variance as n grows.

Why It Matters: Accurate estimators provide reliable parameter estimates for decision-making and data analysis.

### Conclusion

In this lecture, we:

- Explored how errors in parameter estimation are characterized and controlled.
- Evaluated the performance of different estimators for Bernoulli(p).
- Used Chebyshev's inequality to quantify error probabilities.

The concepts discussed are foundational for designing effective estimators that leverage data efficiently while minimizing estimation errors.