## Matrix Theory Assignment 1

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Abstract—This document contains the procedure to get image of a point in a line.

Download the python code from the below link. Go through the README file in the reposotory.

https://github.com/ankuraditya13/EE5609— Assignment-1

## 1 Problem

Find the image of the point  $\binom{3}{8}$  with respect to the line

$$\begin{pmatrix} 1 & 3 \end{pmatrix} \mathbf{x} = 7 \tag{1.0.1}$$

## 2 Solution

For this problem, I am considering the general case. Let the Equation of line be ax + by = c and let the coordinates of,

$$\mathbf{P}(\text{given point}) = \begin{pmatrix} x1 \\ y1 \end{pmatrix}$$

$$\mathbf{Q}(\text{point on mirror}) = \begin{pmatrix} x2 \\ y2 \end{pmatrix}$$

$$\mathbf{R}(\text{image point}) = \begin{pmatrix} x3 \\ y3 \end{pmatrix}$$

Let vector 
$$\mathbf{n} = \begin{pmatrix} a \\ b \end{pmatrix}$$

Let m be the directional vector along the line, ax + by = c.

Hence, 
$$m = \begin{pmatrix} b \\ -a \end{pmatrix}$$

By property in Figure 0, the line PR bisects the mirror equation perpendicularly. Hence,

$$2\mathbf{Q} = \mathbf{P} + \mathbf{R} \tag{2.0.1}$$

Hence the reflection vector  $\mathbf{R}$  is given as,

$$\frac{\mathbf{R}}{2} = \frac{\mathbf{m}\mathbf{m}^T - \mathbf{n}\mathbf{n}^T}{\mathbf{m}^T\mathbf{m} + \mathbf{n}^T\mathbf{n}}\mathbf{P} + c\frac{\mathbf{n}}{\|\mathbf{n}\|^2}$$
(2.0.2)

Hence, substituting the values of x1 = 3, y1 = 8, a = 1, b = 3 and c = 7 we get,

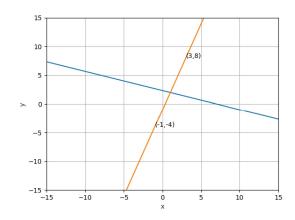


Fig. 0: Image of a point in 2D line

$$\mathbf{P}(\text{given point}) = \begin{pmatrix} 3 \\ 8 \end{pmatrix}$$

$$\mathbf{m} \text{ (direction vector)} = \begin{pmatrix} 3 \\ -1 \end{pmatrix}$$

$$\mathbf{n} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Norm, 
$$|||\mathbf{n}||| = \sqrt[2]{a^2 + b^2}$$

Substituting these values in equation (2.0.2) we get,

$$\mathbf{R} = \begin{pmatrix} -1 \\ -4 \end{pmatrix} \tag{2.0.3}$$

Hence, it is the required answer for image of **P** in line  $\begin{pmatrix} 1 & 3 \end{pmatrix}$  **x** = 7.