

# Ankur Das

## PERSONAL INFO

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## EDUCATION

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2012 - Current    B.S. in Mechanical Engineering, OLIN COLLEGE OF ENGINEERING, Class of 2016  
Needham, MA    Selected Coursework: Design Nature, User Oriented Collaborative Design, Robotics,  
Dynamics, Mechanics of Solids and Structures, Principles of Engineering, Materials  
Science, Transport Phenomena\* (Current)  
GPA: 3.82

2008 - 2012    High School Diploma, BELLARMINE COLLEGE PREPARATORY  
San Jose, CA    GPA: 3.92 Unweighted, 4.57 Weighted

## EXPERIENCE

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FALL 2012 - CURRENT NEEDHAM, MA	<b>RESEARCH OF ELECTRIC VEHICLES AT OLIN</b> <ul style="list-style-type: none"><li>·Current mechanical design lead on FORMULA SAE ELECTRIC racecar</li><li>·Leading Oversaw all design decisions on FSAE car mechanical systems, mentored team members, managed</li><li>·Led suspension design on off/on-road capable three-wheeled electric car</li><li>·Converted gas-powered go-kart to electric powertrain.</li></ul>
SUMMER 2014 BERKELEY, CA	<b>Manufacturing Engineering Intern at ALL POWER LABS</b> <ul style="list-style-type: none"><li>·Created documentation through CAD, technical drawings, and PLM</li><li>·Designed assorted parts for small-scale biomass power generators</li><li>·Communicated with suppliers and fabricators for RFQ creation, DFM, DFX</li></ul>
FALL 2012 - SPRING 2014 NEEDHAM, MA	<b>SAE MINI BAJA</b> <ul style="list-style-type: none"><li>·Created and optimized suspension geometry on off-road vehicle team.</li><li>·Designed knuckles, integrated suspension with chassis and steering.</li></ul>
FALL 2008 - SPRING 2012 SAN JOSE, CA	<b>FRC, VEX ROBOTICS</b> <ul style="list-style-type: none"><li>·2011 FRC World Championship Winners. VEX robotics team captain.</li></ul>

## PROJECTS

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CURRENT	<b>Biomedical CAD and 3d Printing</b> <p>Research in converting biomedical data to 3d models, using 3d printing to clearly visualize complicated structures (i.e. fetus skeletons) for medical students.</p>
FALL 2013	<b>Laminar Flow Fountain</b> <p>Led mechanical design of a small tabletop laminar flow fountain with audio-visual response. Created recycling waterproof system with three powered laminar flow nozzles.</p>
FALL 2012	<b>Remote Controlled Gorilla</b> <p>Designed educational game targeted to fourth graders with limited budget. Designed remote controlled walking gorilla toy.</p>
FALL 2012 - SPRING 2014	<b>Misc. School, Personal Projects</b> <p>Autonomous Tugboat Navigation, Welding and Heat Treatment Analysis, Hand Gesture Laptop Control, Automated Dynamics Equation Generator, 3d Printing, Modular Origami</p>

## SKILLS

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Software: Solidworks, Matlab, LabView, Adobe Suite, Python, DraftSight, Arduino, Arena PLM  
Fabrication: Mill, Lathe, Sheet Metal, MIG Welding, CNC Laser & Plasma Cutter, 3d Printers