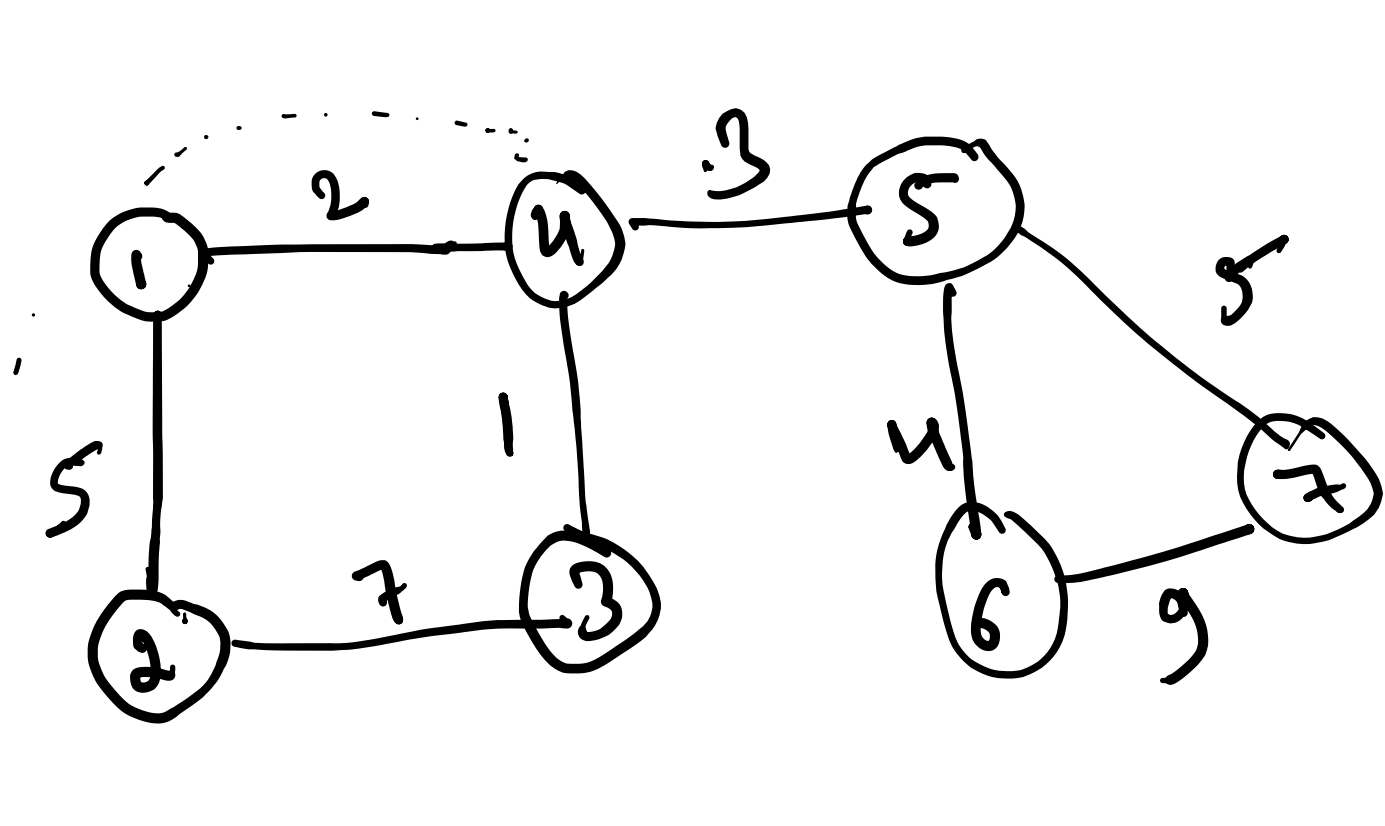
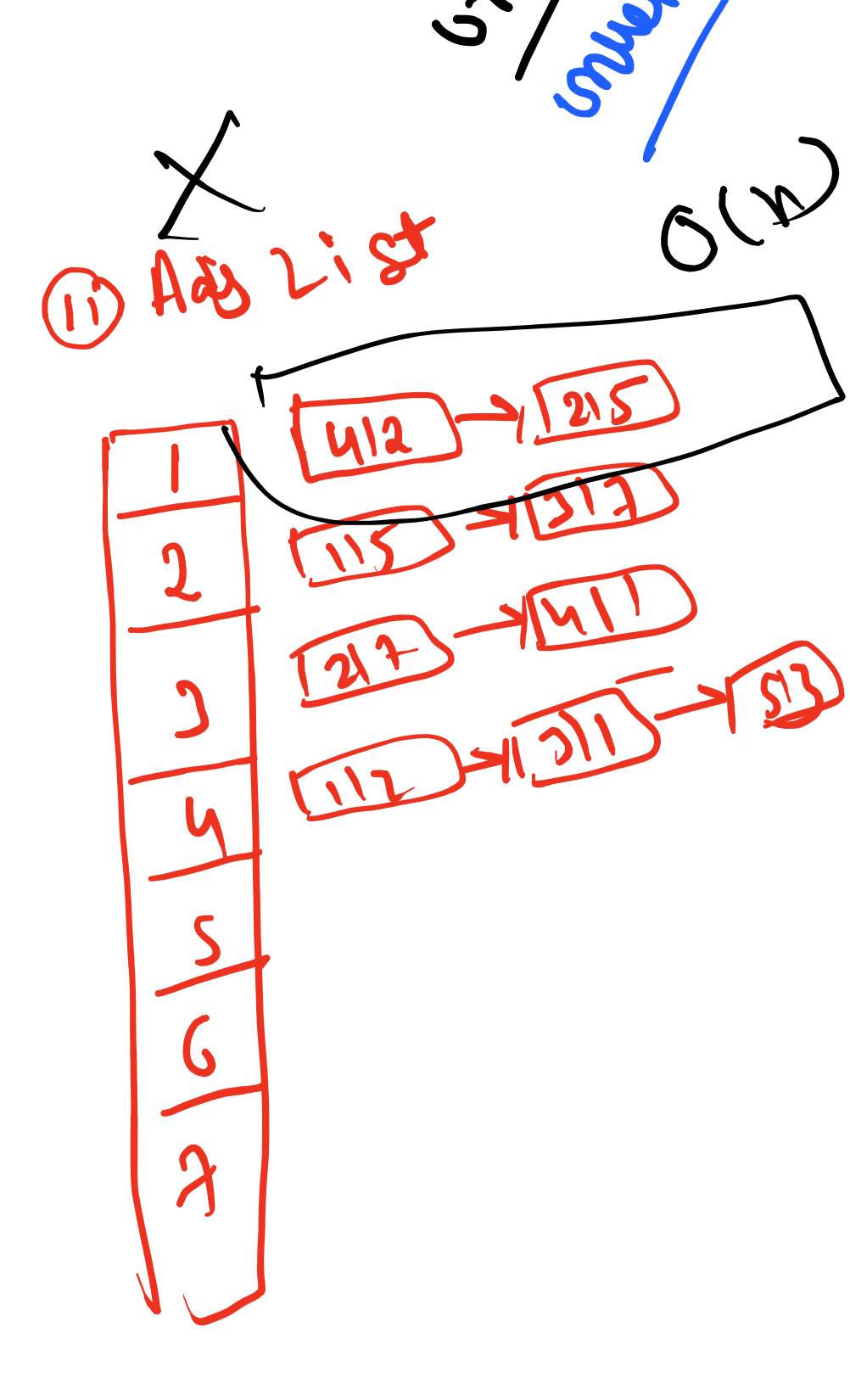
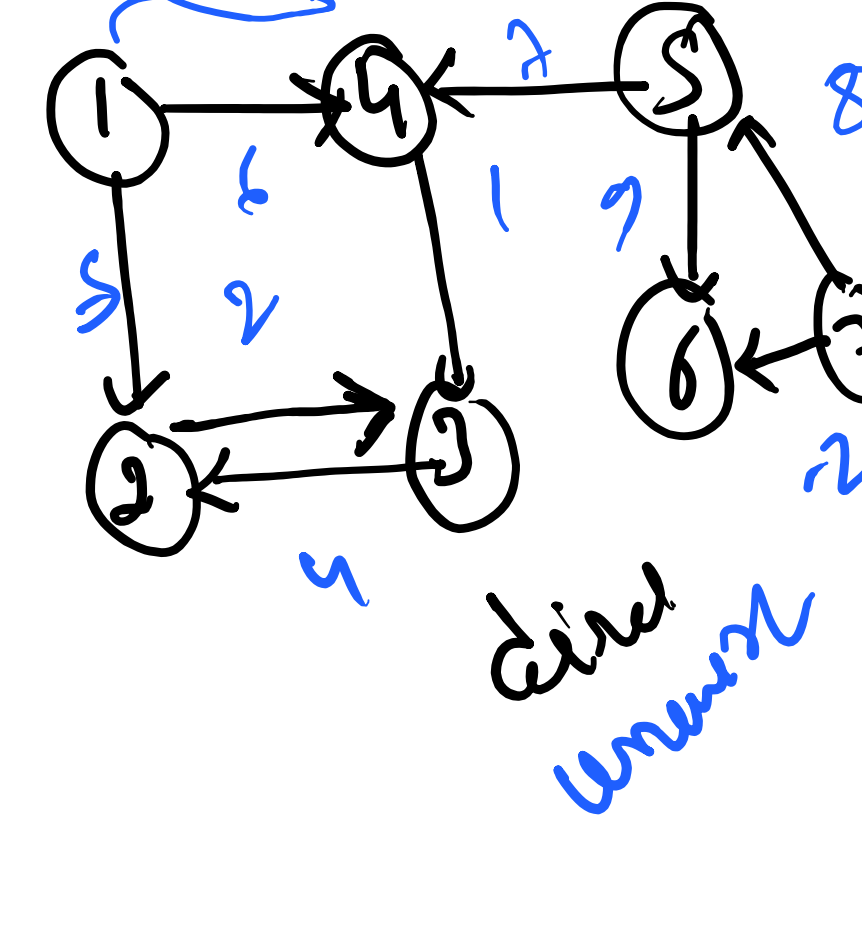
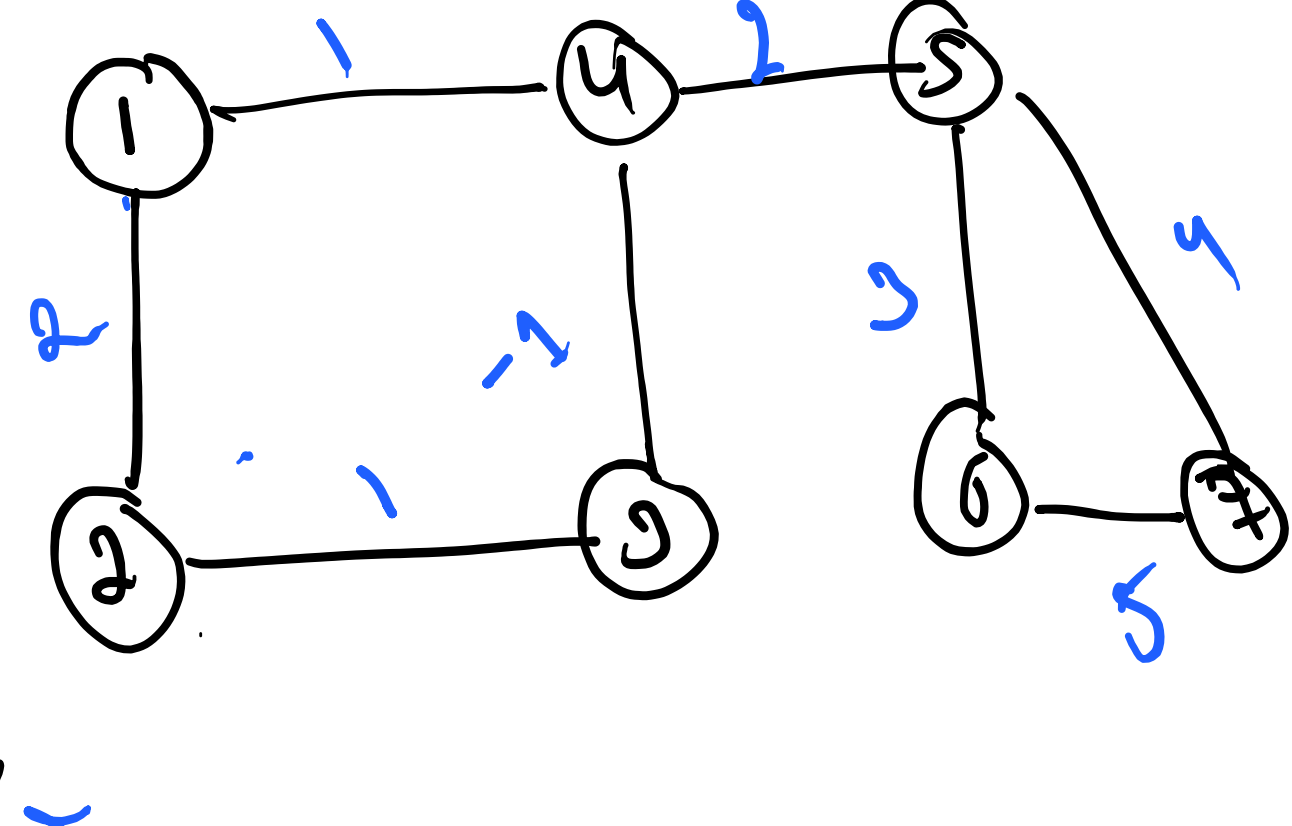
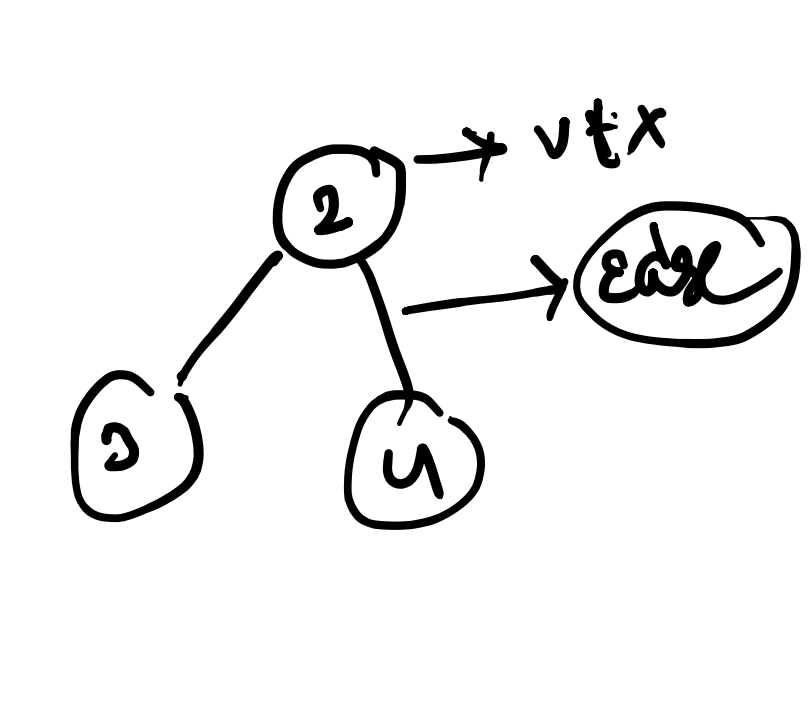
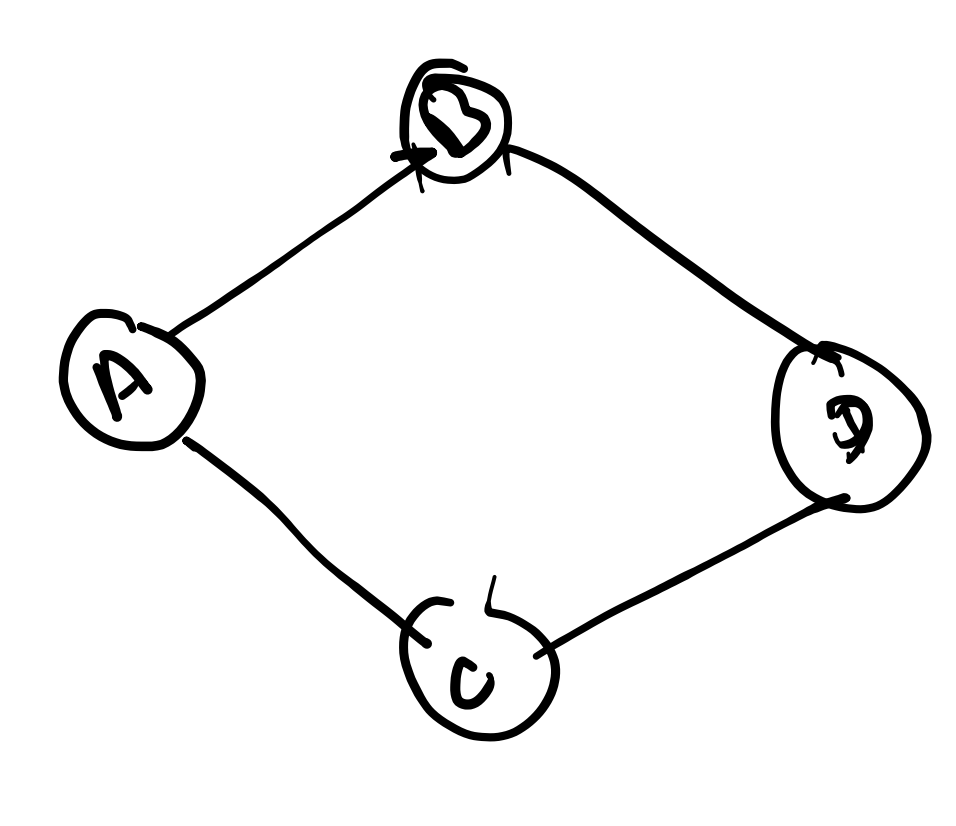


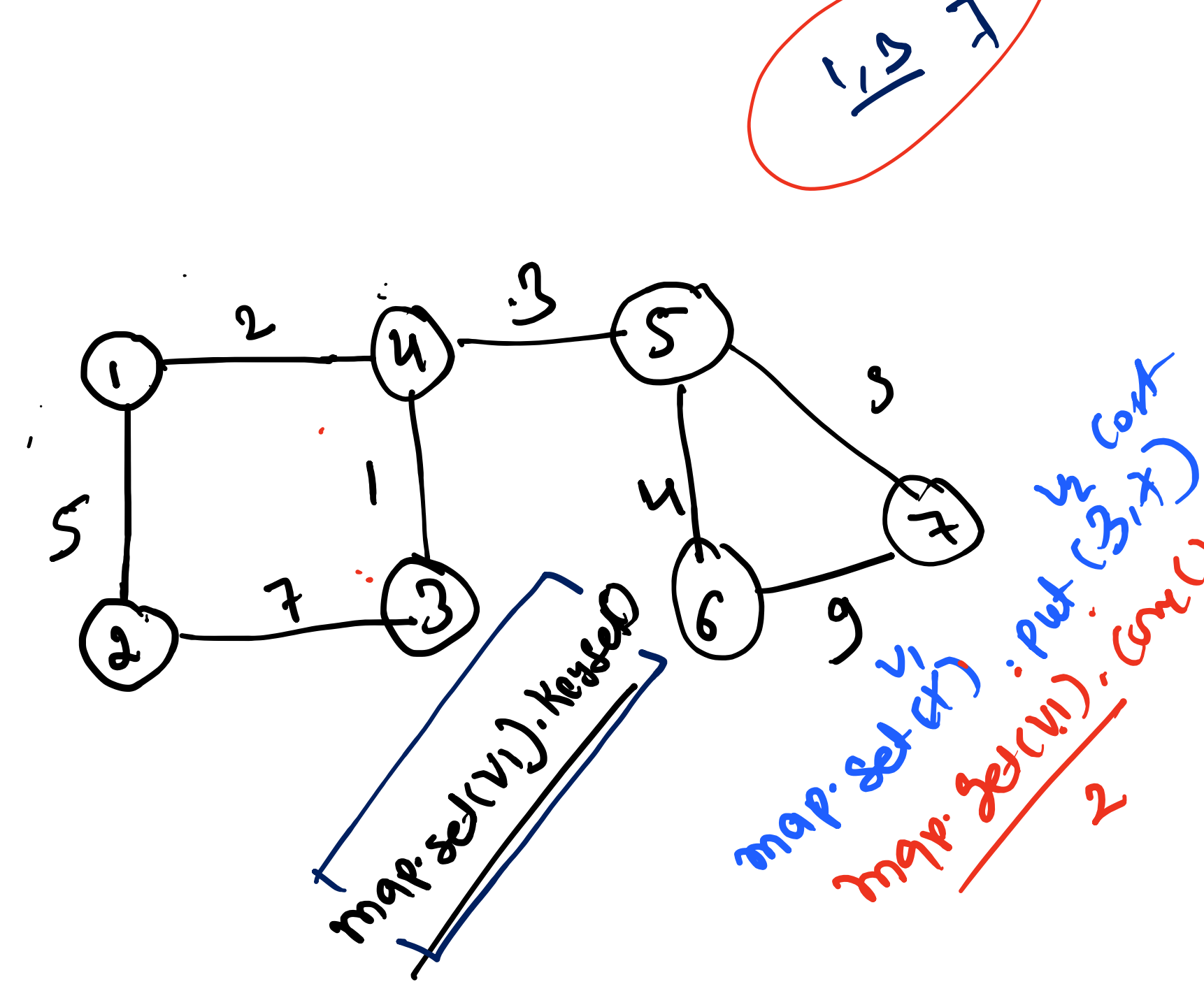
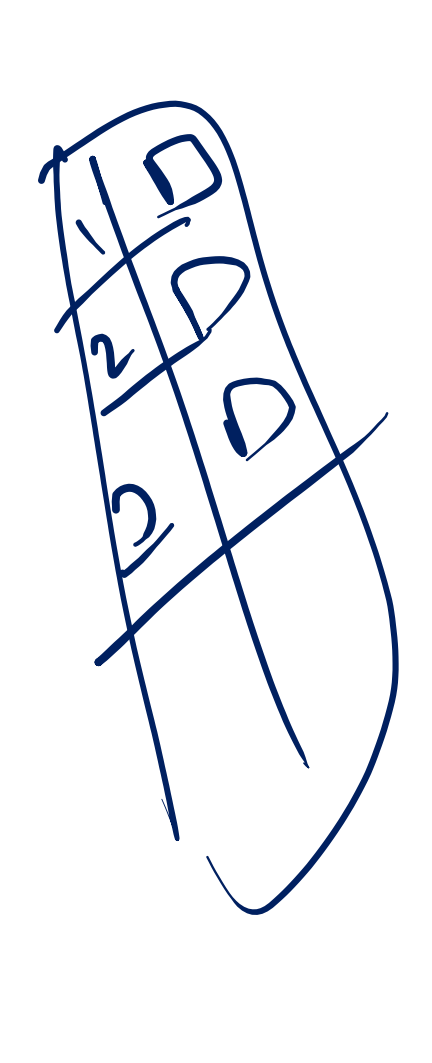
It is finite set ~~edge~~ vtx  
Tree  $\rightarrow$  Graph

Application



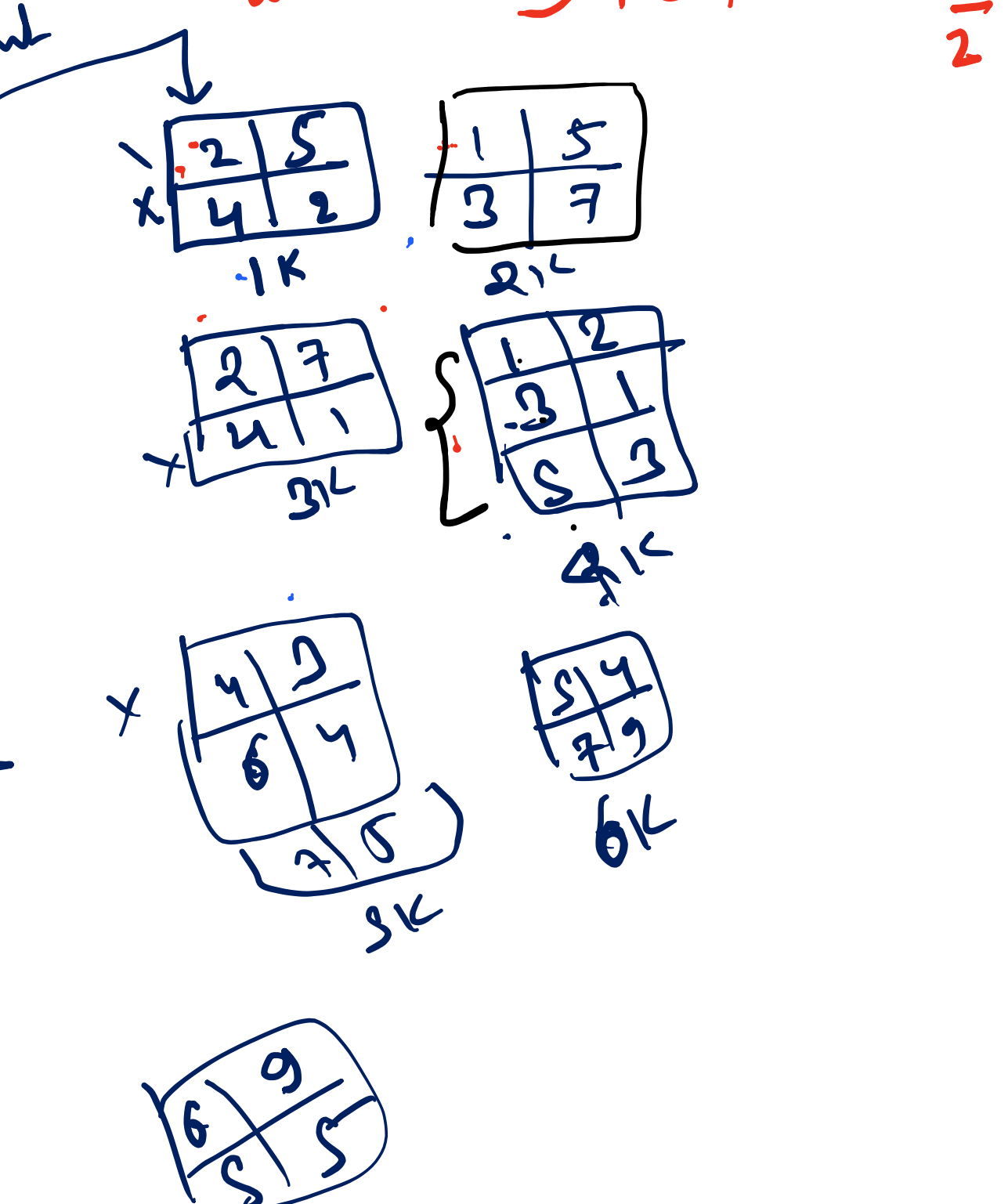
(i) Adj matrix

	1	2	3	4	5	6	7
1	0	5	0	2	0	0	0
2	5	0	7	0	0	0	0
3	0	7	0	1	0	0	0
4	2	0	1	0	3	0	0
5	0	0	0	3	0	4	5
6	0	0	0	0	4	0	9
7	0	0	0	0	5	9	0

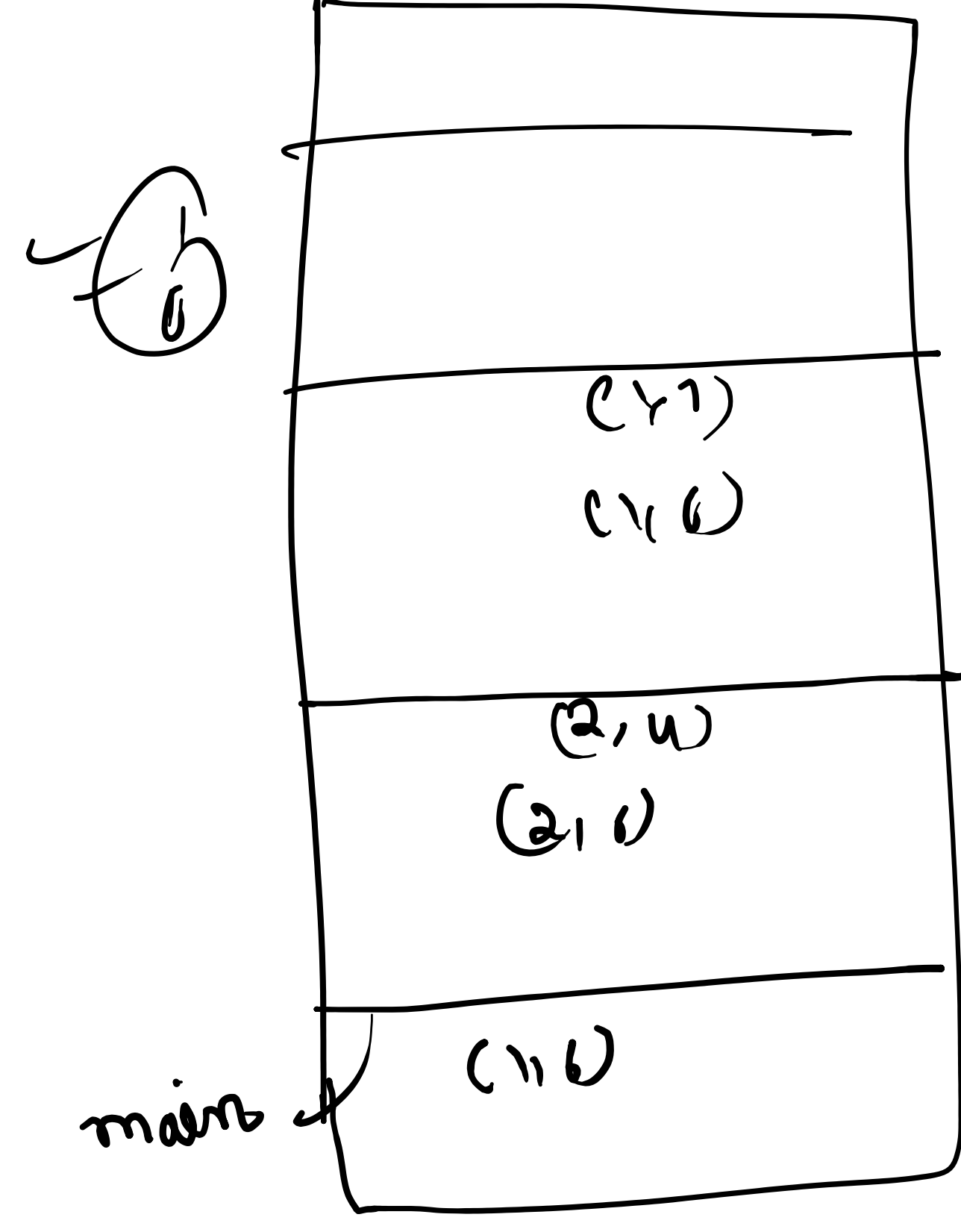


Index

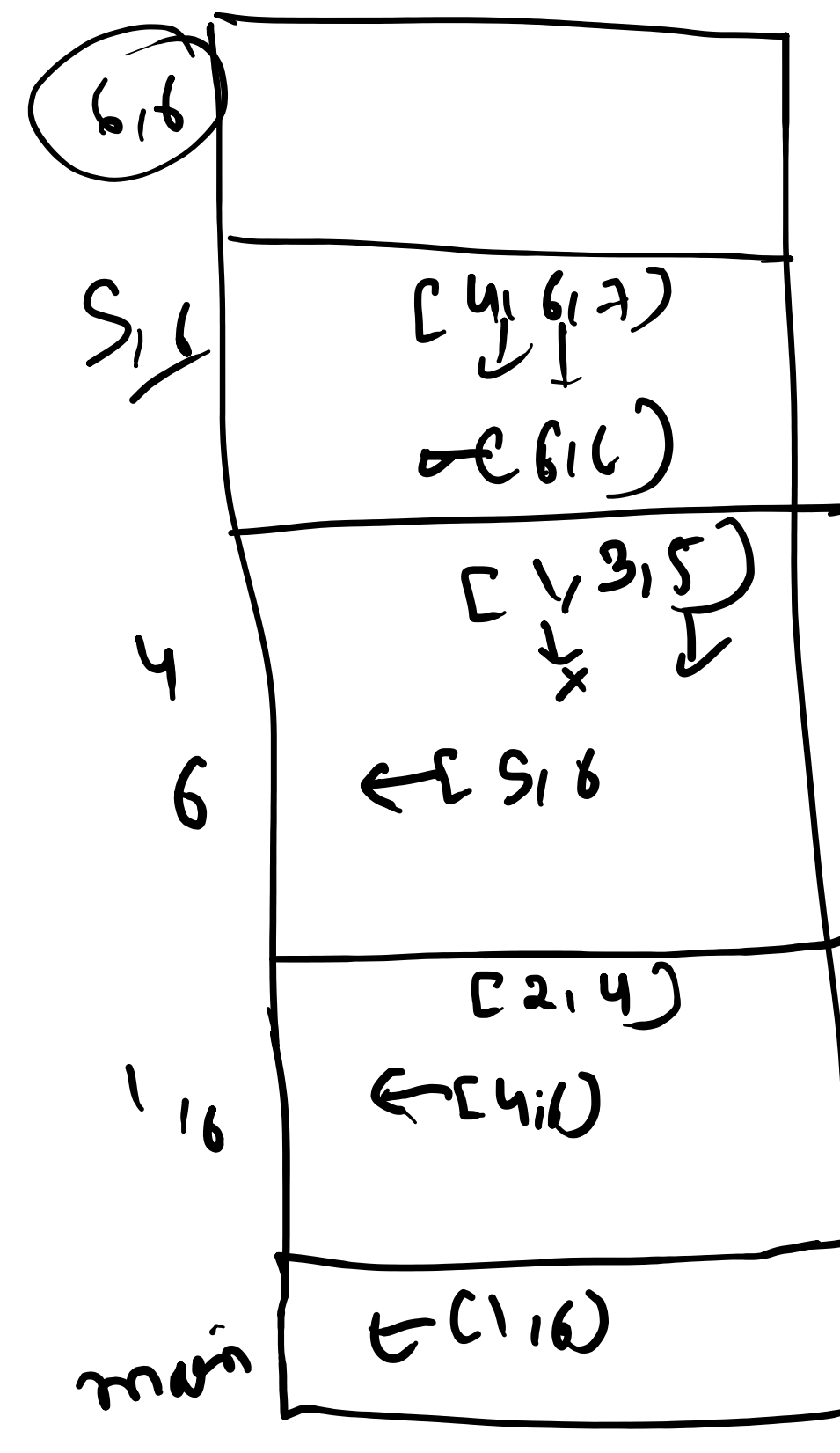
	1	2	3	4	5	6	7
1	1K	2K	3K	4K	5K	6K	7K
2							
3							
4							
5							
6							
7							



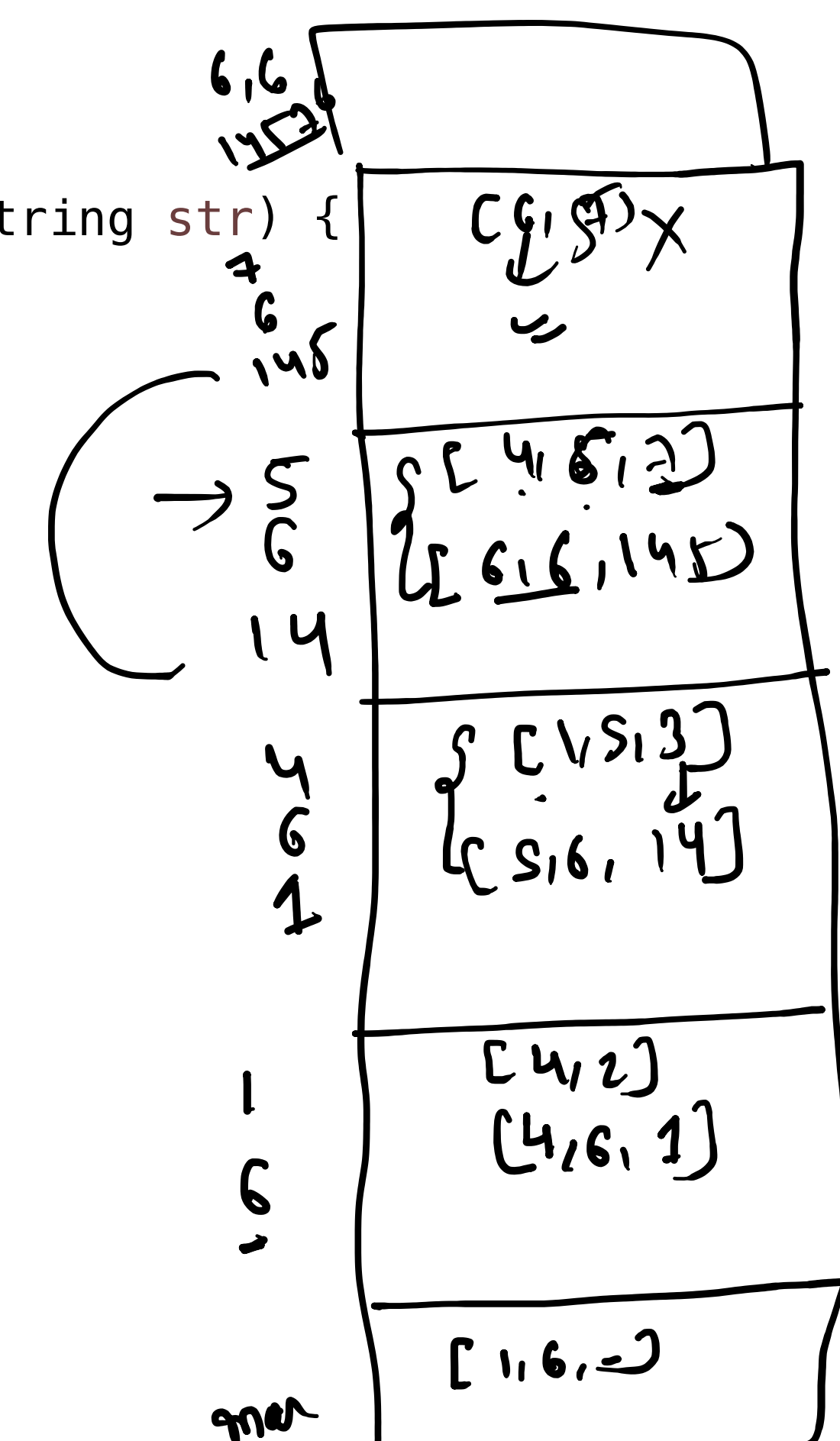
```
public boolean HasPath(int src, int Des) {
    if (src == Des) {
        return true;
    }
    for (int nbrs : map.get(src).keySet()) {
        boolean ans = HasPath(nbrs, Des);
        if (ans == true) {
            return ans;
        }
    }
    return false;
}
```



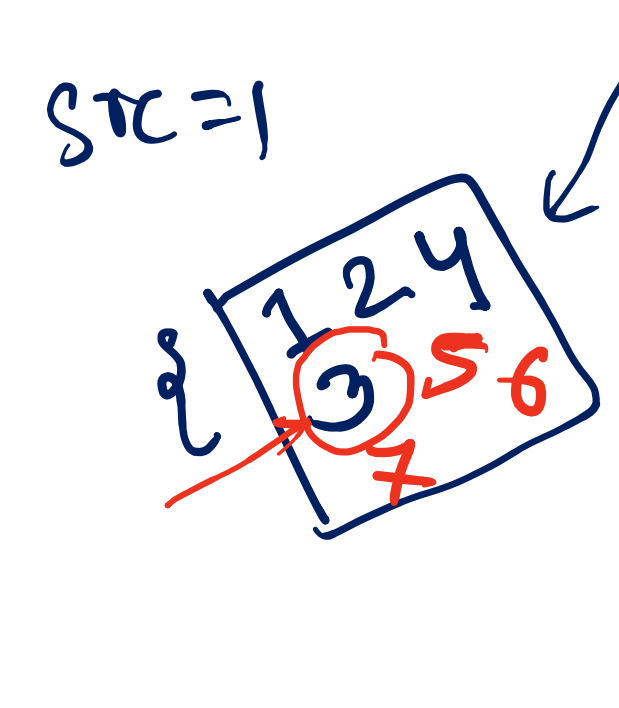
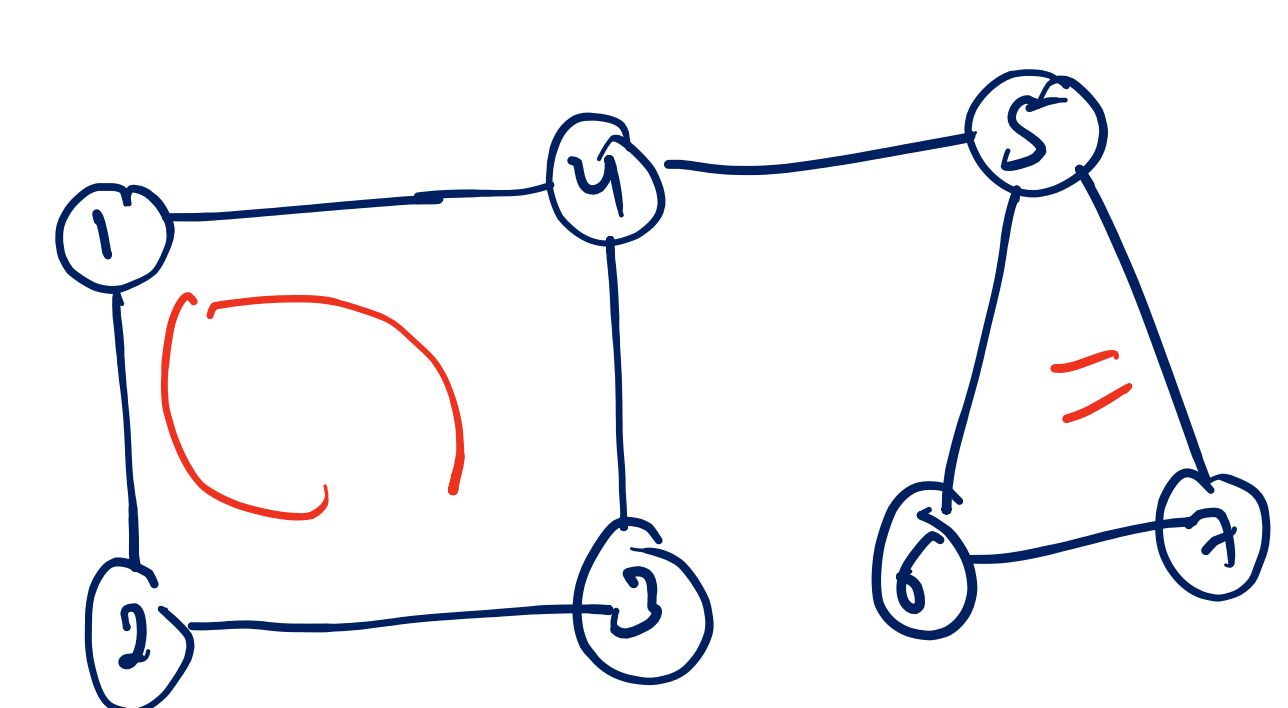
```
public boolean HasPath(int src, int Des, HashSet<Integer> visited) {
    if (src == Des) {
        return true;
    }
    visited.add(src);
    for (int nbrs : map.get(src).keySet()) {
        if (!visited.contains(nbrs)) {
            boolean ans = HasPath(nbrs, Des, visited);
            if (ans == true) {
                return ans;
            }
        }
    }
    return false;
}
```



```
public void PrintPath(int src, int Des, HashSet<Integer> visited, String str) {
    if (src == Des) {
        System.out.println(str);
        return;
    }
    visited.add(src);
    for (int nbrs : map.get(src).keySet()) {
        if (!visited.contains(nbrs)) {
            PrintPath(nbrs, Des, visited, str+src);
        }
    }
}
```

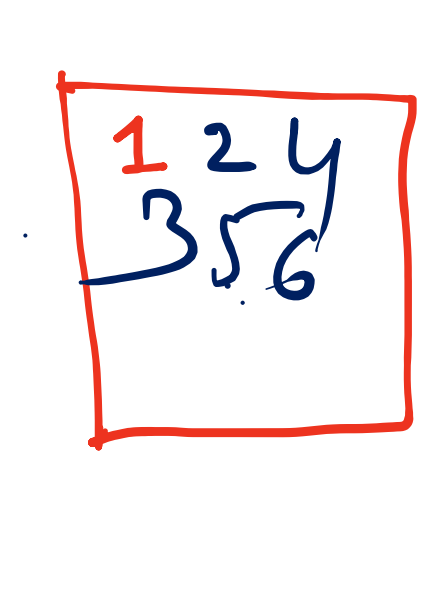
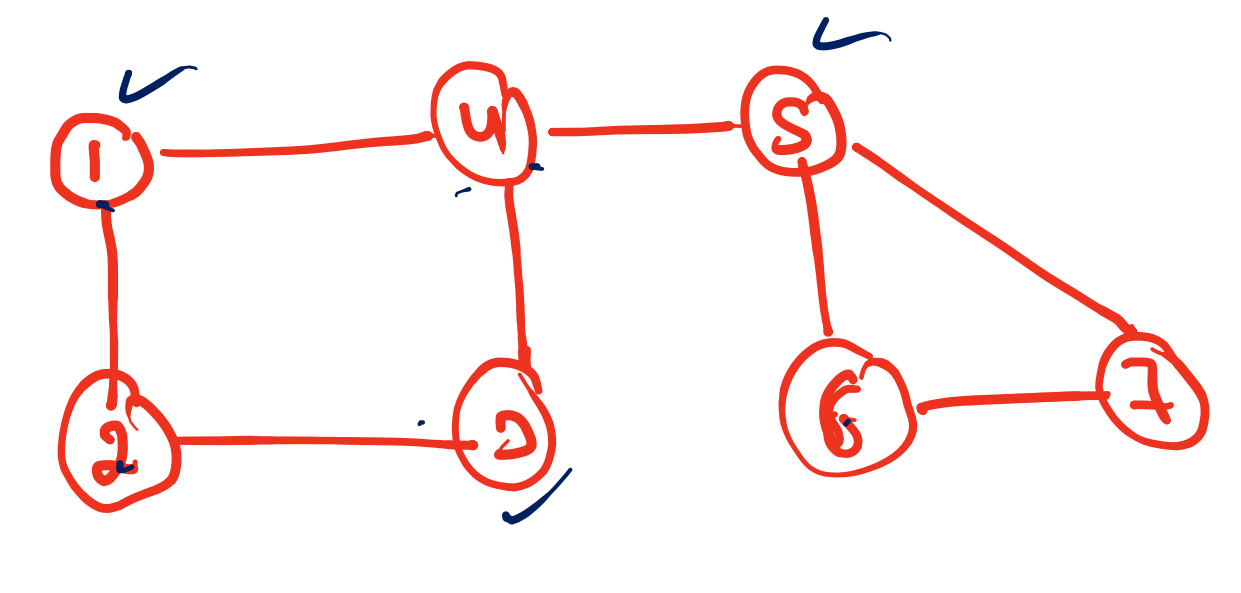


1. Remove
2. Ignore
3. visited
4. self work
5. Add nbrs

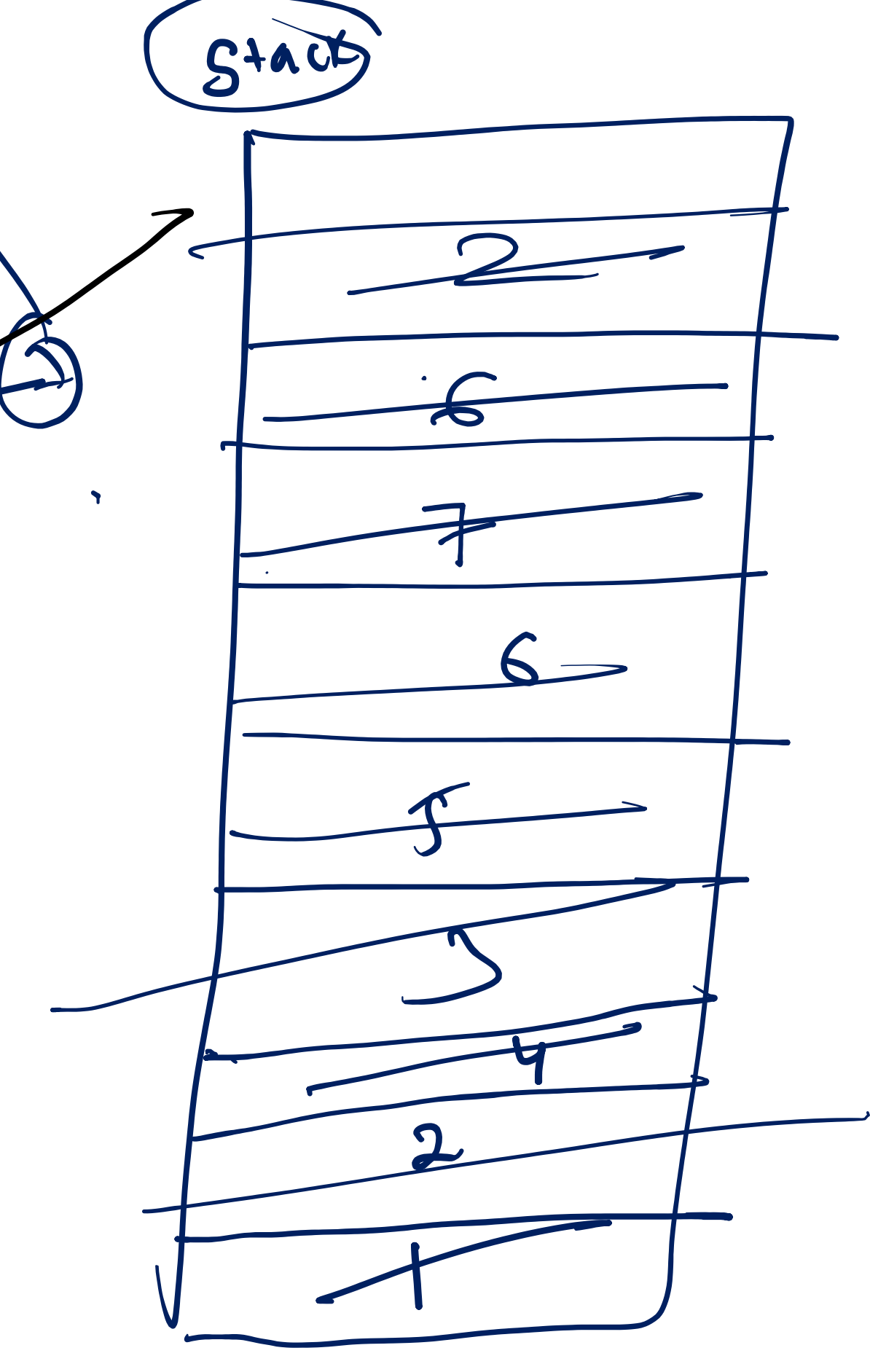
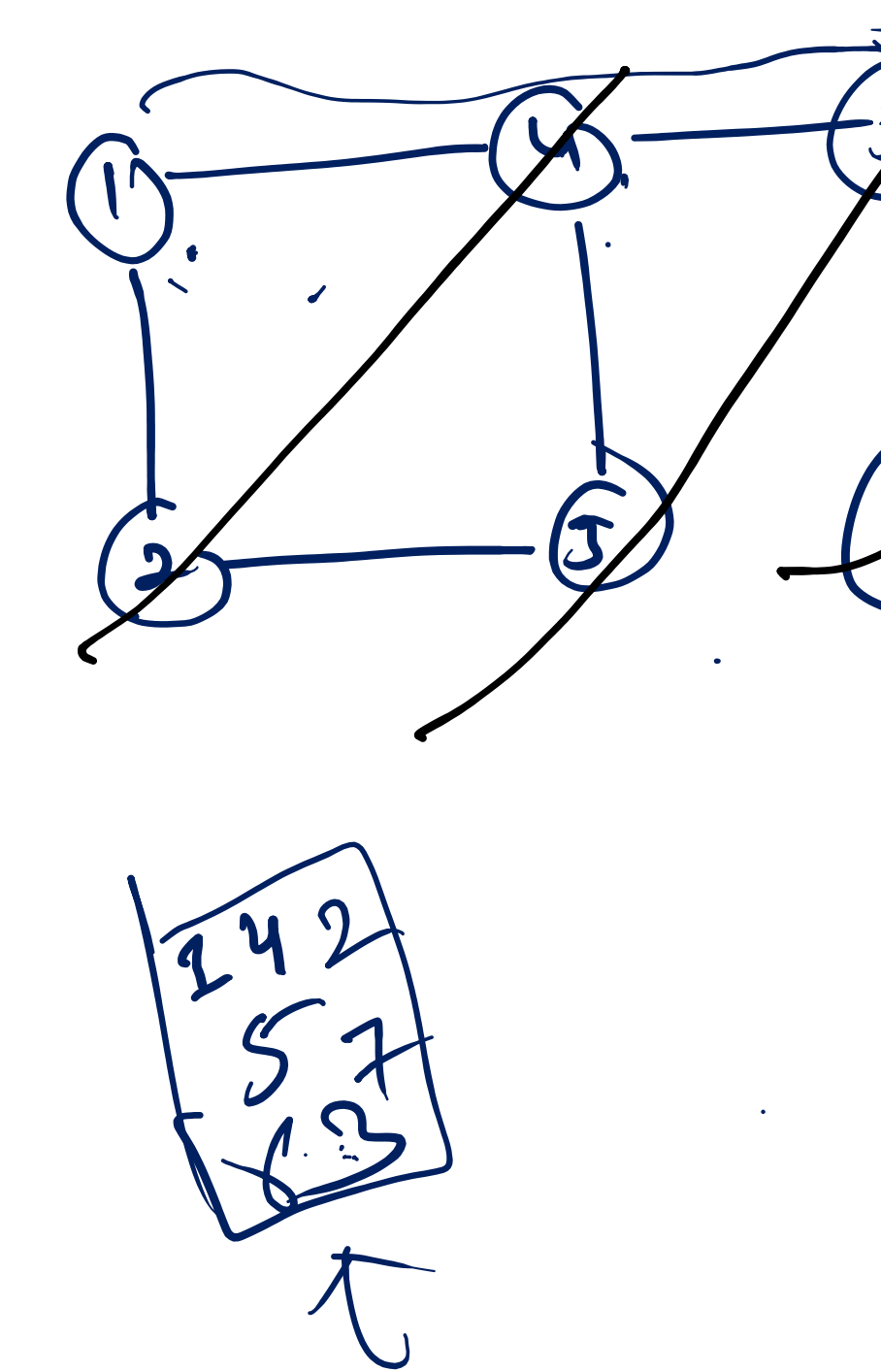


1 2 3 4 5 6 7 8

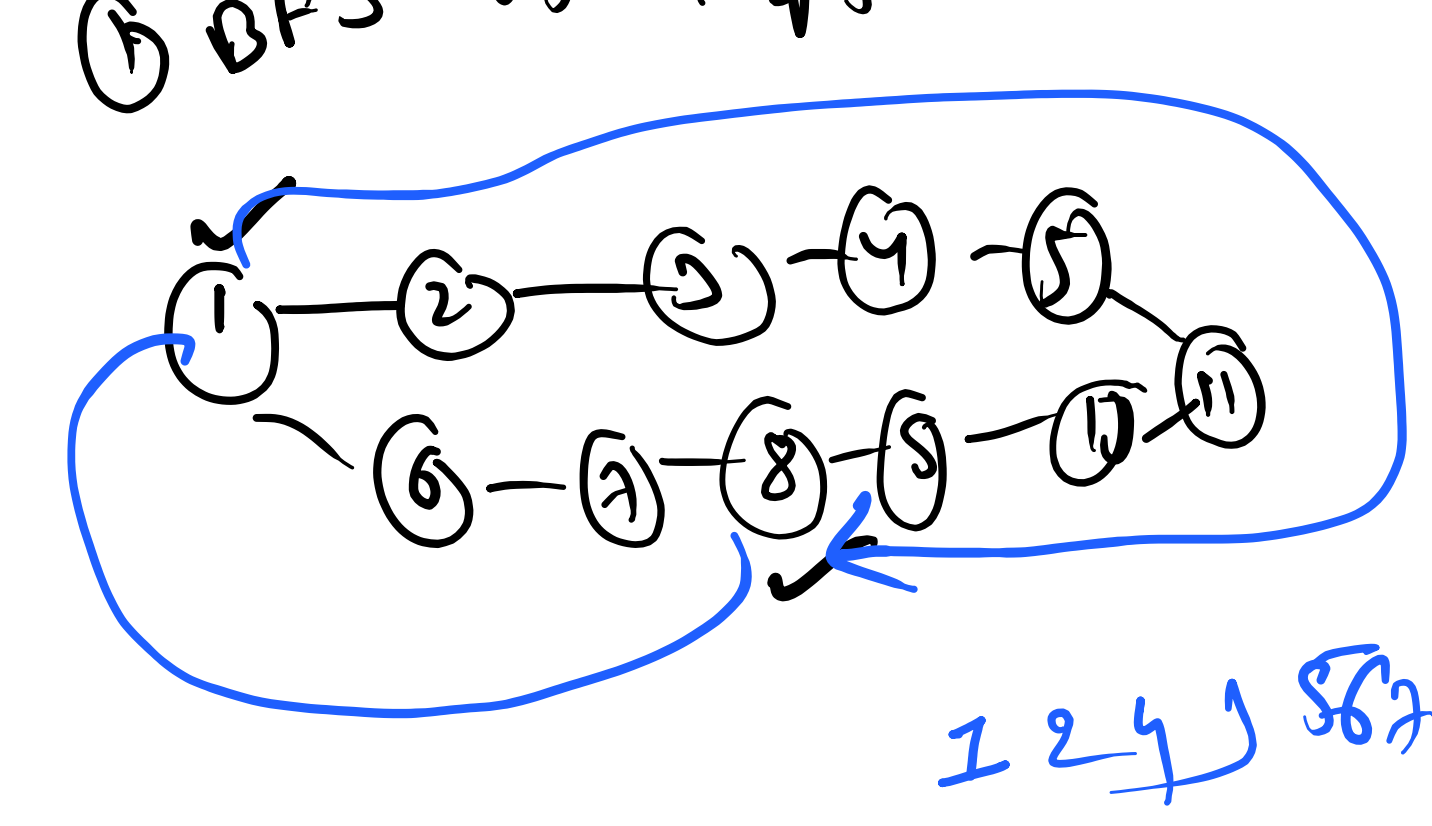
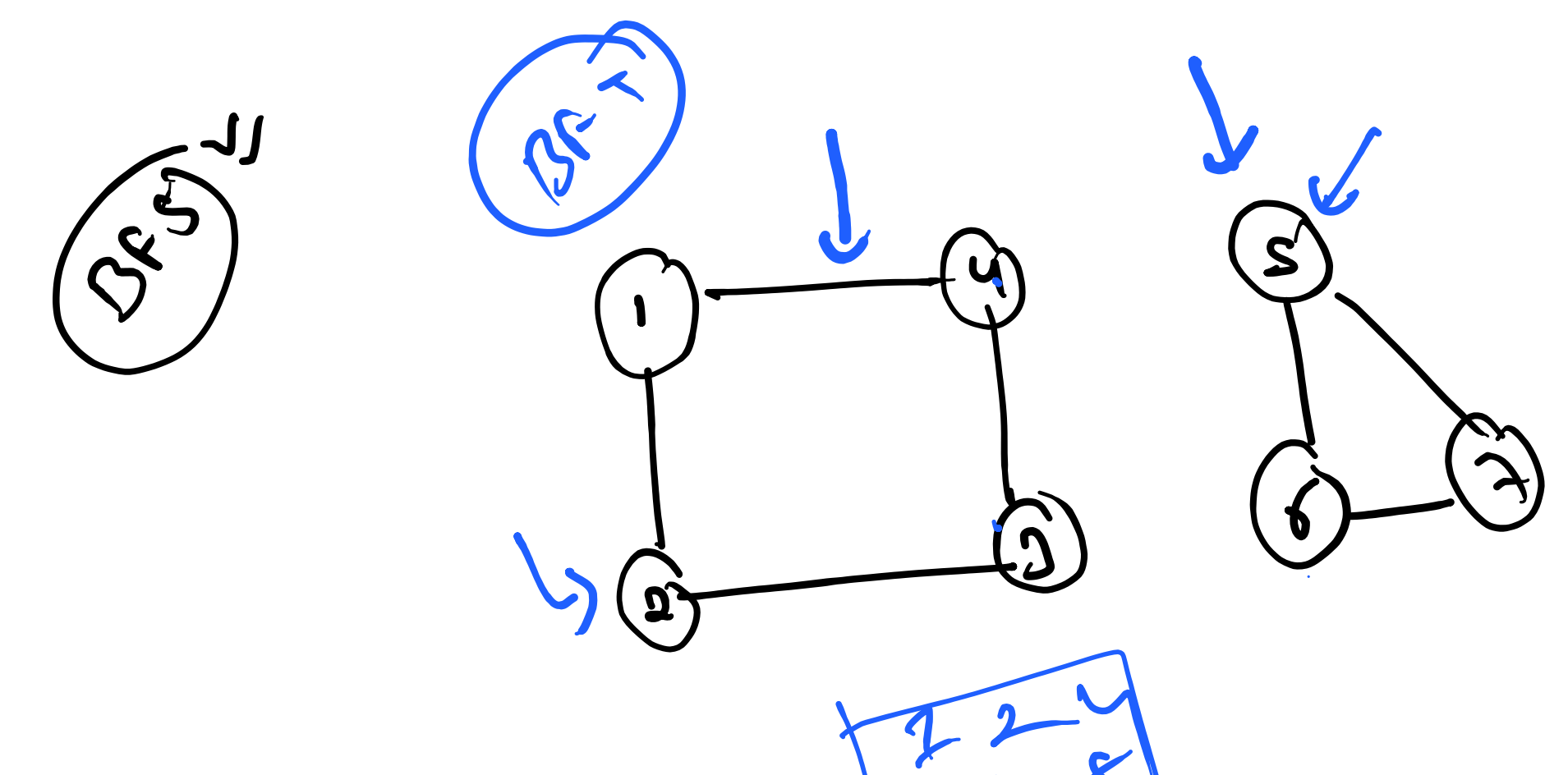
```
public boolean BFS(int src, int des) {
    Queue<Integer> q = new LinkedList<>();
    HashSet<Integer> visited = new HashSet<>();
    q.add(src);
    while (!q.isEmpty()) {
        // 1. remove
        int rv = q.poll();
        // 2. Ignore if Already Visited
        if (visited.contains(rv)) {
            continue;
        }
        // 3. Marked Visited
        visited.add(rv);
        // 4. self work
        if (rv == des) {
            return true;
        }
        // 5. add unvisited nbrs
        for (int nbrs : map.get(rv).keySet()) {
            if (!visited.contains(nbrs)) {
                q.add(nbrs);
            }
        }
    }
    return false;
}
```



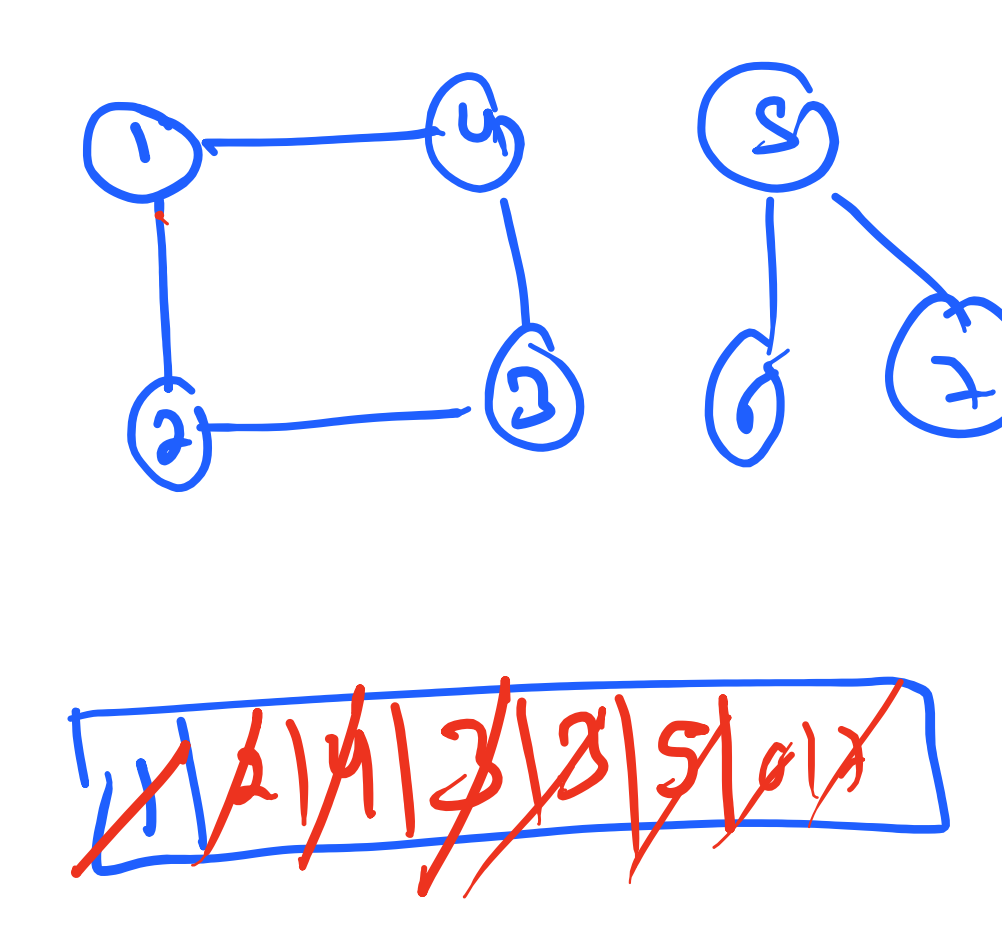
1. remove
2. ignore
3. marked visited
4. self work
5. Add nbrs



DFS VS BFS



```
public void BFS() {
    Queue<Integer> q = new LinkedList<>();
    HashSet<Integer> visited = new HashSet<>();
    for (int src : map.keySet()) {
        if (visited.contains(src)) {
            continue;
        }
        q.add(src);
        while (!q.isEmpty()) {
            // 1. remove
            int rv = q.poll();
            // 2. Ignore if Already Visited
            if (visited.contains(rv)) {
                continue;
            }
            // 3. Marked Visited
            visited.add(rv);
            // 4. self work
            System.out.println(rv+" ");
            // 5. add unvisited nbrs
            for (int nbrs : map.get(rv).keySet()) {
                if (!visited.contains(nbrs)) {
                    q.add(nbrs);
                }
            }
        }
    }
    System.out.println();
}
```



n = 5, edges = [[0,1],[1,2],[2,3],[1,3],[1,4]]

```
public boolean validTree(int n, int[][] edges) {
    HashMap<Integer, List<Integer>> map = new HashMap<>();
    for (int i = 0; i < n; i++) {
        map.put(i, new ArrayList<>());
    }
    for (int i = 0; i < edges.length; i++) {
        int v1=edges[i][0];
        int v2=edges[i][1];
        map.get(v1).add(v2);
        map.get(v2).add(v1);
    }
}
```

