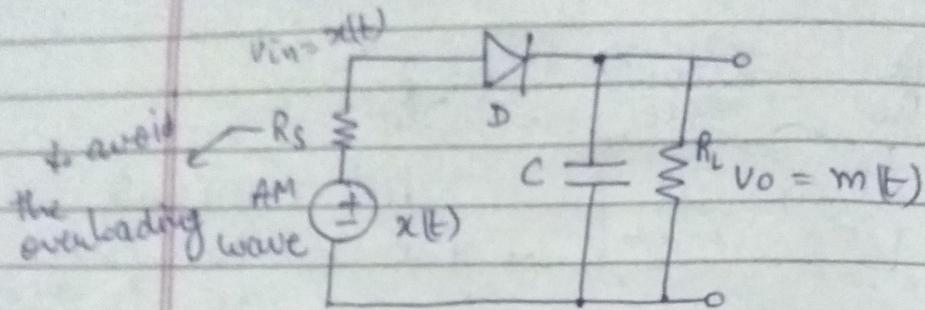


Envelope Detector

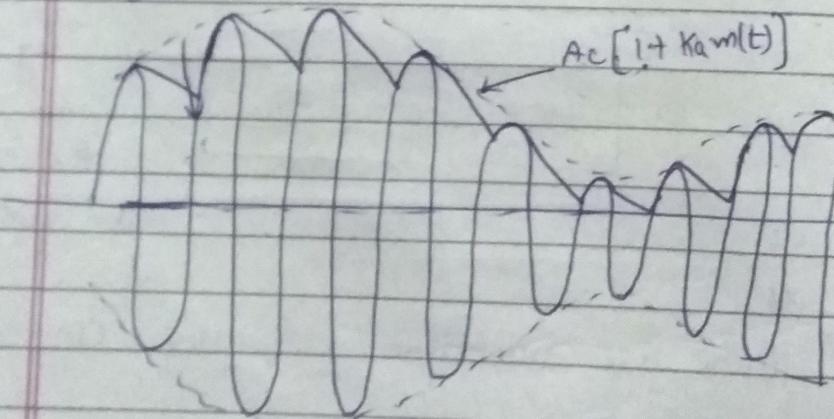


$V_{in} > V_{out}$ diode will be F.B.
 $V_{in} < V_{out}$ diode will be R.B.

carrier

C discharge C char

$A_c [1 + k_m(t)]$



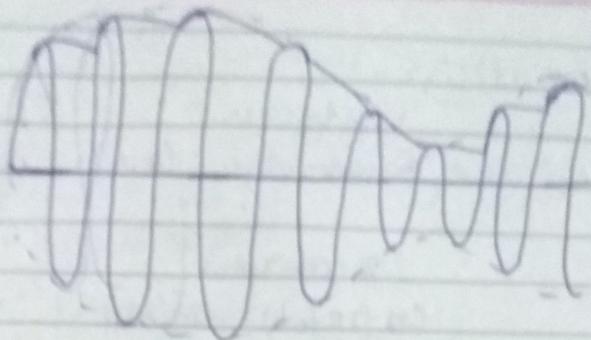
$m(t)$

$$\text{frequency} \propto \frac{1}{T} \quad (T = R \cdot C)$$

T is very large so capacitor discharges very slowly

Bandwidth of transmitted signal = $\frac{W}{T}$

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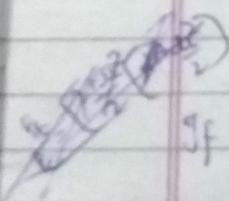
$T \gg \lambda$

If T is very small, it traces the carrier ~~the~~ signal.

$$\frac{1}{f_c} \ll T \ll \frac{1}{f_m}$$

case to trace the message signal.

To utilize the side bands, we use the side band modulation. Either LSB or USB has to be removed and it is upto us which band to remove.



If it is DSB-SC, it will be mentioned.

In DSB-SC,

$$P_t = P_c \frac{m^2}{2} \quad (\text{Pc component is removed } \frac{1}{2} \text{ in it})$$

Transmitted bandwidth = $2B$, original message bandwidth = B . Here Bandwidth is not utilized properly.

To utilize:

Quadrature

① QCM → (Quadrature Carrier Multiplexer)

2-carriers

$$\cos(2\pi f_c t), \sin(2\pi f_c t)$$

- 90° phase shifted.

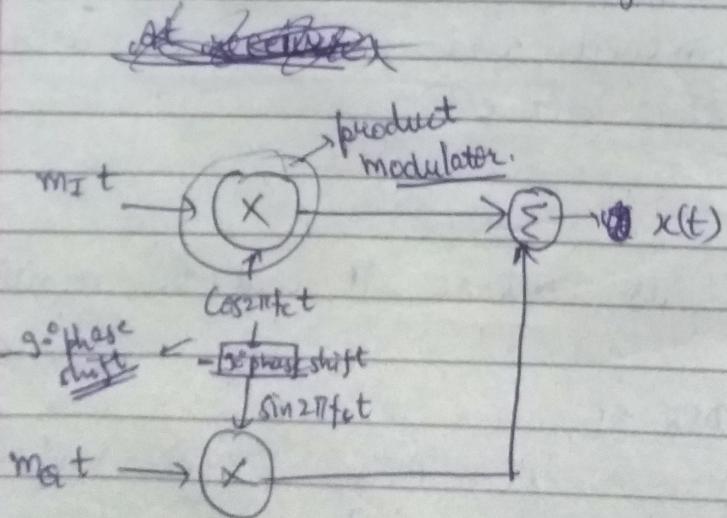
$$x(t)_{DSB-SC} = m_I(t) \cdot c(t)$$

DSB-SC for Quadrature carrier.

$$x(t) = \frac{f_C}{T} m_I(t) \cos(2\pi f_c t) - \frac{f_C}{T} m_Q(t) \sin(2\pi f_c t)$$

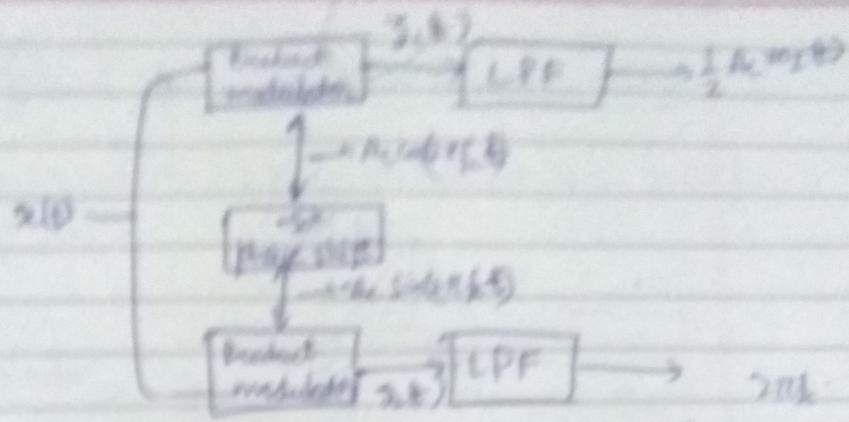
↑
Inphase
↑
Quadrature pha

two message signals.



$$\sin(2\pi f_c t) \times \cos(2\pi f_c t) = \frac{1}{2} \sin(4\pi f_c t) \Rightarrow [LPF] = 0$$

High freq.



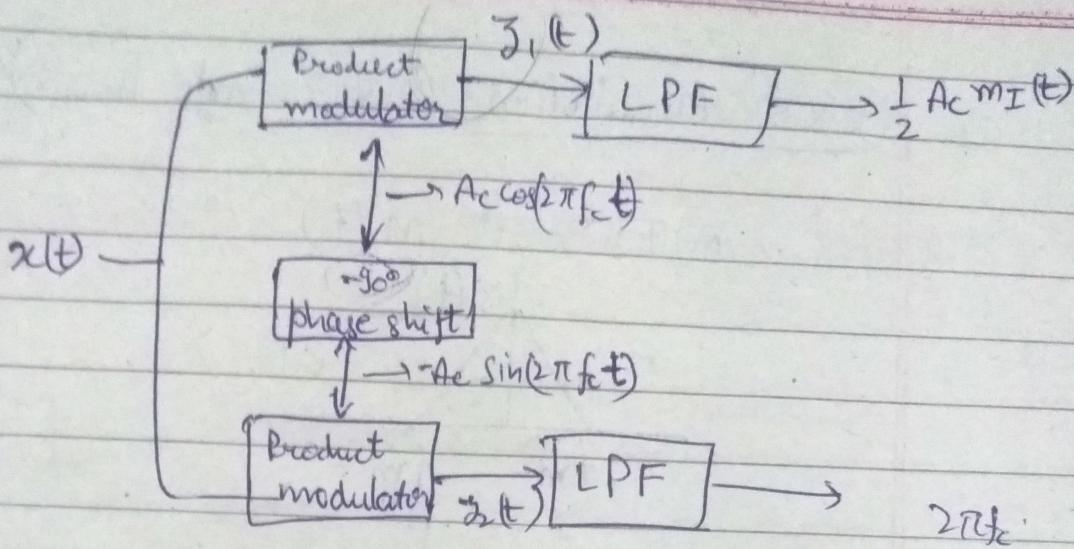
$$z_1(t) = [Ac m_2(t) \cos(2\pi f_1 t) - Ac m_1(t) \sin(2\pi f_1 t)] \\ \times Ac \cos 2\pi f_2 t$$

$$= \frac{Ac m_2(t)}{2} (1 + \cos(4\pi f_1 t)) - \frac{Ac m_1(t)}{2} \sin(4\pi f_1 t) \\ = \frac{Ac m_2(t)}{2} + \underbrace{\frac{Ac m_1(t) \cos(4\pi f_1 t)}{2}}_{\text{LPP}} - \underbrace{\frac{Ac m_1(t) \sin(4\pi f_1 t)}{2}}_{\text{High frequency}}$$

$$= \frac{1}{2} Ac m_2(t)$$

$$z_2(t) = [Ac m_2(t) \cos(2\pi f_1 t) - Ac m_1(t) \sin(2\pi f_1 t)] \underbrace{\frac{1}{2} \text{LPP}}$$

$$z_2(t) = \frac{1}{2} Ac m_1(t)$$



$$\mathcal{J}_1(t) = [A_{cmI}(t) \cos(2\pi f_c t) - A_{cmQ}(t) \sin(2\pi f_c t)] \times \text{Ac} \cos 2\pi f_c t$$

$$= \frac{A_{cmI}(t)}{2} [1 + \cos(4\pi f_c t)] - \frac{A_{cmQ}(t)}{2} \sin 4\pi f_c t$$

$$= \frac{A_{cmI}(t)}{2} + \underbrace{\frac{A_{cmQ}(t) \cos(4\pi f_c t)}{2}}_{2f_c} - \underbrace{\frac{A_{cmQ}(t) \sin(4\pi f_c t)}{2}}_{2f_c}$$

↓ 2f_c 2f_c
 LPF C. High frequency

$$= \frac{1}{2} A_{cmI}(t)$$

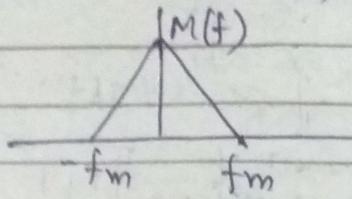
$$\mathcal{J}_2(t) = [A_{cmI}(t) \cos(2\pi f_c t) - A_{cmQ}(t) \sin(2\pi f_c t)] (-\sin 2\pi f_c t)$$

↓
 LPF

$$\mathcal{J}_2(t) = \frac{1}{2} A_{cmQ}(t)$$

② SSB Modulation (Single side band modulation)

$$m(t) \longleftrightarrow M(f)$$

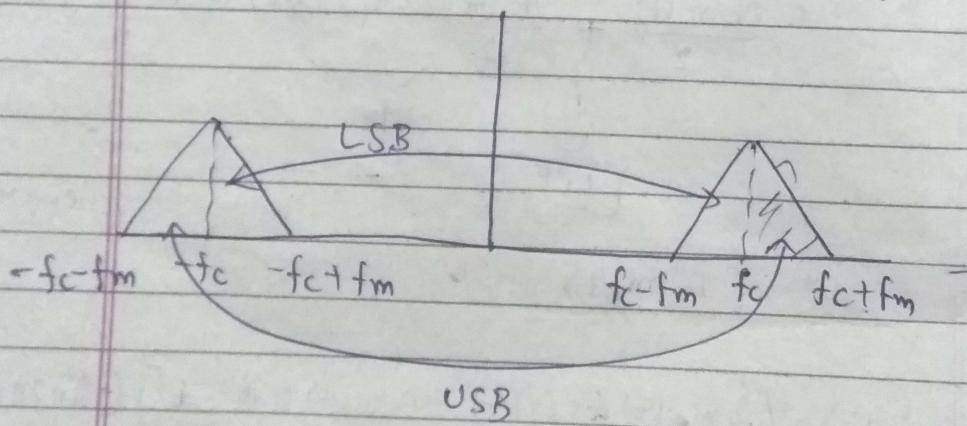


Consider,

$$x(t)_{DSB-SC} = m(t) \cdot \cos(2\pi f_c t)$$

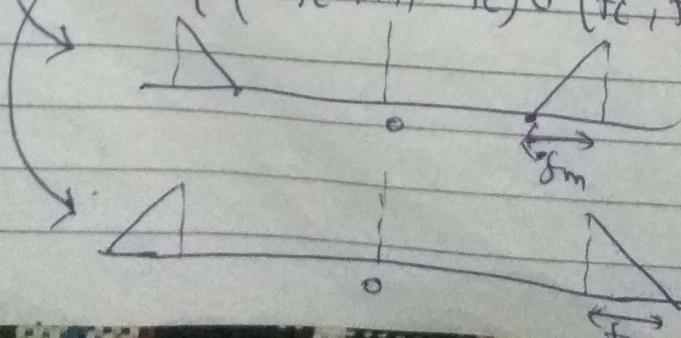
$$X(f) = M(f) \times \left[\frac{1}{2} s(f-f_c) + \frac{1}{2} s(f+f_c) \right]$$

$$X(f) = \left[\frac{1}{2} M(f-f_c) + \frac{1}{2} M(f+f_c) \right]$$



$$LSB = \{ (-f_c, -f_c + f_m) \cup (f_c - f_m, f_c) \}$$

$$USB = \{ (-f_c - f_m, -f_c) \cup (f_c, f_c + f_m) \}$$



Consider

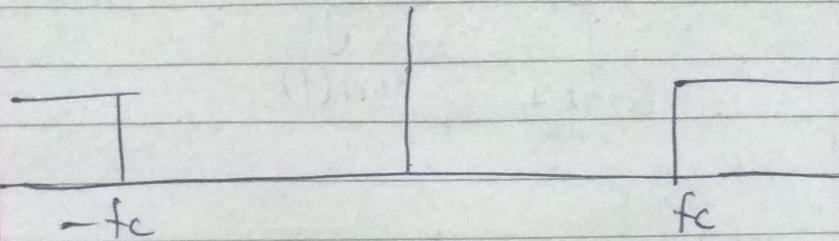
To ge

for

⇒ Freq
modu

modulation

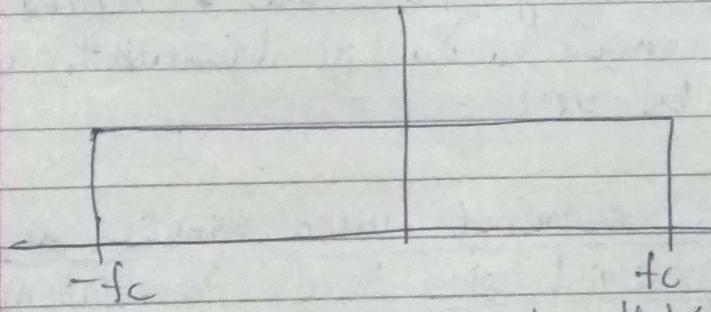
Consider generation of SSB modulation.

To generate ~~LSB~~ SSB, use high pass filter.

$$H_{HPF}(f) = \begin{cases} 1, & |f| \geq f_c \\ 0, & \text{otherwise} \end{cases}$$

+ f_c]

for USB;



$$H_{LPF}(f) = \begin{cases} 1, & |f| \leq f_c \\ 0, & \text{otherwise} \end{cases}$$

method

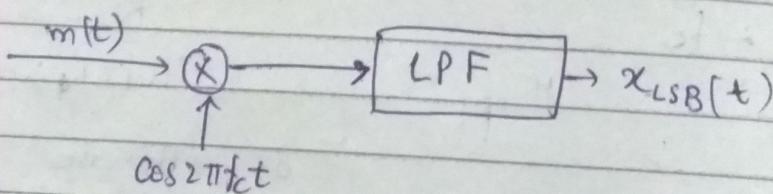
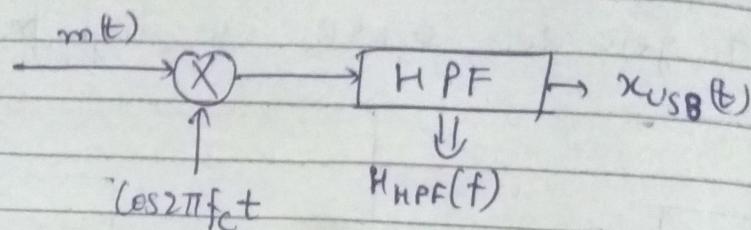
\Rightarrow Frequency discrimination for the SSB modulation.

⇒ Advantages of USB :-

- a) easy to generate.
- b) Have 25% large Bandwidth than SSB.
- c) Filter design is easy.

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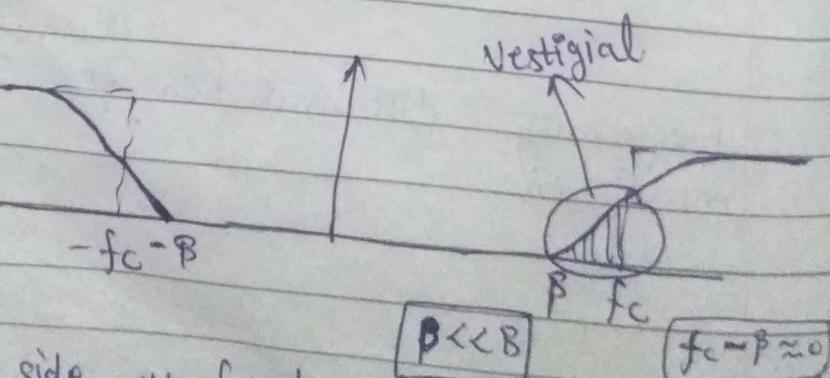
USB generation



Major problem with SSB :-

- ① Sharp cut off filters are needed.
 - ② Video signals (having high bandwidth), w- SSB can't be used.
- ⇒ So to transmit video signals we need USB (vestigial side band modulation).

USB

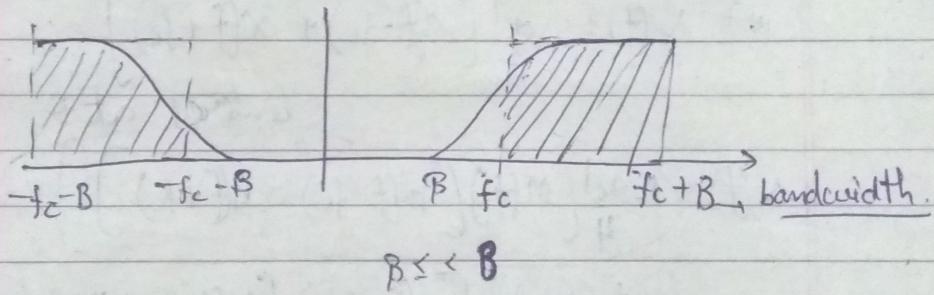
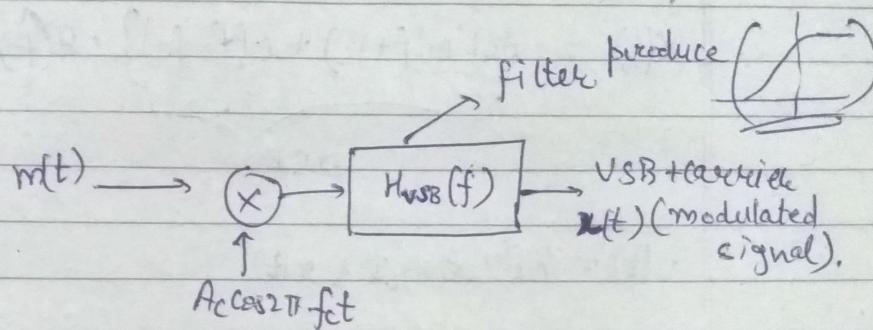


One side band is completely transferred along with partial other side band.

at AC transmitter end

→ here freq. component is high (4-5 MHz) than the freq. freq. in SSB.

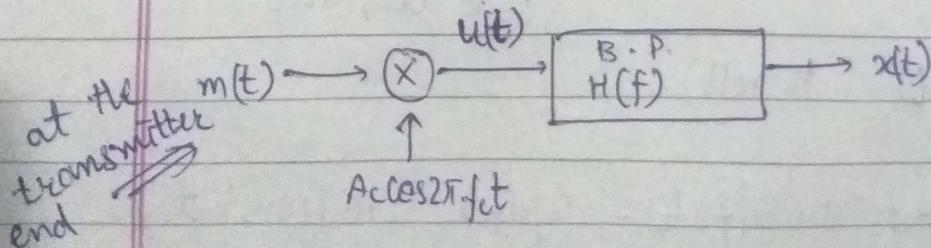
* SSB is used for speech signals (low bandwidth) and VSB is used for video signals.

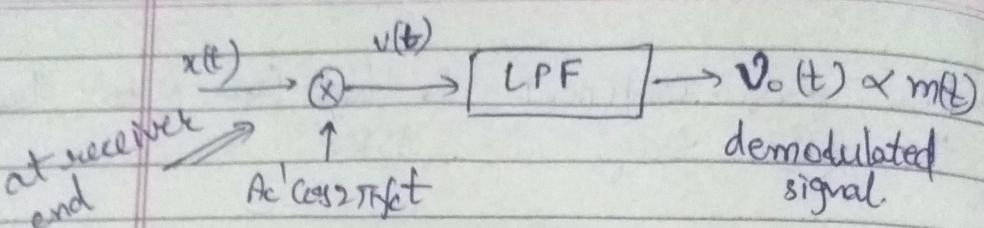


$$x(t) = \frac{Ac}{2} [1 + m(t)] \cos 2\pi f_c t - \frac{Ac}{2} y(t) \sin 2\pi f_c t$$

$$y(t) = f(m(t), \hat{m}(t))$$

$$B_T = B + \beta \quad [\because \beta \ll B]$$





$$X(f) = U(f) \cdot H(f)$$

DSB-SC

$$X(f) = \frac{A_c}{2} [M(f+f_c) + m(f-f_c)] \cdot H(f)$$

DSB

$$v(t) = A_c \cos 2\pi f_c t \cdot x(t)$$

$$vt v(t) = \frac{A_c}{2} [x(f-f_c) + x(f+f_c)]$$

centered at 0

$$v(t) = \left(\frac{A_c A_c}{4} [M(f) [H(f-f_c) + H(f+f_c)]] \right)$$

$$+ \left(\frac{A_c A_c}{4} [M(f-2f_c) [H(f-f_c) + M(f+2f_c) H(f+f_c)]] \right)$$

centered at $2f_c$.

$$V_o(f) = \frac{A_c A_c}{4} M(f) [H(f-f_c) + H(f+f_c)]$$

some constant

$$V_o(t) = K m(t)$$

$$H(f-f_c) + H(f+f_c) = 2H(f_c) = A \text{ (constant)}$$

$$H(f_c) = \frac{1}{2}$$

$$H(f-f_c) + H(f+f_c) = 1 \Rightarrow \text{design filter like this.}$$

If we use VSB if $B = 0$, special case of SSB. Page No.:

But in SSB if $B > 0$, no special Database / doesn't act as SSB because SSB is low freq. while VSB is high freq.

\Rightarrow If we use SSB, we do not have sharp cut-off then we will have delay and phase distortion.

$$S(t) = S_I(t) \cos 2\pi f_c t - S_Q(t) \sin 2\pi f_c t$$

$$S_I(f) = \begin{cases} S(f-f_c) + S(f+f_c), & |f| < B \\ 0, & |f| > B \end{cases}$$

$$S(f) = \frac{1}{2} A_m [M(f-f_c) + M(f+f_c)] \cdot H(f).$$

$$S_I(f) = \begin{cases} \frac{1}{2} A_m m(f) [H(f-f_c) + H(f+f_c)], & |f| < B \\ 0, & |f| > B \end{cases}$$

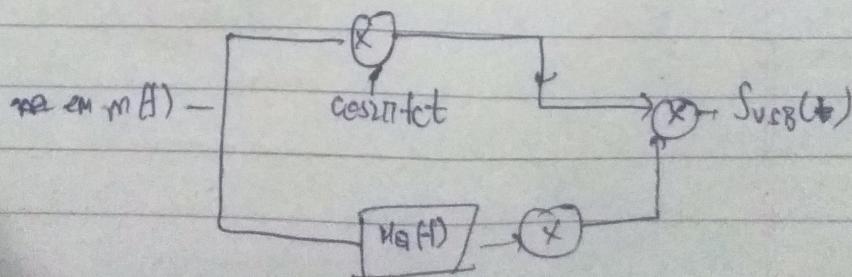
$$S_I(t) = \frac{1}{2} A_m m(t)$$

$$S_Q(f) = \begin{cases} \frac{1}{2} M(f) [S(f-f_c) - S(f+f_c)], & |f| < B \\ 0, & |f| > B \end{cases}$$

$$= \frac{1}{2} \frac{1}{2} M(f) [H(f-f_c) - H(f+f_c)]$$

$$H_Q(f) = \frac{1}{2} [H(f-f_c) + H(f+f_c)].$$

$$m(t) \xrightarrow{H_Q(f)} m'(t)$$



$x(t)$

$$x(t) = x_I \sin 2\pi f_c t - x_Q \cos 2\pi f_c t$$

DSB-SC

$$x_I(t) = m(t), x_Q(t) = 0$$

transfer
function

$$X_I(f) = \begin{cases} \frac{1}{2} A_c M(f) [H(f-f_c) + H(f+f_c)], & |f| < B \\ 0, & |f| > B \end{cases}$$

\Rightarrow Frequency

f

If \Rightarrow

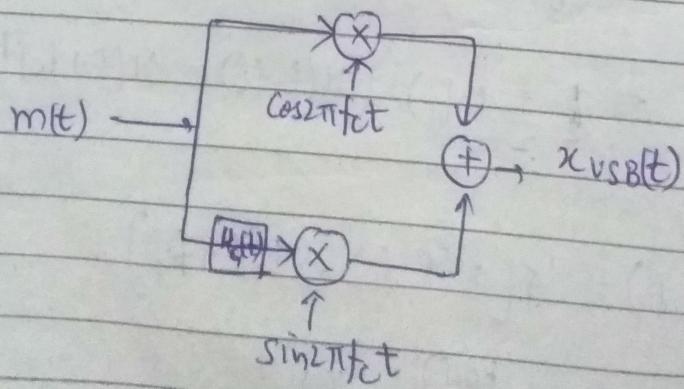
$$x_I(t) = \frac{1}{2} A_c m(t)$$

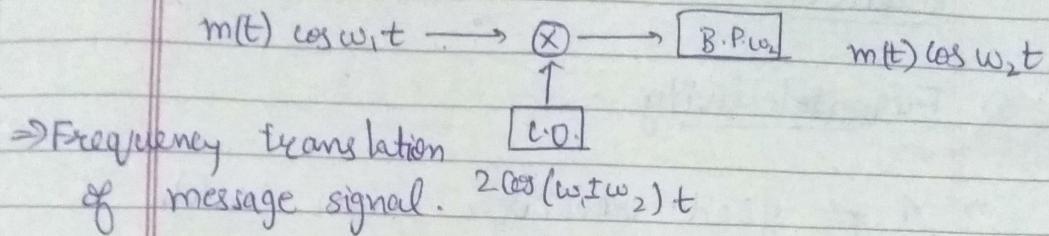
$$X_Q(f) = \begin{cases} \cancel{\frac{1}{2} A_c m(t)} j s(f-f_c) - s(f+f_c), & |f| < B \\ 0, & |f| \geq B \end{cases}$$

message

$$x_{VSB}(t) = \frac{1}{2} A_c m(t) \cos 2\pi f_c t - \frac{1}{2} A_c m'(t) \sin 2\pi f_c t$$

\Rightarrow





if $\Rightarrow m(t) \cdot \cos(\omega_1 + 2\omega_2)t$

$\cos(2\omega_1 + 3\omega_2)$
 $/ \cos(\omega_2)$

$2m(t) \cos \omega_1 t \cos(\omega_1 + \omega_2)t$
 $\times (\cos(2\omega_1 + 3\omega_2) + \cos \omega_2 t)$
 ↓
 filtered out $\Rightarrow \times \cos \omega_2 t$

→ Image frequency of ω_1 .

message $k(t) \cos(\omega_1 \pm 2\omega_2)t$

local oscillator $= 2 \cos(\omega_1 + \omega_2)t$

$\Rightarrow k(t) \cos(2\omega_1 + 3\omega_2)t + k(t) \cos(\omega_2 t)$

L.O. $(\omega_1 + 2\omega_2)$

IF $(\omega_1 + 2\omega_2)$

L.O. $(\omega_1 - \omega_2)$

IF $(\omega_1 - 2\omega_2)$

→ The main use of the translators is to design the oscillator receivers.

Receivers :-

① Freq. selectivity.

→ A good receiver can catch multiple frequencies.

② Sensitivity :-

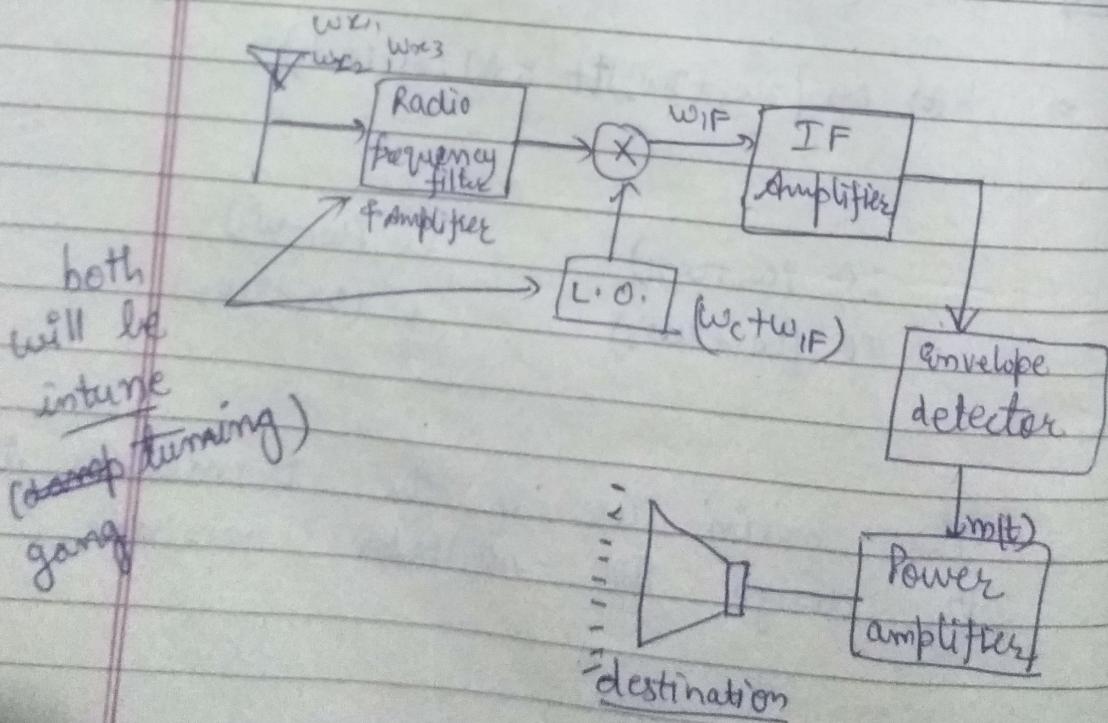
weak signal can also be received.

③ Fidelity..

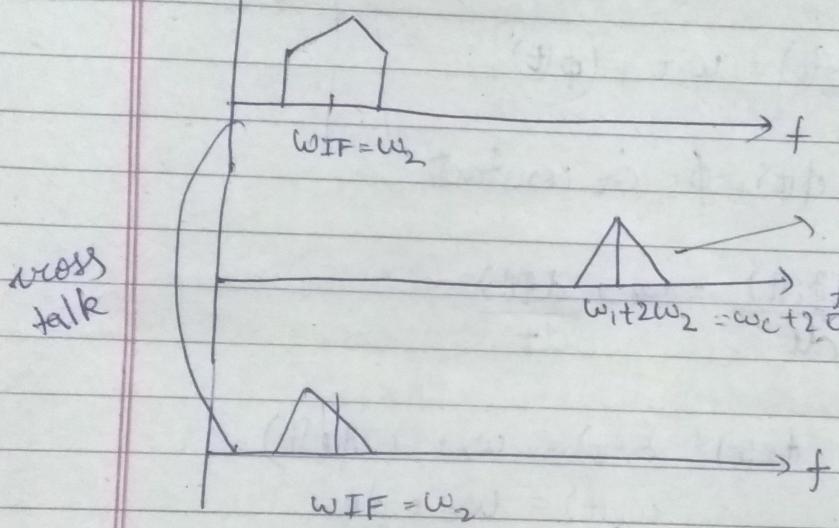
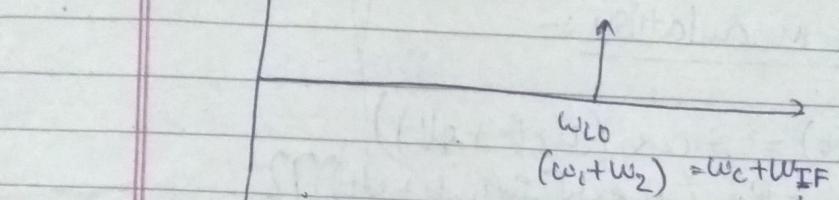
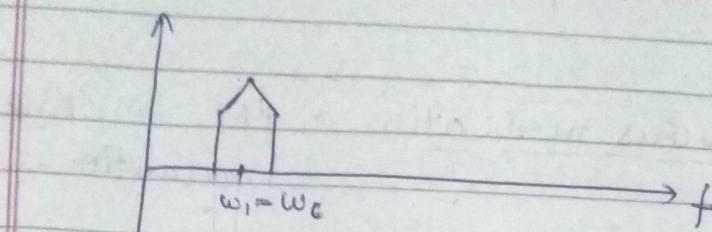
It should be able to produce baseband original baseband signal.

cross talk

Superhetroodyne receiver



100



$$\omega_{IF} = 455 \text{ kHz}$$

Continuous modulation \rightarrow fM, AM, Phase modulation.

Angle modulation :-

C.R.E. :-

$$\begin{aligned} x(t) &= A \cos(w_c t + \phi(t)) \\ &= \operatorname{Re} \left\{ A \exp[j(w_c t + \phi(t))] \right\} \end{aligned}$$

Instantaneous phase $\phi_i(t) = w_c t + \phi(t)$

$\Rightarrow \phi(t) = \phi$ or constant

$$\omega_i(t) = \frac{d\phi_i(t)}{dt} = \omega_c + \frac{d\phi(t)}{dt}$$

$\phi_i(t) = \omega_c t + \phi(t)$

$$\omega_i(t) = \omega_c + \frac{d\phi}{dt}$$

$$\phi(t) \propto m(t)$$

$$\phi(t) = k_p m(t)$$

$$\frac{d\phi(t)}{dt} \propto m(t)$$

$$\frac{d\phi(t)}{dt} = k_f m(t)$$

$$\phi(t) = k_f \int_{-\infty}^t m(\tau) d\tau$$

In stan

$$\frac{d\phi}{dt}$$

A

-A

Instantaneous phase deviation $\Rightarrow \phi(t)$

$\frac{d\phi}{dt}$ = instantaneous frequency deviation.

$-\phi(t) \propto$ (PM)

$$\phi(t) = K_p m(t)$$

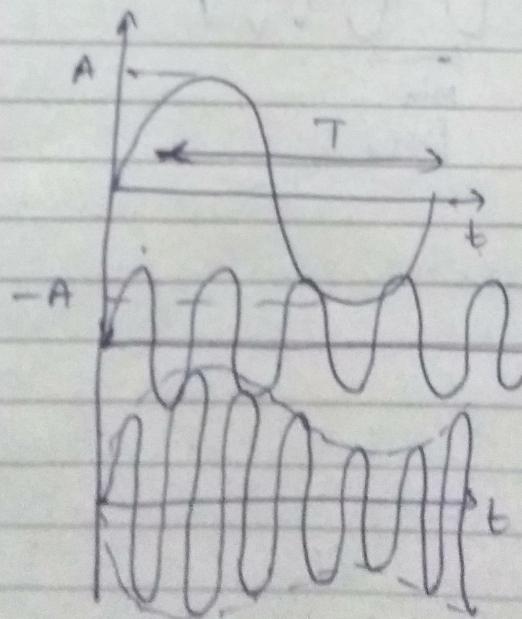
$$\frac{d\phi}{dt} = K_f m(t)$$

$$\phi(t) = K_f \int_{-\infty}^t m(\tau) d\tau \quad (\text{FM})$$

$$x(t) = A \cos(\omega t + \phi(t))$$

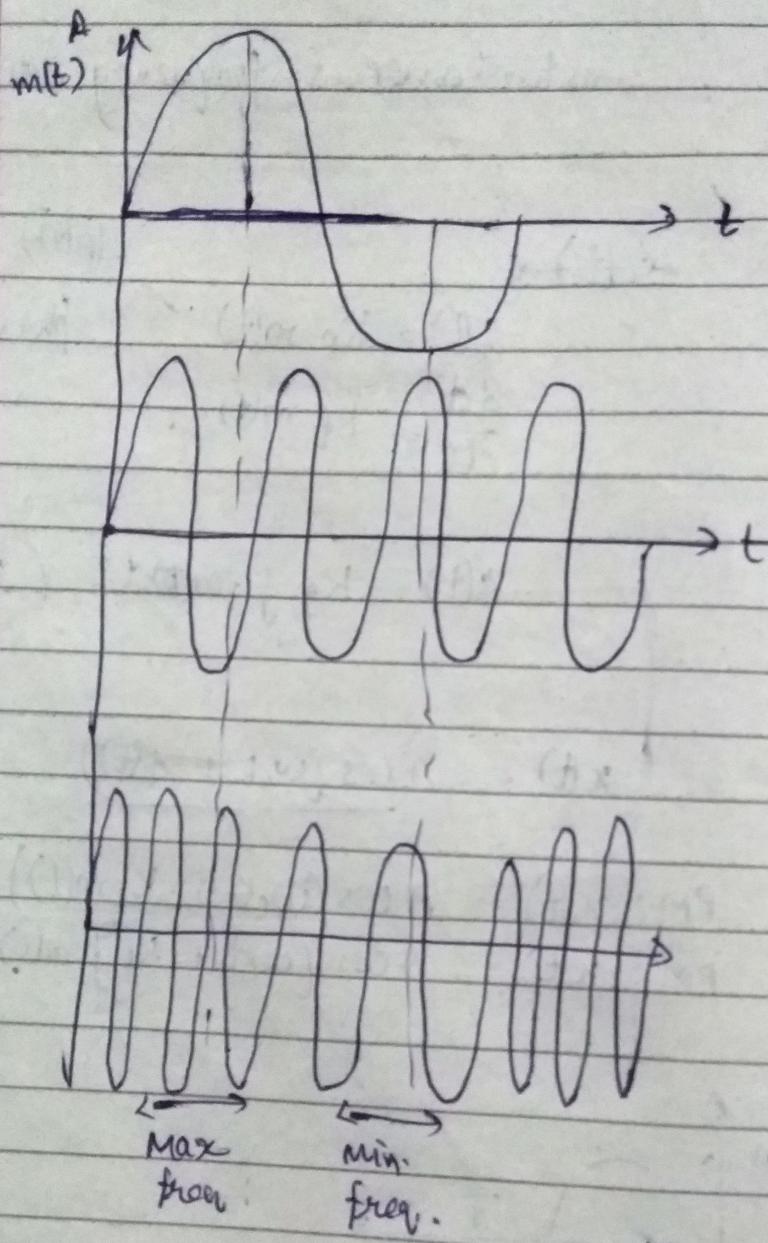
$$\text{PM: } x(t) = A \cos(\omega t + K_p m(t))$$

$$\text{FM: } x(t) = A \cos(\omega t + K_f \int_{-\infty}^t m(\tau) d\tau)$$

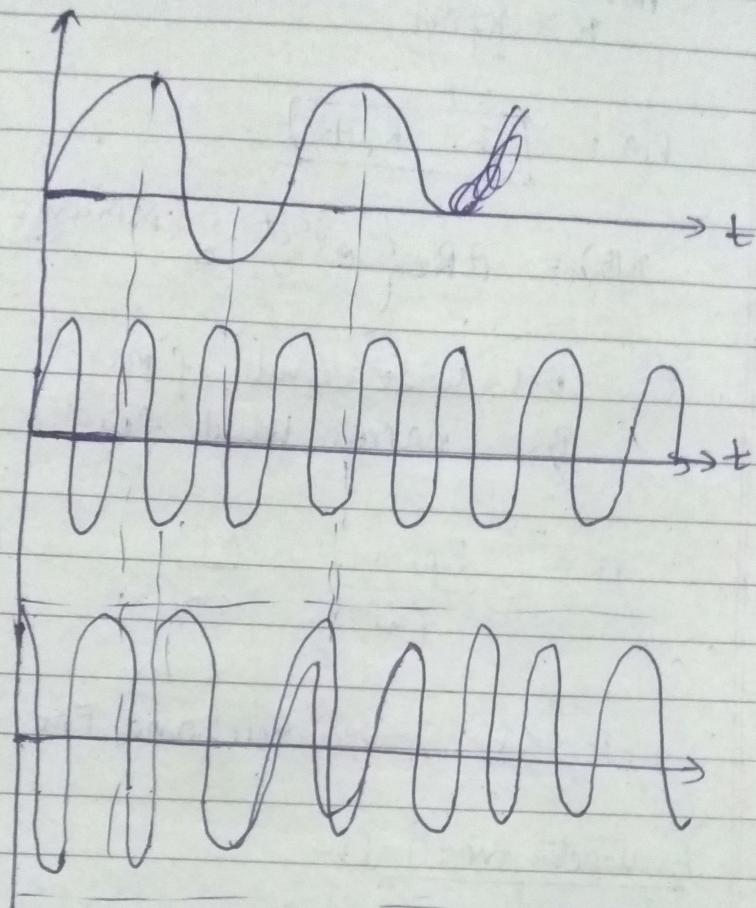


AM modulated wave

Frequency Modulated Wave



Phase modulated wave



- ⇒ FM and PM are non-linear and AM is linear.
 - ⇒ Exact spectrum calculation for angle modulation is difficult.
 - ⇒ Possible to study the spectrum when $m(t)$ is equal to $A_m \cos \omega_m t$
- $m(t) = A_m \cos \omega_m t$
- PM $\phi(t) = K_p A_m \cos \omega_m t$
- PM $\phi(t) = K_f A_m \sin \omega_m t$

$$x_{FM}(t) = A \cos(\omega_c t + \beta \sin \omega_m t)$$

$$\beta = \frac{K_f A_m}{f_m}$$

PM : $\boxed{\beta = K_p A_m}$

$$x(t) = A \operatorname{Re} \{ e^{j\omega_c t} e^{j\beta \sin \omega_m t} \}$$

$B \geq 1$ wide band FM.

$B < 1$ narrow band FM.

$$\beta = \frac{K_f \cdot A_m}{f_m} = \frac{\Delta f}{f_m}$$

K_f = sensitivity
factor (radiation)

$\beta \ll 1$ narrowband FM signal generation

Indirect method :-

$$m(t) = A_m \cos(2\pi f_m t)$$

(contd.)

$$x_{FM}(t) = A \cos(2\pi f_c t + \beta \sin(2\pi f_m t))$$

$\frac{\Delta f}{f_m} \ll 1$

$\Delta f \ll f_m$ (Narrow band FM)

$$x(t) = \underbrace{A \cos(2\pi f_c t + \beta \sin(2\pi f_m t))}_{\text{narrow band FM}}$$

$$x(t) = A \left(\cos(2\pi f_c t) \cos(\beta \sin 2\pi f_m t) - \sin(2\pi f_c t) \sin(\beta \sin 2\pi f_m t) \right)$$

$\beta \ll 1 \approx 0$

$\sin(\beta \sin 2\pi f_m t) \approx 0$

$$x(t) \approx A \left(\cos(2\pi f_c t) \times 1 - \sin(2\pi f_c t) \times 0 \right)$$

NB FM
narrow
band
FM