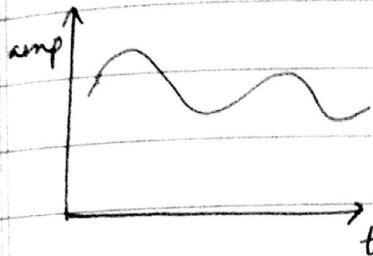


3.1.18

SIGNALS

Analog signal - continuous in time and continuous in amplitude.



Digital signal - ^{Digital} continuous in time and discrete in amplitude



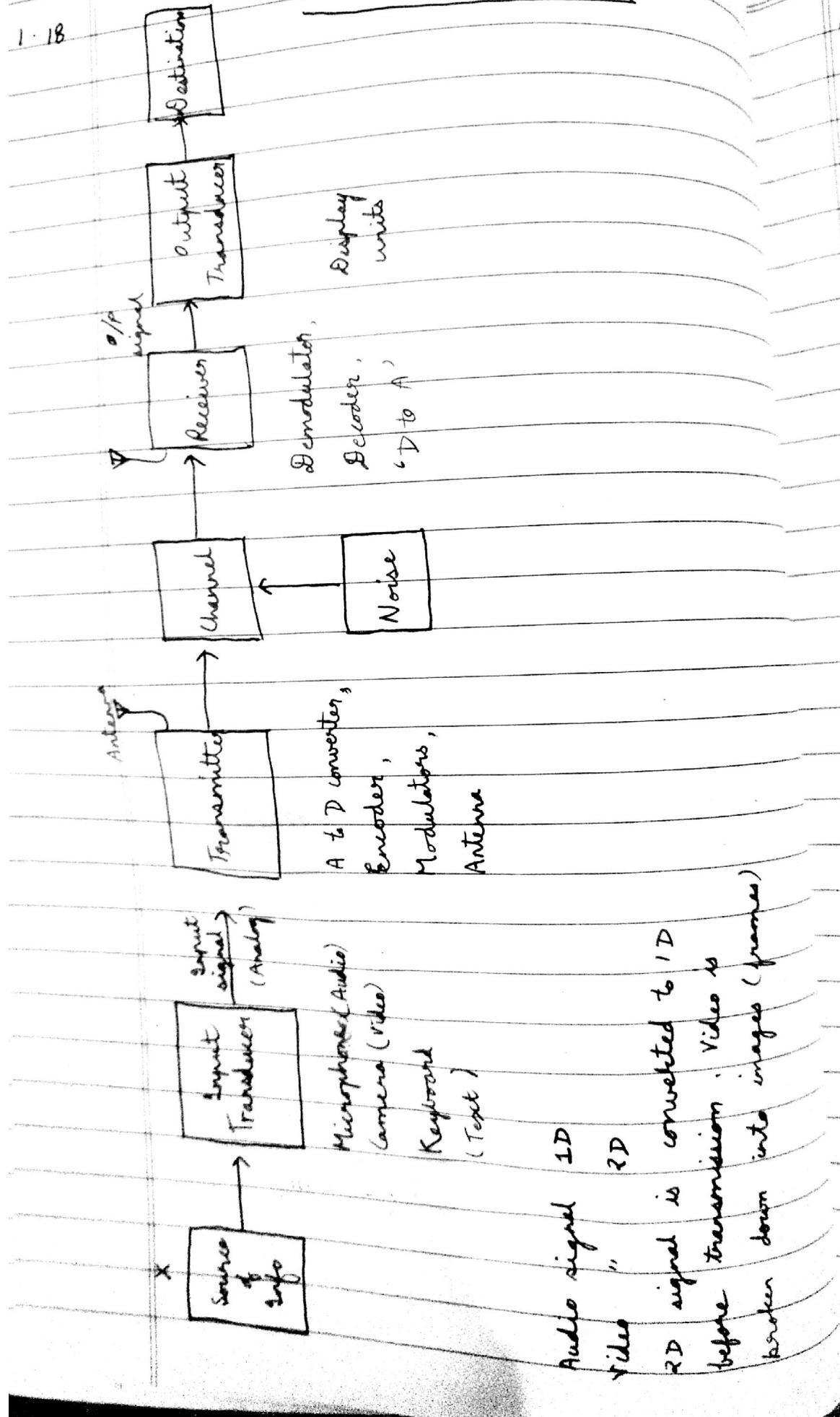
Analog \rightarrow ^{Digital} Sampling

^{Digital} Quantisation

Analog - real time signal, low frequency
more noise

Analog signals are converted to digital
signals for processing.

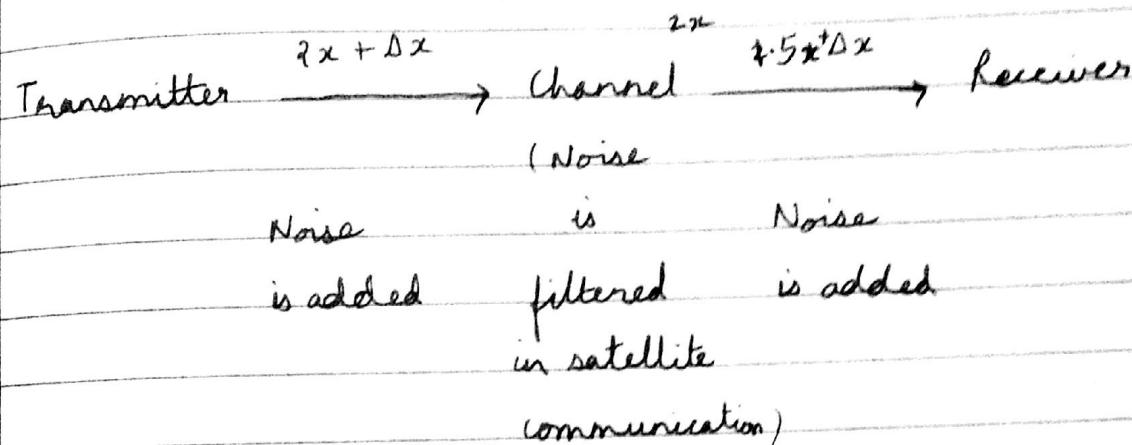
COMMUNICATION SYSTEMS



ATTENUEATION - Reduction in power of the signal.

DISTORTION - Change in wave form of the signal.

Satellite - Amplifies signal, filters noise.



Internal noise & external noise

- | | |
|---|--|
| ↓
Electronic components,
diffusion, random motion of carriers | ↓
<ul style="list-style-type: none"> interference, radiation from mobile ignition of automobiles can be eliminated completely greater effect (Δx) |
|---|--|

$$I \propto f^2 A^2 \quad (\text{Intensity})$$

Base band signal - low frequency signals

(few Hz to KHz) Audio

(MHz) Video

(00 MHz) FM radio

In transmitters, carrier signals have a high frequency. This process is known as modulation.

Carrier signals : GHz

Modulated signal → base band signal + Carrier signal

Low Pass Filter (LPF) should be used after removing noise.

Remove noise $\xrightarrow{\text{then}}$ Amplify signal

8.1.18

Freq. Range	Wavelength	Name	Tr. media	Application
3k - 30 kHz	100 - 10 km	VLF (Very low freq.)	Wire line	Telephony, telegraph
30 - 300 kHz	10 - 1 km	LF	(copper wires)	Aeronautical up
300 - 3 MHz	1 km - 100 m	MF	Ground wave	AM broadcast
3M - 30 MHz	100 - 10 m	HF	Sky wave	CB radio (walkie talkie)

30 - 300 MHz	10 - 1 m	VHF	Co Axial	VHF, TV, FM, Mobile
300 M - 3 G	1m - 10 cm	UHF		
3 G - 30 G	10 cm - 10 m	SHF	Wave guide	TV, SAT, mobile, LAN
10^{14}	10^{15}	$\sim 10^{-6}$ m	IR, VIS, UV	Optical fibre
				Broadband

Band width - Range of frequency transmitted without any loss.

Freq. Band	Carrier - Freq	B.W.
LF	100 kHz	~ 2 kHz
HF	5 MHz	100 kHz
VHF	100 MHz	5 MHz
Microwave	5 GHz	100 MHz
Optical	5×10^4 Hz	$10^6 - 10^7$ Hz

Tr. Medium	Typical Freq	Power (dB/L)
Twisted wire	1 kHz - 100 kHz	0.05 - 3
Coaxial cable	100 kHz - 3 MHz	1 - 4
Wave guide	10 GHz	1.5
Optical fibre	$10^4 - 10^5$	< 0.5

NEED OF MODULATION

- Height of antenna \propto Frequency Wavelength
 $\propto \frac{1}{\text{Frequency of the signal}}$

Modulation is used to reduce the height of antenna.

- Reduce noise and distortion.

Signal to noise ratio : $\frac{\text{Power/strength of signal}}{(\text{SNR}) - \text{Noise of signal}}$

It should be high for an efficient communication system.

Mostly, noise is added in the channel and sometimes at the transmitter end.

As the distance bet the ends of the comon system increases , SNR decreases.

Transceiver - Antenna for for transmitting as well as receiving signals.

SIGNALS

Signal is defined as a set of information.

signal Deterministic - can be represented mathematically

Random - unpredictable,
uncertain

e.g. human speech

Deterministic signal

$$A \cos(\omega_0 t + \phi) = R_c \{ A e^{j(\omega_0 t + \phi)} \}$$

$$= \frac{1}{2} A e^{j(\omega_0 t + \phi)} + \frac{1}{2} A e^{-j(\omega_0 t + \phi)}$$

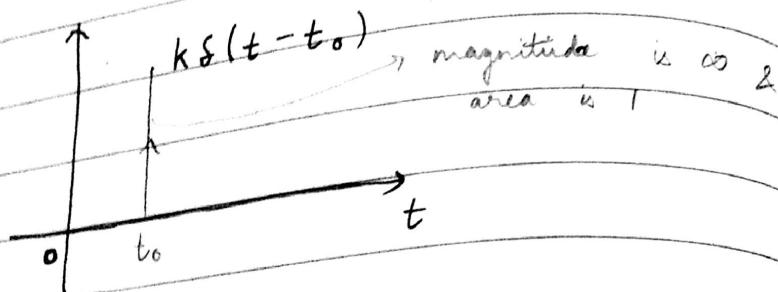
$$\text{Ex. } x(t) = 2 \sin\left(10\pi t - \frac{\pi}{6}\right)$$

$$= e^{j(10\pi t - \frac{2\pi}{3})} + e^{-j(10\pi t - \frac{2\pi}{3})}$$

Impulsive function

$$\int_{-\infty}^{\infty} s(t) dt = 1$$

$$s(t) = 0, t \neq 0$$



1. Shifting property

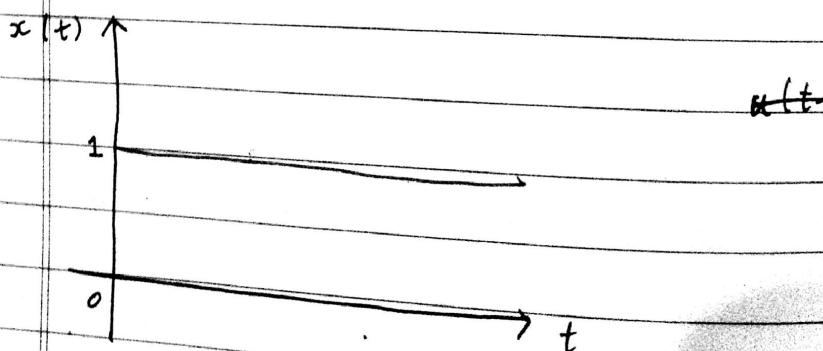
$$\int_{-\infty}^{\infty} x(t) \delta(t - t_0) dt = x(t_0)$$

Proof also
in course

2. Scaling property $\delta(at) = \frac{1}{|a|} \delta(t)$

$$x(t) \delta(t - t_0) = x(t_0) \delta(t)$$

Unit step function



$$\begin{aligned} u(t) &= 1, & t > 0 \\ &= 0, & t < 0 \\ &= \int_{-\infty}^t \delta(x) dx \end{aligned}$$

Fourier series

$$\text{If } x(t + T_0) = x(t) \quad \forall t$$

$$x(t) = \sum_{n=-\infty}^{\infty} X_n e^{j 2\pi n f t}$$

$$\omega_0 = \frac{2\pi}{T_0}$$

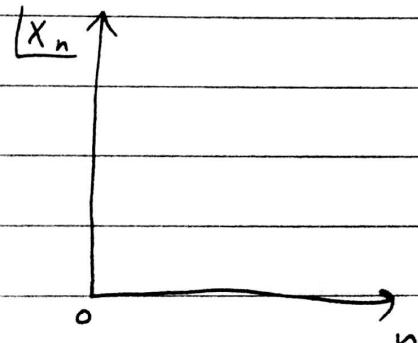
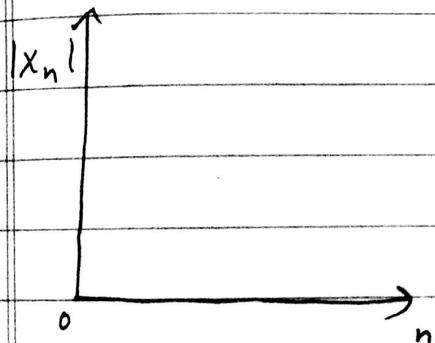
X_n = coefficient of fourier series

$$X_n = \frac{1}{T_0} \int_{t_0}^{t_0 + T_0} x(t) e^{-jn\omega_0 t} dt$$

(Applied for periodic signals)

Magnitude spectrum $|X_n|$

Phase " $\angle X_n = \phi_n$



Properties

- For real $x(t)$; $|X_n| = |X_{-n}|$

$$\angle X_n = -\angle X_{-n}$$

Mag. sp. is symmetric, phase sp. is asymmetric.

- $X_n^* = X_{-n}$ (complex conjugate of X_n)
defined for real signal

Energy signal

$$E_x = \int_{-\infty}^{\infty} |x(t)|^2 dt$$

$$x(t) = \begin{cases} e^{-t}, & t \geq 0 \\ 0, & t < 0 \end{cases}$$
$$= e^{-t} u(t)$$

$$E_x = \int_0^{\infty} |e^{-t}|^2 dt$$

$$= \left[\frac{e^{-2t}}{-2} \right]_0^{\infty} = \frac{1}{2}$$

$$\boxed{E_x = \frac{1}{2}}$$

$x(t)$ is the energy signal.

Power signal

$$i_x = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |x(t)|^2 dt$$

energy of the signal

$$= \lim_{T \rightarrow \infty} \frac{\text{energy in window of size } T}{T}$$

If $P_x < \infty$ (Power is finite),
then the signal is a power signal.

$$\begin{aligned} P_x &= \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |x(t)|^2 dt \\ &= \lim_{T \rightarrow \infty} \frac{E_x}{T} = 0 \quad (x(t) \text{ is energy signal}) \end{aligned}$$

$\rightarrow x(t)$ is power signal -:

$$\begin{aligned} E &= P_x T \\ &= \infty \end{aligned}$$

Window - duration or size

PARSEVAL'S THEOREM

$$P = \frac{1}{T} \int_{-T/2}^{T/2} |x(t)|^2 dt$$

$$= \sum_{n=-\infty}^{\infty} |x_n|^2$$

FOURIER TRANSFORM

Fourier series is defined for infinite periodic signals

" transform " " " any type of signals "

~~$x(t)$ is the fourier transform of $x(t)$~~

$$x(f) = \int_{-\infty}^{\infty} x(t) e^{-j2\pi ft} dt$$

Some analysis is easily done in time domain & some analysis in frequency domain.

15.1

Inverse fourier transform:

$$x(t) = \int_{-\infty}^{\infty} x(f) e^{j2\pi ft} df$$

$$\underline{x(f)} = \left\{ \begin{array}{l} x(f) = |x(f)| e^{j\theta(f)} \end{array} \right.$$

Properties

1. For real signal $x(t)$, $x^*(f) = x(-f)$

2. $\int_{-\infty}^{\infty} |x(t)| dt = \int_{-\infty}^{\infty} |x(f)| df$

Parsvals
theorem

3. Convolution property $x(t) = x_1(t) \oplus x_2(t)$

$$= \int_{-\infty}^{\infty} x_1(\tau) x_2(t-\tau) d\tau$$

$$x_1(t) \oplus x_2(t) \xleftarrow{F} x_1(f) x_2(f)$$

Time delay :- $x(t) \longleftrightarrow x(f)$

$$x(t-t_0) \longleftrightarrow x(f)e^{-j2\pi f t_0}$$

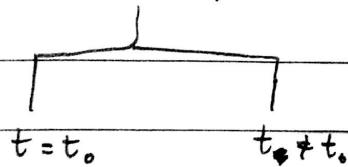
15.1.18 PROOFS

1. Time delay property

$$\delta(x) = \begin{cases} 1, & x=0 \\ 0, & x \neq 0 \end{cases} \quad \text{Impulse function}$$

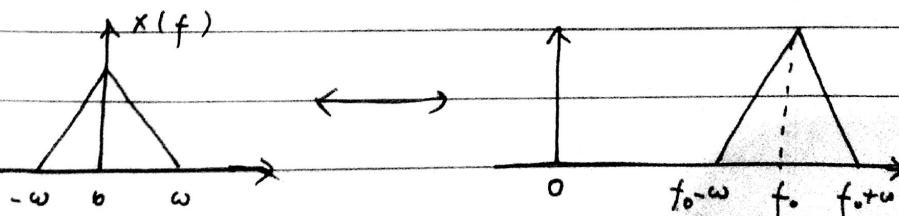
$$\delta(t-t_0) = \begin{cases} 1, & t = t_0 \\ 0, & t \neq t_0 \end{cases}$$

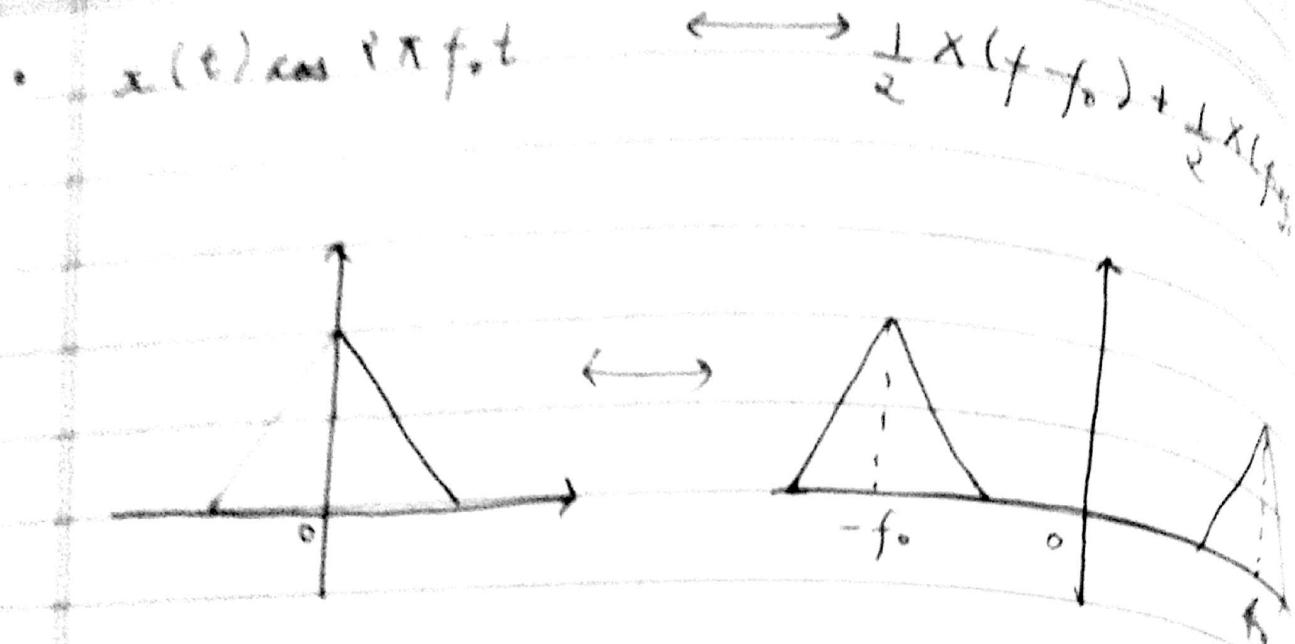
$$\delta(t) \delta(t-t_0) = x(t) \delta(t-t_0)$$



FREQUENCY TRANSLATION

- $x(t) \cdot e^{j2\pi f_0 t} \longleftrightarrow X(f-f_0)$





DIFFERENTIATION PROPERTY

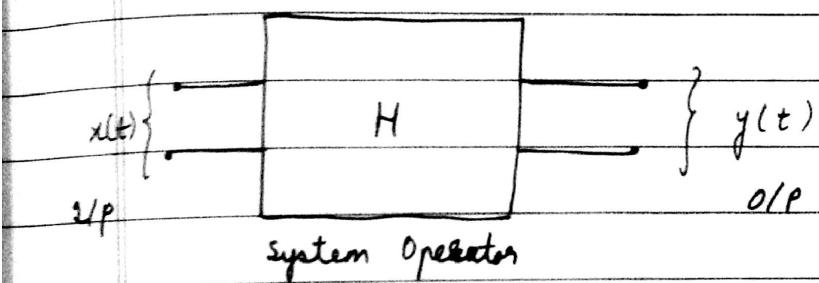
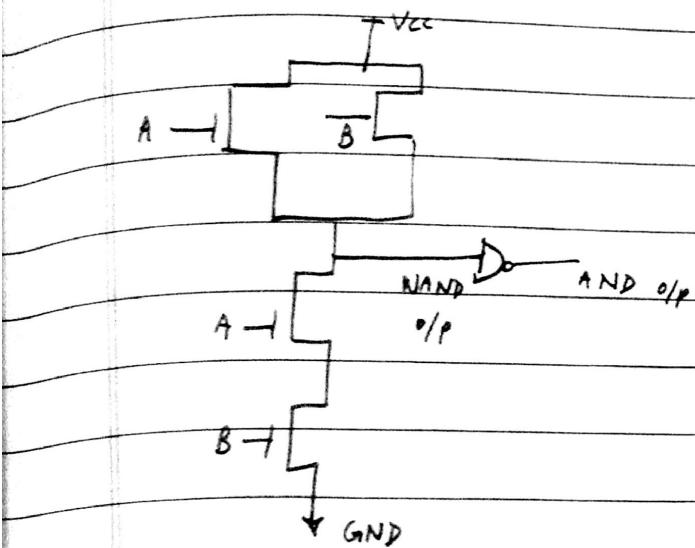
$$\cdot \frac{d^m x(t)}{dt^m} \longleftrightarrow (j 2\pi f)^m X_f$$

$$\int_{-\infty}^{\infty} x(\sigma) d\sigma \longleftrightarrow \frac{1}{j 2\pi f} X(f) + k X(0)$$

15.1.18

SYSTEMS

System - Interconnection of active and passive components to fulfill an application (Electronic and mechanical components).



A system is designed for a specific application system modelling

$$y(t) = H[x(t)], \quad H \rightarrow \text{System operator}$$

LTI system - linear time invariant
Linear time variant systems.

LTI system follows superposition property.
 $x_1(t) \rightarrow y_1(t)$

$x_1(t) \rightarrow y_1(t)$

→ linearity property :-

$a_1 x_1(t) + a_2 x_2(t) \rightarrow a_1 y_1(t) + a_2 y_2(t)$

LTI system (superposition) →

→ Time invariant property

$$x(t) \rightarrow y(t)$$

$$x(t-t_0) \rightarrow y(t-t_0)$$

Delay of the system is assumed to be zero.

Time taken by the system to process the input signal is known as propagation delay time.

t_0 - delay from input side

Delay $\propto \frac{1}{\text{Speed of the system}}$

→ CAUSALITY

$$h(t) = 0 \quad \text{for } t < 0 \quad (\text{LTI + causal system})$$

→ STABILITY

→ (LTI + Stable system) follows Big BIBO property (Bounded input bounded output)

$$|x(t)| < M$$

$$|y(t)| < K$$

(Final 1P 2019)

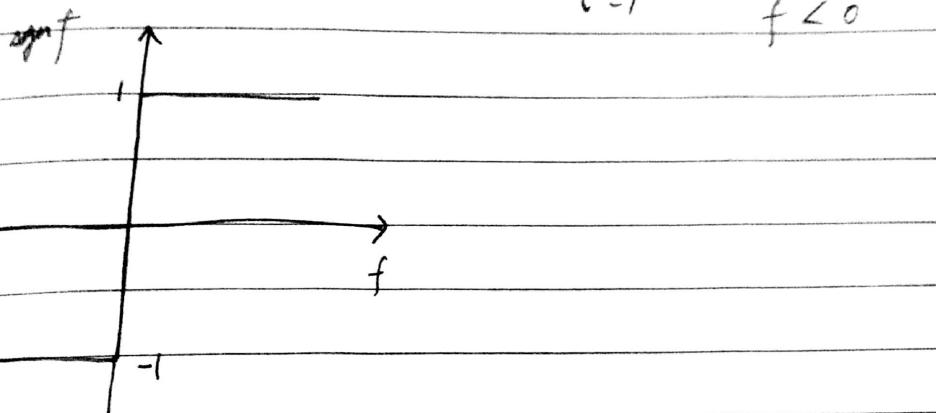
Hilbert Transform

Single side band modulation technique

Consider a LTI filter and its Hilbert transform, $H(f) = j \operatorname{sgn} f$

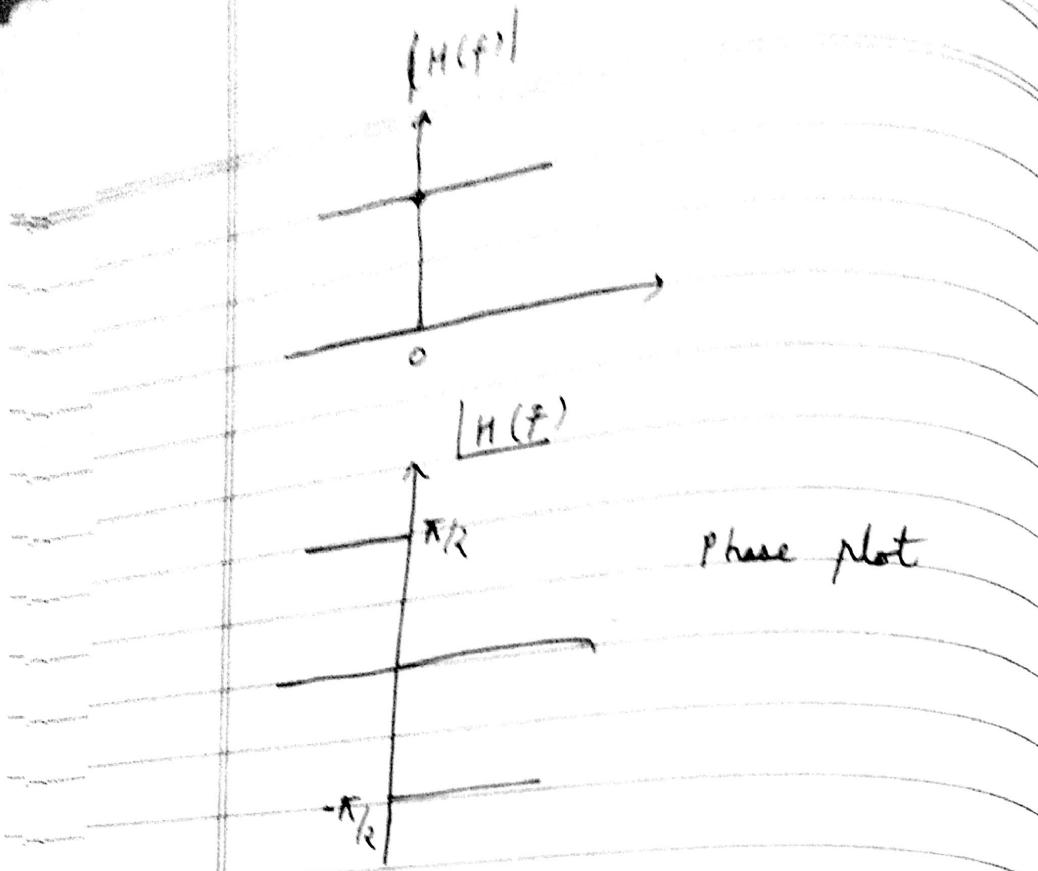
Signum function $\therefore \operatorname{sgn} f = \begin{cases} 1 & f > 0 \\ 0 & f = 0 \\ -1 & f < 0 \end{cases}$

$$\operatorname{sgn} f = \begin{cases} 1 & f > 0 \\ 0 & f = 0 \\ -1 & f < 0 \end{cases}$$



$H(f) = j \operatorname{sgn} f$ Frequency components are shifted.

Phase plot Phase shift of all frequency components of input signal takes place by $-\pi/2$ for +ve component & $+\pi/2$ for -ve component.



$$\frac{t}{\pi} \leftrightarrow \operatorname{sgn} f \quad (\text{Hilbert transform})$$

16.1.18 PROPERTIES

1. $\hat{x}(t) = -x(t)$ Double Hilbert trans

$\hat{x}(t)$ - Hilbert transform of $x(t)$

2. $x(t) = \cos 2\pi f_0 t$

$$\hat{x}(t) = \sin 2\pi f_0 t$$

• $x(t) = \sin 2\pi f_0 t$

$$\hat{x}(t) = -\cos 2\pi f_0 t$$

• $x(t) = e^{j 2\pi f_0 t}$

$$\hat{x}(t) = -j \operatorname{sgn}(2\pi f_0) e^{j 2\pi f_0 t}$$

3. $\hat{x}(f) = (-j \operatorname{sgn} f) \hat{x}(f)$ $\hat{x}(f)$ - Fourier transform of $x(t)$

4. $|x(f)| = |\hat{x}(f)|$

5. $\int x^2(t) dt = \int |x(f)| df$

6. $x(t)$ and $\hat{x}(t)$ are orthogonal.

$$\int_{-\infty}^{\infty} x(t) \hat{x}(t) dt = 0$$

$$\Rightarrow \int_{-\infty}^{\infty} x(f) \hat{x}^*(f) df = \int_{-\infty}^{\infty} x(f) (-j \operatorname{sgn} f) \hat{x}^*(f) df$$

$$= \int_{-\infty}^{\infty} j \operatorname{sgn} f |x(f)|^2 df$$

7. asymmetric function even symmetric function

5. Let $c(t)$ and $m(t)$ have non overlapping spectra (2 diff. signals whose spectra don't overlap)

$c(t)$: carrier signal

$m(t)$: message signal

$$m(t)c(t) = m(t) \cdot \hat{c}(t)$$

$$m(t) \cos \omega_0 t = m(t) \cdot \sin \omega_0 t$$

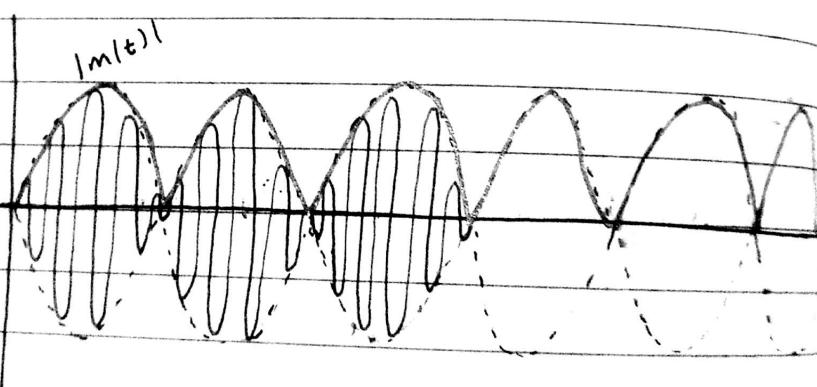
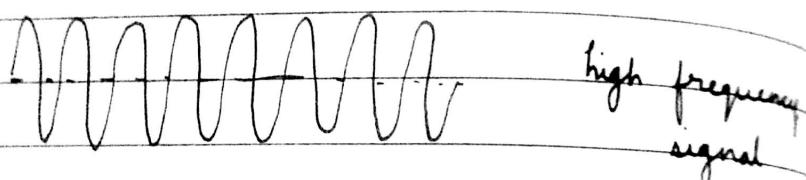
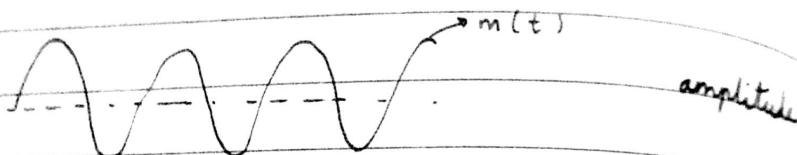
$$m(t) \cdot \sin \omega_0 t = -m(t) \cos \omega_0 t$$

APPLICATIONS OF HILBERT TRANSFORM

$x(t)$ is a real valued function (e.g.)
 $x_p(t)$: complex valued signal of $x(t)$

$$x_p(t) = x(t) + jx'(t)$$

$$m(t) \cdot \cos(\omega_0 t + \theta)$$



Modulating signal

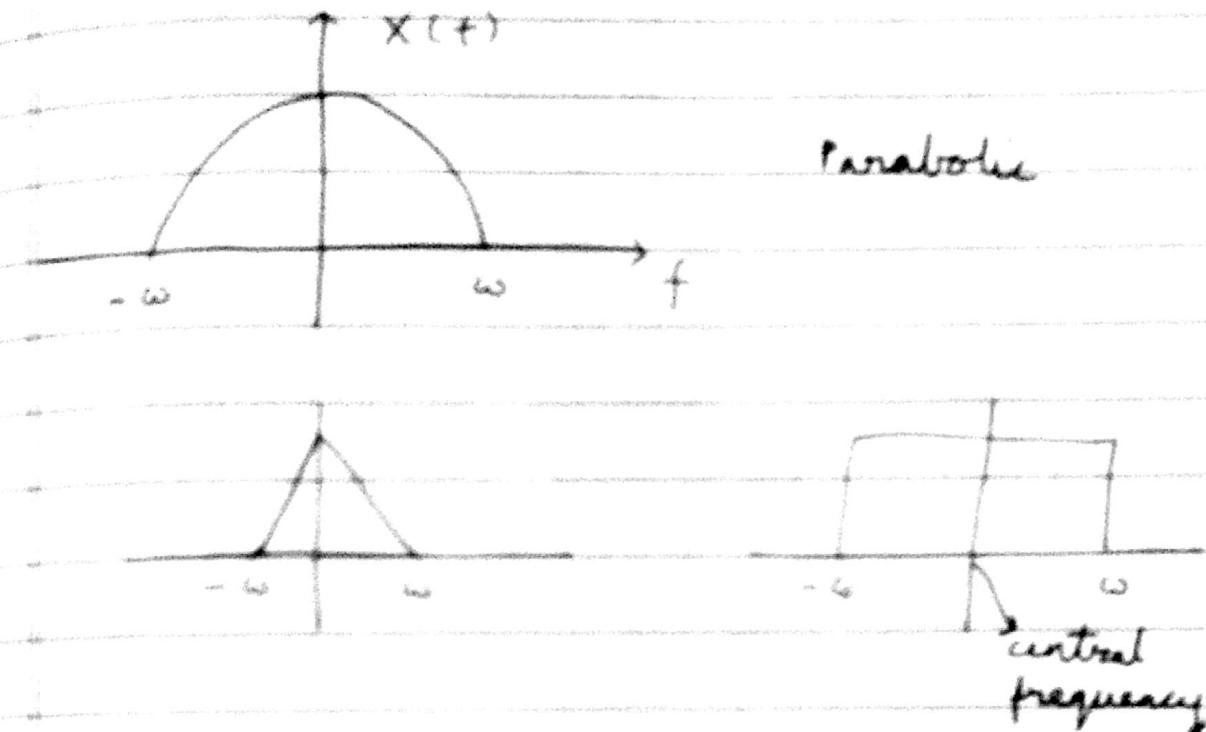
$$\begin{aligned} m(t) \cos(\omega_0 t + \theta) &= m(t) \cos \omega_0 t \cos \theta \\ &\quad - m(t) \sin \omega_0 t \sin \theta \end{aligned}$$

$$\begin{aligned} \text{Magnitude} &= \sqrt{m^2(t) \cos^2 \theta + m^2(t) \sin^2 \theta} \\ &= |m(t)| \end{aligned}$$

complex envelope of $x(t)$

$$x_p(t) = x(t) + j\hat{x}(t)$$

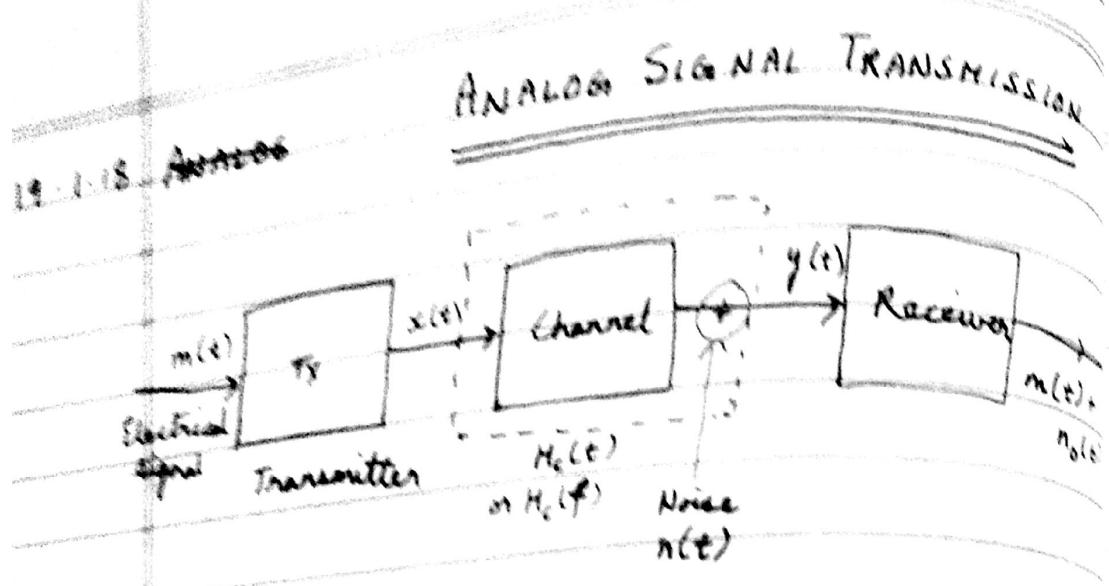
$$|x_p(t)|$$



The shape may be any of the above
but the frequency range remains the
same

Complex Envelope representation Band Pass Signal

D.S.B & S.S.B modulation techniques



Channel is modelled as LTI system

$y(t) = \text{base band signal} + \text{noise}$

Receiver tries to reduce noise as much as possible.

$n_r(t)$: resonant noise

(mostly internal.)

Ideal channel

Ideal filter : Noise ~ 0

Condition - Distortion less transmission

$$y(t) = kx(t - t_0)$$

k - Scaling factor

t_0 - Delay

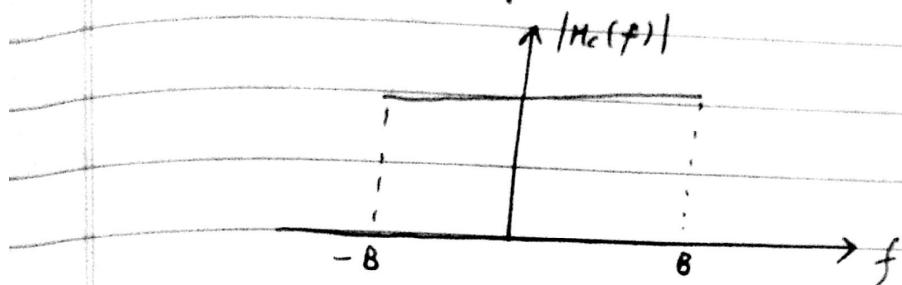
$$y(f) = k e^{j 2\pi f t_0} x(f)$$

Ideal channel

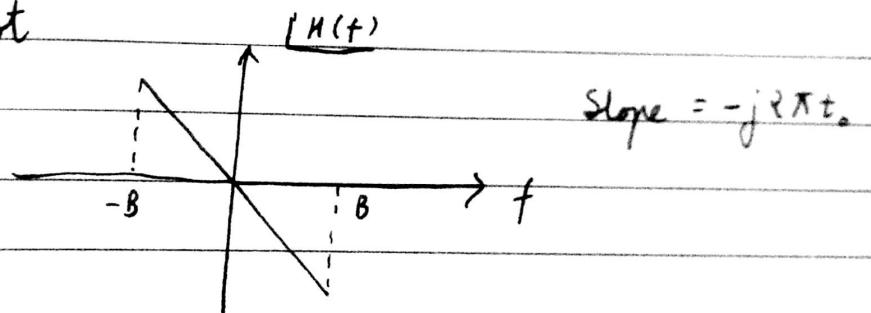
$$H_c(f) = k e^{-j2\pi f t_0}$$

t_0 - propagation delay

Magnitude plot of $H_c(f)$:



Phase plot



$k < 1$: Attenuation factor

$k > 1$: Amplification "

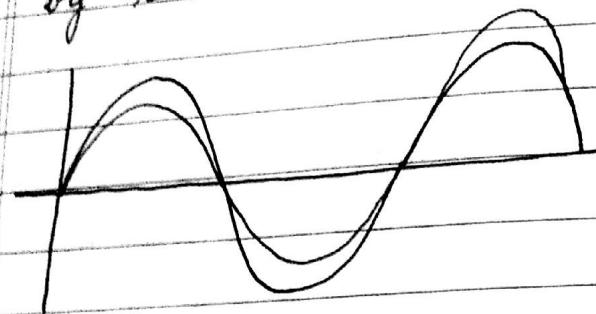
Amplitude should not be from $-\infty$ to ∞ (in the graph), it should be in the given range ($-B$ to B)

Distortion - if the range of f in mag. plot & phase plot are different
(Linear distortion)

LINEAR AMPLITUDE DISTORTION

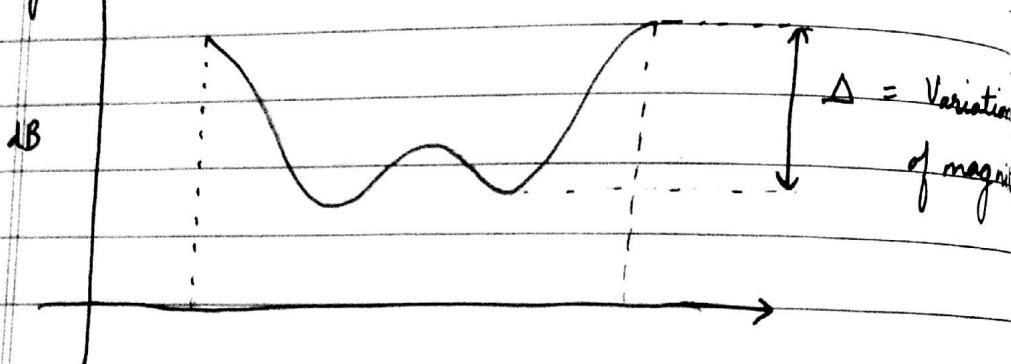
$$|H_c(f)| \neq k$$

All message signals are not modified by the same attenuation factor k .



Scaling factor k differs at different points.

$$20 \log |H_c(f)|$$



If $\Delta > 1$, amplitude distortion should be eliminated.
If $\Delta < 1$, distortion can be neglected.

PHASE DISTORTION / DELAY DISTORTION

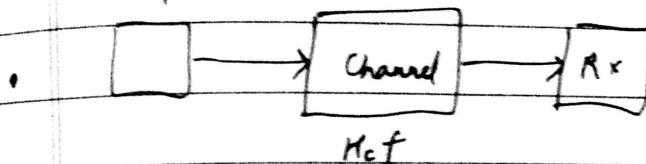
$$H_c(f) = -2\pi f t_0 + m\pi \quad |f| < B$$

If phase plot is not linear

All frequency components are not delay by the same factor.

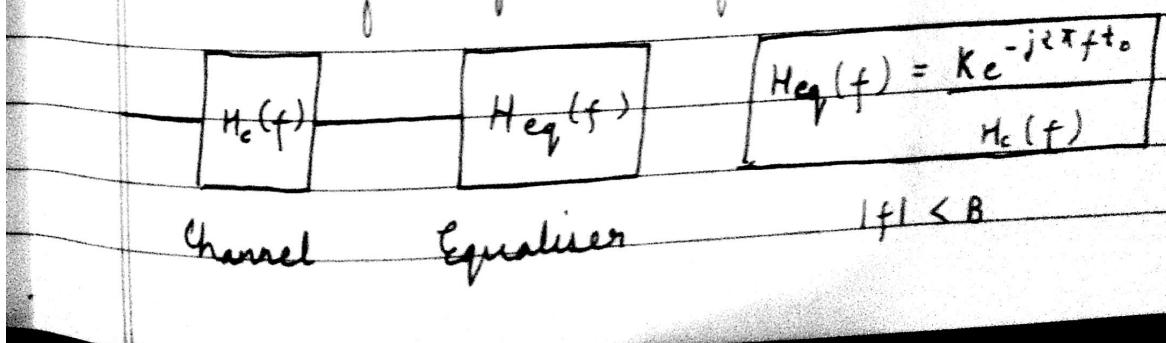
• Delay distortions are not important in speech transmission because ears are insensitive to delay distortion.

• Data transmission is highly sensitive to delay distortion.



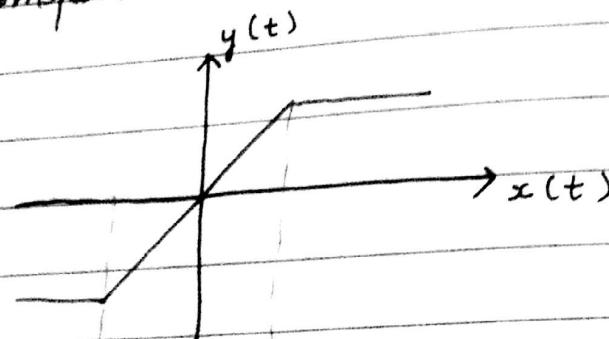
Receiver function is the inverse of that of channel to eliminate noise distortion.

Equalisation - Amp and phase distortion eliminated by adding an equaliser at the receiver end, the function of which is the inverse of the transfer function of the channel.



NON LINEAR DISTORTIONS

Non linear distortion arises due to non linear transfer characteristics of amplifiers, mixers and other electronic components in the communication system.



linear characteristics followed after that saturation occurs

$$y(t) = A x(t)$$

(valid in the linear range)

$$y(t) = a_1 x(t) + a_2 x^2(t) + a_3 x^3(t) + \dots$$

q. $y(t) = a_1 x(t) + a_2 x^2(t)$

Evaluate a_1 and a_2 .

$$x(t) \rightarrow f$$

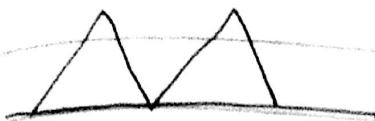
$$x(t) = \sin 2\pi f t$$

$$y(t) = a_1 \sin 2\pi f t + a_2 \sin^2 2\pi f t$$

$\xrightarrow{2f} \downarrow$ (non linear dist.)

$$x(t) \rightarrow f_1, f_2$$

$$y(t) = f_1, f_2, f_1 + f_2, 2f_1$$



Interference /
Cross talk

- disturbing other
frequency components

2.9.18

LINEAR MODULATION

Need of modulation

- SNR becomes high (efficient transmission),
- Reduce the size of antenna.
- Increase bandwidth of message signal.
- Frequency division multiplexing.
- Noise reduction is better with modulation.
- Energy losses less for high frequency.

MODULATE - Change, tune or translate

Amp, freq, phase modulation

Modulating amp, freq, phase of carrier signal.

Baseband signal - data, audio, video
(low frequency)

ADVANTAGES OF MODULATION

1. Ease of radiation
2. Multiplexing - multiple signals can be passed
3. Convenient signal processing
4. Noise reduction - depends on baseband signal & carrier frequency

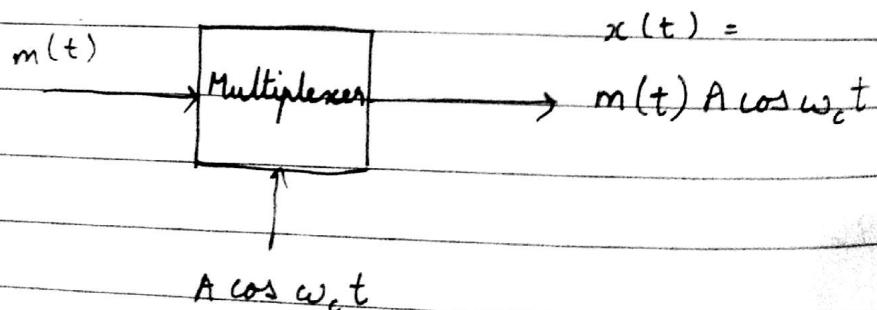
5. ~~Converser~~

Message signal : $m(t)$ (low freq)

$m(t) = a$. Message signal can be of arbitrary form. It need not be sinusoidal.

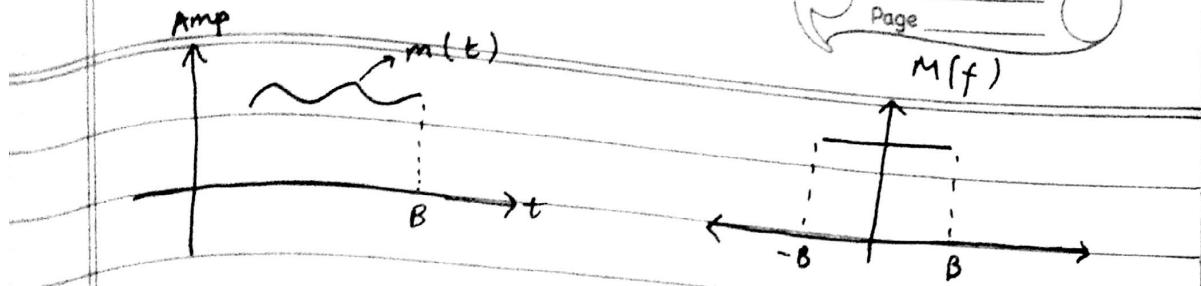
Carrier signal : $A \cos \omega_c t$ (high freq)

Frequency translation



DSB - SC : Double side band with suppressed carrier

$$x(f) = \frac{A}{2} [M(f + f_c) + M(f - f_c)]$$

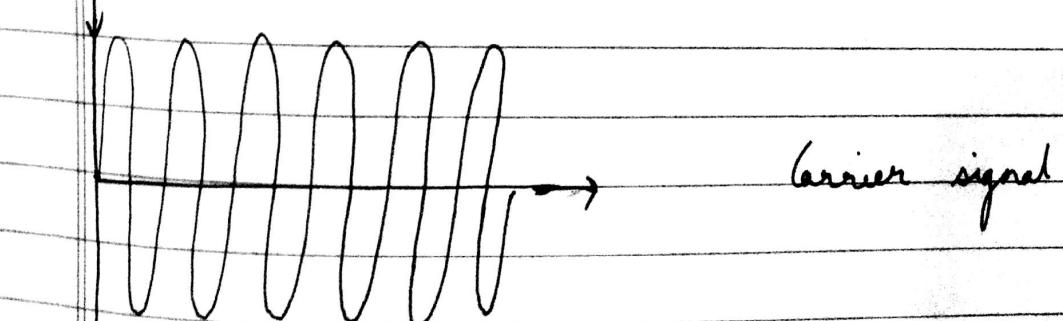
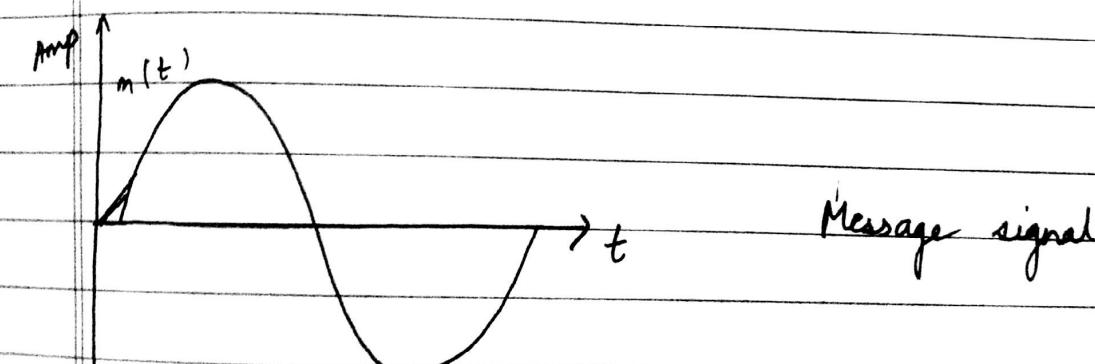
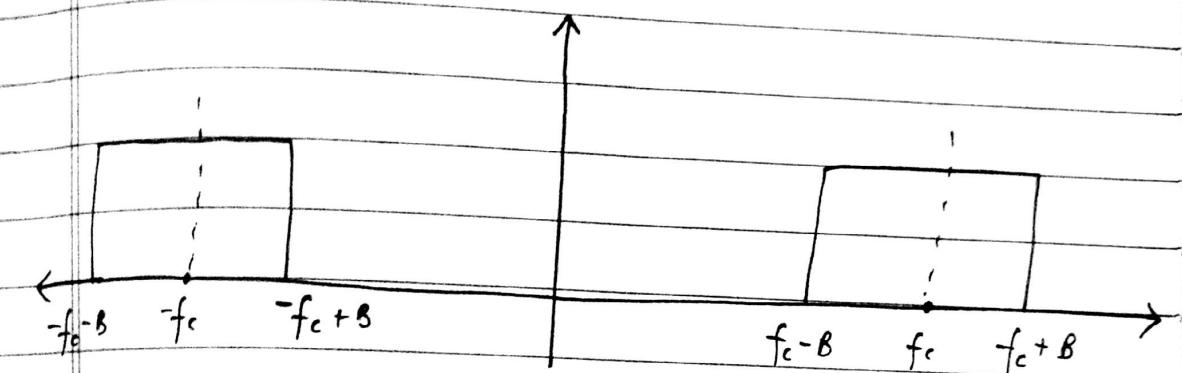


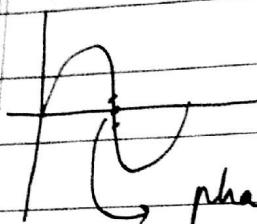
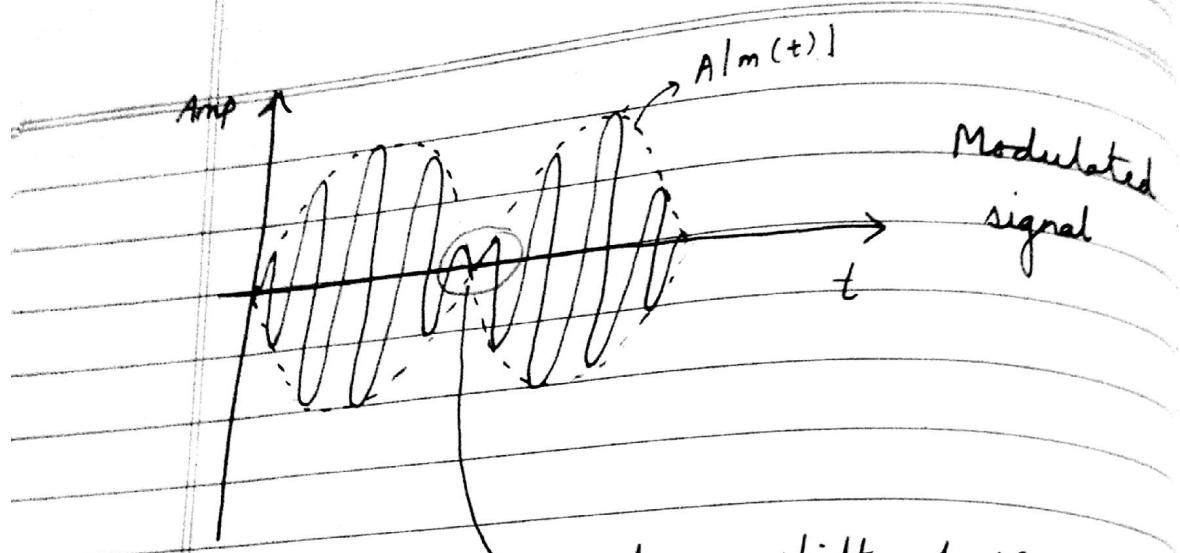
Bandwidth of message signal = B

Range $[-B, B]$

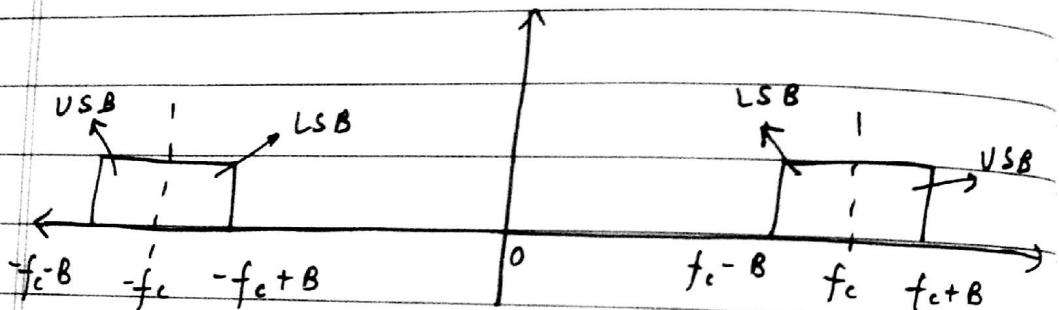
Message consists only $[0, B]$

We are representing $M(f)$ & $m(t)$ in the frequency domain $(-B, B)$.





phase shift of 180
(+ve the 0 - ve)

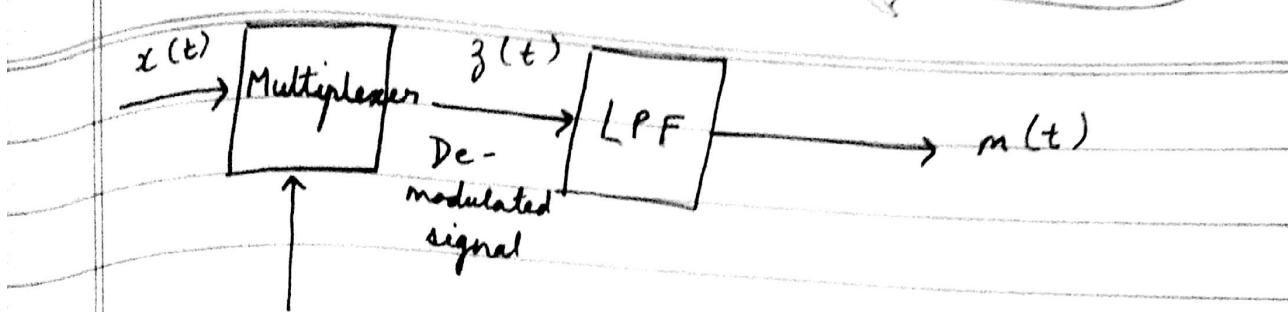


LSB - Lower side band

USB - Upper side band
(Double side band)

$$x(t) \rightarrow m(t)$$

Receiver end
(Modulated signal)



$\sqrt{2} \cos \omega_c t$

(Carrier signal)

Quartz oscillator - used to produce constant frequency.

Capacitor does not generate const. freq.

LPF - Low pass filter

Filters high frequency and lets low freq. pass.

This multiplexing is known as demultiplexing.

DSB-SC

$$x(t) = A m(t) \cos \omega_c t$$

$$\sqrt{2} \cos \omega_c t$$

$$z(t) = k^* [m(t) \cos \omega_c t] [\sqrt{2} \cos \omega_c t]$$

$$= k [m(t) \sqrt{2} \cos^2 \omega_c t]$$

$$= k m(t) + k m(t) \cos 2\omega_c t$$

↓
needed

LPF
passes

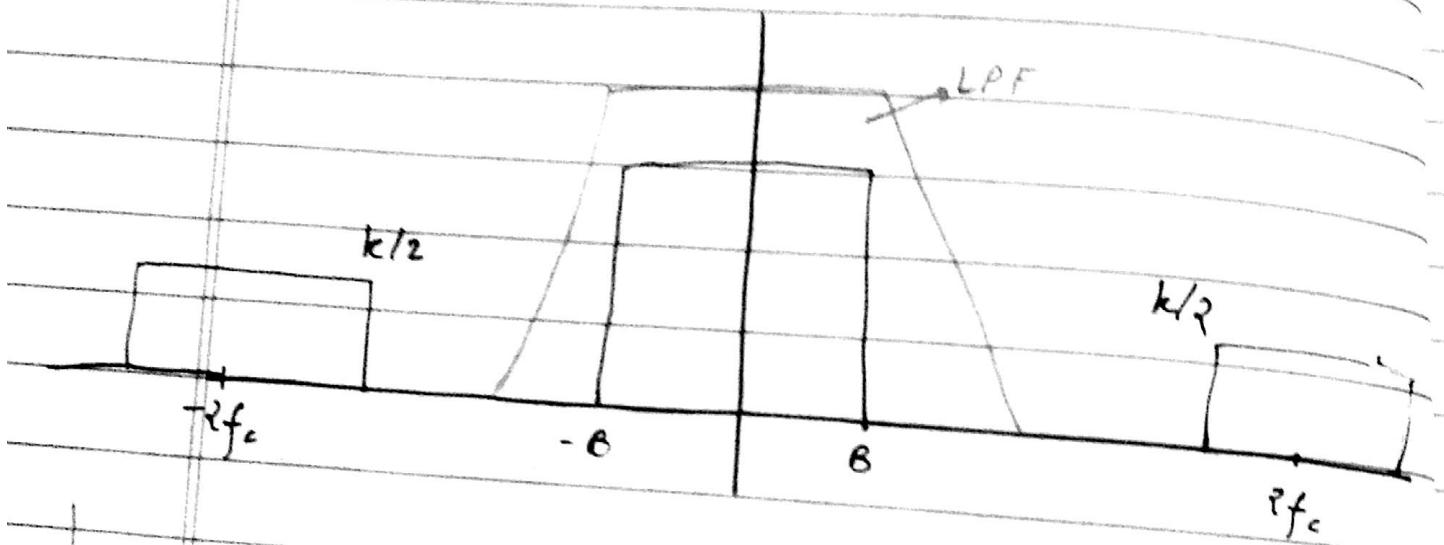
↓
not needed

LPF
removed

$$z(f) = kM(f) + \frac{k}{2} [M(f - 2f_c) + M(f + 2f_c)]$$

high freq
(removed)

$M(f)$: Baseband signal



If modulated and demodulated freq is not the same, accurate baseband signal will not be obtained.

Synchronised carrier is required for this process.

COHERENCE

Carrier (at receiver end) : $\sqrt{2} \cos [(\omega_c + \delta\omega)t + \phi]$
very small value

Carrier should be the same at receiver end and transmitter end.

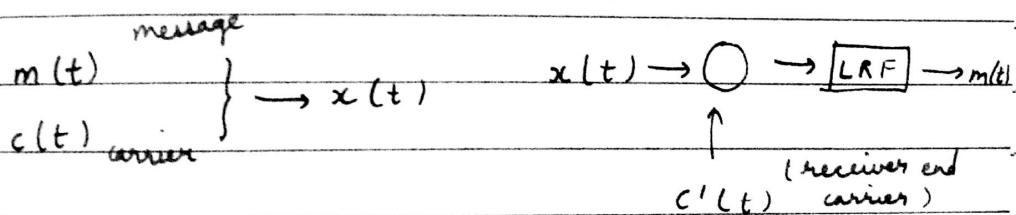
$$1. \delta\omega = 0 \quad \sqrt{2} \cos(\omega_c t + \phi)$$

$$\text{if } \phi = \pi/2 \quad -\sqrt{2} \sin \omega_c t$$

$$2. \delta\omega \neq 0, \phi = 0$$

Wobbling effect - Extra frequency component is introduced at the receiver end.

Demodulated signal is distorted.



If $c'(t)$ & $c(t)$ are not the same then Wobbling effect occurs for linear amplitude modulation $\phi = 0$

DSB Carrier is not suppressed.

Also referred to as DSB-AM

DSB-AM

DSB-SC

$$c(t) = A_c \cos(2\pi f_c t)$$

A_c = amp

f_c = freq

$$x(t) = A_c [1 + k_a m(t)] \cos(2\pi f_c t)$$

DSB-AM

k_a = amp. sensitivity factor

(not present in DSB-SC)

Volt⁻¹

$m(t)$

↑

0

↓

$c(t)$

$x(t)$

$A_c[1 + k_a m(t)]$

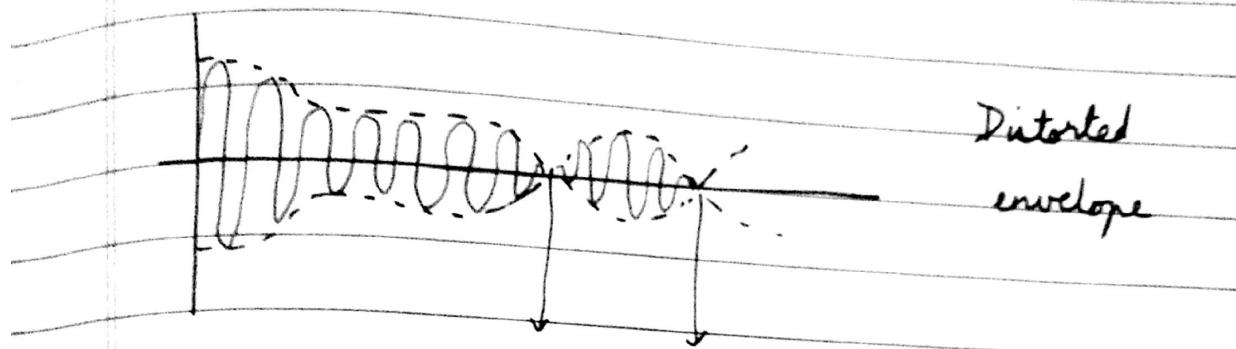
$k_a m(t) < 1$

$1 + k_a m(t) > 1$

$\therefore x(t)$ does not meet zero crossing

Envelope of $x(t) = k_m(t) m(t)$

- The waveform $x(t)$ occurs when $k_m(t) < 1$
- The waveform goes till zero crossing if $k_m(t) \geq 1$ and modulated signal envelope is distorted.



Assumption $f_c \gg B$

(BW of message signal)

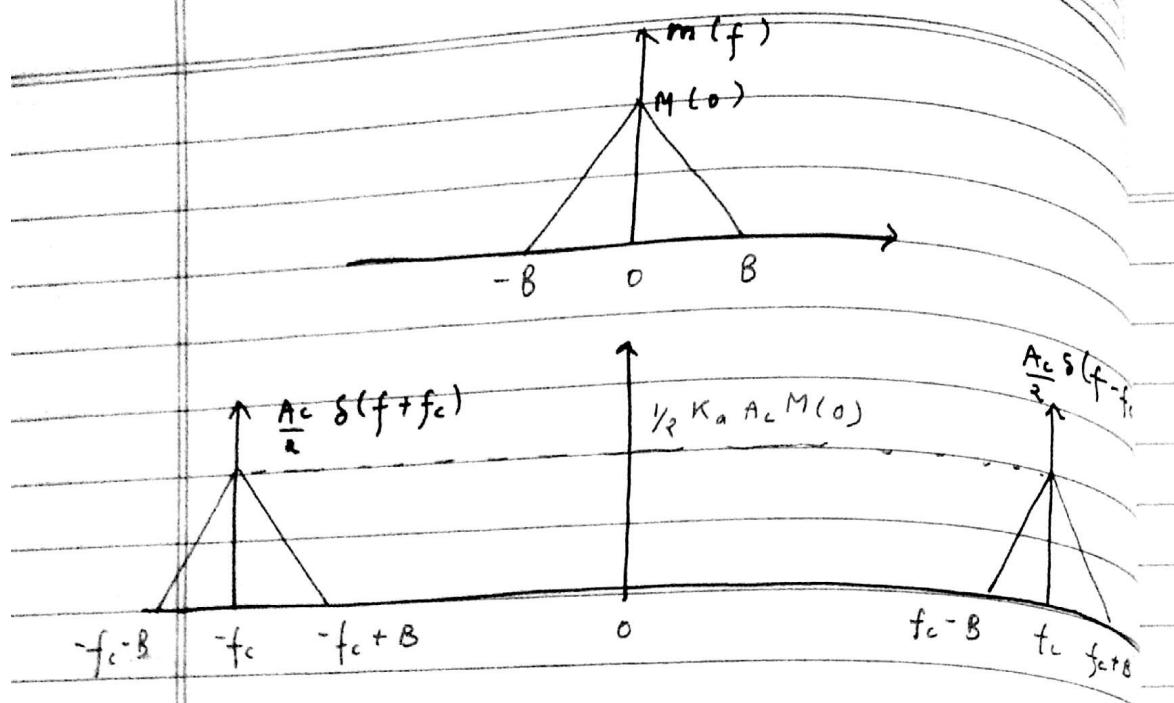
Fourier transform of $x(t)$

$$x(f) = \frac{A_c}{2} [S(f-f_c) + S(f+f_c)] \quad \begin{matrix} \text{because of this} \\ \text{carrier freq} \\ \text{is present} \end{matrix}$$

DSB-AM

$$+ K_m \frac{A_c}{2} [M(f-f_c) + M(f+f_c)]$$

Consider message signal $m(t)$ is band limited.



$$\text{BW of message signal} = B$$

$$B_T = 2B$$

BW of transmitted signal

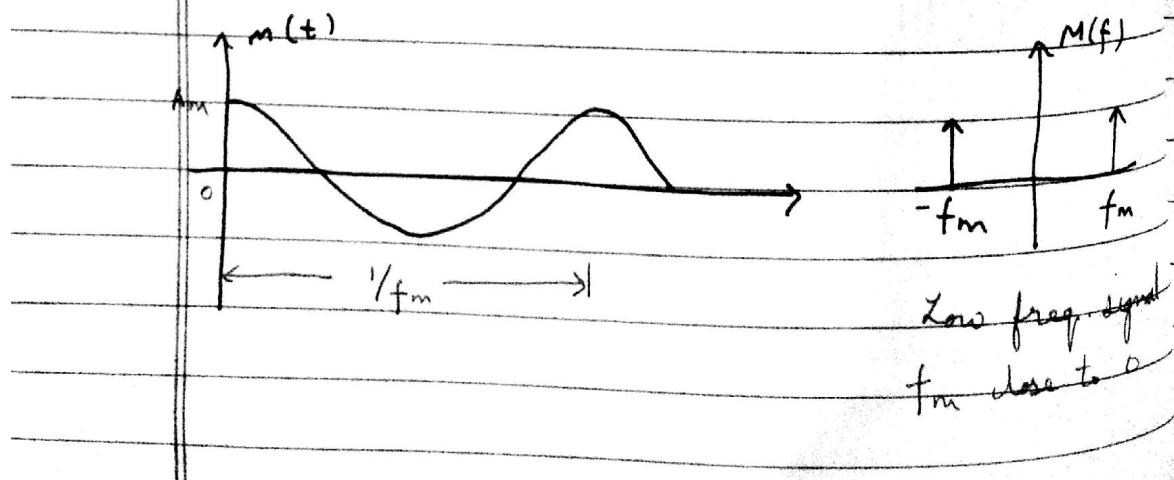
$$\rightarrow m(t) = A_m \cos(2\pi f_m t)$$

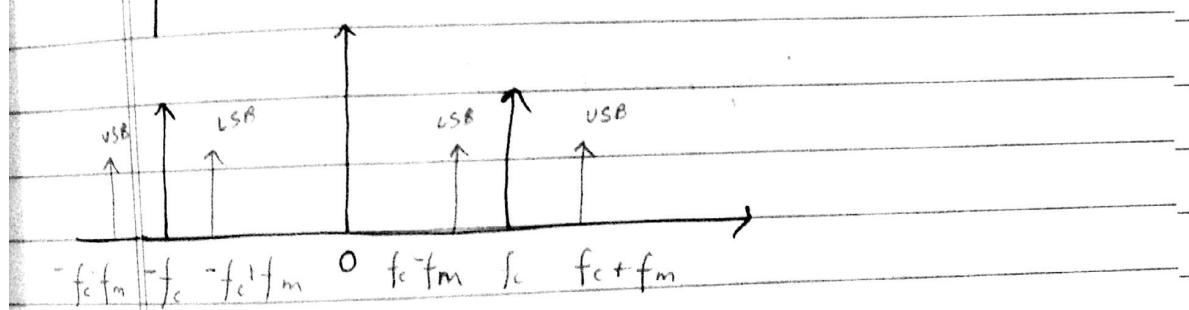
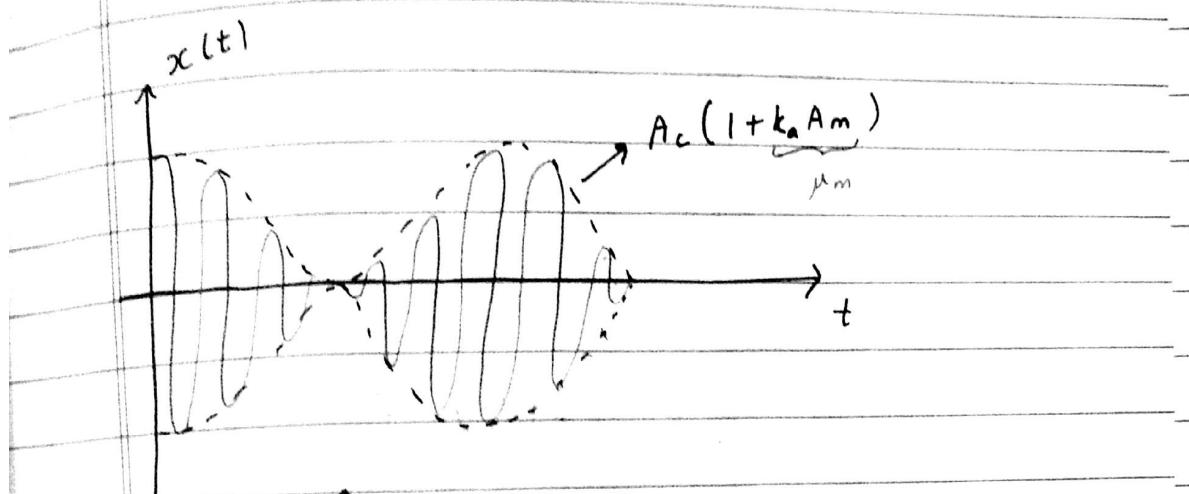
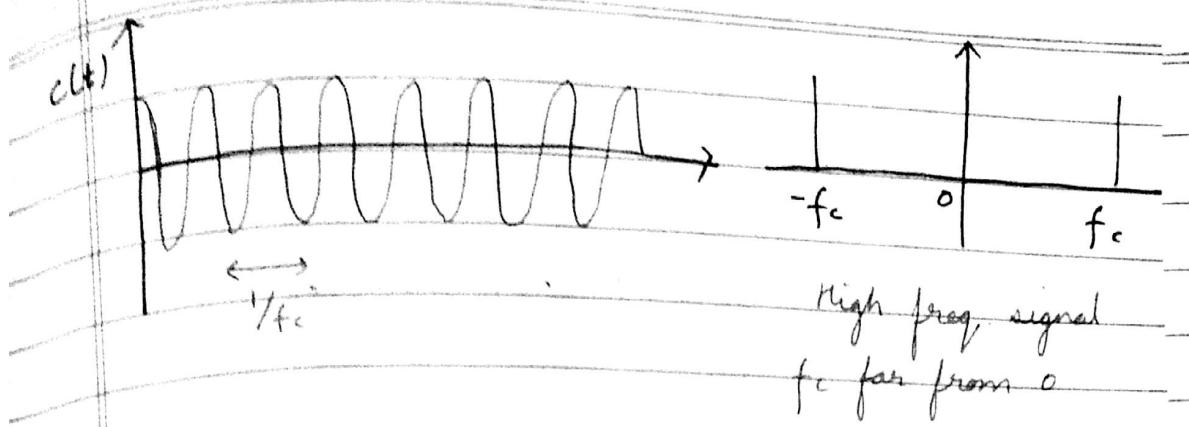
Single tone message signal - consists of only one frequency

$$x(t) = A_c [1 + k_a A_m \cos(2\pi f_m t)] \cos 2\pi f_t t$$

$\mu = k_a A_m$ modulation factor

$\mu < 1$ to avoid envelope distortion or overmodulation.





$$\frac{A_{\max}}{A_{\min}} = \frac{A_c[1+\mu]}{A_c[1-\mu]}$$

$$\mu = \frac{A_{\max} - A_{\min}}{A_{\max} + A_{\min}}$$

Modulation factor

Power of carrier signal $P_c = \frac{1}{2} A_c^2$

$$P_{USB} = \frac{1}{8} A_c^2 \mu^2 ; P_{LSB} = \frac{1}{8} A_c^2 \mu^2$$

single tone
only 1 value of f_m

6.3.18:

$$x(t) = A_c [1 + \mu \cos(2\pi f_m t)] \cos(2\pi f_c t)$$

$m(t) = A_m \cos(2\pi f_m t)$

$x(t)$ $= A_c [1 + k_m m(t)] \cos 2\pi f_c t$
DSB - AM



imp for ques

$$X(f) = \frac{1}{2} A_c [\delta(f-f_c) + \delta(f+f_c)]$$

Fourier

transform $+ \frac{1}{4} \mu A_c [\delta(f-f_c-f_m) + \delta(f+f_c+f_m)]$

$$+ \frac{1}{4} \mu A_c [\delta(f-f_c+f_m) + \delta(f+f_c-f_m)]$$

\rightarrow rms of this $\rightarrow P_{USB}$

Case I: Voltage is given

$$\rightarrow \text{Carrier power } (P_c) = \frac{A_c^2}{2}$$

$$P = V I$$

$$P = V^2 \rightarrow V_{rms}$$

$$(R) \rightarrow 1 \Omega$$

$$\rightarrow \text{Upper side band Power } (P_{USB}) = \frac{1}{8} \mu^2 A_c^2$$

$$\rightarrow \text{Lower " " " } (P_{LSB}) = \frac{1}{8} \mu^2 A_c^2$$

$$\begin{aligned} \text{Total power } P_t &= P_c + P_{USB} + P_{LSB} \\ &= \frac{A_c^2}{2} \left[1 + \frac{\mu^2}{2} \right] \end{aligned}$$

$$P_t = P_c \left[1 + \frac{\mu^2}{2} \right]$$

$$\frac{P_t}{P_c} = \frac{3 + \mu^2}{2}$$

$$\frac{P_t}{P_{cB}} = \frac{A_c^2}{2} \frac{4^{-2}}{\mu^2 A_c^2} [1 + \mu^2/2]$$

 P_{cB}

$$\frac{P_t}{P_{cB}} = \frac{3 + \mu^2}{\mu^2}$$

To avoid distortion $\mu < 1$

$$\rightarrow P_c = \left(\frac{A_c}{\sqrt{2}} \right)^2 \text{rms} = \frac{A_c^2}{2} \quad (R=1,2)$$

R

$\rightarrow \mu = 1$ Perfect modulation

$$P_t = 3$$

 P_{cB}

Case II: Current is given

$$\frac{P_{AM}}{P_c} = \frac{P_t}{P_c} = \left(1 + \frac{\mu^2}{2} \right) = \frac{(I_t)^2 R}{(I_c)^2 R}$$

$$\left\{ P = VI = I^2 R \right\}$$

$$\Rightarrow \left(\frac{I_t}{I_c} \right)^2 = 1 + \frac{\mu^2}{2}$$

$$I_t = I_c \sqrt{1 + \frac{\mu^2}{2}}$$

MULTI FREQUENCY COMPONENTS

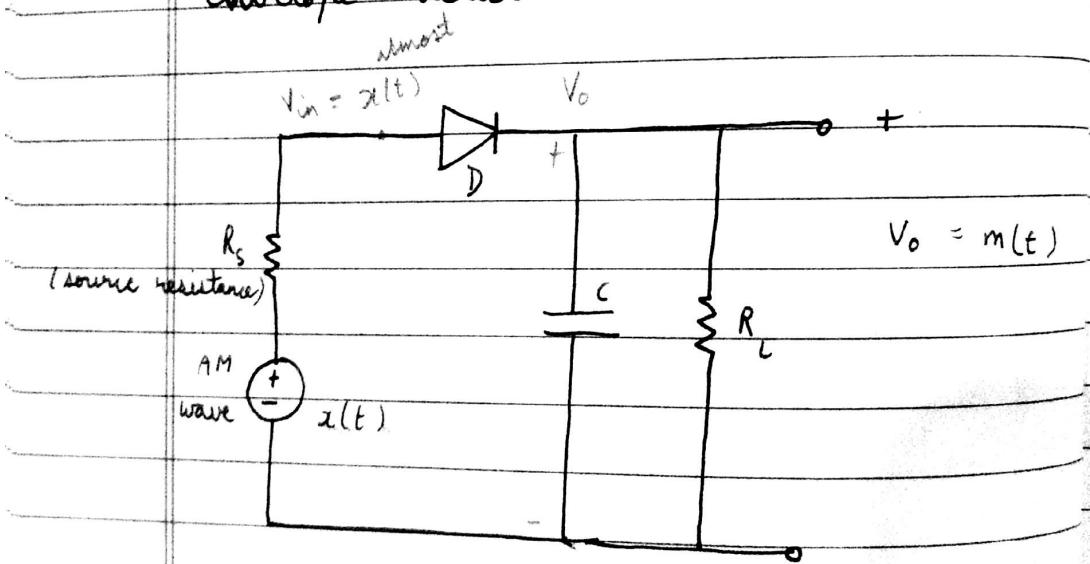
$f_{m1}, f_{m2}, f_{m3}, \dots$
Multiple modulation factors are obtained
 $\mu_1, \mu_2, \mu_3, \dots$

$$\mu_t = \sqrt{\mu_1^2 + \mu_2^2 + \mu_3^2 + \dots}$$

Total
modulation
index

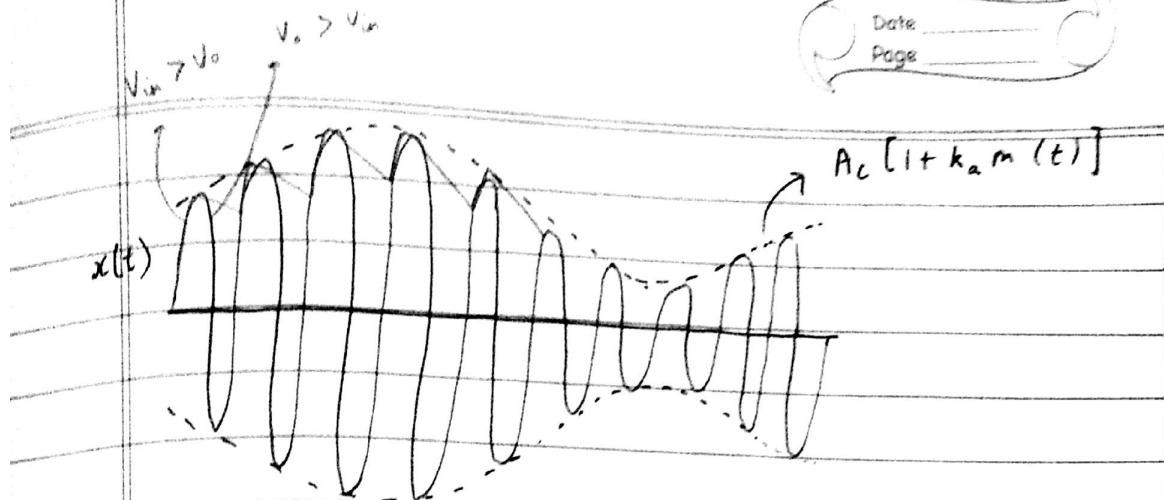
Retrieving $m(t)$ from $x(t)$ at receiver end

Envelope detector is used.



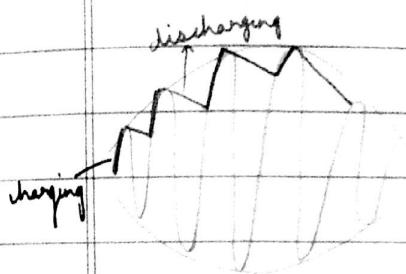
$R_s \rightarrow$ to avoid overloading hazards

V_o traces the envelope of the modulated signal.



$V_{in} > V_o$ D is forward biased
capacitor charges

$V_o > V_{in}$ D is reverse biased
capacitor discharges



C and R_s values
should be chosen
appropriately to avoid
too fast or too slow
charging and discharging

The exact envelope is not tracked, path
close to the envelope is tracked.

Envelope detector :- TV receiver & radio receiver
use this to make tuning easy

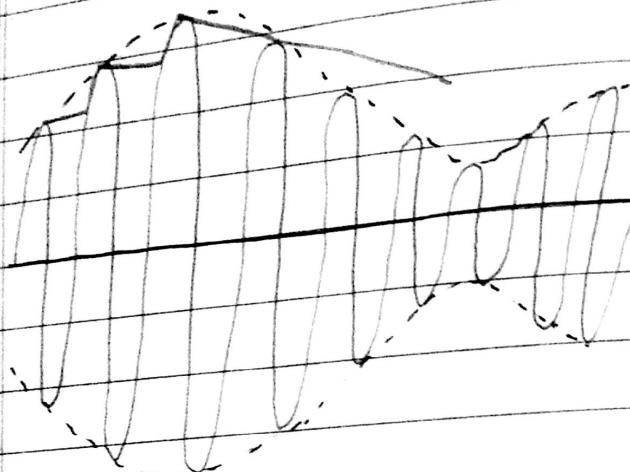
Frequency band of FM :- 98 - 108 MHz

Knob present on TV - for tuning diff.
frequency bands

Time constant

$$\tau = R_t C$$

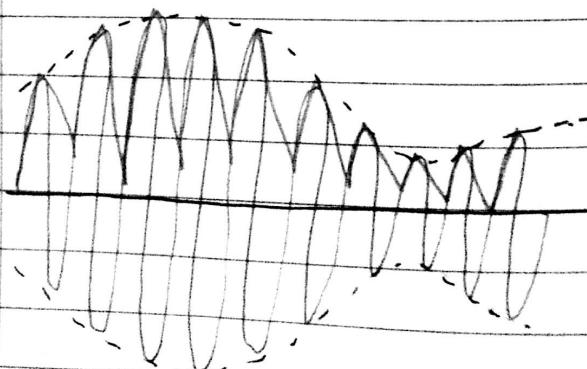
- If τ is very large
+ R_t, C not chosen properly
Capacitor discharges very slowly



Peaks are not tracked due to slow discharging ; message signal is lost.

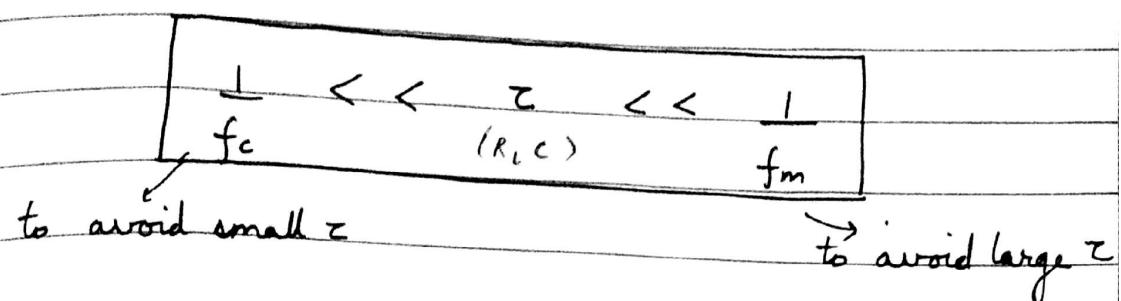
- If τ is very small

Capacitor discharges very fast



Instead of tracing the envelope , it traces the carrier signal

- Selection of τ



** Frequency is not utilized properly. $\frac{1}{2}B$ is transmitted but freq. band of signal is B & freq bands on left & right of origin (L & USB)

2 signals :- B_1, B_2
 left side → right side

Single side band modulation

Vestigial " " "

complete removal
of L band

partial removal
of R band

One side band has to be transmitted &
the other has to be eliminated.

7-8-18

67%

DSB - SC

DSB - AM

$$\frac{P_{DSB}}{P_t} = \frac{\mu^2}{2 + \mu^2}$$
$$= \frac{1}{3} = 33\% \quad (\mu \leq 1)$$

$$P_t = P_c \left(1 + \frac{\mu^2}{2} \right) = P_c \left[\frac{\mu^2}{2} \right]$$

To reduce power DSB-SC method

$$x_{DSB-SC}(t) = \frac{m(t)s(t)}{[1 + k_m m(t)]c(t)}$$

Q CM

Quadrature curvature multip

2 carriers (90° phase diff.) & 2 mod
 $\cos(2\pi f_c t)$, $\sin(2\pi f_c t)$

To utilize power \rightarrow DSB-SC

$$x(t) = \underset{DSB-SC}{m(t)c(t)}$$

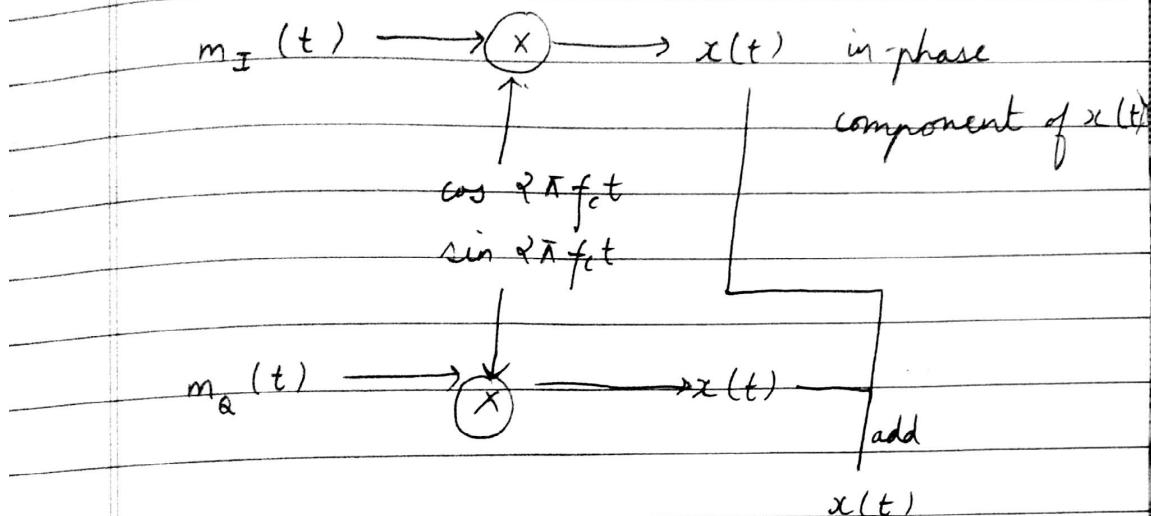
$$x(t) = A_c m_1^{''(t)} \cos(2\pi f_c t) - A_c m_2^{''(t)} \sin(2\pi f_c t)$$

m_1 modulated with $\cos(t)$
 m_2 " " "
" " "
" " "

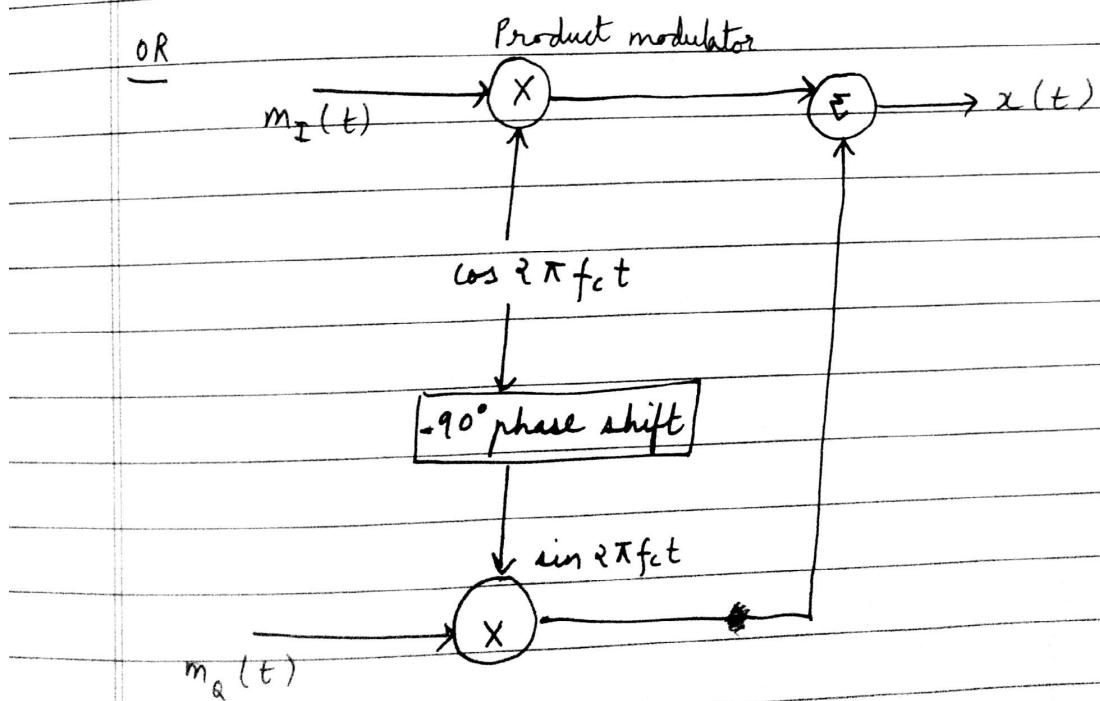
m_I - In phase component
 m_Q - Quadrature "

At the receiver end :-

Carriers - $\sin 2\pi f_c t$ $\cos 2\pi f_c t$



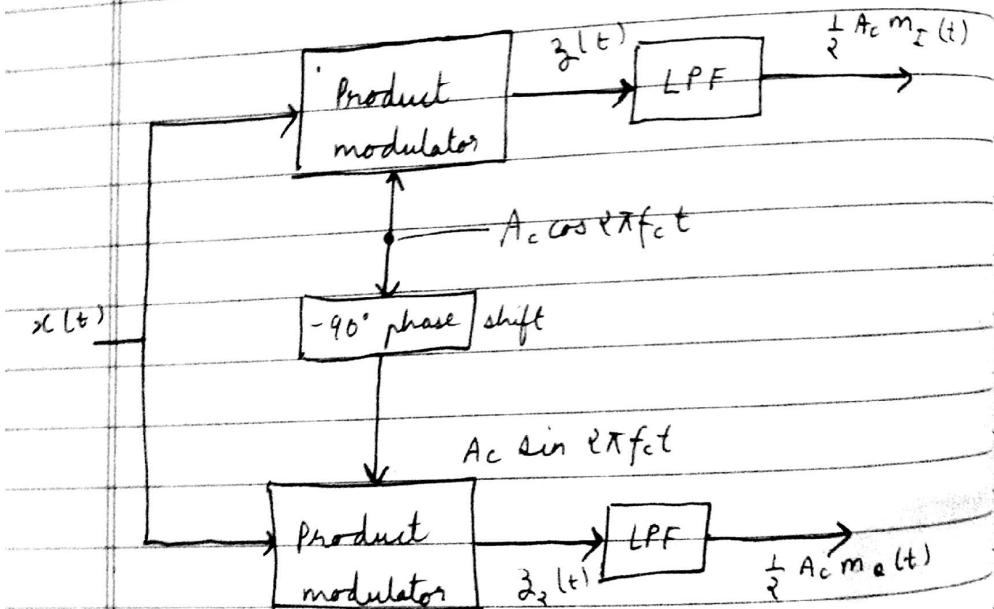
OR



- If A_c is multiplied with $\cos(2\pi f_c t)$
 we get in-phase component at demodulation end
- $A_c \times \sin(2\pi f_c t) \rightarrow$ quadrature comp.

Orthogonal signals : $\cos(2\pi f_c t)$
 (carrier) $\sin(2\pi f_c t)$

$$\cos(2\pi f_c t) \times \sin(2\pi f_c t) = \frac{1}{2} \sin(4\pi f_c t)$$



$$z_1(t) = [A_c m_I(t) \cos(2\pi f_c t) - A_c m_Q(t) \sin(2\pi f_c t)] \cos(2\pi f_c t)$$

$$= \frac{A_c m_I(t)}{2} (1 + \cos(4\pi f_c t)) - \frac{A_c m_Q(t)}{2} \sin(4\pi f_c t)$$

π f_c

$$z(t) = \frac{A_c m_x(t)}{2} + \frac{A_c m_I(t)}{2} \cos(2\pi f_c t)$$

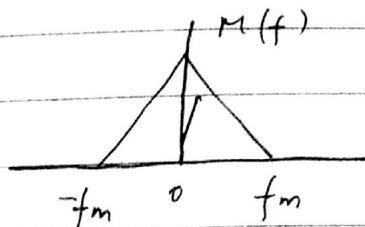
$$- \frac{A_c m_Q(t)}{2} \sin(2\pi f_c t)$$

 f_c

$$z(t) = \left[\frac{A_c m_x(t)}{2} \cos(2\pi f_c t) - \frac{A_c m_Q(t)}{2} \sin(2\pi f_c t) \right] \sin(2\pi f_c t)$$

SSB (Single side band) modulation

$$m(t) \longleftrightarrow M(f)$$

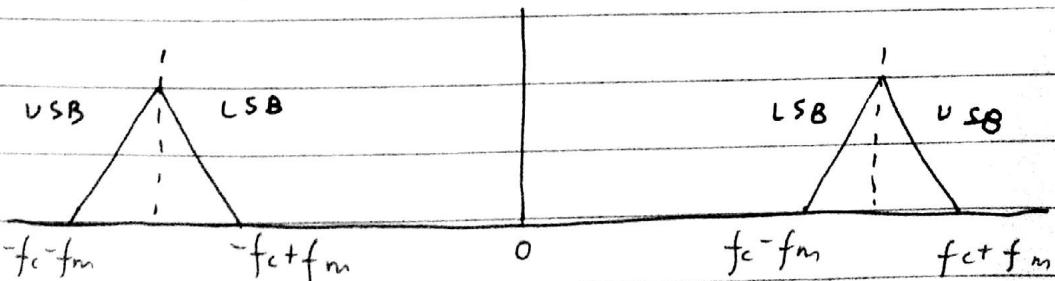


DSB signal with single tone modulation :-

$$x(t) = m(t) \cos(2\pi f_c t)$$

$$X(f) = M(f) \left[\frac{1}{2} \delta(f - f_c) + \frac{1}{2} \delta(f + f_c) \right]$$

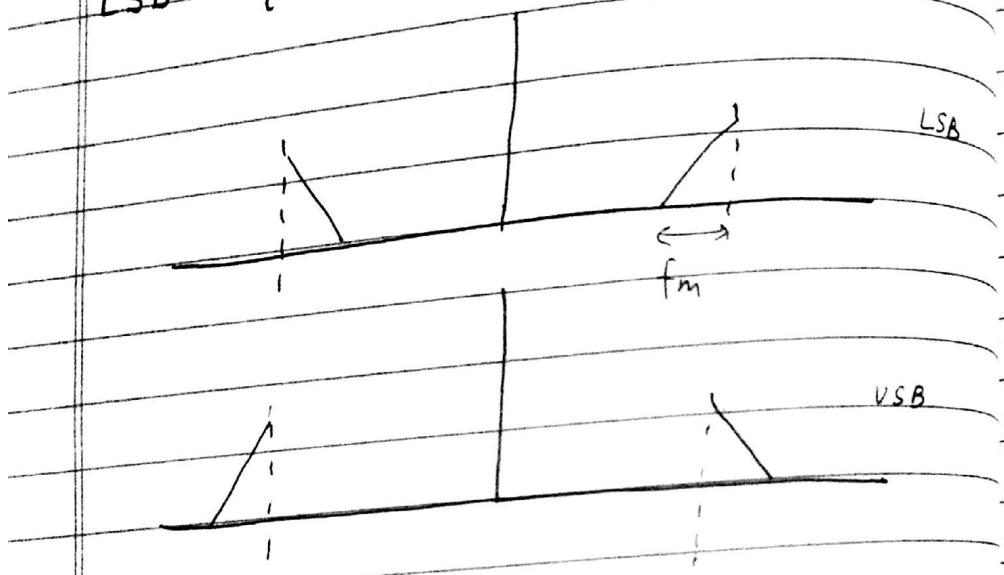
$$= \frac{1}{2} M(f - f_c) + \frac{1}{2} M(f + f_c)$$



Either LSB or VSB has to be eliminated

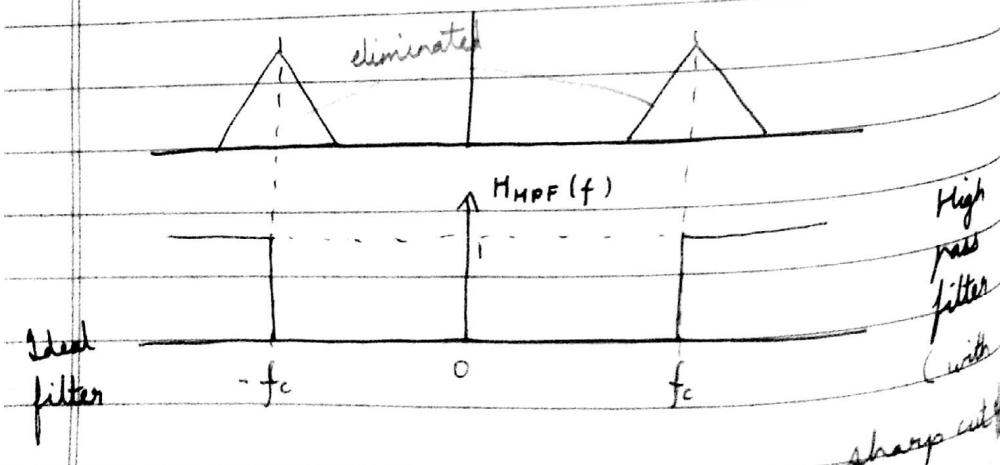
$$USB = \{(-f_c - f_m, -f_c) \cup (f_c, f_c + f_m)\}$$

$$LSB = \{(-f_c, -f_c + f_m) \cup (f_c, f_c + f_m)\}$$



BW is f_m in both cases.

After DSB modulation, add some component to remove VSB (if LSB is required)

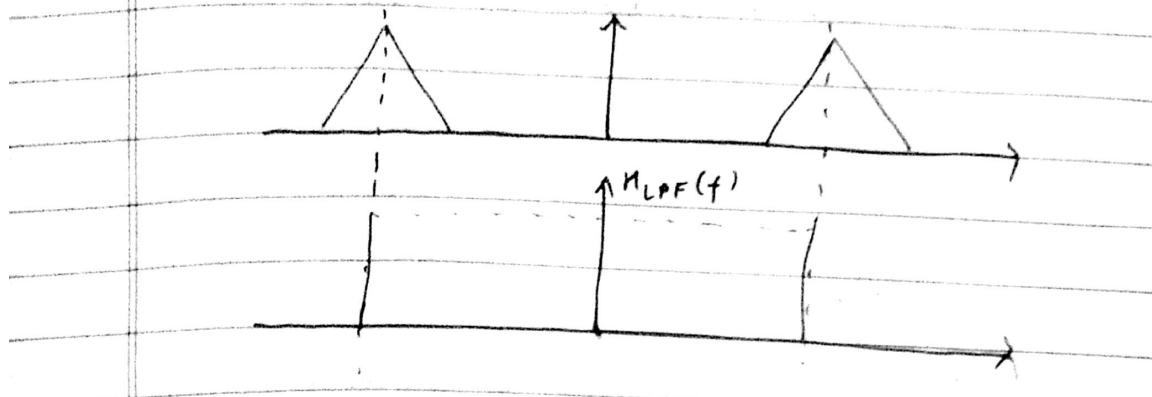


$$H_{MPF}(f) = \begin{cases} 1 & ; |f_c| \geq f_c \\ 0 & ; \text{otherwise} \end{cases}$$

If Fourier transform - proof
Properties
Tell SSB mod & demod

Date _____
Page _____
Reference _____
E.M. Phase and X

To cut-off LSB - :

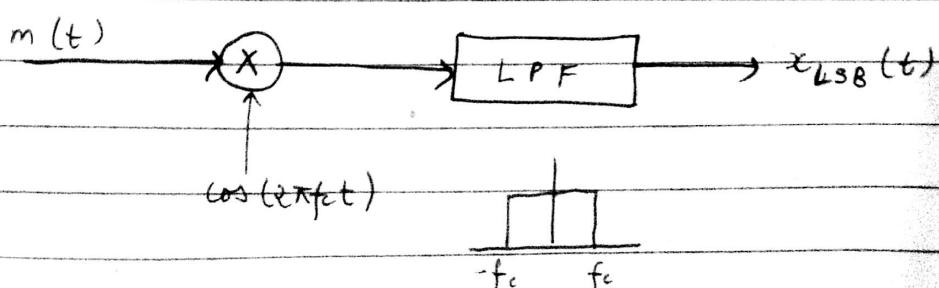
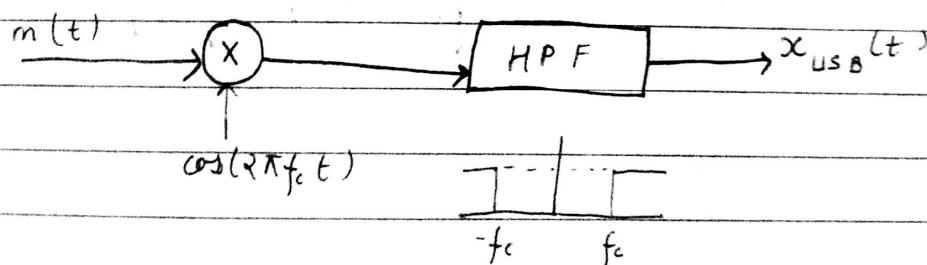


$$H_{LPF}(f) = \begin{cases} 1 & ; |f_c| \leq f \\ 0 & ; \text{otherwise} \end{cases}$$

Frequency discrimination method

(Using low pass or high pass filter after DSB-AM)

USB GENERATION



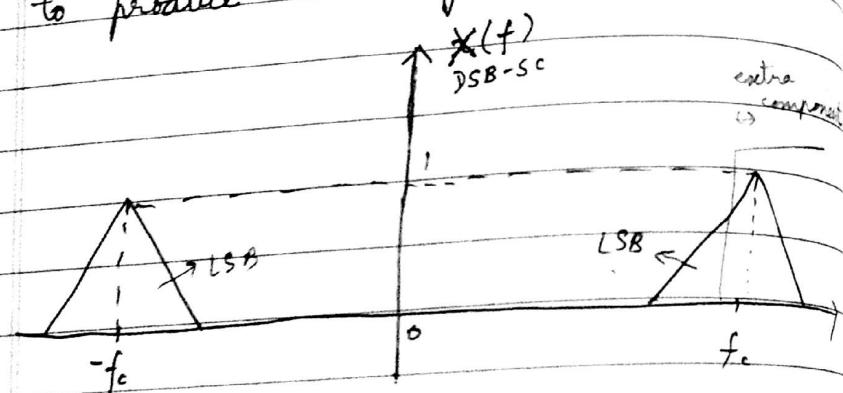
12.2.18

To generate $x(t)$:- Balanced modulator
generation & using modulators are used.

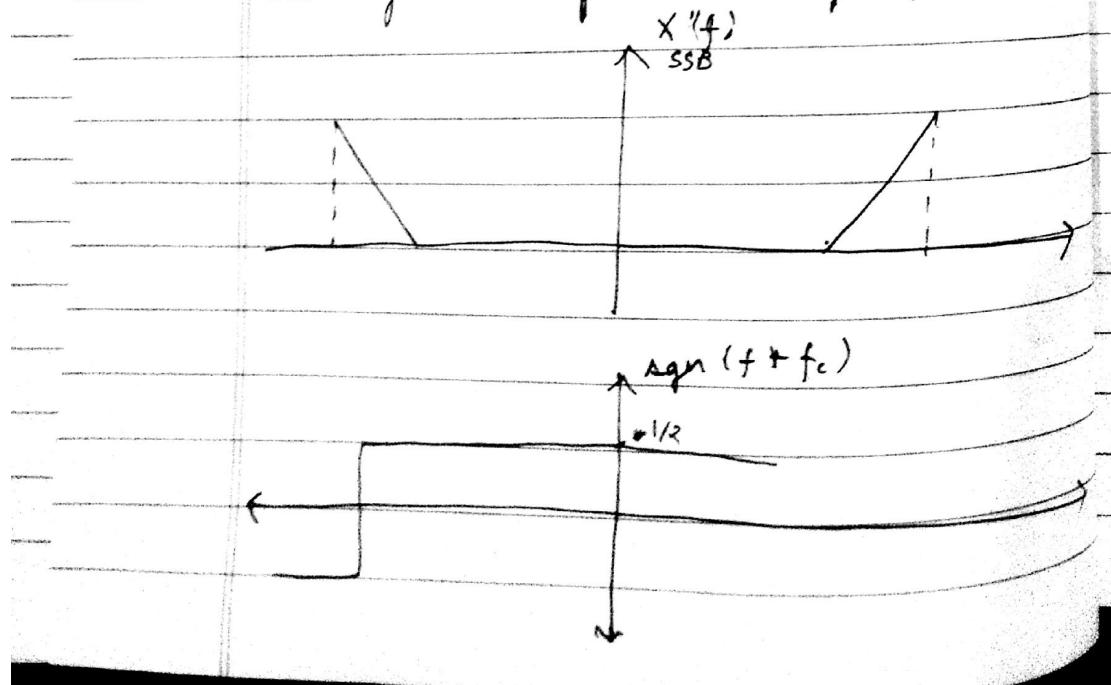
SSB modulation and demodulation

$x(t)$
DSB-SC

Ideal filter designing is impossible
From DSB-SC modulated signal is used
to produce SSB signal.



High pass or low pass filters may
be ideal. Phase transformers can be
suitably used for this purpose.



$$-\operatorname{sgn}(f - f_c)$$

1/2

$$H_t(f) = \frac{1}{2} [\operatorname{sgn}(f + f_c) - \operatorname{sgn}(f - f_c)]$$

$$X_{DSB}(f) = \frac{1}{2} A_c [M(f + f_c) + M(f - f_c)]$$

Multiplying the above equations -

$$X_{SSB}(f) = \frac{1}{4} A_c [M(f + f_c) \operatorname{sgn}(f + f_c) + M(f - f_c) \operatorname{sgn}(f + f_c)]$$

$$= \frac{1}{4} A_c [M(f + f_c) \operatorname{sgn}(f - f_c) + M(f - f_c) \operatorname{sgn}(f - f_c)]$$

$$= \frac{1}{4} A_c [M(f + f_c) \operatorname{sgn}(f + f_c) - M(f - f_c) \operatorname{sgn}(f - f_c)]$$

$$+ \frac{1}{4} A_c [M(f - f_c) \operatorname{sgn}(f + f_c) - M(f + f_c) \operatorname{sgn}(f - f_c)]$$

$$= \frac{1}{4} A_c [M(f + f_c) + M(f - f_c)] +$$

$$\frac{1}{4} A_c [M(f + f_c) \operatorname{sgn}(f + f_c) - M(f - f_c) \operatorname{sgn}(f - f_c)]$$

$$\star \frac{1}{2} A_c m(t) \cos \omega_c t \Leftrightarrow \frac{1}{4} A_c [M(f + f_c) + M(f - f_c)]$$

$$\hat{m}(t) \Leftrightarrow -j \operatorname{sgn} f M(f)$$

$$m(t) e^{\pm j 2\pi f_c t} \Leftrightarrow M(f \mp f_c)$$

$$\hat{m}(t) e^{\pm j 2\pi f_c t} \leftrightarrow -j M(f \mp f_c) \operatorname{sgn}(f \mp f_c)$$

$$\frac{1}{4} \int \left[M(f + f_c) \operatorname{sgn}(f + f_c) - M(f - f_c) \operatorname{sgn}(f - f_c) \right]$$

$$= -A_c \frac{1}{4j} \hat{m}(t) e^{-j 2\pi f_c t} +$$

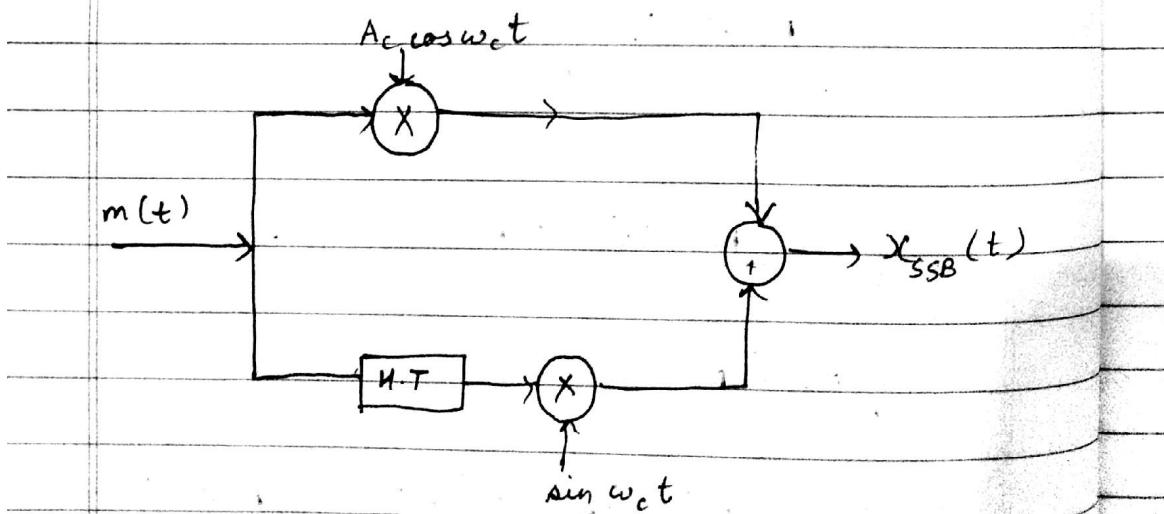
$$A_c \frac{1}{4j} \hat{m}(t) e^{j 2\pi f_c t}$$

$$= \frac{1}{2} A_c \hat{m}(t) \sin 2\pi f_c t$$

\rightarrow HSB

$$x_{SSB}(t) = \frac{1}{2} A_c m(t) \cos \omega_c t$$

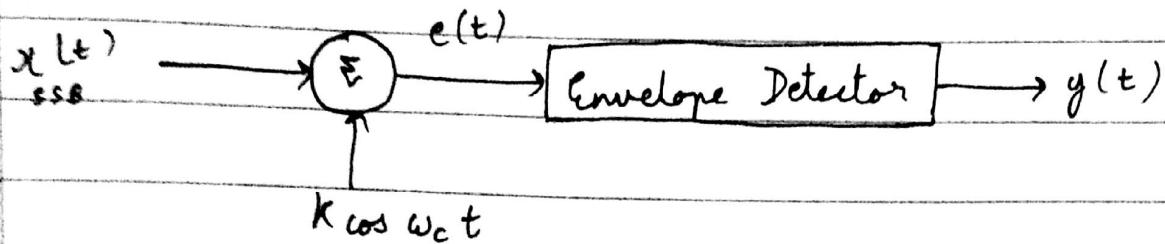
$$\frac{1}{2} A_c m(t) \sin \omega_c t$$



Phase component must be zero, otherwise message signal is not received properly

{No warbling effect, $\theta = 0$

Synchronous modulation :- carrier same at mod & demod end }



SSB \rightarrow to utilize bandwidth

✓ Transmitting multiple signals Book
 $m_1(t), m_2(t)$

Interference effect