Assignment-2

hillClimbing.cpp contains implementation of HillClimbing (Steepest Ascent search) technique of finding local maxima. This greedy algorithm many a time fails to find global optima as optimal path depends on start state.

procedures

```
int cal h(const string&);
vector<string> getNextState(const string&);
bool hill_climb(const string&, const string&);
void printPath(string);
int main();
int cal_h(const string&)::
input: current state as a string
return: -1*(number of tiles displaced from its respective position in goal_state).
vector<string> getNextState(const string&)::
input: current state as a string
return: vector of string containing possible next states obtained by up, down, right, left
movement of blank tile (taken as '0' in string).
bool hill_climb(const string&, const string&)::
input: start_state as a string, goal_state as a string
return: 'true' if goal_state reachable from start_state using greedy strategy followed by
steepest ascent, else 'false'.
void printPath(const string&)::
input: string
it prints (sub) optimal path of reaching goal state from start state.
Uses a map<string, string> to get parent of a state.
hillClimbing.cpp::
compile:: g++ hillClimbing.cpp -o hillClimbing
         hillClimbing < inp.txt
run::
----- example run-----
inp.txt::
813
024
```

765

run:: \Documents\iitp_sem7\AI\assign2>hillClimbing <inp.txt Start State Matrix of size=3*3 HILL CLIMB start_state: 813024765 goal_state: 123804765 SUCCESS Solution Steps:: 8 1 3 0 2 4 7 6 5 |0|1|3| |8|2|4| 7 6 5 |1|0|3| |8|2|4| 7 6 5 1 2 3 8 0 4 7 6 5 States Discovered = 9 Solution at depth = 3SUCCESS

----- example run 2 -----

input:: provide 'start_state' as '9 tile numbers' in range [0,8] delimited by 'space/line'.

Documents\iitp_sem7\AI\assign2>hillClimbing
Start_State Matrix of size=3*3
2 3 4 0 8 5 7 6 1
HILL CLIMB
start_state: 234085761
goal_state: 123804765
FAIL!