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#include<SoftwareSerial.h>           //program for tilt,temperature,gsm,buzzer
SoftwareSerial mySerial(9,10);      //pins for GSM module

float temp ;

const int xPin = A5;
const int yPin = A4;
const int zPin = A3;
int a;
int b;

void setup()
{
  mySerial.begin(9600);
  Serial.begin(9600);

  pinMode(A5,INPUT); //A3,A4,A5 for accelerometer as tilt sensor
  pinMode(A4,INPUT);
  pinMode(A3,INPUT);

  pinMode(7,OUTPUT); //Buzzer pin
  pinMode(8,OUTPUT); //waterpump relay pin
  pinMode(9,INPUT); //sound sensor pin
  a=0;

}

void loop()
{
  a=0;
  int c = digitalRead(9);

  int X = analogRead(xPin);
  int Y = analogRead(yPin);
  int Z = analogRead(zPin);
  Serial.print(int(X));
  Serial.print(" ");
  Serial.print(int(Y));
  Serial.print(" ");
  Serial.print(int(Z));
  Serial.println();
  delay(1000);

  temp = analogRead(A0);
  temp = temp * 0.48828125;
  Serial.print("TEMPERATURE: ");
  Serial.print(temp);
  Serial.print("*C");
  Serial.println();
  delay(1000);

  if(c==0)
  {
    Serial.print("No poaching sound is detected");
  }
}

```



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}

else
{
    a=1; //buzer is get ON
    Serial.print("sound sensor is detected");
    Serial.print(" Buzzer ON ");
    mySerial.println("AT+CMGF=1"); //message start sending
    delay(1000);
    mySerial.println("AT+CMGS=\"+919307089049\\r\"");
    delay(1000);
    mySerial.println("poaching activity is detected,tree cutting is
going on");

    delay(100);
    mySerial.println((char)26);
    delay(1000);
}

if((((315<X)&&(X<360))&&((310<Y)&&(Y<340))&&((270<Z)&&(Z<290)))
{
    Serial.print("Straight possition");
}

else
{
    a=1; //buzer is get ON
    Serial.print("tree is tilt");
    Serial.print(" Buzzer ON ");
    mySerial.println("AT+CMGF=1"); //message start sending
    delay(1000);
    mySerial.println("AT+CMGS=\"+919307089049\\r\"");
    delay(1000);
    mySerial.println("poaching activity is detected tree is tilted
above its critical angle");

    delay(100);
    mySerial.println((char)26);
    delay(1000);
}

if(temp >= 60)
{
    a=1 ; //buzer is get ON
    Serial.print(" ""temprature warning");
    Serial.print(" Buzzer ON ");
    digitalWrite(8,HIGH); //water pump is ON
    Serial.print(" ""water pump is on");
    mySerial.println("AT+CMGF=1"); //message start sending
    delay(1000);
    mySerial.println("AT+CMGS=\"+919307089049\\r\"");
    delay(1000);
    mySerial.println("poaching activity is detected farm
temprature is too high");

    delay(100);
    mySerial.println((char)26);
    delay(1000);
}

else
{

```



```
        Serial.print("temprature normal");  
    }  
    if(a==1)  
    {  
        digitalWrite(7,HIGH);  
    }  
        else  
        {  
            digitalWrite(7,LOW);  
        }  
    }
```

