

MIT Sailing System

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My Background - Designing High Performance Systems

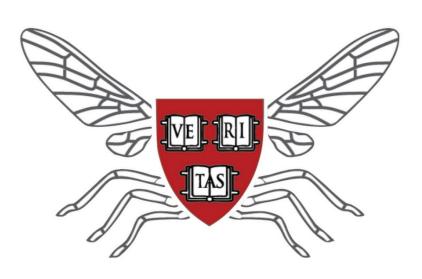








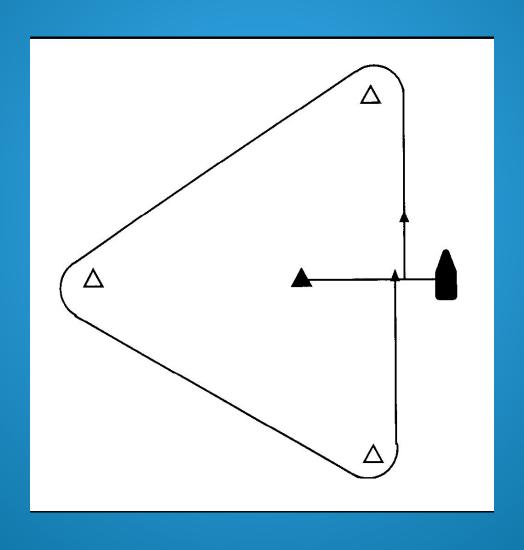








Competitive Environment: Triangle Course



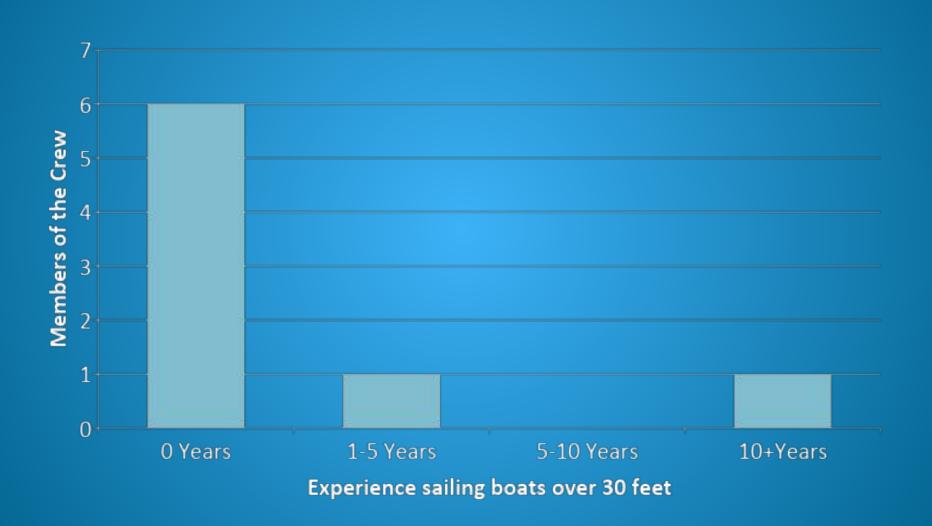
Management Environment

- Dynamic situations
- Many variables
- Few repeating situations

Year 1

Learning the Ropes

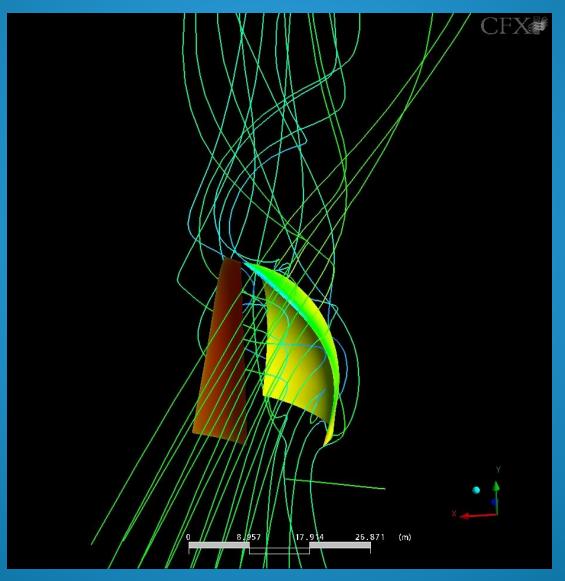
Team Skills



Fundamentals



Sailing is complex



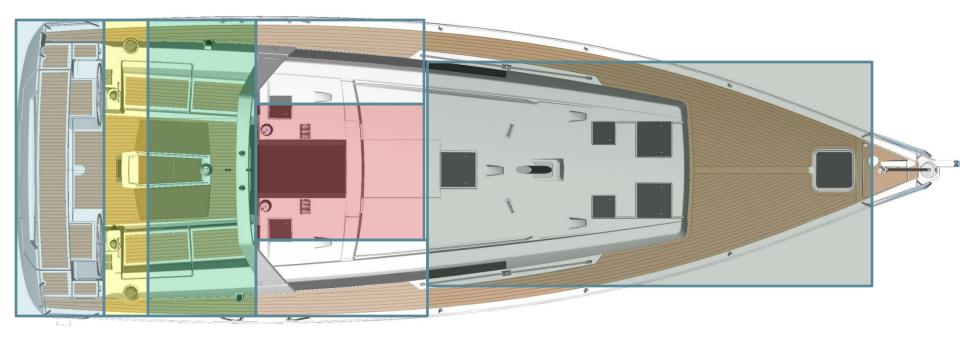
Noisy Indicators



One Shot Deployment



Distribute Responsibility



Getting Started



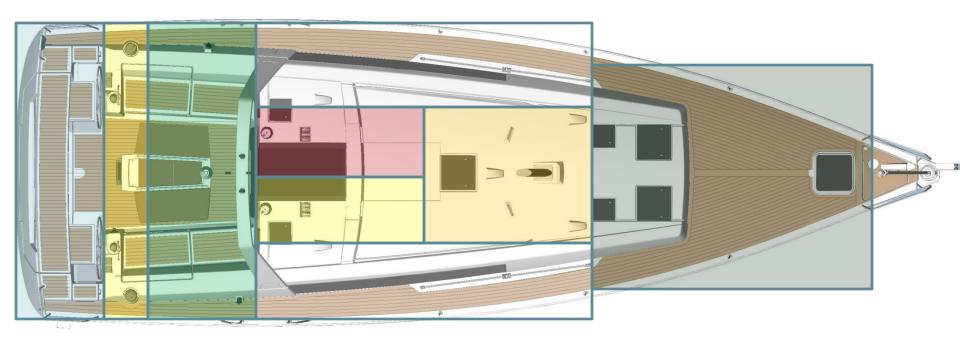
Expectations



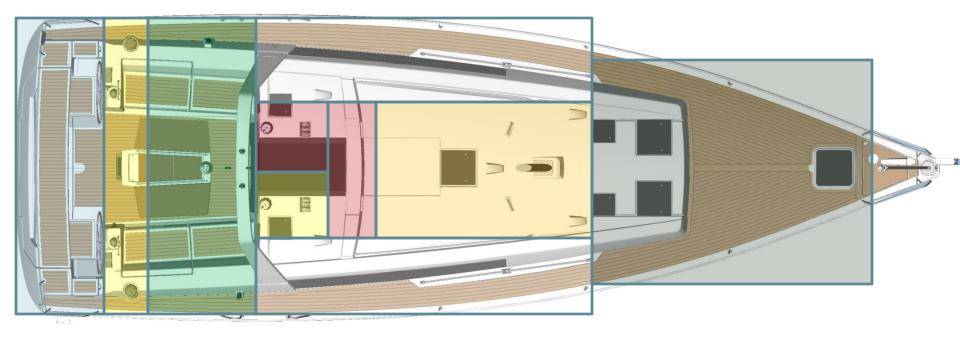
Actual



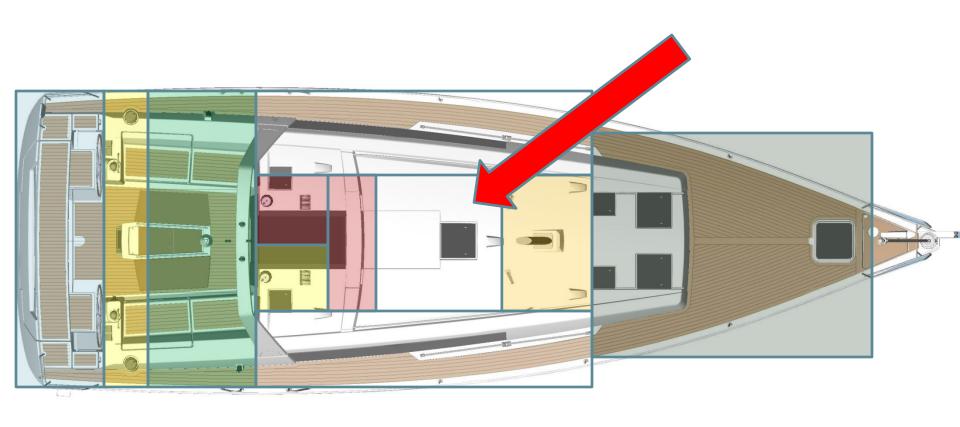
Re-Distribute Responsibility



Add Responsibility, Closed feedback



Safety and Lookout



Year 2

Mission: Return home with more friends than we left with

Team Alignment

Results

Actions

Behaviors

Qualities

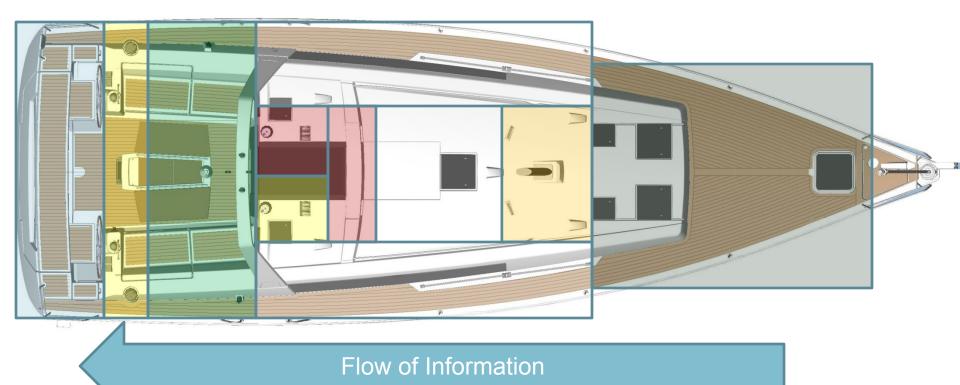
Perform

Learn from mistakes, share work

Acknowledge mistakes

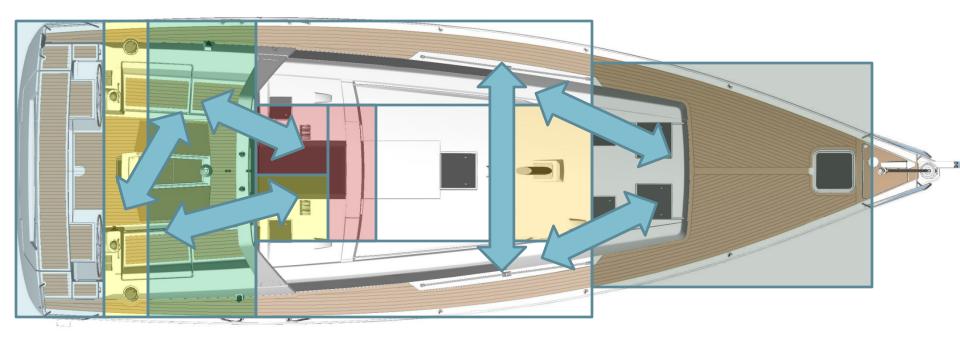
Smart, Humble, Collaborative, Desire to Win

Traditional Communication

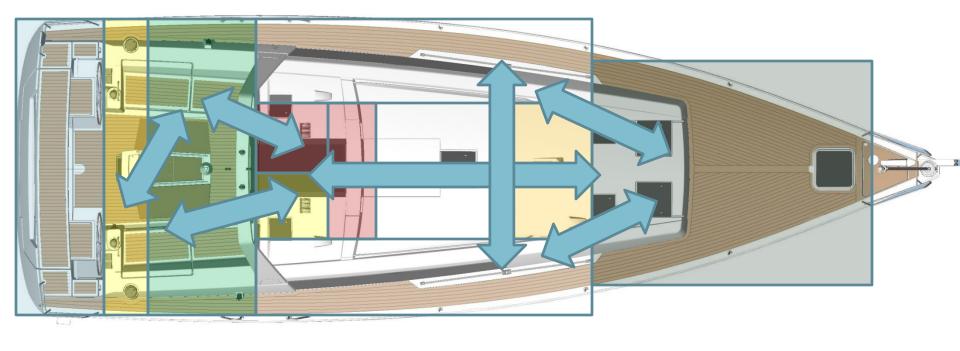


Flow of Directions

Local Communication



Distributed Communication



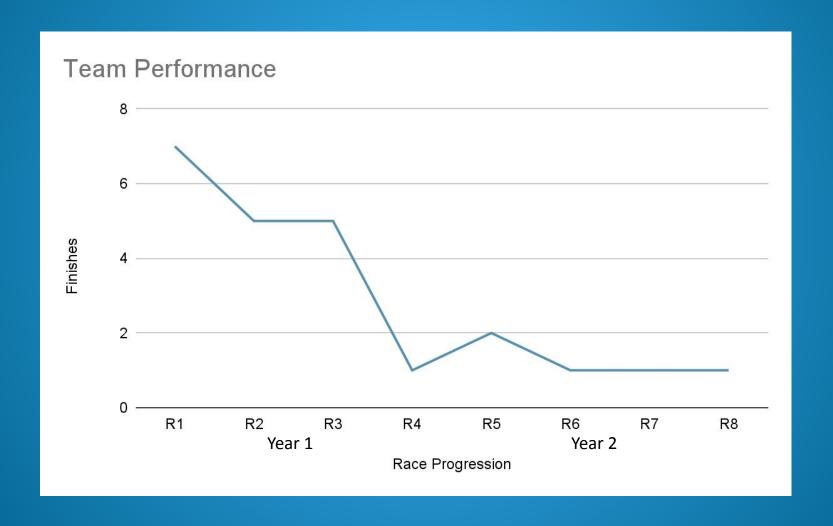
Agile



Stop The Boat



Rapid Improvement



The Finals



Results



Repeatability



New Boat

New Skippers

New Crew

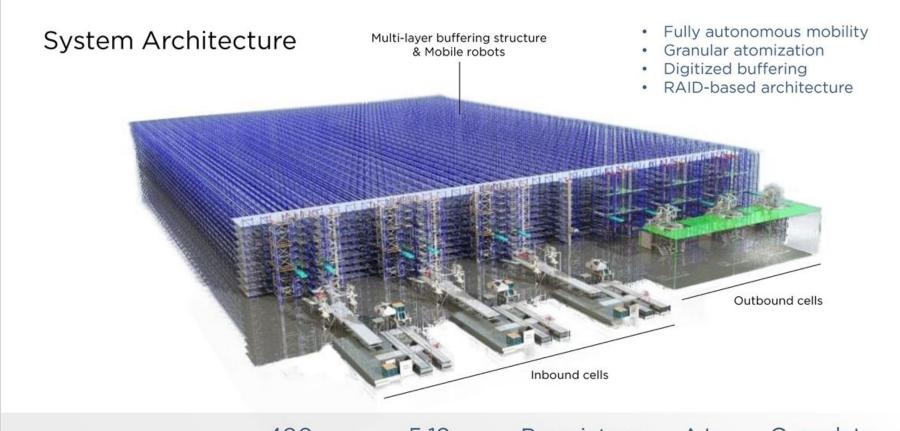
High Performance System





2023 Pursuit Champions

Recent Work - Al Driven Teamwork



A typical system has...

~400 autonomous EV mobile robots 5-10 inbound & outbound cells Proprietary

A.I.

Complete autonomy & modularity

Quantitative System Design and Performance Optimization

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