

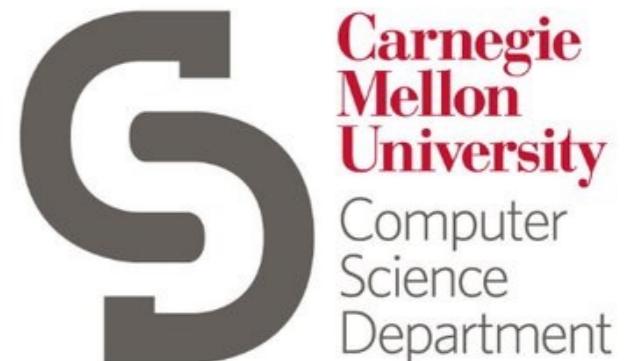
Parallel Complexity Analysis with Temporal Session Types

Ankush Das

Jan Hoffmann

Frank Pfenning

ICFP, Sep 26, 2018



What is Parallel Complexity? ²



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Total time of computation?

What is Parallel Complexity?²



Total time of computation?

Depends on amount of parallelism in system

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a.k.a. Span

Total time of computation?

Depends on amount of parallelism in system

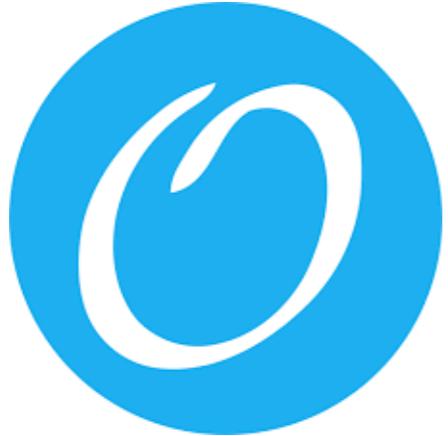
Data
Dependencies

Wait for
Messages

Data Races
Shared Memory

Why Parallel Complexity?

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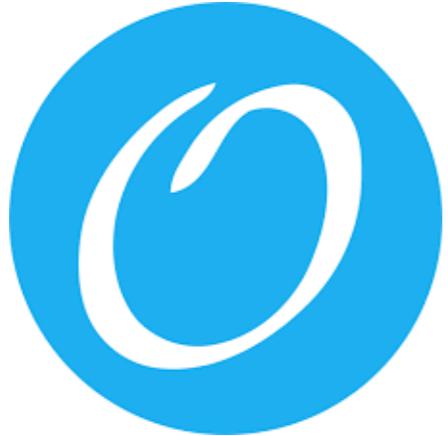


Complexity of Parallel Algorithms

Blelloch (Comm. ACM '96)

Why Parallel Complexity?

3



Complexity of Parallel Algorithms

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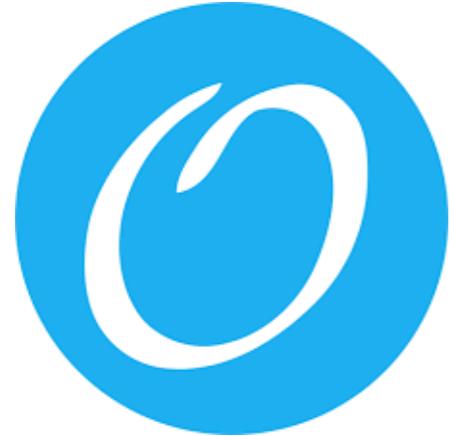


Design of Optimal Scheduling Policies

Acar et. al. (JFP '16)

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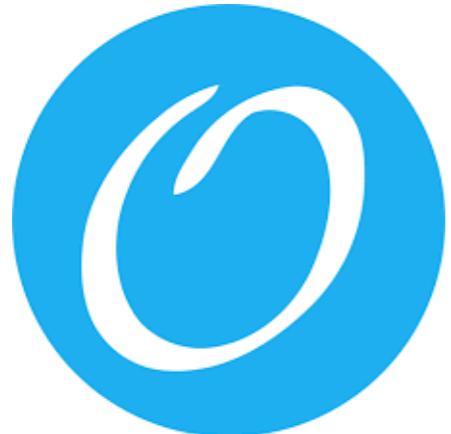
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Throughput and Latency of Streams

Mamouras et. al. (PLDI '17)

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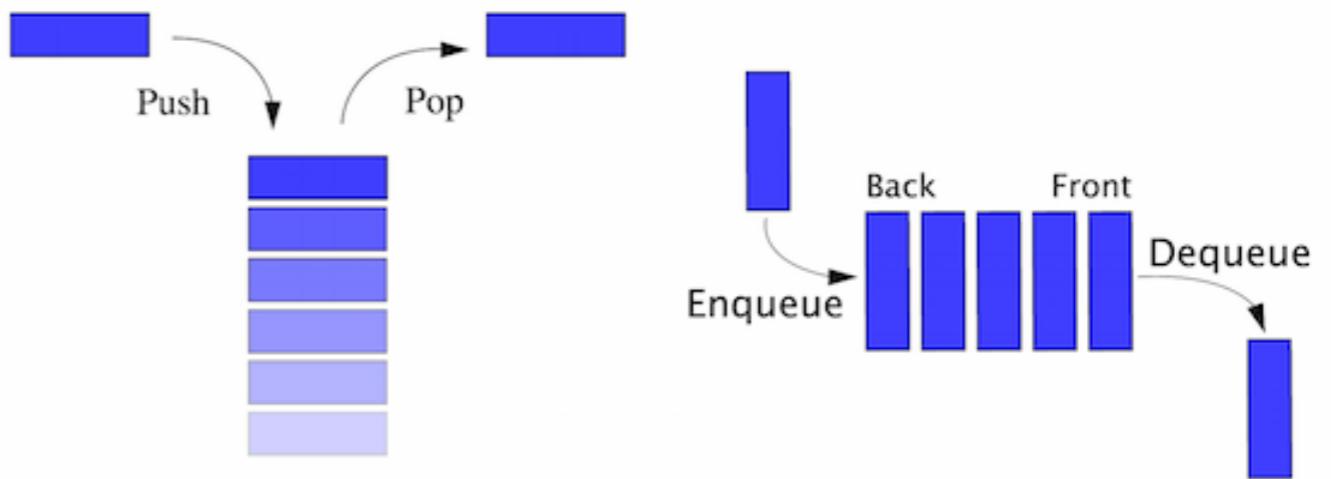
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Response Time of Concurrent Data Structures

Ellen and Brown (PODC '16)

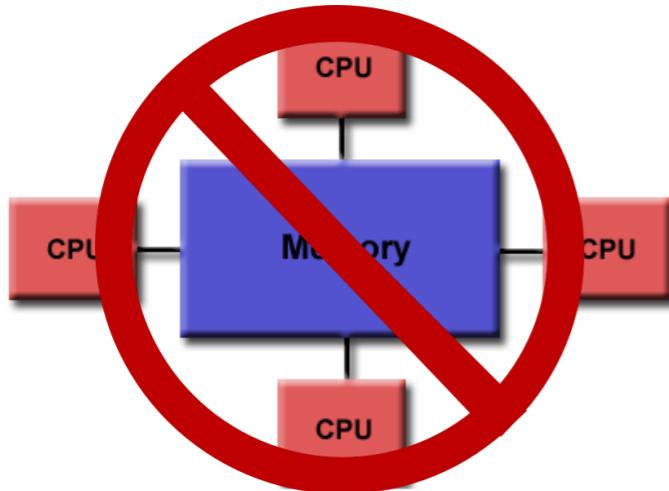
Why Session Types?

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Concurrent Programs are hard to analyze!

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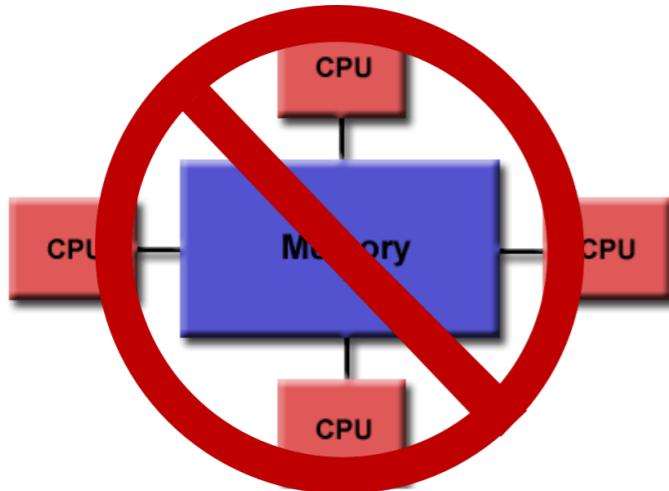
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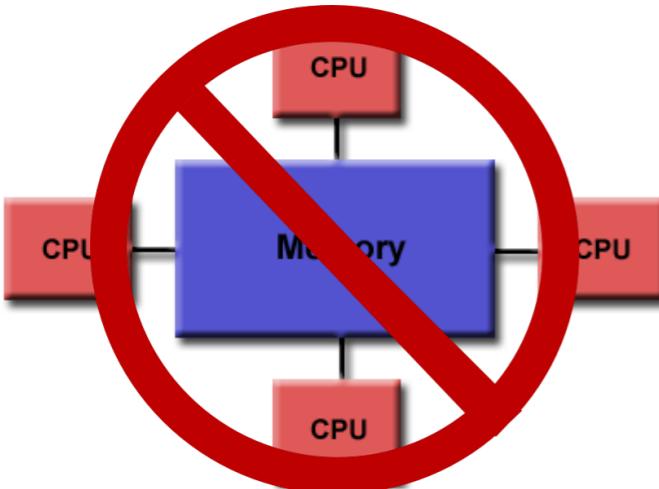
No Shared Memory



Types strictly enforce
communication protocols

Why Session Types?

Concurrent Programs are hard to analyze!



No Shared Memory



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Deadlock Freedom

What are Session Types?

- ▶ Implement message-passing concurrent programs
- ▶ Communication via typed bi-directional channels
- ▶ Curry-Howard isomorphism with intuitionistic linear logic

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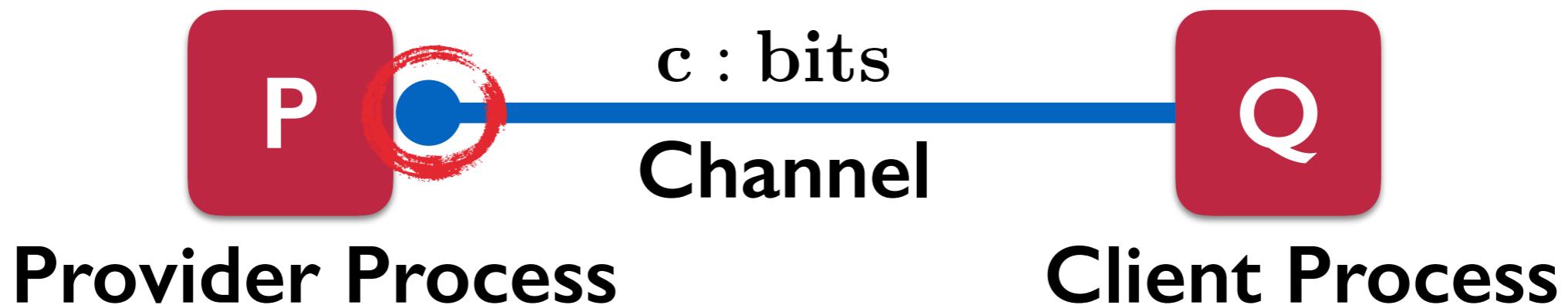


What are Session Types?

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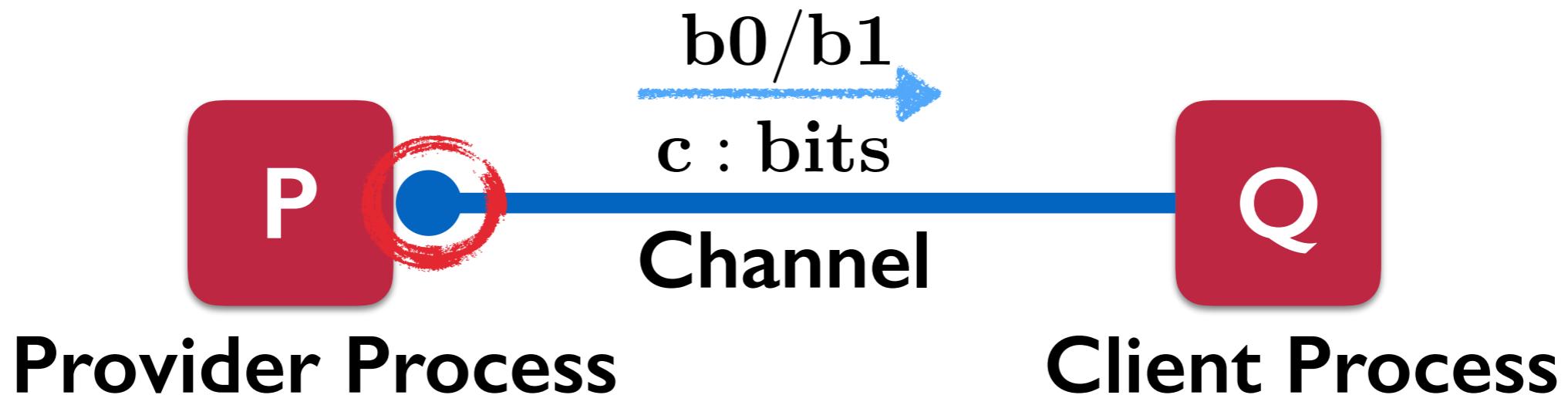
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Contributions

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Type system to analyze timings of message exchanges of session-typed programs

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Type system to analyze timings of message exchanges of session-typed programs

- ▶ types define the *timing* of message exchanges
- ▶ provides *precision* and *flexibility*
- ▶ proved *sound* w.r.t. *cost semantics* tracking time
- ▶ *conservative* extension to typical session type system
- ▶ applies to all *standard* session types examples
- ▶ can be *parameterized* to count resource of interest

How is time defined?

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\mathcal{R} cost model

Unit delay after
each receive

\mathcal{RS} cost model

Unit delay after each
receive and send

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\mathcal{R} cost model

Unit delay after
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\mathcal{RS} cost model

Unit delay after each
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- ▶ Expressed by inserting appropriate delays in the source code, only the delays cost time
- ▶ Programmer specifies cost model, compiler automatically inserts delays for type checking

$$\Omega \vdash P :: (x : S)$$

Definition of the Types

Track Message Rates



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Compute output rate given input rate

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timing of messages \Leftrightarrow Parallel Complexity

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Compute output rate given input rate

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Necessary:
need exact input/
output rate to ensure
compositionality

Sufficient:
span can be thought as
timing of final message

Example: Bit Streams

`bits = $\oplus\{b0 : \text{bits}, b1 : \text{bits}, \$: 1\}$`

`. + two :: (c : bits)`

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bits = $\oplus\{b0 : \text{bits}, b1 : \text{bits}, \$: 1\}$

• **+ two :: (c : bits)**

```
c ← two =
  c.b0 ;
  c.bl ;
  c.$ ;
close c
```

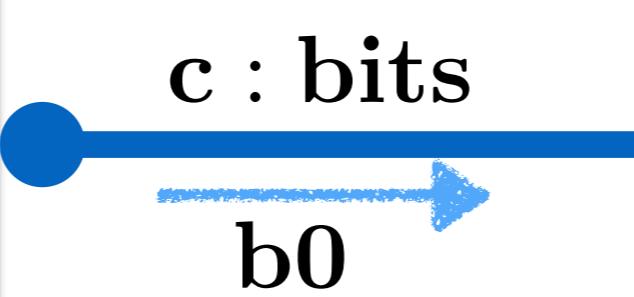
c : bits

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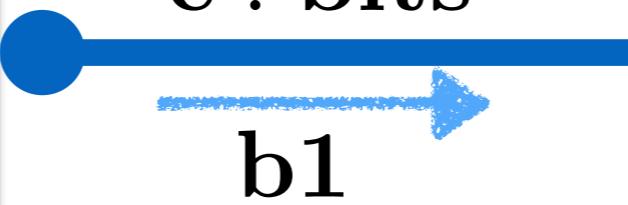


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b1 b0

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Example: Bit Streams

10

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Timing Information?

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Timing Information?

Sending a message
causes unit delay

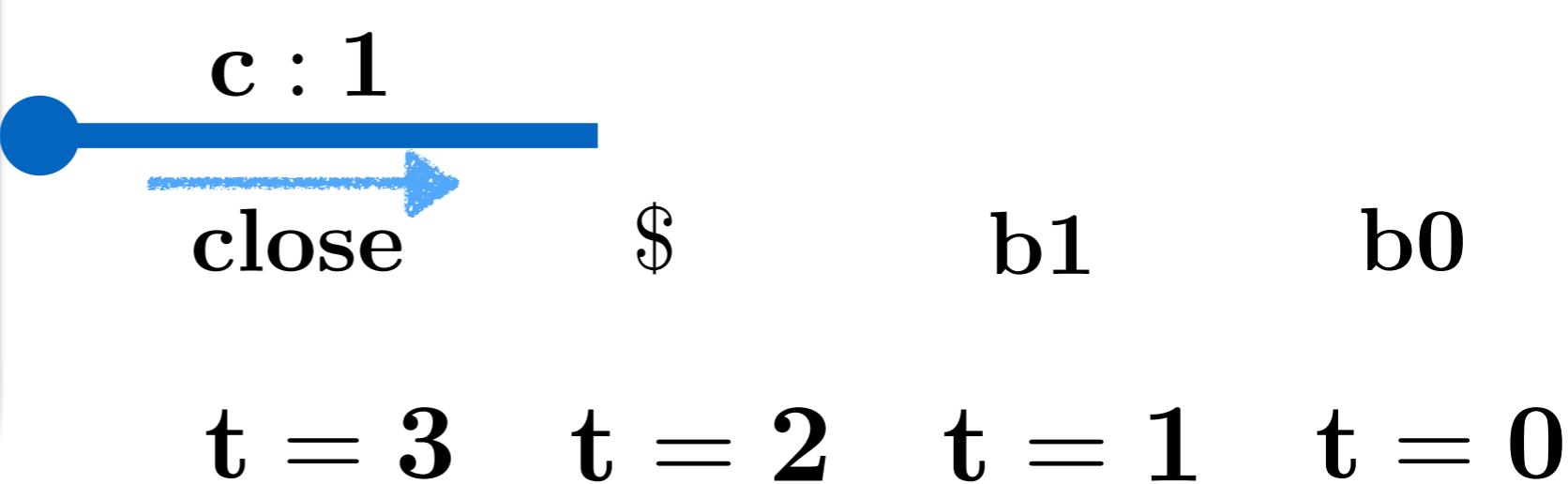
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Enforcing Time in the Type¹¹

$$\text{bits} = \oplus\{\text{b0} : \textcircled{O}\text{bits}, \text{b1} : \textcircled{O}\text{bits}, \$: \textcircled{O}1\}$$

Enforcing Time in the Type

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Next Operator - expresses unit delay

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$\mathbf{c} : \text{bits}$

Enforcing Time in the Type

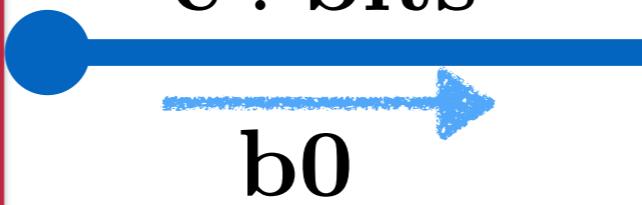
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$c : \text{bits}$

b0

$t = 1 \quad t = 0$

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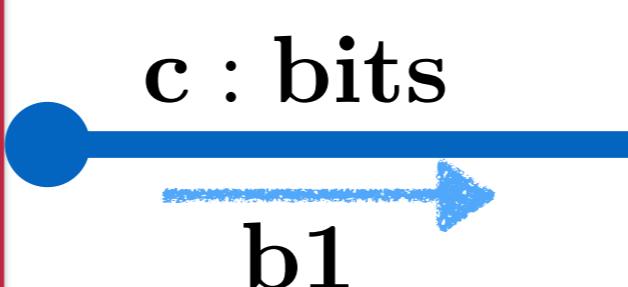
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t = 1 t = 0

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b1 b0
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$c : \text{bits}$

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t = 2 t = 1 t = 0

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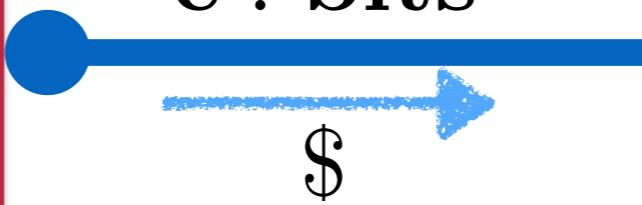
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$b1 \quad b0$
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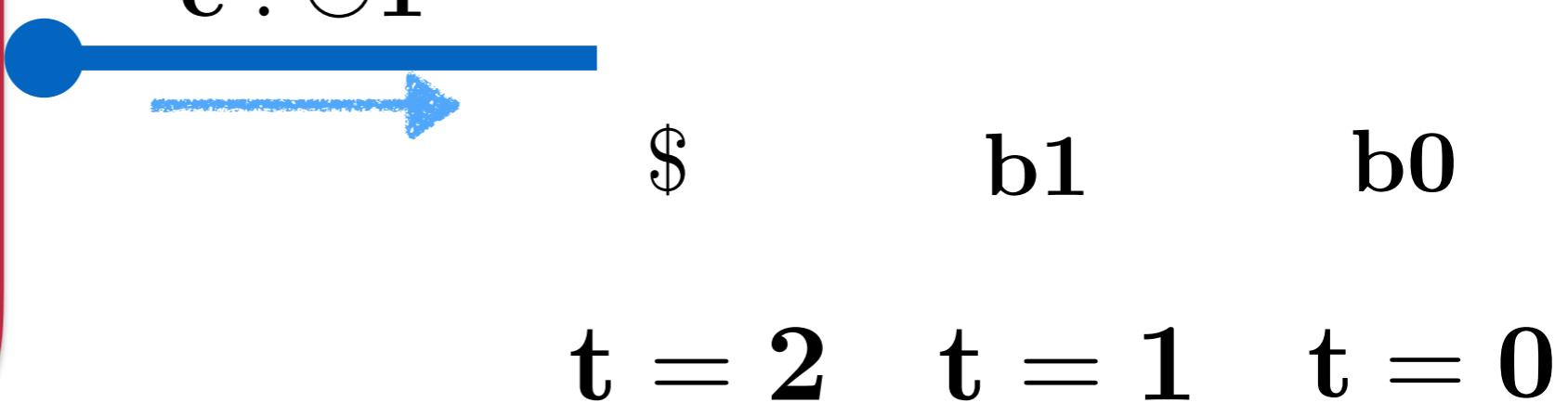
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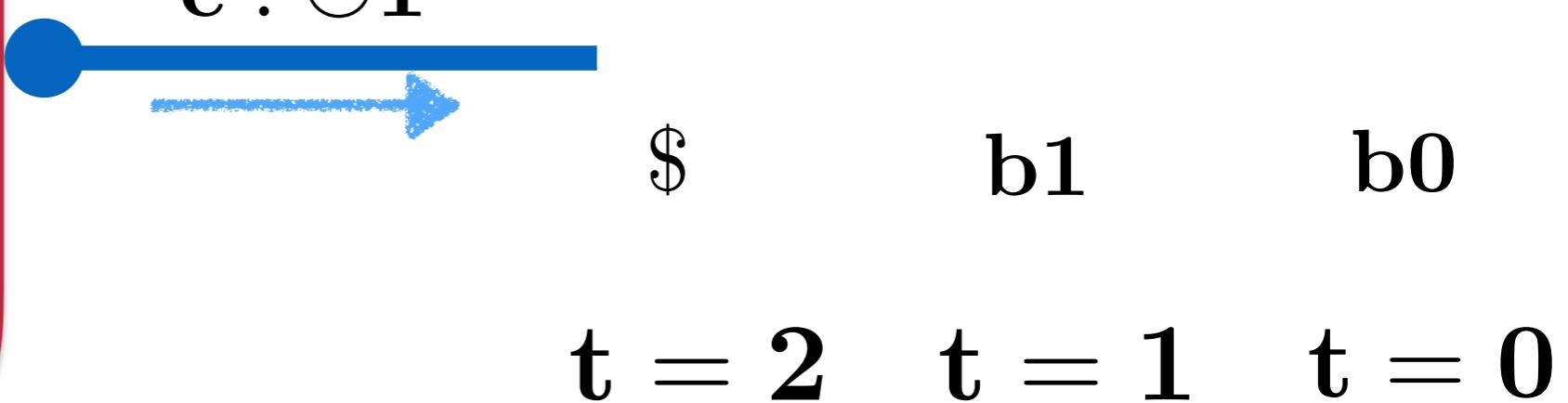
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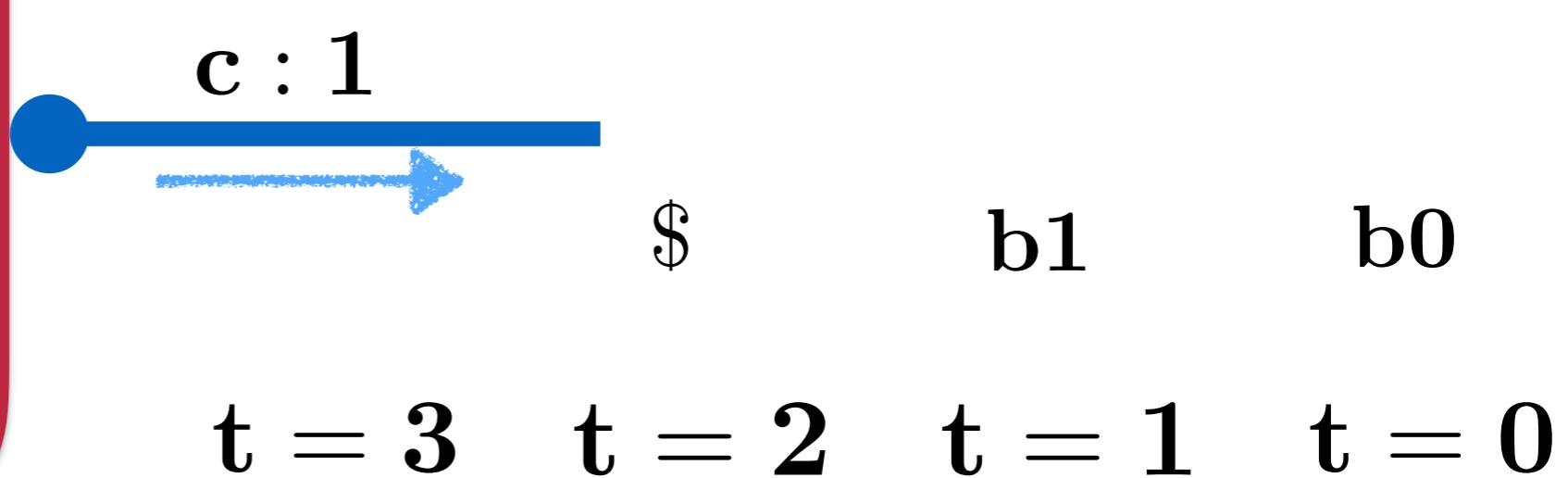
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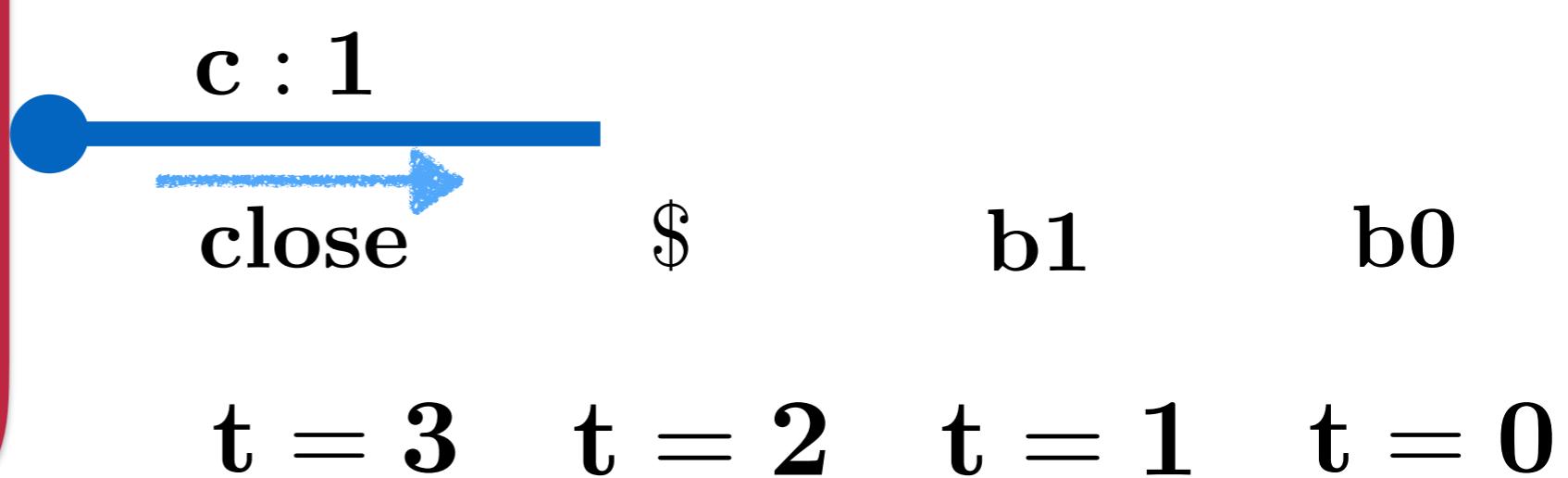
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Typing Rule (\circ)

applied
pointwise

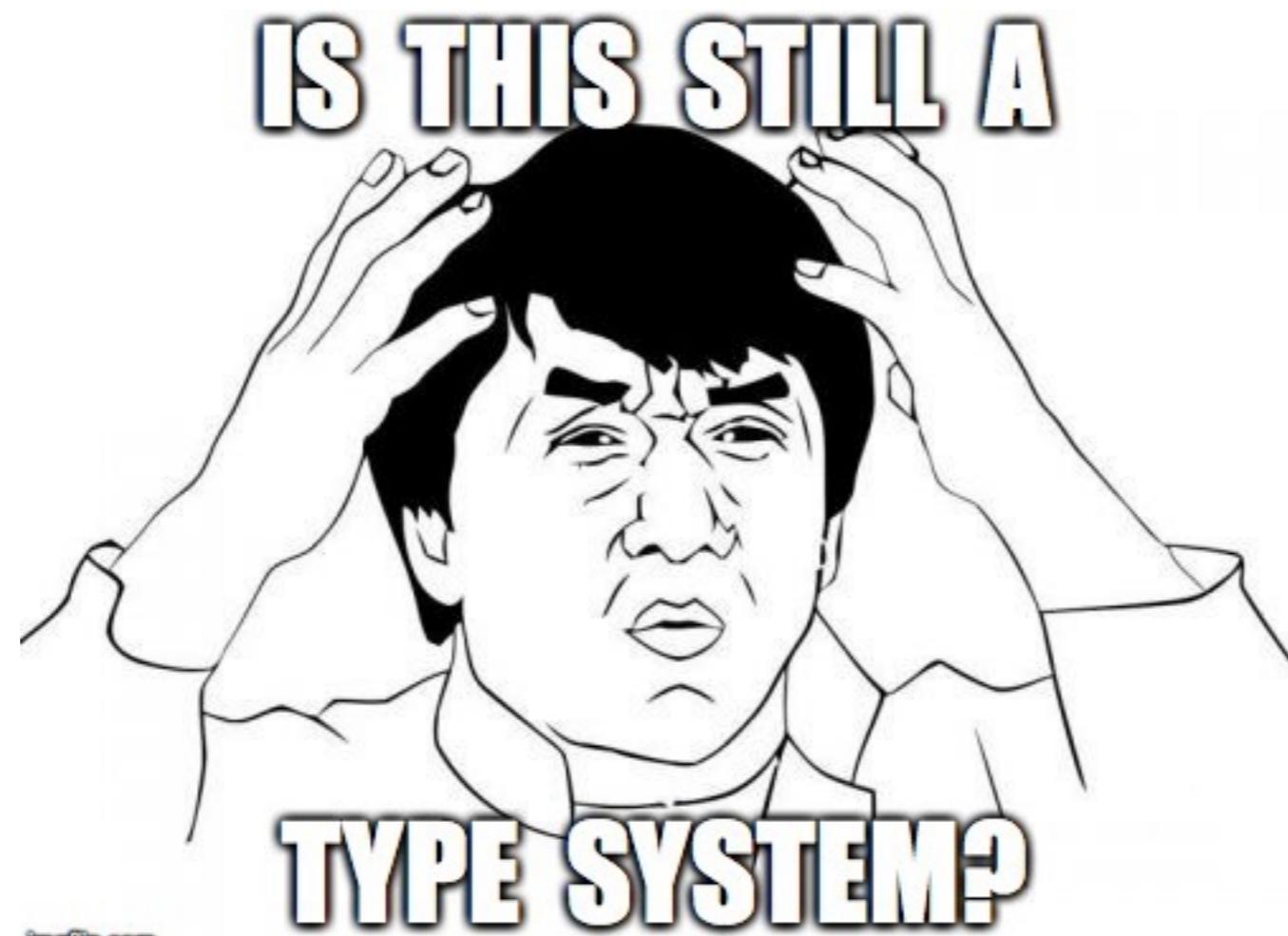
$$\frac{\Omega \vdash P :: (x : S)}{\circ\Omega \vdash \text{delay}; P :: (x : \circ S)}$$

Typing Rule (\circ)

applied
pointwise

$$\frac{\Omega \vdash P :: (x : S)}{\circ\Omega \vdash \text{delay}; P :: (x : \circ S)}$$

breaks the locality property of type system!



Bit Streams

\mathcal{R} cost model

$\text{bits} = \oplus\{\text{b0} : \circ^r \text{bits}, \text{b1} : \circ^r \text{bits}, \$: \circ^r 1\}$

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Bit Streams

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Bit Streams

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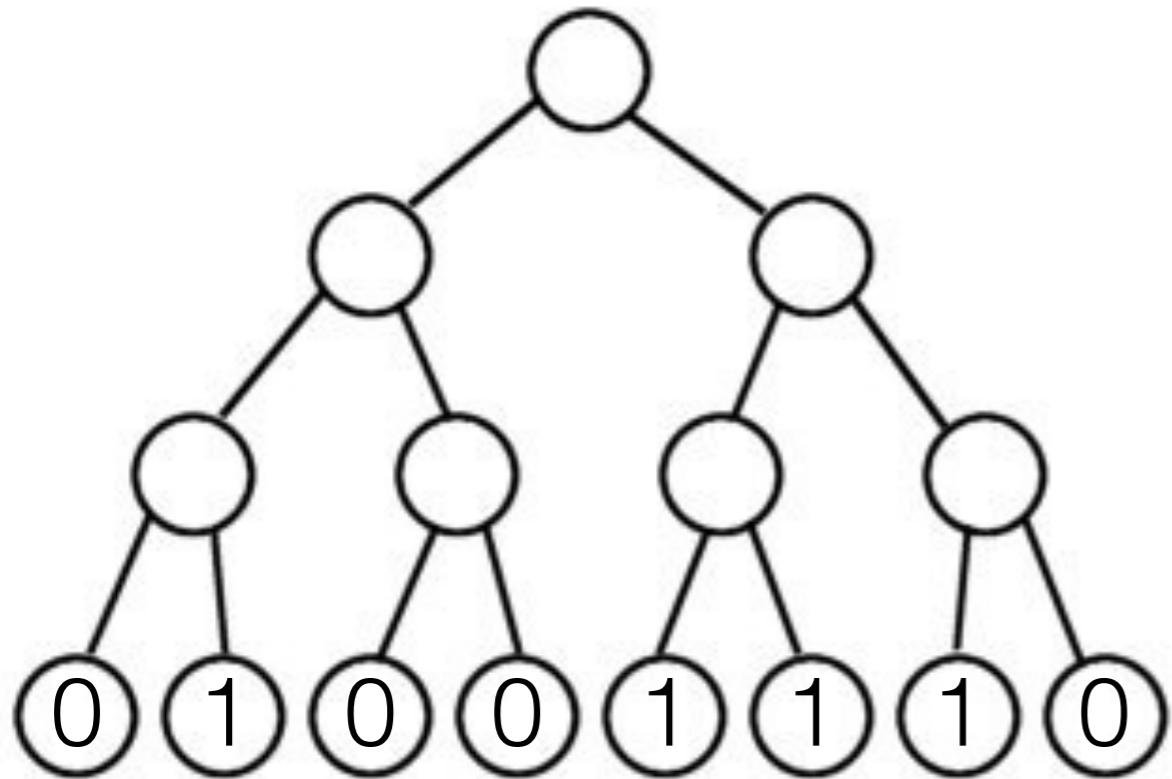


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$$x : \text{bits} \vdash \text{plus2} :: (z : \circ \circ \text{bits})$$

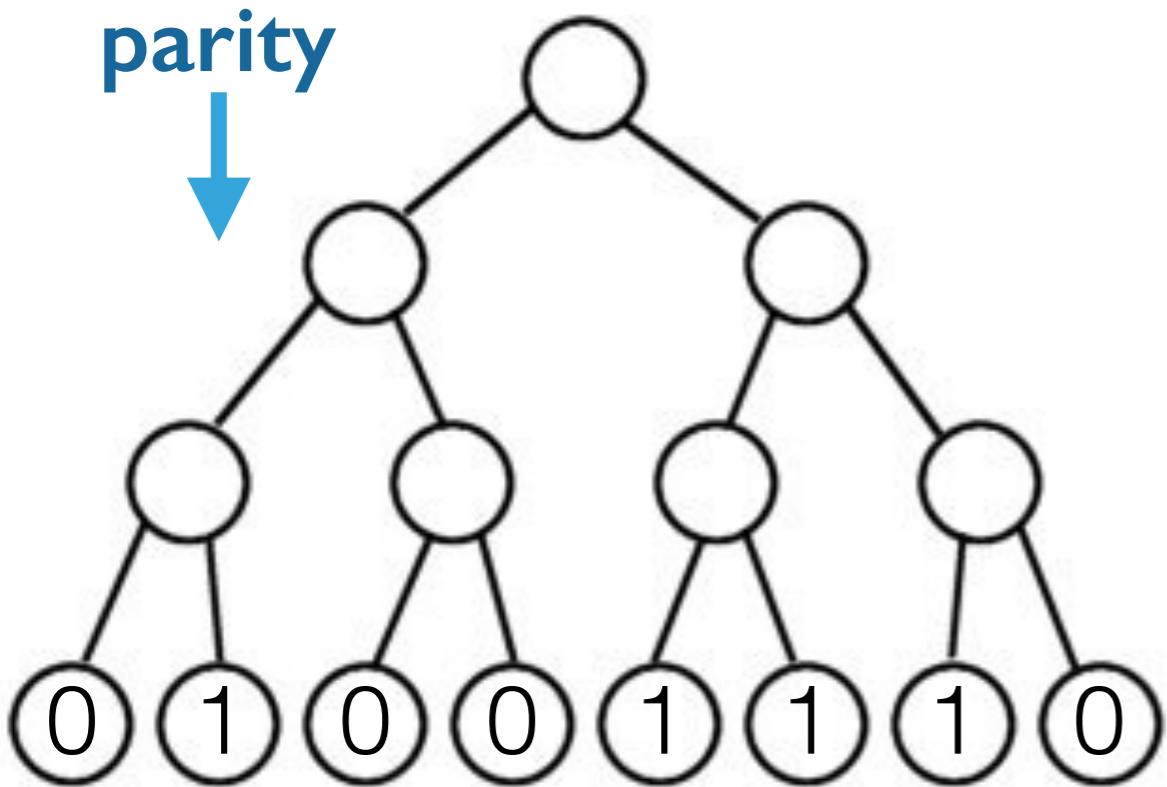
Fork-Join Parallelism



0s and 1s at the leaves

Compute the parity

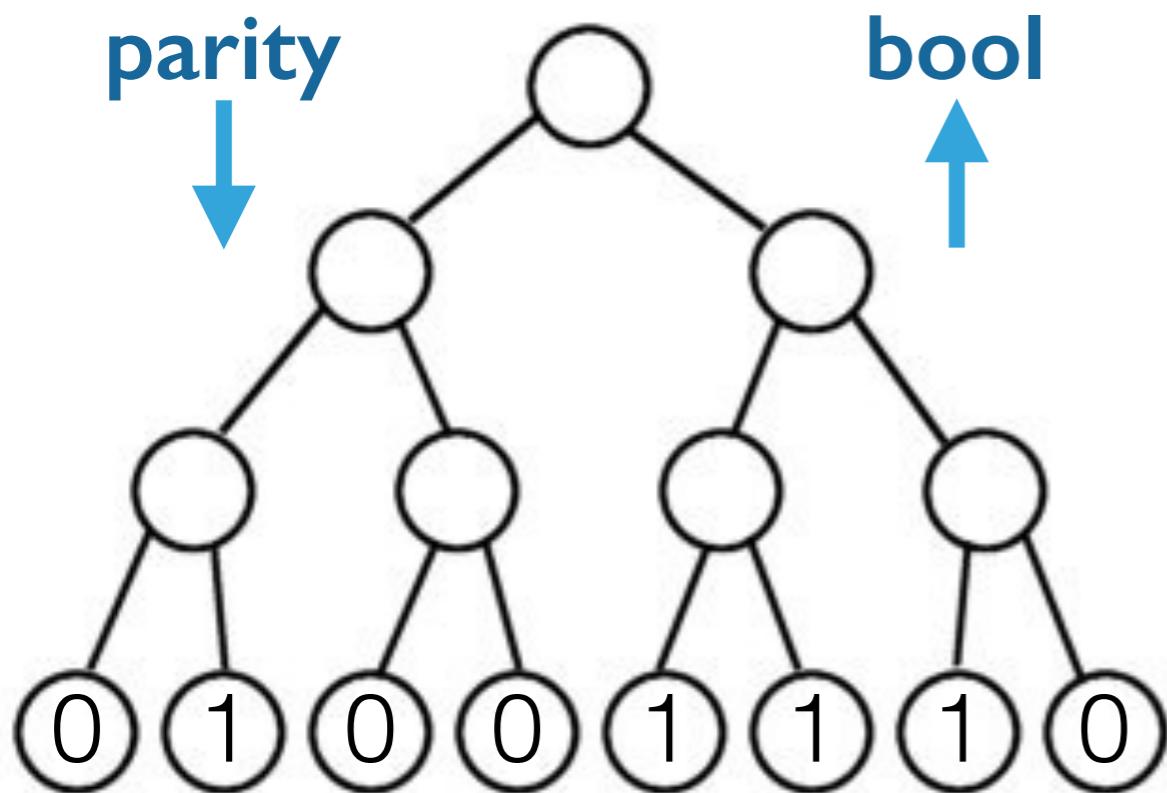
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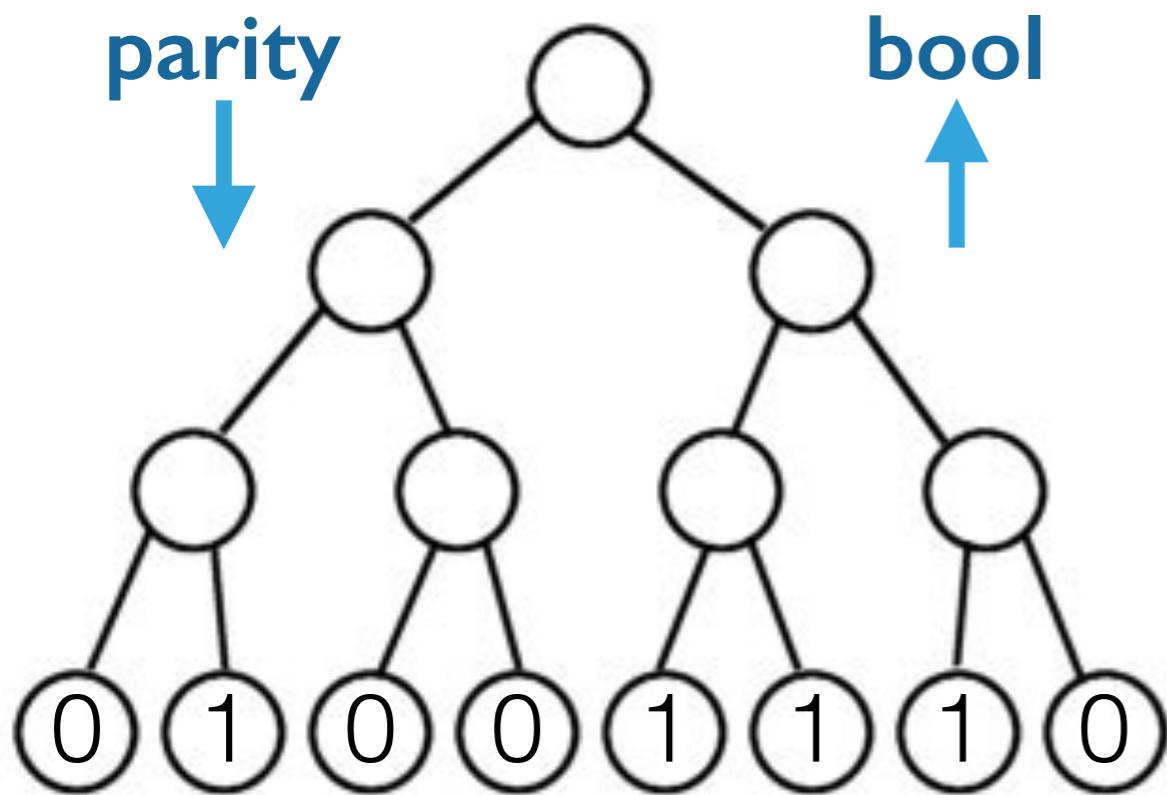
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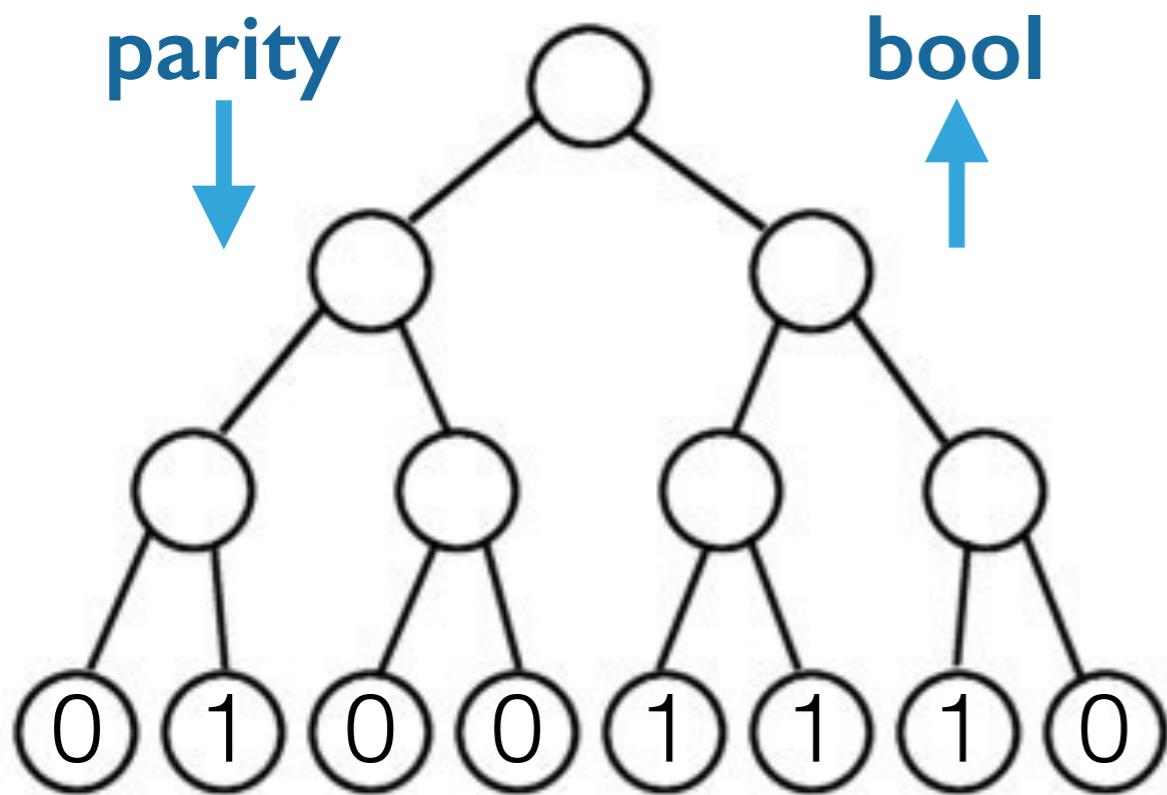
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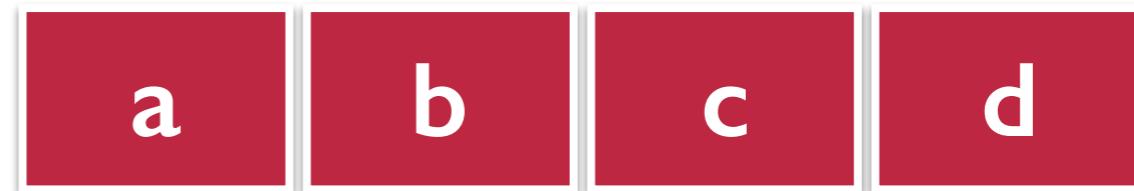
RS cost model

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Counting xors

$\text{tree}[h] = \&\{\text{parity} : \bigcirc^h\text{bool}\}$

Can we type the queue?



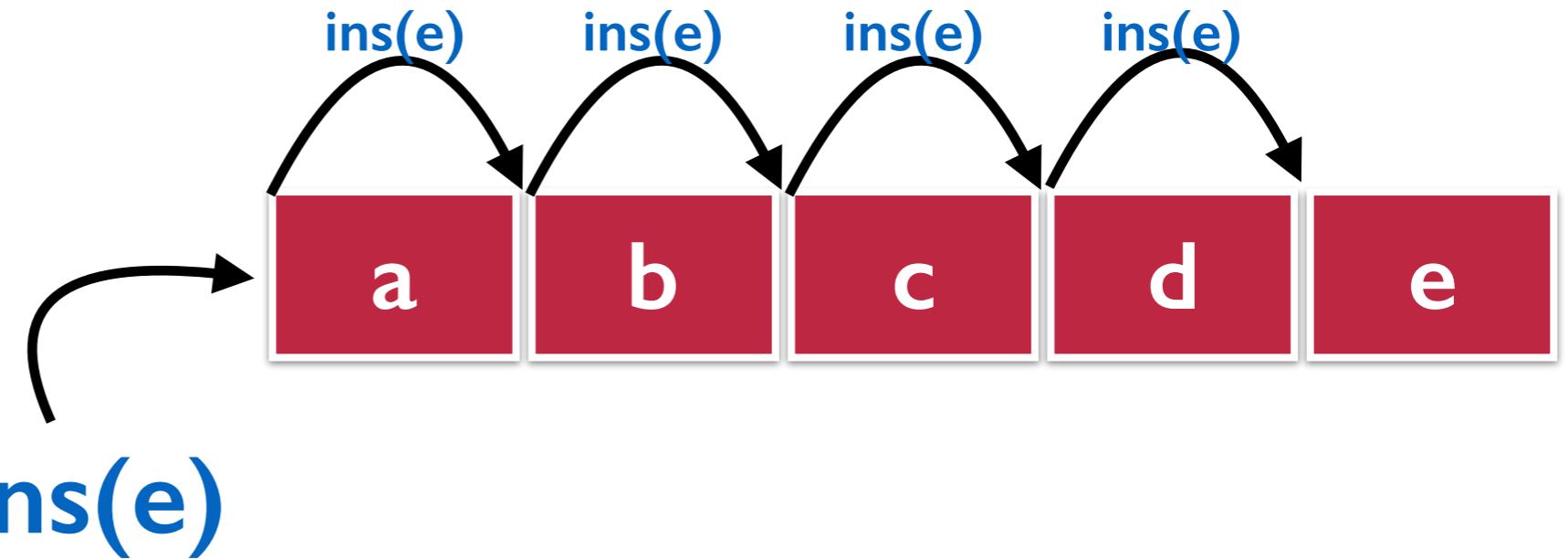
Can we type the queue?

15



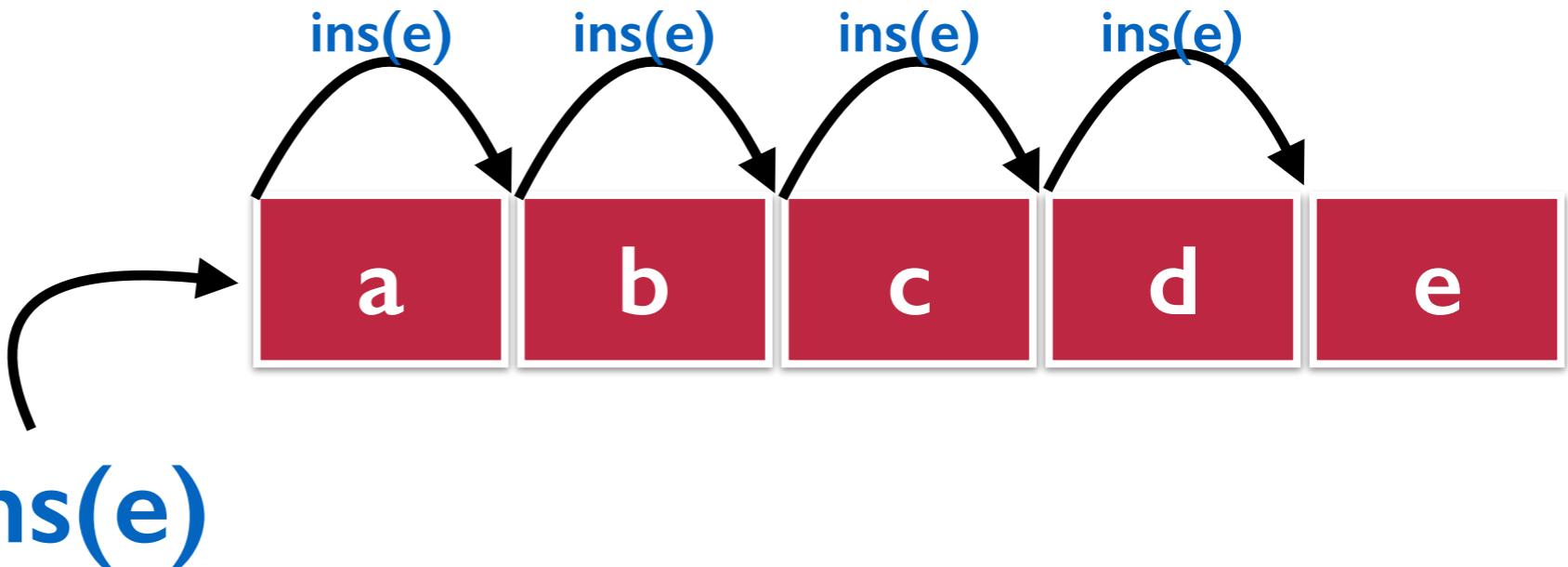
Can we type the queue?

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Can we type the queue?

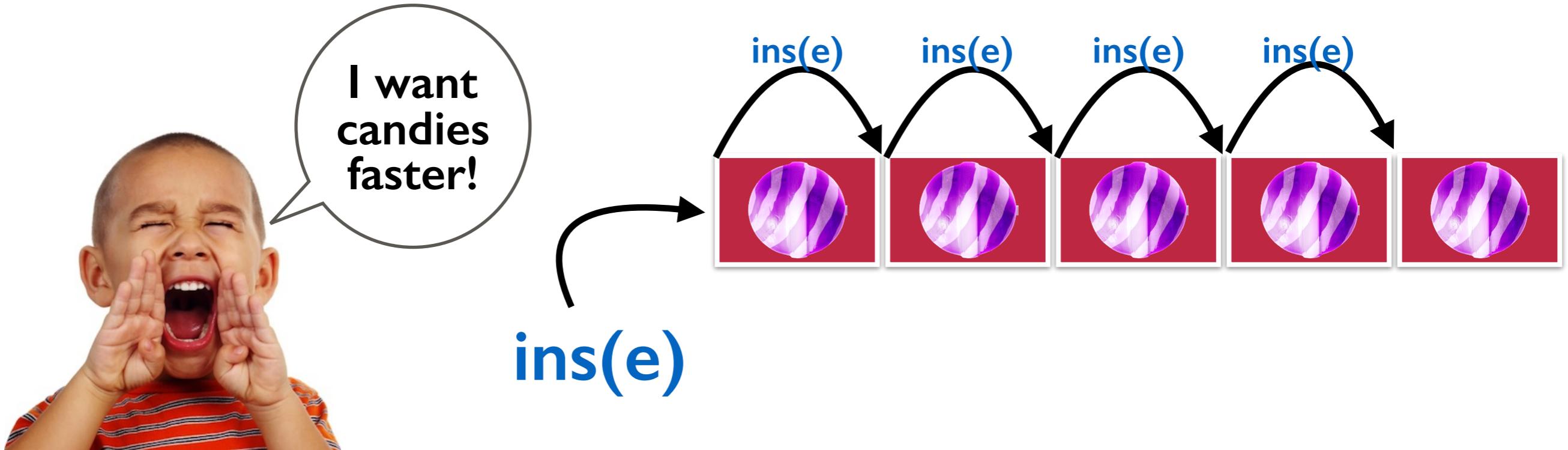
15



- ▶ Next operator only expresses constant insertion rate
- ▶ But rate of insertion at the tail depends on the size of the queue — longer the queue, slower the rate
- ▶ To maintain a constant rate at the tail, new elements must be inserted at a faster rate than the previous one

Can we type the queue?

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The Next Operator
is too precise!

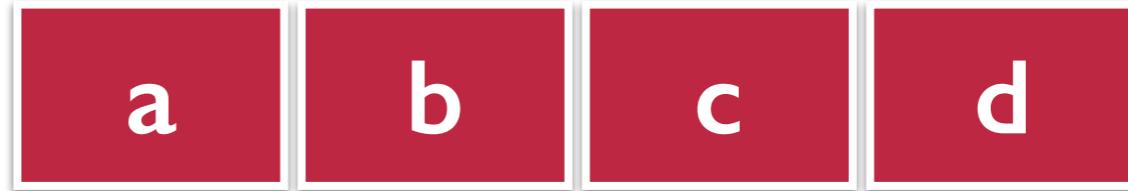
**Adding Flexibility
to the Type System**

Providing Flexibility

- ▶ **The Box Operator (\square)**
 - ▶ Provider Action: always be ready to receive token
 - ▶ Client Action: eventually send the token
 - ▶ Provider doesn't know when the token will come, only the client does
 - ▶ Different from \bigcirc operator where both provider and client knew the timing of message exchange
- ▶ **The Diamond Operator (\diamond)**
 - ▶ Dual of the Box operator (provider and client flip)

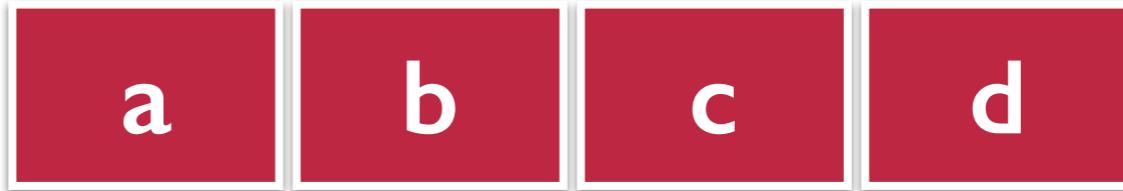
Typing the Queue

18


$$\begin{aligned} \text{queue}_A = & \&\{\text{ins} : A \multimap \text{queue}_A, \\ & \text{del} : \bigoplus\{\text{none} : 1, \\ & \qquad \qquad \qquad \text{some} : A \otimes \text{queue}_A\}\} \end{aligned}$$

Typing the Queue

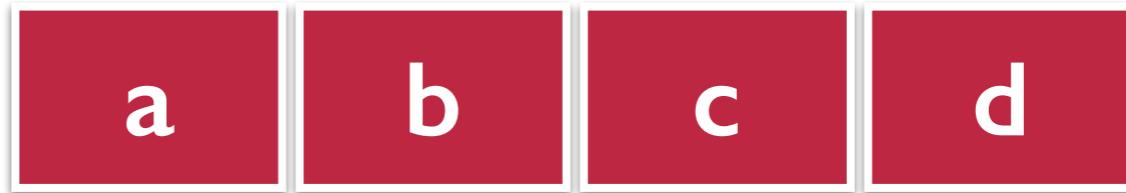
18



**offers choice
of ins/del**

$\text{queue}_A = \&\{\text{ins} : A \multimap \text{queue}_A,$
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Typing the Queue



**offers choice
of ins/del**

**recv element
of type A**

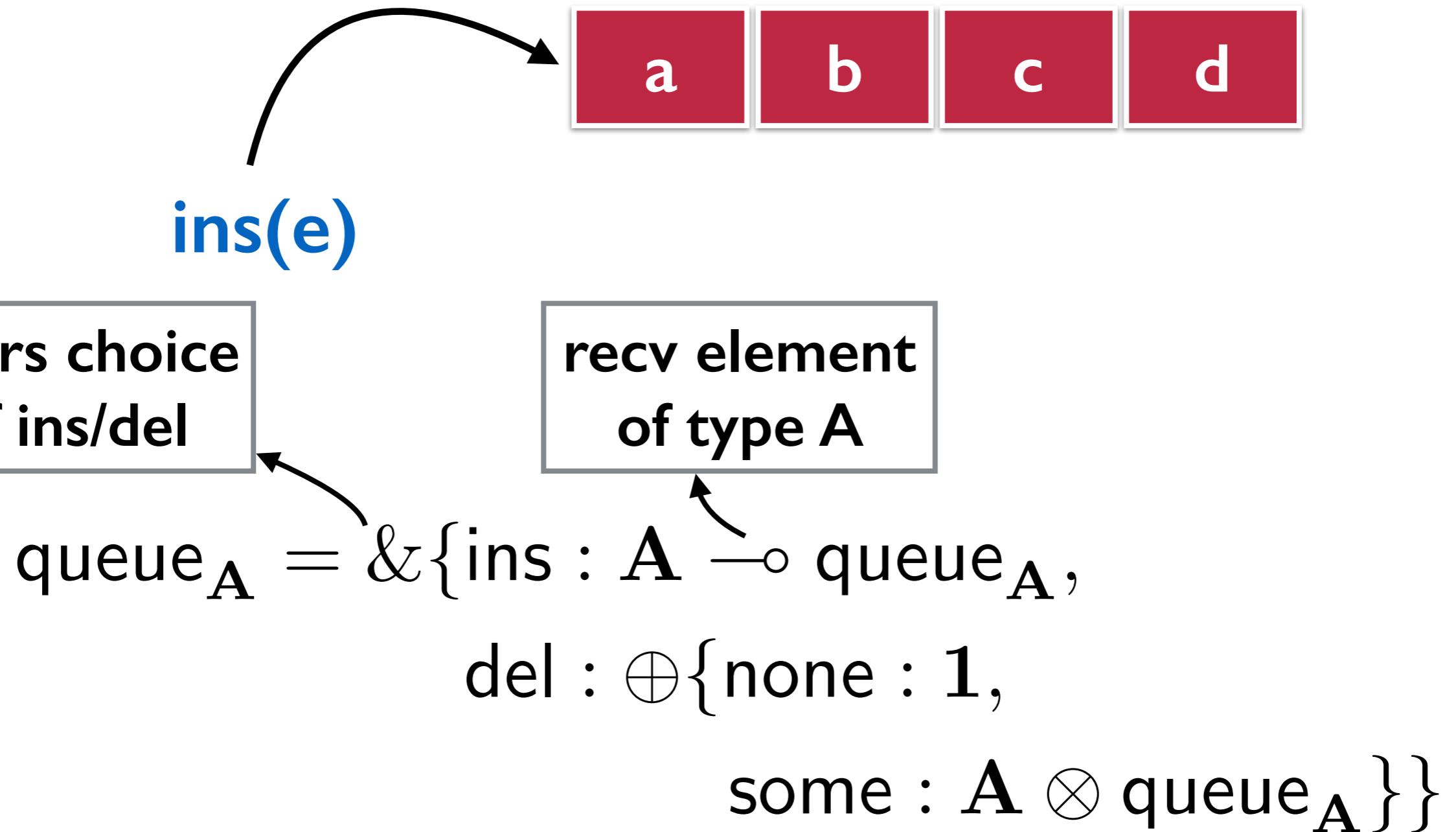
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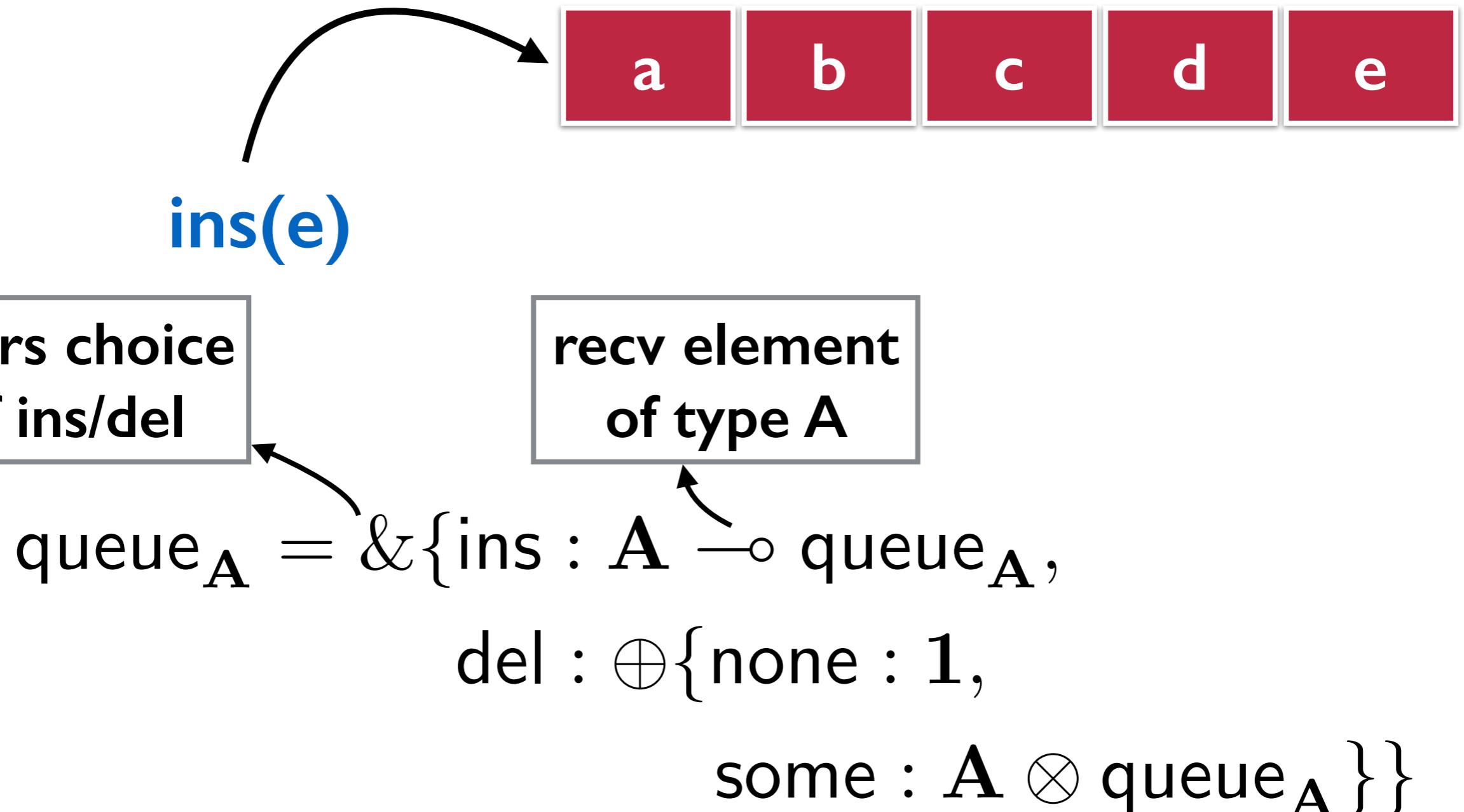
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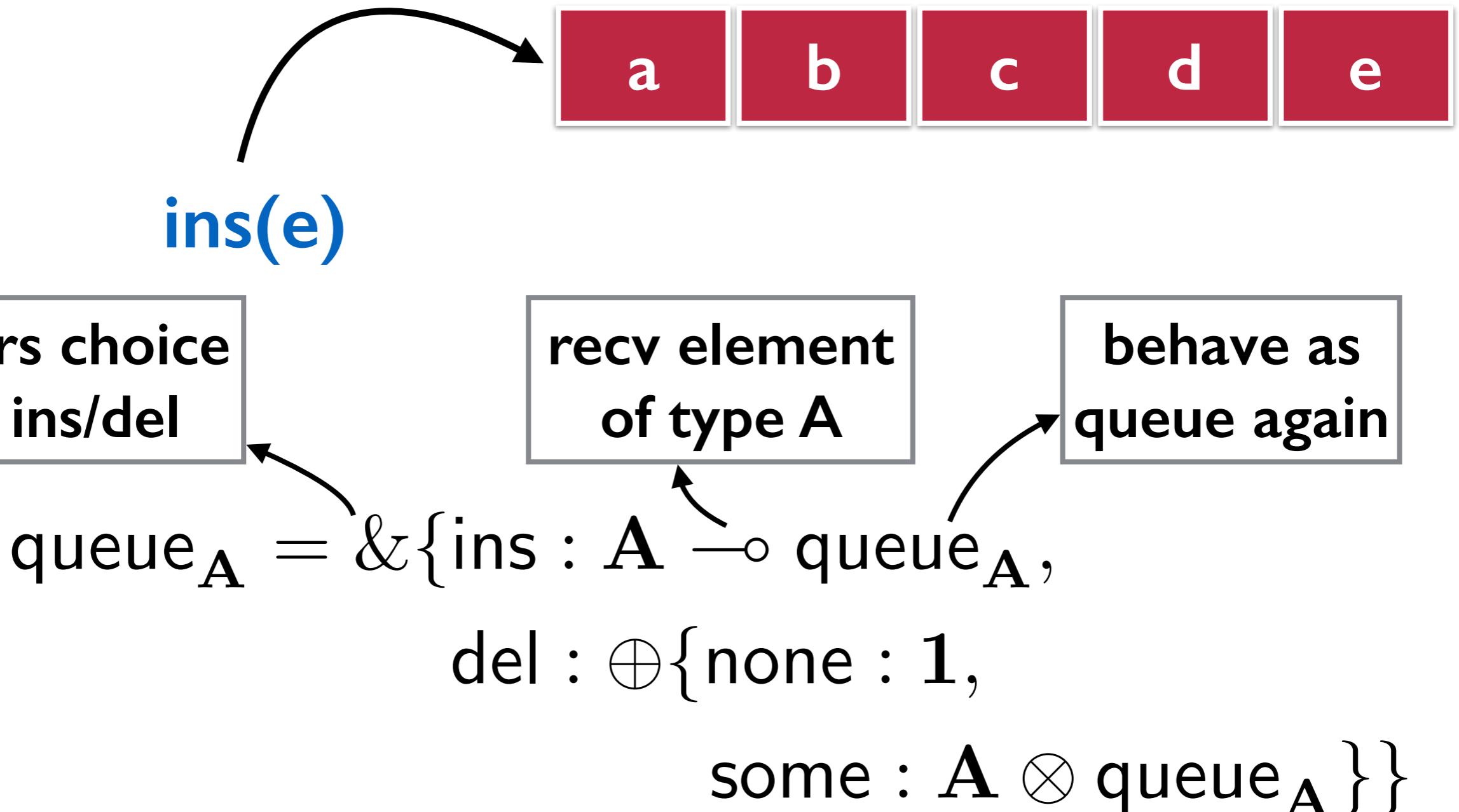
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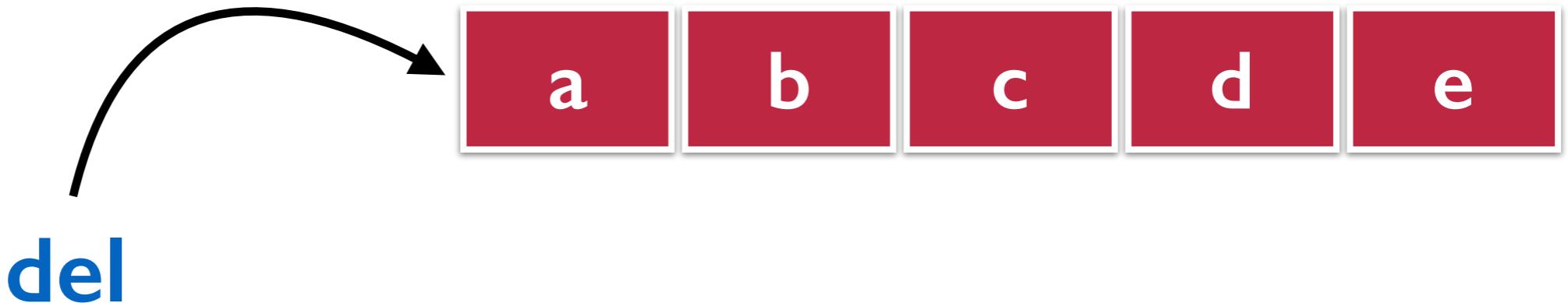
Typing the Queue

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Typing the Queue

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offers choice
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Typing the Queue



del

**offers choice
of ins/del**

$$\text{queue}_A = \&\{\text{ins} : A \multimap \text{queue}_A,$$

$$\text{del} : \oplus\{\text{none} : 1,$$

**send none if
queue is empty**

$$\text{some} : A \otimes \text{queue}_A \})\}$$

Typing the Queue



del

offers choice
of ins/del

$\text{queue}_A = \&\{\text{ins} : A \multimap \text{queue}_A,$

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terminate

send none if
queue is empty

$\text{some} : A \otimes \text{queue}_A\})\}$

Typing the Queue

18

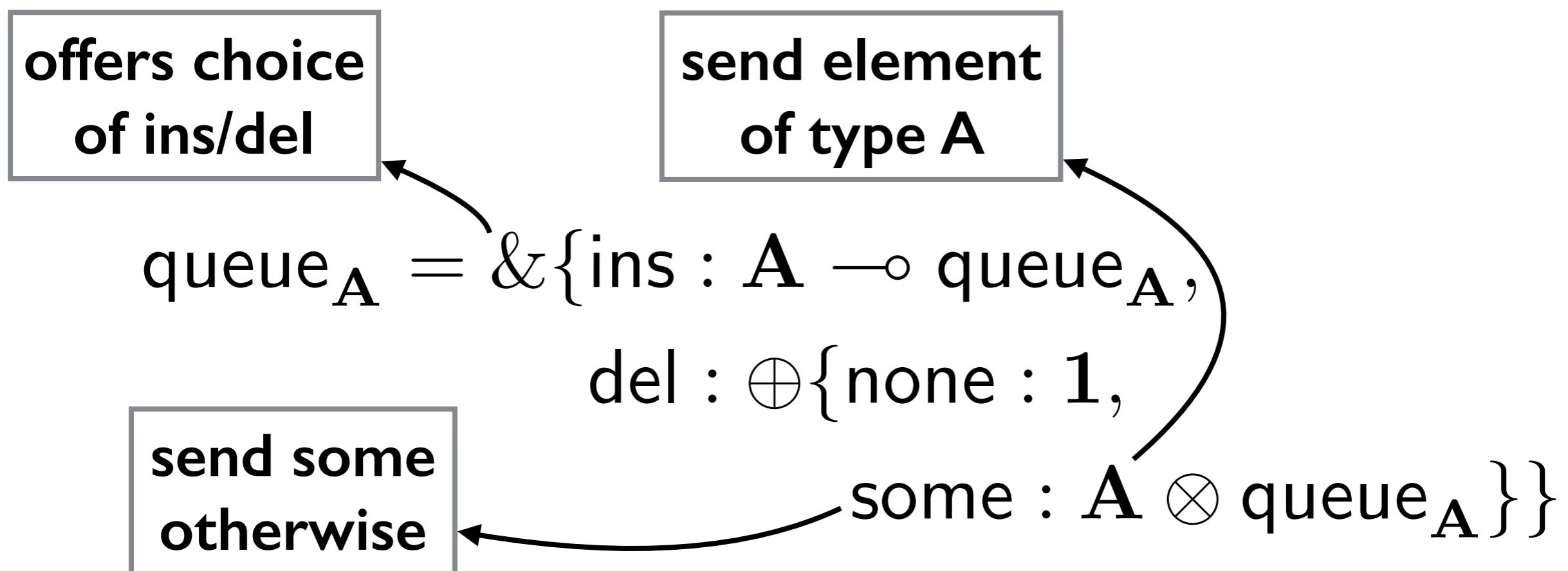
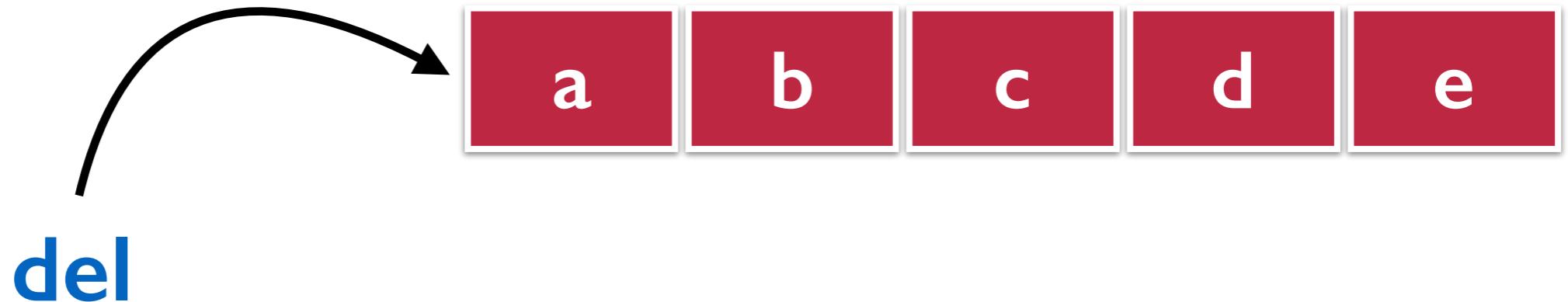


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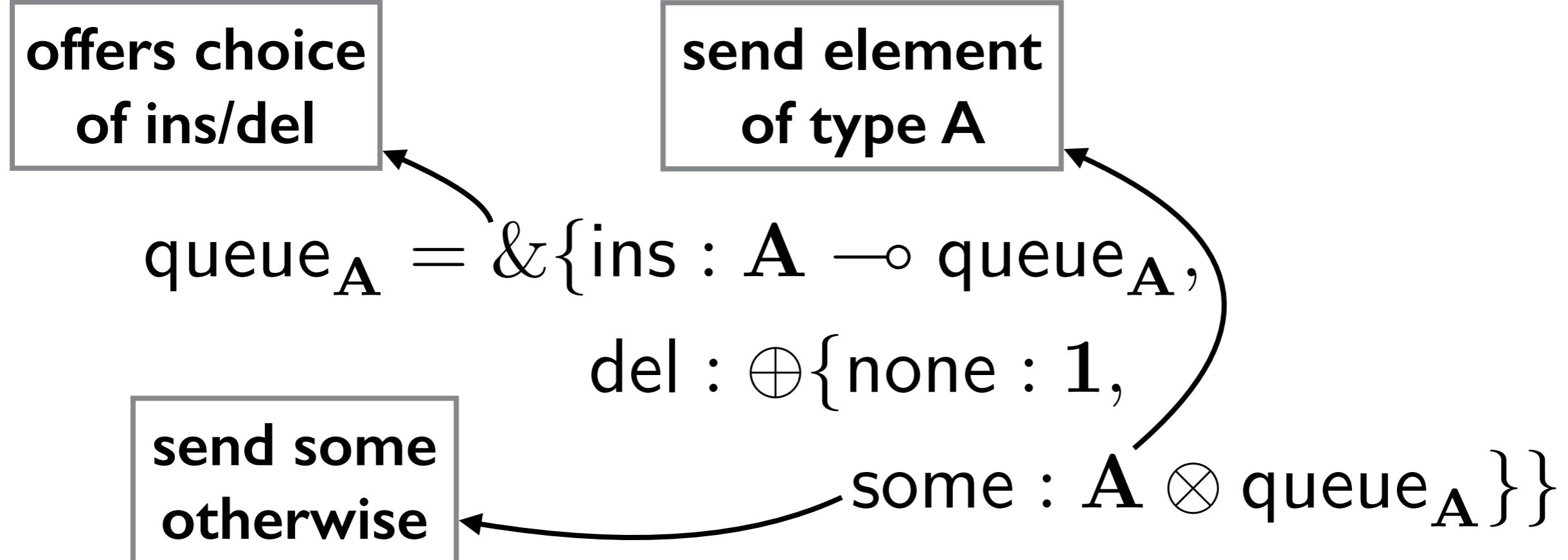
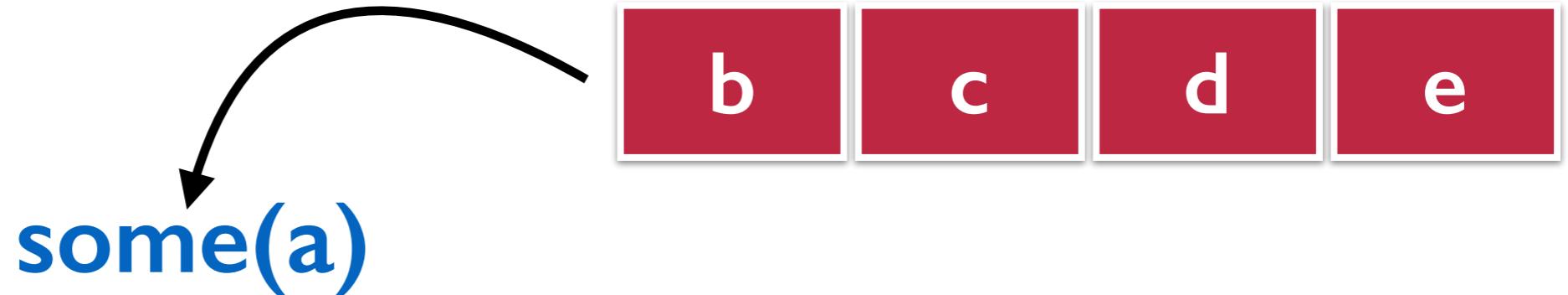
send some
otherwise

Typing the Queue



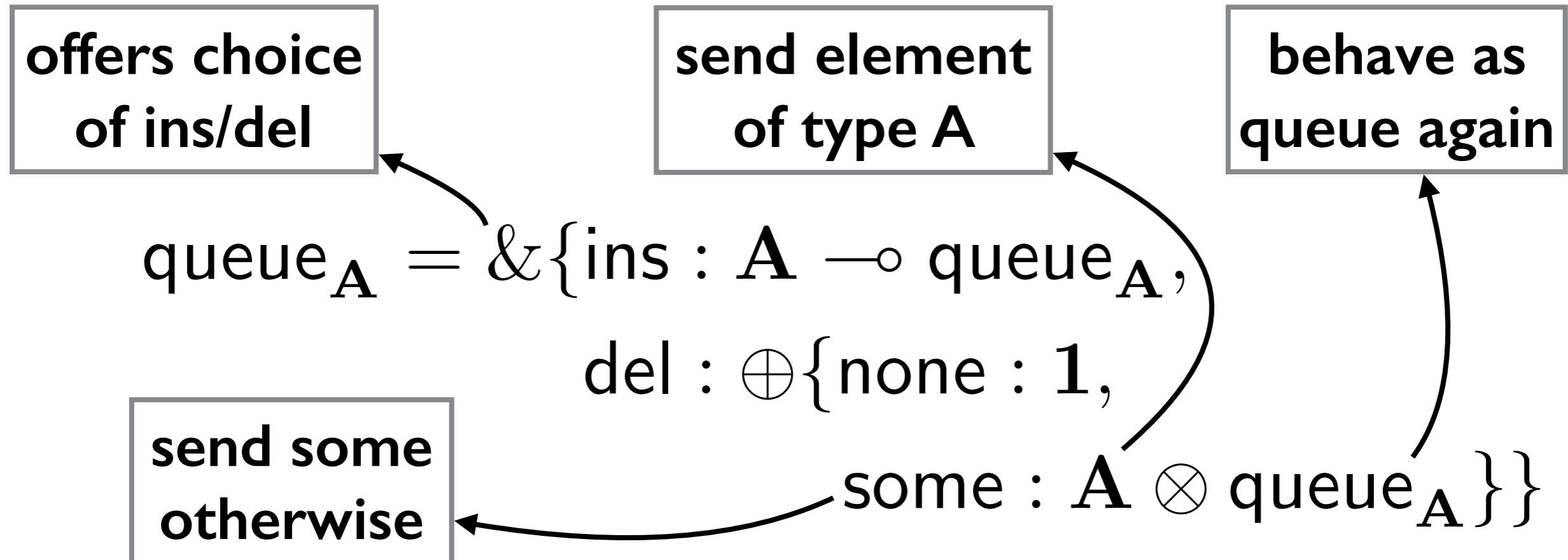
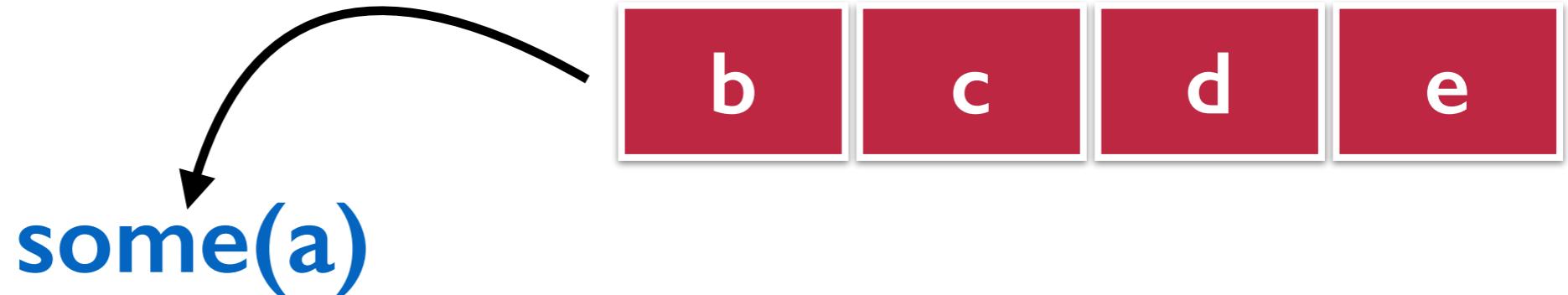
Typing the Queue

18



Typing the Queue

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Response Time of Queues

19

$$\begin{aligned} \text{queue}_A = & \square \& \{ \text{ins} : \bigcirc(\square A \multimap \bigcirc^3 \text{queue}_A) \}, \\ \text{del} : \bigcirc \oplus \{ & \text{none} : \bigcirc 1, \\ & \text{some} : \bigcirc(\square A \otimes \bigcirc \text{queue}_A) \} \} \end{aligned}$$

Response Time of Queues

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Can always accept ins/del messages

Response Time of Queues

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Response time for insertion: 3

Response Time of Queues

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Can always accept ins/del messages

Response time for insertion: 3

Response time for deletion: 1

Response Time of Queues

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Can always accept ins/del messages

Response time for insertion: 3

Response time for deletion: 1

Precision

WE ARE
HERE!

Flexibility

Typing Rules(\Box)

Typing Rules(\square)

Exchanged token is a now! message

$$\frac{\Omega \text{ delayed } \square \quad \Omega \vdash P :: (x : S)}{\Omega \vdash \text{when? } x ; P :: (x : \square S)} \square R$$

delayed \square = $\circ^* \square T \rightarrow$ can be delayed indefinitely

Typing Rules(\square)

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$\text{delayed } \square = \circ^* \square T \rightarrow$ can be delayed indefinitely

$$\frac{\Omega, x : S \vdash Q :: (z : T)}{\Omega, x : \square S \vdash \text{now! } x ; Q :: (z : T)} \square L$$

Stacks vs Queues

RS cost model

$\text{stack}_A = \square \& \{\text{ins} : \bigcirc(\square A \multimap \bigcirc \text{stack}_A)\},$

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Stacks vs Queues

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Which one's more efficient?

Stacks vs Queues

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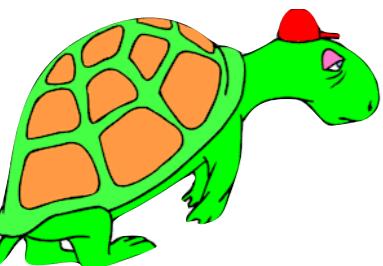
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Which one's more efficient?

Features of Type System

22

- ▶ **Parametric:** time can be defined using a cost model
- ▶ **Compositional:** types describe individual processes, not just whole programs
- ▶ **Precise & Flexible:** \circlearrowleft operator provides precision.
 \square , \diamond operators provide flexibility
- ▶ **Conservative:** only added 3 type operators
- ▶ **General:** works on all standard examples
- ▶ **Automatic:** supports automatic type checking, type inference future work

Cost Semantics

$\text{proc}(c, t, P)$

**Process P offering along
channel c at local time t**

Cost Semantics

$\text{proc}(c, t, P)$

**Process P offering along
channel c at local time t**

Soundness Theorem:
message timings realized by the local clocks
matches the timing predicted by the type system

What else is in the paper?

24

- ▶ Interaction of \square , \diamond with \circlearrowright operators
- ▶ Sound and complete *subtyping* relation
- ▶ *Time Reconstruction* — inserting *delay*, *now!*, *when?* automatically from the program type
- ▶ *Cost Semantics* — each process stores a *local clock*, expresses timing at runtime, connected to the type system by a proof of *progress* and *preservation*
- ▶ Connection to the standard cost semantics
- ▶ Typing a set of processes at *different local clocks*

Conclusion

Conclusion

Type System
analyzes timing of
message exchanges

Soundness
Theorem

Cost Semantics
local clocks at
each process

Properties

conservative extension, added 3 type operators

○ provides precision, □, ♦ provide flexibility

Examples

throughput and latency of bit stream processors

response time of stacks vs queues

list examples: append, map, fold (many more in paper!)