

Name : .....

Roll No. : .....

Invigilator's Signature : .....

**CS/B.Tech (ME/PE)/SEM-6/ME-602/2010**

**2010**

**MECHATRONICS AND MODERN CONTROL**

*Time Allotted : 3 Hours*

*Full Marks : 70*

*The figures in the margin indicate full marks.*

*Candidates are required to give their answers in their own words  
as far as practicable*

**GROUP – A**

**( Multiple Choice Type Questions )**

1. Choose the correct alternatives for any ten of the following :  $10 \times 1 = 10$
- i) LVDT can measure
    - a) strain
    - b) displacement
    - c) force
    - d) all of these.
  - ii) Differential amplifier
    - a) amplifies the difference between the input voltages
    - b) compares which of the two voltages is larger
    - c) inverts the potential difference
    - d) none of these.
  - iii) Pressure can be measured by the use of
    - a) The Bourdon Tube
    - b) Accelerometer
    - c) Tachometer
    - d) Encoder.

CS/B.Tech (ME/PE)/SEM-6/ME-602/2010

CS/B.Tech (ME/PE)/SEM-6/ME-602/2010

xi) The Boolean equation for the XOR gate is

- a)  $A \cdot B = Q$
- b)  $\overline{A} = Q$
- c)  $A + B = Q$
- d) None of these.

xii) In a word microprocessor means

- a) CPU-on-a-chip
- b) ALU-on-a-chip
- c) Computer-on-a-chip
- d) IC-on-a-chip
- e) microscope processing.

xiii) Semiconductor type tempeature sensor is

- a) RTD
- b) Thermistor
- c) Thermometer
- d) Pyrometer.

xiv) Non Maskable interrupt is

- a) RST 7 5
- b) RST 6·5
- c) TRAP
- d) INTR.

xv) Self generating transducers are

- a) passive transducer
- b) active transducer
- c) primary transducer
- d) secondary transducer.

CS/B.Tech (ME/PE)/SEM-6/ME-602/2010

**GROUP – B**

**( Short Answer Type Questions )**

Answer any *three* of the following.       $3 \times 5 = 15$

2. In binary coding  $A = 1001001011$  and  $B = 110001101$ . Find the value of  $A + B$  and  $A - B$  in binary and hexadecimal format.
3. State the characteristics of stepper and brush less DC motor.
4. Compare between hydraulic and pneumatic control circuit system.
5. What effect does a flow control valve have on an actuator ? What is another way to control the flow rate to an actuator ? Describe the difference between meter-in and meter-out flow control. Draw a hydraulic cylinder with meter-in-flow control of both strokes.
6. Write short notes on operational amplifier and also state its applications.       $\frac{1}{2} + \frac{1}{2} + 2 + 2$

**GROUP – C**

**( Long Answer Type Questions )**

Answer any *three* of the following.       $3 \times 15 = 45$

7. a) State the role of PLC. Draw a ladder logic program where an electric motor is to be run by using one open contact push button switch, one closed contact push button switch and a relay switch.      7

CS/B.Tech (ME/PE)/SEM-6/ME-602/2010

- b) Write the names and main functions of hydraulic symbols are marked ( by 1 to 10 ) in the hydraulic circuit diagram of an automobile breaking system given in figure. 8

Figure 1 : Hydraulically control automobile breaking system circuit diagram.

CS/B.Tech (ME/PE)/SEM-6/ME-602/2010

8. a) Along with the necessary circuit explain how 4 numbers of bonded strain gauges can be used for measuring force giving the highest sensitivity. 6
- b) How a thermostat can be used as a controller ? 4
- c) What is piezoelectricity ? How can it be used as force measurement or pressure sensor ? 5
9. Show that output voltage is proportional to mechanical strain for small change in gauge resistance.

A resistance is bonded to a beam of 50 mm long and having a cross section of  $5 \text{ mm}^2$  and Young modulus  $E = 200 \text{ GPa}$ . The strain gauge has a unstrained resistance of  $220 \Omega$  and gauge factor ( GF ) of 2 when a load is applied a resistance change by  $0.013 \Omega$ . Find the change of length of the beam and amount of force applied to beam.

10. a) Prove that, NOR gates are the universal gates. 3
- b) Describe with block diagram an 8085 microprocessor. What are the importances of microprocessors and microcontrollers ? 8
- c) Write a program for Intel 8085 microprocessor to add two binary numbers  $A = 11$  and  $B = 10$  and store the result. 4

CS/B.Tech (ME/PE)/SEM-6/ME-602/2010

11. a) Compare the characteristics of open-loop and closed-loop control systems in machines or process control applications. 5
- b) A closed-loop system shown in Figure. 1 has a process transfer function  $G(s)=\frac{1}{s(s+4)}$  and is used with proportional control. Obtain the following : 10
- i) the system type
  - ii) the steady-state errors when used with a step input and ramp input.

Figure. 2 : System with proportional control

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