

## Bias Variance Tradeoff

As usual, we are given a dataset  $D = \{(x_1, y_1), \dots, (x_n, y_n)\}$  drawn iid from some distribution  $P(X, Y)$ .

We will assume a regression setting, i.e.  $y \in \mathbb{R}$ .

→ Note: Proof in regression setting is easier that is why we will be using it.

Let us consider that for any given input  $x$  there might not exist a unique label  $y$ .

For example,  $x$  describes features of a house (eg bedrooms, carpet area, etc) and the label  $y$  its price.

Two different house with identical description might get sold at a different price.

Hence, for any given feature vector  $x$ , there is distribution over possible labels.

expected label (given  $x \in \mathbb{R}^d$ ):

$$\bar{y}(x) = E_{y|x}[Y] = \int y P(y|x) dy.$$

Alright, so we draw our training dataset  $D$ , consisting  $n$  inputs, i.i.d from the distribution  $P$ .

As second step we typically call some machine learning algorithm  $A$  on this data set to learn a hypothesis (aka classifier).

$$h_D = A(D)$$

For a given ~~test~~  $h_D$ , learned on data set  $D$  with algorithm  $A$ , we can compute the generalization error (as measured in squared loss) as follows:

Expected Test Error (given  $h_D$ ):

$$E_{(x,y) \sim P} [(h_D(x) - y)^2] = \iint (h_D(x) - y)^2 P(x, y) dx dy.$$

Note - other loss functions can also be used, we are using squared loss for the ease of proof.

Expected classifier (given A)

$$\bar{h} = E_{D \sim p^n}[h_D] = \int_D h_D P(D) dD.$$

Here  $P(D)$  is probability of drawing  $D$  from  $p^n$ .

Here,  $\bar{h}$  is a weighted average over functions.

Expected test error (given A) -

$$E_{\substack{(x,y) \sim P \\ D \sim p^n}}[(h_D(x) - y)^2] = \int_D \int_x \int_y (h_D(x) - y)^2 P(D) dx dy dD.$$

$D$  is our training points and  $(x, y)$  pairs are the test points.

This expression is of interest to us because it evaluates the quality of a machine learning algorithm  $A$  with respect to a data distribution  $P(X, Y)$ .

Now, let's decompose it further.

$$\begin{aligned}
 E_{x,y,D}[(h_D(x) - y)^2] &= E_{x,y,D}[(h_D(x) - \bar{h}(x)) + (\bar{h}(x) - y)]^2 \\
 &= E_{x,D}[(\bar{h}_D(x) - \bar{h}(x))^2] + 2E_{x,y,D}[(h_D(x) - \bar{h}(x)) \cdot (\bar{h}(x) - y)] \\
 &\quad + E_{x,y}[(\bar{h}(x) - y)^2]
 \end{aligned}$$

The middle term of the above equation is 0.

$$\begin{aligned}
 E_{x,y,D}[(h_D(x) - \bar{h}(x))(\bar{h}(x) - y)] &= E_{x,y}[E_D[h_D(x) - \bar{h}(x)](\bar{h}(x) - y)] \\
 &= E_{x,y}[(E_D[h_D(x)] - \bar{h}(x))(\bar{h}(x) - y)] \\
 &= E_{x,y}[(\bar{h}(x) - \bar{h}(x))(\bar{h}(x) - y)] \\
 &= E_{x,y}[0] = 0.
 \end{aligned}$$

Hence we are left with

$$E_{x,y,D}[(h_D(x) - y)^2] = \underbrace{E_{x,D}[(\bar{h}_D(x) - \bar{h}(x))^2]}_{\text{variance}} + E_{x,y}[(\bar{h}(x) - y)^2]$$



Expanding the term,

$$\begin{aligned} E_{n,y}[(\bar{h}(x) - y)^2] &= E_{n,y}[(\bar{h}(x) - \bar{y}(x)) + (\bar{y}(x) - y)]^2 \\ &= E_{n,y}[(\bar{y}(x) - y)^2] + E_n[(\bar{h}(x) - \bar{y}(x))^2] \\ &\quad + 2 E_{n,y}[(\bar{h}(x) - \bar{y}(x))(\bar{y}(x) - y)] \\ &\quad \underbrace{\hspace{10em}}_{\text{Noise}} \quad \underbrace{\hspace{10em}}_{\text{Bias}^2} \\ &\quad \underbrace{\hspace{10em}}_{= 0} \end{aligned}$$

Proving that third term will be zero.

$$\begin{aligned} E_{n,y}[(\bar{h}(x) - \bar{y}(x))(\bar{y}(x) - y)] &= E_n[E_{y|x}[(\bar{y}(x) - y)(\bar{h}(x) - \bar{y}(x))]] \\ &= E_n[E_{y|x}[(\bar{y}(x) - y)(\bar{h}(x) - \bar{y}(x))]] \\ &= E_n[(\bar{y}(x) - E_{y|x}[y])(\bar{h}(x) - \bar{y}(x))] \\ &= E_n[(\bar{y}(x) - \bar{y}(x))(\bar{h}(x) - \bar{y}(x))] \\ &= E_n[0] \\ &= 0. \end{aligned}$$

Finally,

$$E_{x,y,D}[(h_D(x) - y)^2]$$

$$= E_{x,D}[\underbrace{(h_D(x) - \bar{h}(x))^2}_{\text{variance}}] + E_{x,y}[\underbrace{(\bar{y}(x) - y)^2}_{\text{Noise}}]$$

$$+ E_x[\underbrace{(\bar{h}(x) - \bar{y}(x))^2}_{\text{Bias}^2}]$$