CS7643: Deep Learning Fall 2019 HW3 Solutions

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1 Recurrent Neural Network

1.1 Vanilla RNN for parity function

Following the homework instructions, we are looking W and b such as:

$$[y_t] = act \left(W \cdot \begin{bmatrix} y_{t-1} \\ x_t \end{bmatrix} + b \right)$$

Following the instruction in the instructions, we can build the following truth table:

Table 1: Truth table of y_t

This table is basically the truth table of an XOR function. We saw during the last homework that such a function can't be represented by a single neurone and a linear activation.

Hopefully we are here free to use the activation function we want. If a linear activation is unable to represent XOR, an absolute activation function is a good fit.

Using the information from above we can quickly our neurone as:

$$[y_t] = abs \left(\begin{bmatrix} 1 & -1 \end{bmatrix} \cdot \begin{bmatrix} y_{t-1} \\ x_t \end{bmatrix} + 0 \right)$$

We can now apply this set of weight to the four possible incomes, as displayed on Table 2

If we then apply the activation function we chose to the value of Table 2, we easily fall back on the truth table of XOR, as showed on Table 3.

The above results assume that h is initialized with a value of zero.

$$\begin{array}{c|cccc}
 & y_{t-1} \\
 & 0 & 1 \\
\hline
 & 0 & 0 & 1 \\
x_t & 1 & -1 & 0
\end{array}$$

Table 2: Value table of our neurone for all possible inputs

$$\begin{array}{c|ccccc}
 & y_{t-1} \\
 & 0 & 1 \\
\hline
 & 0 & 0 & 1 \\
 & 1 & 1 & 0
\end{array}$$

Table 3: Value table output of our neurone for all possible inputs with the preset weights and bias as well as the selected activation function

1.2 LSTM for parity function

As said in Question 1.1, we want to build a network such as:

$$h_t = XOR\left(h_{t-1}, x_t\right)$$

In this question we have a lot of variable and a lot of different combination are so possible to get the correct results. We are here going to make it as simple as possible, to help the correction and the redaction of this report.

First we are going to set that $C_t = h_t$, this is easy to make by using the following weights:

$$W_o = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
$$b_o = 1$$

Which give us $o_t = 1$, which translate in:

$$h_t = o_t \cdot tanh(C_t)$$

= $tanh(C_t)$
= C_t for $C_t \in 0, 1$

On the same idea we define $C_t^{\sim} = 1 - h_t$ with:

$$W_C = \begin{bmatrix} -1\\0 \end{bmatrix}$$
$$b_C = 1$$

Now we want f_t to be 1 if x_t is zero and 0 otherwise:

$$W_t = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$
$$b_t = 1$$

Now we want i_t to be 1 if x_t is one and 0 otherwise:

$$W_t = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$
$$b_t = 0$$

As previously, we assume here that C_t and h_t are initialised to zero.

1.3 When to stop in beam search?

We know from the definition, that adding a new element in B_i have two different effect. First, as the final score is the product of probability, the score of the b+1 length sentences can only be smaller or equal than for the one of the highest scoring sentence of length b. Second, $best_{\leq i}$ can only be smaller or equal to $best_{\leq i+1}$ for obvious reason. It will stay the same if there is no sentence of length i+1 with higher score.

Which lead us the conclusion that $best_{\leq i}$ is defined and is the highest scoring item in B_i . Then all new sentence in B_{i+1} would have a lower score than the highest scoring item in B_i , which here is $best_{\leq i}$, because of the first point cited previously. Which mean that any sentence longer than i would have lower or equal score than $best_{\leq i}$.

1.4 Exploding Gradients

For this question we will suppose that W is a diagonalizable matrix, which is implied by the fact that it's eigenvalues are given in the subject.

With that in mind, we know that it exist a matrix Q such as:

$$W^T = QDQ^{-1}$$

With D being a diagonal matrix with the eigenvalues of W on the diagonal (and Q the eigenvectors).

Using this we can easily rewrite the given equation as:

$$h_t = W^T h_{t-1}$$
$$= QDQ^{-1} h_{t-1}$$
$$h_t = QD^t Q^{-1} h_0$$

It is trivial that raising a diagonal matrix to a power t is equivalent to raise each of it's diagonal element to the power t. So depending on the value of the eigenvalues, raising the matrix D to a high power will make the diagonal element tend to zero (vanish) if they are smaller than one (in absolute value). If they are bigger than one (in absolute value) they will diverge to infinity. Or change signs / stay the same of they are 1 or -1.

This matrix is then used to compute the output, h_t , but also in the backward pass to propagate the gradient. Especially for the first inputs. So the gradient could be multiplied by values that are either too big (exploding) or too small (vanishing).

- 2 Coding: Sequence models for image captioning
- 2.1 RNN Captioning

RNN_Captioning

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1 Image Captioning with RNNs

In this exercise you will implement a vanilla recurrent neural networks and use them it to train a model that can generate novel captions for images.

```
In [1]: # As usual, a bit of setup
       from __future__ import print_function
        import time, os, json
        import numpy as np
        import matplotlib.pyplot as plt
        from cs231n.gradient_check import eval_numerical_gradient, eval_numerical_gradient_arr
        from cs231n.rnn_layers import *
        from cs231n.captioning_solver import CaptioningSolver
        from cs231n.classifiers.rnn import CaptioningRNN
        from cs231n.coco_utils import load_coco_data, sample_coco_minibatch, decode_captions
        from cs231n.image_utils import image_from_url
       %matplotlib inline
       plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
       plt.rcParams['image.interpolation'] = 'nearest'
       plt.rcParams['image.cmap'] = 'gray'
        # for auto-reloading external modules
        # see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
        %load_ext autoreload
        %autoreload 2
        def rel_error(x, y):
            """ returns relative error """
            return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + np.abs(y))))
```

1.1 Install h5py

The COCO dataset we will be using is stored in HDF5 format. To load HDF5 files, we will need to install the h5py Python package. From the command line, run: pip install h5py If you receive a permissions error, you may need to run the command as root: sudo pip install h5py

You can also run commands directly from the Jupyter notebook by prefixing the command with the "!" character:

```
In [2]: !pip install h5py
```

```
Requirement already satisfied: h5py in /home/nicolas/.local/lib/python3.6/site-packages (2.8.0 Requirement already satisfied: six in /home/nicolas/.local/lib/python3.6/site-packages (from harmonic already satisfied: numpy>=1.7 in /home/nicolas/.local/lib/python3.6/site-packages
```

2 Microsoft COCO

For this exercise we will use the 2014 release of the Microsoft COCO dataset which has become the standard testbed for image captioning. The dataset consists of 80,000 training images and 40,000 validation images, each annotated with 5 captions written by workers on Amazon Mechanical Turk

You should have already downloaded the data by changing to the cs231n/datasets directory and running the script get_assignment3_data.sh. If you haven't yet done so, run that script now. Warning: the COCO data download is ~1GB.

We have preprocessed the data and extracted features for you already. For all images we have extracted features from the fc7 layer of the VGG-16 network pretrained on ImageNet; these features are stored in the files train2014_vgg16_fc7.h5 and val2014_vgg16_fc7.h5 respectively. To cut down on processing time and memory requirements, we have reduced the dimensionality of the features from 4096 to 512; these features can be found in the files train2014_vgg16_fc7_pca.h5 and val2014_vgg16_fc7_pca.h5.

The raw images take up a lot of space (nearly 20GB) so we have not included them in the download. However all images are taken from Flickr, and URLs of the training and validation images are stored in the files train2014_urls.txt and val2014_urls.txt respectively. This allows you to download images on the fly for visualization. Since images are downloaded on-the-fly, you must be connected to the internet to view images.

Dealing with strings is inefficient, so we will work with an encoded version of the captions. Each word is assigned an integer ID, allowing us to represent a caption by a sequence of integers. The mapping between integer IDs and words is in the file coco2014_vocab.json, and you can use the function decode_captions from the file cs231n/coco_utils.py to convert numpy arrays of integer IDs back into strings.

There are a couple special tokens that we add to the vocabulary. We prepend a special <START> token and append an <END> token to the beginning and end of each caption respectively. Rare words are replaced with a special <UNK> token (for "unknown"). In addition, since we want to train with minibatches containing captions of different lengths, we pad short captions with a special <NULL> token after the <END> token and don't compute loss or gradient for <NULL> tokens. Since they are a bit of a pain, we have taken care of all implementation details around special tokens for you.

You can load all of the MS-COCO data (captions, features, URLs, and vocabulary) using the load_coco_data function from the file cs231n/coco_utils.py. Run the following cell to do so:

```
data = load_coco_data(pca_features=True)
        # Print out all the keys and values from the data dictionary
        for k, v in data.items():
            if type(v) == np.ndarray:
                print(k, type(v), v.shape, v.dtype)
            else:
                print(k, type(v), len(v))
train captions <class 'numpy.ndarray'> (400135, 17) int32
train image idxs <class 'numpy.ndarray'> (400135,) int32
val captions <class 'numpy.ndarray'> (195954, 17) int32
val_image_idxs <class 'numpy.ndarray'> (195954,) int32
train_features <class 'numpy.ndarray'> (82783, 512) float32
val_features <class 'numpy.ndarray'> (40504, 512) float32
idx_to_word <class 'list'> 1004
word_to_idx <class 'dict'> 1004
train_urls <class 'numpy.ndarray'> (82783,) <U63</pre>
val_urls <class 'numpy.ndarray'> (40504,) <U63</pre>
```

2.1 Look at the data

It is always a good idea to look at examples from the dataset before working with it.

You can use the sample_coco_minibatch function from the file cs231n/coco_utils.py to sample minibatches of data from the data structure returned from load_coco_data. Run the following to sample a small minibatch of training data and show the images and their captions. Running it multiple times and looking at the results helps you to get a sense of the dataset.

Note that we decode the captions using the decode_captions function and that we download the images on-the-fly using their Flickr URL, so **you must be connected to the internet to view images**.

```
In [7]: # Sample a minibatch and show the images and captions
   batch_size = 3

captions, features, urls = sample_coco_minibatch(data, batch_size=batch_size)
for i, (caption, url) in enumerate(zip(captions, urls)):
    plt.imshow(image_from_url(url))
    plt.axis('off')
        caption_str = decode_captions(caption, data['idx_to_word'])
        plt.title(caption_str)
        plt.show()
```

<START> and outside <UNK> area with a couch and umbrella <END>



<START> a pizza on a board has <UNK> tomatoes and <UNK> <END>



<START> a dog sits in a cage on the back of a motorcycle <END>



3 Recurrent Neural Networks

As discussed in lecture, we will use recurrent neural network (RNN) language models for image captioning. The file cs231n/rnn_layers.py contains implementations of different layer types that are needed for recurrent neural networks, and the file cs231n/classifiers/rnn.py uses these layers to implement an image captioning model.

We will first implement different types of RNN layers in cs231n/rnn_layers.py.

4 Vanilla RNN: step forward

Open the file cs231n/rnn_layers.py. This file implements the forward and backward passes for different types of layers that are commonly used in recurrent neural networks.

First implement the function rnn_step_forward which implements the forward pass for a single timestep of a vanilla recurrent neural network. After doing so run the following to check your implementation. You should see errors less than 1e-8.

```
In [8]: N, D, H = 3, 10, 4

x = np.linspace(-0.4, 0.7, num=N*D).reshape(N, D)
prev_h = np.linspace(-0.2, 0.5, num=N*H).reshape(N, H)
Wx = np.linspace(-0.1, 0.9, num=D*H).reshape(D, H)
Wh = np.linspace(-0.3, 0.7, num=H*H).reshape(H, H)
b = np.linspace(-0.2, 0.4, num=H)
```

5 Vanilla RNN: step backward

In the file cs231n/rnn_layers.py implement the rnn_step_backward function. After doing so run the following to numerically gradient check your implementation. You should see errors less than 1e-8.

```
In [9]: from cs231n.rnn_layers import rnn_step_forward, rnn_step_backward
       np.random.seed(231)
       N, D, H = 4, 5, 6
       x = np.random.randn(N, D)
       h = np.random.randn(N, H)
       Wx = np.random.randn(D, H)
       Wh = np.random.randn(H, H)
       b = np.random.randn(H)
        out, cache = rnn_step_forward(x, h, Wx, Wh, b)
       dnext_h = np.random.randn(*out.shape)
        fx = lambda x: rnn_step_forward(x, h, Wx, Wh, b)[0]
        fh = lambda prev_h: rnn_step_forward(x, h, Wx, Wh, b)[0]
        fWx = lambda Wx: rnn_step_forward(x, h, Wx, Wh, b)[0]
        fWh = lambda Wh: rnn step forward(x, h, Wx, Wh, b)[0]
        fb = lambda b: rnn_step_forward(x, h, Wx, Wh, b)[0]
        dx_num = eval_numerical_gradient_array(fx, x, dnext_h)
        dprev_h_num = eval_numerical_gradient_array(fh, h, dnext_h)
       dWx_num = eval_numerical_gradient_array(fWx, Wx, dnext_h)
        dWh_num = eval_numerical_gradient_array(fWh, Wh, dnext_h)
        db_num = eval_numerical_gradient_array(fb, b, dnext_h)
        dx, dprev_h, dWx, dWh, db = rnn_step_backward(dnext_h, cache)
       print('dx error: ', rel_error(dx_num, dx))
        print('dprev_h error: ', rel_error(dprev_h_num, dprev_h))
       print('dWx error: ', rel_error(dWx_num, dWx))
```

```
print('dWh error: ', rel_error(dWh_num, dWh))
    print('db error: ', rel_error(db_num, db))

dx error: 4.0192769090159184e-10
dprev_h error: 2.5632975303201374e-10
dWx error: 8.820222259148609e-10
dWh error: 4.703287554560559e-10
db error: 7.30162216654e-11
```

6 Vanilla RNN: forward

Now that you have implemented the forward and backward passes for a single timestep of a vanilla RNN, you will combine these pieces to implement a RNN that process an entire sequence of data.

In the file cs231n/rnn_layers.py, implement the function rnn_forward. This should be implemented using the rnn_step_forward function that you defined above. After doing so run the following to check your implementation. You should see errors less than 1e-7.

```
In [10]: N, T, D, H = 2, 3, 4, 5
        x = np.linspace(-0.1, 0.3, num=N*T*D).reshape(N, T, D)
        h0 = np.linspace(-0.3, 0.1, num=N*H).reshape(N, H)
        Wx = np.linspace(-0.2, 0.4, num=D*H).reshape(D, H)
        Wh = np.linspace(-0.4, 0.1, num=H*H).reshape(H, H)
        b = np.linspace(-0.7, 0.1, num=H)
        h, = rnn_forward(x, h0, Wx, Wh, b)
        expected_h = np.asarray([
           Γ
             [-0.42070749, -0.27279261, -0.11074945, 0.05740409, 0.22236251],
             [-0.39525808, -0.22554661, -0.0409454, 0.14649412, 0.32397316],
             [-0.42305111, -0.24223728, -0.04287027, 0.15997045, 0.35014525],
          ],
             [-0.55857474, -0.39065825, -0.19198182, 0.02378408,
                                                                  0.23735671],
             [-0.27150199, -0.07088804, 0.13562939, 0.33099728, 0.50158768],
             [-0.51014825, -0.30524429, -0.06755202,
                                                     0.17806392,
                                                                  0.40333043]])
        print('h error: ', rel_error(expected_h, h))
```

h error: 7.728466158305164e-08

7 Vanilla RNN: backward

In the file cs231n/rnn_layers.py, implement the backward pass for a vanilla RNN in the function rnn_backward. This should run back-propagation over the entire sequence, calling into the rnn_step_backward function that you defined above. You should see errors less than 5e-7.

```
In [11]: np.random.seed(231)
         N, D, T, H = 2, 3, 10, 5
         x = np.random.randn(N, T, D)
         h0 = np.random.randn(N, H)
         Wx = np.random.randn(D, H)
         Wh = np.random.randn(H, H)
         b = np.random.randn(H)
         out, cache = rnn_forward(x, h0, Wx, Wh, b)
         dout = np.random.randn(*out.shape)
         dx, dh0, dWx, dWh, db = rnn_backward(dout, cache)
         fx = lambda x: rnn_forward(x, h0, Wx, Wh, b)[0]
         fh0 = lambda h0: rnn_forward(x, h0, Wx, Wh, b)[0]
         fWx = lambda Wx: rnn_forward(x, h0, Wx, Wh, b)[0]
         fWh = lambda Wh: rnn forward(x, h0, Wx, Wh, b)[0]
         fb = lambda b: rnn_forward(x, h0, Wx, Wh, b)[0]
         dx_num = eval_numerical_gradient_array(fx, x, dout)
         dh0_num = eval_numerical_gradient_array(fh0, h0, dout)
         dWx_num = eval_numerical_gradient_array(fWx, Wx, dout)
         dWh_num = eval_numerical_gradient_array(fWh, Wh, dout)
         db_num = eval_numerical_gradient_array(fb, b, dout)
         print('dx error: ', rel_error(dx_num, dx))
         print('dh0 error: ', rel_error(dh0_num, dh0))
         print('dWx error: ', rel_error(dWx_num, dWx))
         print('dWh error: ', rel_error(dWh_num, dWh))
         print('db error: ', rel_error(db_num, db))
dx error: 1.5382468491701097e-09
dh0 error: 3.3839681556240896e-09
dWx error: 7.150535245339328e-09
dWh error: 1.297338408201546e-07
db error: 1.4889022954777414e-10
```

8 Word embedding: forward

In deep learning systems, we commonly represent words using vectors. Each word of the vocabulary will be associated with a vector, and these vectors will be learned jointly with the rest of the system.

In the file cs231n/rnn_layers.py, implement the function word_embedding_forward to con-

vert words (represented by integers) into vectors. Run the following to check your implementation. You should see error around 1e-8.

```
In [12]: N, T, V, D = 2, 4, 5, 3
        x = np.asarray([[0, 3, 1, 2], [2, 1, 0, 3]])
        W = np.linspace(0, 1, num=V*D).reshape(V, D)
        out, _ = word_embedding_forward(x, W)
        expected out = np.asarray([
                0.07142857, 0.14285714],
          [ 0.64285714, 0.71428571, 0.78571429],
          [0.21428571, 0.28571429, 0.35714286],
          [ 0.42857143, 0.5,
                                  0.57142857]],
         [[ 0.42857143, 0.5, 0.57142857],
          [ 0.21428571, 0.28571429, 0.35714286],
                 0.07142857, 0.14285714],
          [ 0.,
          [ 0.64285714, 0.71428571, 0.78571429]]])
        print('out error: ', rel_error(expected_out, out))
out error: 1.000000094736443e-08
```

9 Word embedding: backward

Implement the backward pass for the word embedding function in the function word_embedding_backward. After doing so run the following to numerically gradient check your implementation. You should see errors less than 1e-11.

```
In [13]: np.random.seed(231)

N, T, V, D = 50, 3, 5, 6
x = np.random.randint(V, size=(N, T))
W = np.random.randn(V, D)

out, cache = word_embedding_forward(x, W)
dout = np.random.randn(*out.shape)
dW = word_embedding_backward(dout, cache)

f = lambda W: word_embedding_forward(x, W)[0]
dW_num = eval_numerical_gradient_array(f, W, dout)

print('dW error: ', rel_error(dW, dW_num))

dW error: 3.2774595693100364e-12
```

10 Temporal Affine layer

At every timestep we use an affine function to transform the RNN hidden vector at that timestep into scores for each word in the vocabulary. Because this is very similar to the affine layer that you implemented in assignment 2, we have provided this function for you in the temporal_affine_forward and temporal_affine_backward functions in the file cs231n/rnn_layers.py. Run the following to perform numeric gradient checking on the implementation. You should see errors less than 1e-9.

```
In [14]: np.random.seed(231)
         # Gradient check for temporal affine layer
         N, T, D, M = 2, 3, 4, 5
         x = np.random.randn(N, T, D)
         w = np.random.randn(D, M)
         b = np.random.randn(M)
         out, cache = temporal_affine_forward(x, w, b)
         dout = np.random.randn(*out.shape)
         fx = lambda x: temporal_affine_forward(x, w, b)[0]
         fw = lambda w: temporal_affine_forward(x, w, b)[0]
         fb = lambda b: temporal_affine_forward(x, w, b)[0]
         dx_num = eval_numerical_gradient_array(fx, x, dout)
         dw_num = eval_numerical_gradient_array(fw, w, dout)
         db_num = eval_numerical_gradient_array(fb, b, dout)
         dx, dw, db = temporal_affine_backward(dout, cache)
         print('dx error: ', rel_error(dx_num, dx))
         print('dw error: ', rel_error(dw_num, dw))
         print('db error: ', rel_error(db_num, db))
dx error: 2.9215945034030545e-10
dw error: 1.5772088618663602e-10
db error: 3.252200556967514e-11
```

11 Temporal Softmax loss

In an RNN language model, at every timestep we produce a score for each word in the vocabulary. We know the ground-truth word at each timestep, so we use a softmax loss function to compute loss and gradient at each timestep. We sum the losses over time and average them over the minibatch.

However there is one wrinkle: since we operate over minibatches and different captions may have different lengths, we append <NULL> tokens to the end of each caption so they all have the

same length. We don't want these <NULL> tokens to count toward the loss or gradient, so in addition to scores and ground-truth labels our loss function also accepts a mask array that tells it which elements of the scores count towards the loss.

Since this is very similar to the softmax loss function you implemented in assignment 1, we have implemented this loss function for you; look at the temporal_softmax_loss function in the file cs231n/rnn_layers.py.

Run the following cell to sanity check the loss and perform numeric gradient checking on the function. You should see an error for dx less than 1e-7.

```
In [15]: # Sanity check for temporal softmax loss
         from cs231n.rnn_layers import temporal_softmax_loss
         N, T, V = 100, 1, 10
         def check_loss(N, T, V, p):
             x = 0.001 * np.random.randn(N, T, V)
             y = np.random.randint(V, size=(N, T))
             mask = np.random.rand(N, T) <= p</pre>
             print(temporal_softmax_loss(x, y, mask)[0])
         check_loss(100, 1, 10, 1.0) # Should be about 2.3
         check_loss(100, 10, 10, 1.0) # Should be about 23
         check_loss(5000, 10, 10, 0.1) # Should be about 2.3
         # Gradient check for temporal softmax loss
         N, T, V = 7, 8, 9
         x = np.random.randn(N, T, V)
         y = np.random.randint(V, size=(N, T))
         mask = (np.random.rand(N, T) > 0.5)
         loss, dx = temporal_softmax_loss(x, y, mask, verbose=False)
         dx_num = eval_numerical_gradient(lambda x: temporal_softmax_loss(x, y, mask)[0], x, v
         print('dx error: ', rel_error(dx, dx_num))
2.3027781774290146
23.025985953127226
2.2643611790293394
dx error: 2.583585303524283e-08
```

12 RNN for image captioning

Now that you have implemented the necessary layers, you can combine them to build an image captioning model. Open the file cs231n/classifiers/rnn.py and look at the CaptioningRNN class.

Implement the forward and backward pass of the model in the loss function. For now you only need to implement the case where cell_type='rnn' for vanialla RNNs; you will implement the LSTM case later. After doing so, run the following to check your forward pass using a small test case; you should see error less than 1e-10.

```
In [16]: N, D, W, H = 10, 20, 30, 40
         word_to_idx = {'<NULL>': 0, 'cat': 2, 'dog': 3}
         V = len(word_to_idx)
         T = 13
         model = CaptioningRNN(word_to_idx,
                   input_dim=D,
                   wordvec dim=W,
                   hidden_dim=H,
                   cell type='rnn',
                   dtype=np.float64)
         # Set all model parameters to fixed values
         for k, v in model.params.items():
             model.params[k] = np.linspace(-1.4, 1.3, num=v.size).reshape(*v.shape)
         features = np.linspace(-1.5, 0.3, num=(N * D)).reshape(N, D)
         captions = (np.arange(N * T) % V).reshape(N, T)
         loss, grads = model.loss(features, captions)
         expected_loss = 9.83235591003
         print('loss: ', loss)
         print('expected loss: ', expected_loss)
         print('difference: ', abs(loss - expected loss))
loss: 9.832355910027387
expected loss: 9.83235591003
difference: 2.6130209107577684e-12
```

Run the following cell to perform numeric gradient checking on the CaptioningRNN class; you should errors around 5e-6 or less.

```
In [17]: np.random.seed(231)

batch_size = 2
timesteps = 3
input_dim = 4
wordvec_dim = 5
hidden_dim = 6
word_to_idx = {'<NULL>': 0, 'cat': 2, 'dog': 3}
vocab_size = len(word_to_idx)
```

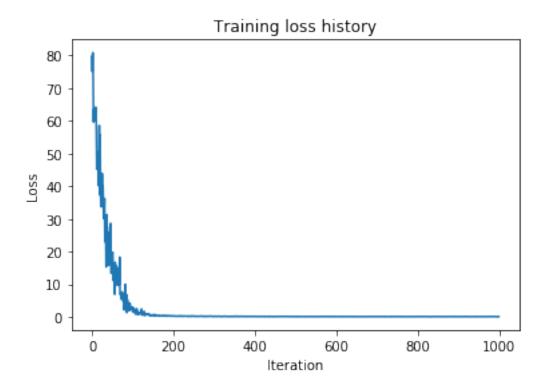
```
captions = np.random.randint(vocab_size, size=(batch_size, timesteps))
         features = np.random.randn(batch_size, input_dim)
         model = CaptioningRNN(word_to_idx,
                   input_dim=input_dim,
                   wordvec_dim=wordvec_dim,
                   hidden_dim=hidden_dim,
                   cell_type='rnn',
                   dtype=np.float64,
         loss, grads = model.loss(features, captions)
         for param_name in sorted(grads):
             f = lambda _: model.loss(features, captions)[0]
             param_grad_num = eval_numerical_gradient(f, model.params[param_name], verbose=Fal
             e = rel_error(param_grad_num, grads[param_name])
             print('%s relative error: %e' % (param_name, e))
W_embed relative error: 2.331070e-09
W_proj relative error: 1.112417e-08
W_vocab relative error: 4.274379e-09
Wh relative error: 5.858117e-09
Wx relative error: 1.590657e-06
b relative error: 9.727211e-10
b_proj relative error: 1.934807e-08
b_vocab relative error: 7.087097e-11
```

13 Overfit small data

Similar to the Solver class that we used to train image classification models on the previous assignment, on this assignment we use a CaptioningSolver class to train image captioning models. Open the file cs231n/captioning_solver.py and read through the CaptioningSolver class; it should look very familiar.

Once you have familiarized yourself with the API, run the following to make sure your model overfit a small sample of 100 training examples. You should see losses of less than 0.1.

```
)
        small_rnn_solver = CaptioningSolver(small_rnn_model, small_data,
                    update_rule='adam',
                    num_epochs=100,
                    batch_size=10,
                    optim_config={
                      'learning_rate': 1e-3,
                    },
                    lr_decay=0.95,
                    verbose=True, print_every=100,
                  )
        small_rnn_solver.train()
         # Plot the training losses
        plt.plot(small_rnn_solver.loss_history)
        plt.xlabel('Iteration')
        plt.ylabel('Loss')
        plt.title('Training loss history')
        plt.show()
(Iteration 1 / 1000) loss: 79.682039
(Iteration 101 / 1000) loss: 2.252850
(Iteration 201 / 1000) loss: 0.332144
(Iteration 301 / 1000) loss: 0.178722
(Iteration 401 / 1000) loss: 0.165500
(Iteration 501 / 1000) loss: 0.149312
(Iteration 601 / 1000) loss: 0.156000
(Iteration 701 / 1000) loss: 0.109197
(Iteration 801 / 1000) loss: 0.118053
(Iteration 901 / 1000) loss: 0.083934
```



14 Test-time sampling

Unlike classification models, image captioning models behave very differently at training time and at test time. At training time, we have access to the ground-truth caption, so we feed ground-truth words as input to the RNN at each timestep. At test time, we sample from the distribution over the vocabulary at each timestep, and feed the sample as input to the RNN at the next timestep.

In the file cs231n/classifiers/rnn.py, implement the sample method for test-time sampling. After doing so, run the following to sample from your overfitted model on both training and validation data. The samples on training data should be very good; the samples on validation data probably won't make sense.

Note: Some of the URLs are missing and will throw an error; re-run this cell until the output is at least 2 good caption samples.

plt.title('%s\n%s\nGT:%s' % (split, sample_caption, gt_caption))
plt.axis('off')
plt.show()

train
a boy is jumping in the air on his skateboard <END>
GT:<START> a boy is jumping in the air on his skateboard <END>



train
a boy surfing a wave with a pink and yellow surf board <END>
GT:<START> a boy surfing a wave with a pink and yellow surf board <END>



val a plate of food sitting on <END> GT:<START> a man is taking a picture of some sandwiches <END>



val
woman cat sitting looking a on top of the dry <END>
GT:<START> doughnuts sitting on a brown bag on a table <END>



2.2 LSTM Captioning

LSTM_Captioning

October 23, 2019

1 Image Captioning with LSTMs

In the previous exercise you implemented a vanilla RNN and applied it to image captioning. In this notebook you will implement the LSTM update rule and use it for image captioning.

```
In [1]: # As usual, a bit of setup
        from __future__ import print_function
        import time, os, json
        import numpy as np
        import matplotlib.pyplot as plt
        import nltk
        from cs231n.gradient_check import eval_numerical_gradient, eval_numerical_gradient_arr
        from cs231n.rnn_layers import *
        from cs231n.captioning_solver import CaptioningSolver
        from cs231n.classifiers.rnn import CaptioningRNN
        from cs231n.coco_utils import load_coco_data, sample_coco_minibatch, decode_captions
        from cs231n.image_utils import image_from_url
       %matplotlib inline
       plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
        plt.rcParams['image.interpolation'] = 'nearest'
       plt.rcParams['image.cmap'] = 'gray'
        # for auto-reloading external modules
        \# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
       %load ext autoreload
        %autoreload 2
       def rel_error(x, y):
            """ returns relative error """
            return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + np.abs(y))))
```

2 Load MS-COCO data

As in the previous notebook, we will use the Microsoft COCO dataset for captioning.

```
In [2]: # Load COCO data from disk; this returns a dictionary
        # We'll work with dimensionality-reduced features for this notebook, but feel
        # free to experiment with the original features by changing the flag below.
        data = load_coco_data(pca_features=True)
        # Print out all the keys and values from the data dictionary
        for k, v in data.items():
            if type(v) == np.ndarray:
                print(k, type(v), v.shape, v.dtype)
            else:
                print(k, type(v), len(v))
train_captions <class 'numpy.ndarray'> (400135, 17) int32
train_image_idxs <class 'numpy.ndarray'> (400135,) int32
val_captions <class 'numpy.ndarray'> (195954, 17) int32
val_image_idxs <class 'numpy.ndarray'> (195954,) int32
train_features <class 'numpy.ndarray'> (82783, 512) float32
val_features <class 'numpy.ndarray'> (40504, 512) float32
idx_to_word <class 'list'> 1004
word_to_idx <class 'dict'> 1004
train_urls <class 'numpy.ndarray'> (82783,) <U63</pre>
val_urls <class 'numpy.ndarray'> (40504,) <U63
```

3 LSTM

If you read recent papers, you'll see that many people use a variant on the vanialla RNN called Long-Short Term Memory (LSTM) RNNs. Vanilla RNNs can be tough to train on long sequences due to vanishing and exploding gradiants caused by repeated matrix multiplication. LSTMs solve this problem by replacing the simple update rule of the vanilla RNN with a gating mechanism as follows.

Similar to the vanilla RNN, at each timestep we receive an input $x_t \in \mathbb{R}^D$ and the previous hidden state $h_{t-1} \in \mathbb{R}^H$; the LSTM also maintains an H-dimensional *cell state*, so we also receive the previous cell state $c_{t-1} \in \mathbb{R}^H$. The learnable parameters of the LSTM are an *input-to-hidden* matrix $W_x \in \mathbb{R}^{4H \times D}$, a *hidden-to-hidden* matrix $W_h \in \mathbb{R}^{4H \times H}$ and a *bias vector* $b \in \mathbb{R}^{4H}$.

At each timestep we first compute an *activation vector* $a \in \mathbb{R}^{4H}$ as $a = W_x x_t + W_h h_{t-1} + b$. We then divide this into four vectors $a_i, a_f, a_o, a_g \in \mathbb{R}^H$ where a_i consists of the first H elements of a, a_f is the next H elements of a, etc. We then compute the *input gate* $g \in \mathbb{R}^H$, *forget gate* $f \in \mathbb{R}^H$, *output gate* $o \in \mathbb{R}^H$ and *block input* $g \in \mathbb{R}^H$ as

where σ is the sigmoid function and tanh is the hyperbolic tangent, both applied elementwise. Finally we compute the next cell state c_t and next hidden state h_t as

$$c_t = f \odot c_{t-1} + i \odot g$$
 $h_t = o \odot \tanh(c_t)$

where \odot is the elementwise product of vectors.

In the rest of the notebook we will implement the LSTM update rule and apply it to the image captioning task.

In the code, we assume that data is stored in batches so that $X_t \in \mathbb{R}^{N \times D}$, and will work with *transposed* versions of the parameters: $W_x \in \mathbb{R}^{D \times 4H}$, $W_h \in \mathbb{R}^{H \times 4H}$ so that activations $A \in \mathbb{R}^{N \times 4H}$ can be computed efficiently as $A = X_t W_x + H_{t-1} W_h$

4 LSTM: step forward

Implement the forward pass for a single timestep of an LSTM in the <code>lstm_step_forward</code> function in the file <code>cs231n/rnn_layers.py</code>. This should be similar to the <code>rnn_step_forward</code> function that you implemented above, but using the LSTM update rule instead.

Once you are done, run the following to perform a simple test of your implementation. You should see errors around 1e-8 or less.

```
In [3]: N, D, H = 3, 4, 5
       x = np.linspace(-0.4, 1.2, num=N*D).reshape(N, D)
       prev_h = np.linspace(-0.3, 0.7, num=N*H).reshape(N, H)
       prev_c = np.linspace(-0.4, 0.9, num=N*H).reshape(N, H)
       Wx = np.linspace(-2.1, 1.3, num=4*D*H).reshape(D, 4 * H)
       Wh = np.linspace(-0.7, 2.2, num=4*H*H).reshape(H, 4*H)
       b = np.linspace(0.3, 0.7, num=4*H)
       next_h, next_c, cache = lstm_step_forward(x, prev_h, prev_c, Wx, Wh, b)
       expected_next_h = np.asarray([
           [ 0.24635157, 0.28610883, 0.32240467, 0.35525807, 0.38474904],
           [0.49223563, 0.55611431, 0.61507696, 0.66844003, 0.7159181],
           [ 0.56735664, 0.66310127, 0.74419266, 0.80889665, 0.858299 ]])
       expected_next_c = np.asarray([
           [ 0.32986176, 0.39145139, 0.451556, 0.51014116, 0.56717407],
           [0.66382255, 0.76674007, 0.87195994, 0.97902709, 1.08751345],
           [ 0.74192008, 0.90592151, 1.07717006, 1.25120233, 1.42395676]])
       print('next_h error: ', rel_error(expected_next_h, next_h))
       print('next_c error: ', rel_error(expected_next_c, next_c))
next_h error: 5.7054131967097955e-09
next_c error: 5.8143123088804145e-09
```

5 LSTM: step backward

Implement the backward pass for a single LSTM timestep in the function <code>lstm_step_backward</code> in the file <code>cs231n/rnn_layers.py</code>. Once you are done, run the following to perform numeric gradient checking on your implementation. You should see errors around <code>1e-6</code> or less.

```
In [4]: np.random.seed(231)
```

```
N, D, H = 4, 5, 6
        x = np.random.randn(N, D)
       prev_h = np.random.randn(N, H)
       prev_c = np.random.randn(N, H)
       Wx = np.random.randn(D, 4 * H)
       Wh = np.random.randn(H, 4 * H)
       b = np.random.randn(4 * H)
       next_h, next_c, cache = lstm_step_forward(x, prev_h, prev_c, Wx, Wh, b)
       dnext_h = np.random.randn(*next_h.shape)
       dnext_c = np.random.randn(*next_c.shape)
        fx h = lambda x: lstm_step_forward(x, prev_h, prev_c, Wx, Wh, b)[0]
       fh_h = lambda h: lstm_step_forward(x, prev_h, prev_c, Wx, Wh, b)[0]
        fc_h = lambda c: lstm_step_forward(x, prev_h, prev_c, Wx, Wh, b)[0]
       fWx_h = lambda Wx: lstm_step_forward(x, prev_h, prev_c, Wx, Wh, b)[0]
       fWh_h = lambda Wh: lstm_step_forward(x, prev_h, prev_c, Wx, Wh, b)[0]
        fb_h = lambda b: lstm_step_forward(x, prev_h, prev_c, Wx, Wh, b)[0]
       fx_c = lambda x: lstm_step_forward(x, prev_h, prev_c, Wx, Wh, b)[1]
       fh c = lambda h: lstm step forward(x, prev h, prev c, Wx, Wh, b)[1]
       fc_c = lambda c: lstm_step_forward(x, prev_h, prev_c, Wx, Wh, b)[1]
       fWx_c = lambda Wx: lstm_step_forward(x, prev_h, prev_c, Wx, Wh, b)[1]
       fWh_c = lambda Wh: lstm_step_forward(x, prev_h, prev_c, Wx, Wh, b)[1]
        fb_c = lambda b: lstm step_forward(x, prev_h, prev_c, Wx, Wh, b)[1]
       num_grad = eval_numerical_gradient_array
       dx_num = num_grad(fx_h, x, dnext_h) + num_grad(fx_c, x, dnext_c)
       dh_num = num_grad(fh_h, prev_h, dnext_h) + num_grad(fh_c, prev_h, dnext_c)
        dc_num = num_grad(fc_h, prev_c, dnext_h) + num_grad(fc_c, prev_c, dnext_c)
       dWx_num = num_grad(fWx_h, Wx, dnext_h) + num_grad(fWx_c, Wx, dnext_c)
        dWh_num = num_grad(fWh_h, Wh, dnext_h) + num_grad(fWh_c, Wh, dnext_c)
        db_num = num_grad(fb_h, b, dnext_h) + num_grad(fb_c, b, dnext_c)
        dx, dh, dc, dWx, dWh, db = lstm_step_backward(dnext_h, dnext_c, cache)
       print('dx error: ', rel_error(dx_num, dx))
        print('dh error: ', rel_error(dh_num, dh))
       print('dc error: ', rel_error(dc_num, dc))
       print('dWx error: ', rel_error(dWx_num, dWx))
       print('dWh error: ', rel_error(dWh_num, dWh))
       print('db error: ', rel_error(db_num, db))
dx error: 6.335163002532046e-10
dh error: 3.3963774090592634e-10
```

dc error: 1.5221723979041107e-10

dWx error: 2.1010960934639614e-09 dWh error: 9.712296109943072e-08 db error: 2.491522041931035e-10

6 LSTM: forward

In the function lstm_forward in the file cs231n/rnn_layers.py, implement the lstm_forward function to run an LSTM forward on an entire timeseries of data.

When you are done, run the following to check your implementation. You should see an error around 1e-7.

```
In [5]: N, D, H, T = 2, 5, 4, 3
    x = np.linspace(-0.4, 0.6, num=N*T*D).reshape(N, T, D)
    h0 = np.linspace(-0.4, 0.8, num=N*H).reshape(N, H)
    Wx = np.linspace(-0.2, 0.9, num=4*D*H).reshape(D, 4 * H)
    Wh = np.linspace(-0.3, 0.6, num=4*H*H).reshape(H, 4 * H)
    b = np.linspace(0.2, 0.7, num=4*H)

    h, cache = lstm_forward(x, h0, Wx, Wh, b)

    expected_h = np.asarray([
        [[ 0.01764008,  0.01823233,  0.01882671,  0.0194232 ],
        [ 0.11287491,  0.12146228,  0.13018446,  0.13902939],
        [ 0.31358768,  0.33338627,  0.35304453,  0.37250975]],
        [[ 0.45767879,  0.4761092,  0.4936887,   0.51041945],
        [ 0.6704845,   0.69350089,  0.71486014,  0.7346449 ],
        [ 0.81733511,  0.83677871,  0.85403753,  0.86935314]]])

    print('h error: ', rel_error(expected_h, h))
```

7 LSTM: backward

h error: 8.610537452106624e-08

Implement the backward pass for an LSTM over an entire timeseries of data in the function <code>lstm_backward</code> in the file <code>cs231n/rnn_layers.py</code>. When you are done, run the following to perform numeric gradient checking on your implementation. You should see errors around <code>1e-7</code> or less.

```
h0 = np.random.randn(N, H)
       Wx = np.random.randn(D, 4 * H)
       Wh = np.random.randn(H, 4 * H)
        b = np.random.randn(4 * H)
        out, cache = lstm_forward(x, h0, Wx, Wh, b)
        dout = np.random.randn(*out.shape)
       dx, dh0, dWx, dWh, db = lstm_backward(dout, cache)
        fx = lambda x: lstm_forward(x, h0, Wx, Wh, b)[0]
        fh0 = lambda h0: lstm_forward(x, h0, Wx, Wh, b)[0]
        fWx = lambda Wx: lstm_forward(x, h0, Wx, Wh, b)[0]
        fWh = lambda Wh: lstm_forward(x, h0, Wx, Wh, b)[0]
        fb = lambda b: lstm_forward(x, h0, Wx, Wh, b)[0]
        dx_num = eval_numerical_gradient_array(fx, x, dout)
        dh0_num = eval_numerical_gradient_array(fh0, h0, dout)
        dWx num = eval numerical gradient array(fWx, Wx, dout)
        dWh_num = eval_numerical_gradient_array(fWh, Wh, dout)
        db_num = eval_numerical_gradient_array(fb, b, dout)
       print('dx error: ', rel_error(dx_num, dx))
       print('dh0 error: ', rel_error(dh0_num, dh0))
        print('dWx error: ', rel_error(dWx_num, dWx))
       print('dWh error: ', rel_error(dWh_num, dWh))
       print('db error: ', rel_error(db_num, db))
dx error: 6.9939005453315376e-09
dh0 error: 1.5042746972106784e-09
dWx error: 3.226295800444722e-09
dWh error: 2.6984653167426663e-06
db error: 8.23662763415198e-10
```

8 LSTM captioning model

Now that you have implemented an LSTM, update the implementation of the loss method of the CaptioningRNN class in the file cs231n/classifiers/rnn.py to handle the case where self.cell_type is lstm. This should require adding less than 10 lines of code.

Once you have done so, run the following to check your implementation. You should see a difference of less than 1e-10.

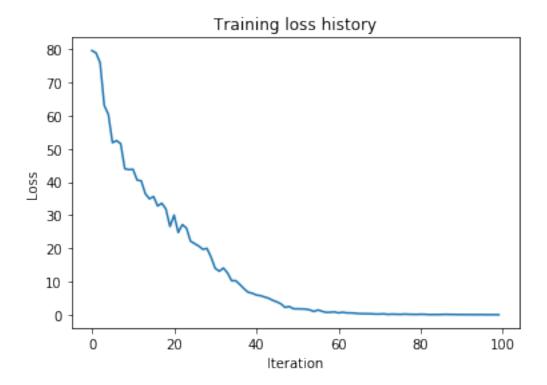
```
In [7]: N, D, W, H = 10, 20, 30, 40
          word_to_idx = {'<NULL>': 0, 'cat': 2, 'dog': 3}
        V = len(word_to_idx)
        T = 13
```

```
model = CaptioningRNN(word_to_idx,
                  input_dim=D,
                  wordvec_dim=W,
                  hidden_dim=H,
                  cell_type='lstm',
                  dtype=np.float64)
        # Set all model parameters to fixed values
        for k, v in model.params.items():
          model.params[k] = np.linspace(-1.4, 1.3, num=v.size).reshape(*v.shape)
        features = np.linspace(-0.5, 1.7, num=N*D).reshape(N, D)
        captions = (np.arange(N * T) % V).reshape(N, T)
        loss, grads = model.loss(features, captions)
        expected_loss = 9.82445935443
       print('loss: ', loss)
       print('expected loss: ', expected_loss)
       print('difference: ', abs(loss - expected_loss))
loss: 9.824459354432264
expected loss: 9.82445935443
difference: 2.2648549702353193e-12
```

9 Overfit LSTM captioning model

Run the following to overfit an LSTM captioning model on the same small dataset as we used for the RNN previously. You should see losses less than 0.5.

```
batch_size=25,
                   optim_config={
                     'learning_rate': 5e-3,
                   },
                   lr_decay=0.995,
                   verbose=True, print_every=10,
                 )
        small_lstm_solver.train()
        # Plot the training losses
       plt.plot(small_lstm_solver.loss_history)
       plt.xlabel('Iteration')
       plt.ylabel('Loss')
       plt.title('Training loss history')
       plt.show()
(Iteration 1 / 100) loss: 79.551150
(Iteration 11 / 100) loss: 43.829101
(Iteration 21 / 100) loss: 30.062616
(Iteration 31 / 100) loss: 14.020179
(Iteration 41 / 100) loss: 6.005075
(Iteration 51 / 100) loss: 1.849338
(Iteration 61 / 100) loss: 0.634570
(Iteration 71 / 100) loss: 0.285278
(Iteration 81 / 100) loss: 0.233098
(Iteration 91 / 100) loss: 0.121929
```



10 LSTM test-time sampling

Modify the sample method of the CaptioningRNN class to handle the case where self.cell_type is lstm. This should take fewer than 10 lines of code.

When you are done run the following to sample from your overfit LSTM model on some training and validation set samples.

```
In [9]: for split in ['train', 'val']:
    minibatch = sample_coco_minibatch(small_data, split=split, batch_size=2)
    gt_captions, features, urls = minibatch
    gt_captions = decode_captions(gt_captions, data['idx_to_word'])

sample_captions = small_lstm_model.sample(features)
    sample_captions = decode_captions(sample_captions, data['idx_to_word'])

for gt_caption, sample_caption, url in zip(gt_captions, sample_captions, urls):
    plt.imshow(image_from_url(url))
    plt.title('%s\n%s\nGT:%s' % (split, sample_caption, gt_caption))
    plt.axis('off')
    plt.show()
```

train
a man standing on the side of a road with bags of luggage <END>
GT:<START> a man standing on the side of a road with bags of luggage <END>



train
a man <UNK> with a bright colorful kite <END>
GT:<START> a man <UNK> with a bright colorful kite <END>



val
a person <UNK> with a <UNK> <END>
GT:<START> a sign that is on the front of a train station <END>



val
a cat is <UNK> and a big <END>
GT:<START> a car is parked on a street at night <END>



11 Train a good captioning model (extra credit for 4803)

Using the pieces you have implemented in this and the previous notebook, train a captioning model that gives decent qualitative results (better than the random garbage you saw with the overfit models) when sampling on the validation set. You can subsample the training set if you want; we just want to see samples on the validation set that are better than random.

In addition to qualitatively evaluating your model by inspecting its results, you can also quantitatively evaluate your model using the BLEU unigram precision metric. In order to achieve full credit you should train a model that achieves a BLEU unigram score of >0.3. BLEU scores range from 0 to 1; the closer to 1, the better. Here's a reference to the paper that introduces BLEU if you're interested in learning more about how it works.

Feel free to use PyTorch for this section if you'd like to train faster on a GPU... though you can definitely get above 0.3 using your Numpy code. We're providing you the evaluation code that is compatible with the Numpy model as defined above... you should be able to adapt it for PyTorch if you go that route.

Create the model in the file cs231n/classifiers/mymodel.py. You can base it after the CaptioningRNN class. Write a text comment in the delineated cell below explaining what you tried in your model.

Also add a cell below that trains and tests your model. Make sure to include the call to evaluate_model which prints out your highest validation BLEU score for full credit.

```
In [10]: def BLEU_score(gt_caption, sample_caption):
             gt_caption: string, ground-truth caption
             sample_caption: string, your model's predicted caption
             Returns unigram BLEU score.
             reference = [x for x in gt_caption.split(' ')
                          if ('<END>' not in x and '<START>' not in x and '<UNK>' not in x)]
             hypothesis = [x for x in sample_caption.split(' ')
                           if ('<END>' not in x and '<START>' not in x and '<UNK>' not in x)]
             BLEUscore = nltk.translate.bleu_score.sentence_bleu([reference], hypothesis, weig
             return BLEUscore
         def evaluate_model(model):
             model: CaptioningRNN model
             Prints unigram BLEU score averaged over 1000 training and val examples.
             BLEUscores = {}
             for split in ['train', 'val']:
                 minibatch = sample_coco_minibatch(data, split=split, batch_size=1000)
                 gt_captions, features, urls = minibatch
                 gt_captions = decode_captions(gt_captions, data['idx_to_word'])
```

```
sample_captions = model.sample(features)
sample_captions = decode_captions(sample_captions, data['idx_to_word'])

total_score = 0.0
for gt_caption, sample_caption, url in zip(gt_captions, sample_captions, urls total_score += BLEU_score(gt_caption, sample_caption)

BLEUscores[split] = total_score / len(sample_captions)

for split in BLEUscores:
    print('Average BLEU score for %s: %f' % (split, BLEUscores[split]))
```

12 write a description of your model here:

Same model as the LSTM Numpy implementation, with fine tunned hyper parameters and more data. Training take times.

All paramters were changed, the most important one was probably the hidden dim (and the data quantity) a large batch size allowed to get the gradiant right while a lower learning rate was needed to take into account the large number of iteration vs the small number of epoch. This trainning was completed on around 12 hours on a 12 threads desktop Intel i7-8700 CPU.

```
In [14]: # write your code to train your model here.
         from cs231n.classifiers.mymodel import MyModel
         my_data = load_coco_data(max_train=None)
         my_lstm_model = MyModel(
                   cell_type='lstm',
                   word_to_idx=data['word_to_idx'],
                   input_dim=data['train_features'].shape[1],
                   hidden_dim=2048,
                   wordvec_dim=256,
                   dtype=np.float32,
                 )
         my_lstm_solver = CaptioningSolver(my_lstm_model, my_data,
                    update_rule='adam',
                    num_epochs=3,
                    batch_size=1024,
                    optim_config={
                      'learning_rate': 1e-4,
                    },
                    lr_decay=0.9,
                    verbose=True, print_every=1,
```

```
my_lstm_solver.train()
         # Plot the training losses
        plt.plot(my_lstm_solver.loss_history)
        plt.xlabel('Iteration')
        plt.ylabel('Loss')
        plt.title('Training loss history')
        plt.show()
         # make sure to include the call to evaluate model which prints out your highest valid
        print("LSTM score:")
        evaluate_model(small_lstm_model)
        print("My model score:")
         evaluate_model(my_lstm_model)
(Iteration 1 / 1170) loss: 77.767695
(Iteration 2 / 1170) loss: 76.677468
(Iteration 3 / 1170) loss: 76.428032
(Iteration 4 / 1170) loss: 77.299044
(Iteration 5 / 1170) loss: 76.416580
(Iteration 6 / 1170) loss: 76.095531
(Iteration 7 / 1170) loss: 76.133898
(Iteration 8 / 1170) loss: 76.046990
(Iteration 9 / 1170) loss: 75.971192
(Iteration 10 / 1170) loss: 75.810697
(Iteration 11 / 1170) loss: 75.118970
(Iteration 12 / 1170) loss: 75.109374
(Iteration 13 / 1170) loss: 75.126804
(Iteration 14 / 1170) loss: 74.419421
(Iteration 15 / 1170) loss: 74.496195
(Iteration 16 / 1170) loss: 73.733022
(Iteration 17 / 1170) loss: 73.046076
(Iteration 18 / 1170) loss: 72.252211
(Iteration 19 / 1170) loss: 71.724380
(Iteration 20 / 1170) loss: 70.920663
(Iteration 21 / 1170) loss: 69.919237
(Iteration 22 / 1170) loss: 68.250768
(Iteration 23 / 1170) loss: 67.003846
(Iteration 24 / 1170) loss: 63.476444
(Iteration 25 / 1170) loss: 61.653228
(Iteration 26 / 1170) loss: 60.116551
(Iteration 27 / 1170) loss: 59.649217
(Iteration 28 / 1170) loss: 58.109839
(Iteration 29 / 1170) loss: 56.234807
(Iteration 30 / 1170) loss: 55.763547
(Iteration 31 / 1170) loss: 55.955834
(Iteration 32 / 1170) loss: 56.089155
(Iteration 33 / 1170) loss: 54.322441
(Iteration 34 / 1170) loss: 54.870358
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(Iteration 35 / 1170) loss: 53.879896
(Iteration 36 / 1170) loss: 53.968145
(Iteration 37 / 1170) loss: 53.402411
(Iteration 38 / 1170) loss: 53.305978
(Iteration 39 / 1170) loss: 54.039428
(Iteration 40 / 1170) loss: 52.548754
(Iteration 41 / 1170) loss: 52.227963
(Iteration 42 / 1170) loss: 52.663542
(Iteration 43 / 1170) loss: 52.060988
(Iteration 44 / 1170) loss: 52.002039
(Iteration 45 / 1170) loss: 52.399127
(Iteration 46 / 1170) loss: 52.358968
(Iteration 47 / 1170) loss: 51.642286
(Iteration 48 / 1170) loss: 51.396217
(Iteration 49 / 1170) loss: 51.864611
(Iteration 50 / 1170) loss: 51.966383
(Iteration 51 / 1170) loss: 51.737526
(Iteration 52 / 1170) loss: 51.305973
(Iteration 53 / 1170) loss: 50.934631
(Iteration 54 / 1170) loss: 51.189282
(Iteration 55 / 1170) loss: 51.298938
(Iteration 56 / 1170) loss: 50.841360
(Iteration 57 / 1170) loss: 50.241599
(Iteration 58 / 1170) loss: 50.717055
(Iteration 59 / 1170) loss: 50.157340
(Iteration 60 / 1170) loss: 49.956023
(Iteration 61 / 1170) loss: 50.112098
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(Iteration 63 / 1170) loss: 50.597938
(Iteration 64 / 1170) loss: 49.622576
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(Iteration 78 / 1170) loss: 49.244343
(Iteration 79 / 1170) loss: 47.892459
(Iteration 80 / 1170) loss: 48.606674
(Iteration 81 / 1170) loss: 49.016801
(Iteration 82 / 1170) loss: 48.700789
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(Iteration 83 / 1170) loss: 48.202232
(Iteration 84 / 1170) loss: 48.731822
(Iteration 85 / 1170) loss: 49.042803
(Iteration 86 / 1170) loss: 48.494692
(Iteration 87 / 1170) loss: 48.209117
(Iteration 88 / 1170) loss: 48.558433
(Iteration 89 / 1170) loss: 47.750019
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(Iteration 91 / 1170) loss: 47.420152
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(Iteration 105 / 1170) loss: 47.249143
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(Iteration 107 / 1170) loss: 46.846252
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(Iteration 110 / 1170) loss: 47.231530
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(Iteration 112 / 1170) loss: 46.666806
(Iteration 113 / 1170) loss: 46.539856
(Iteration 114 / 1170) loss: 46.652779
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(Iteration 117 / 1170) loss: 46.045492
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(Iteration 128 / 1170) loss: 45.452052
(Iteration 129 / 1170) loss: 46.089094
(Iteration 130 / 1170) loss: 46.000802
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(Iteration 131 / 1170) loss: 45.739796
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(Iteration 275 / 1170) loss: 38.658895
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(Iteration 428 / 1170) loss: 33.532482
(Iteration 429 / 1170) loss: 33.523491
(Iteration 430 / 1170) loss: 33.909504
(Iteration 431 / 1170) loss: 33.649231
(Iteration 432 / 1170) loss: 33.806889
(Iteration 433 / 1170) loss: 34.040699
(Iteration 434 / 1170) loss: 34.336868
(Iteration 435 / 1170) loss: 32.894914
(Iteration 436 / 1170) loss: 33.366539
(Iteration 437 / 1170) loss: 34.031822
(Iteration 438 / 1170) loss: 33.498356
(Iteration 439 / 1170) loss: 33.989025
(Iteration 440 / 1170) loss: 33.769363
(Iteration 441 / 1170) loss: 33.441488
(Iteration 442 / 1170) loss: 33.859746
(Iteration 443 / 1170) loss: 34.013168
(Iteration 444 / 1170) loss: 33.319034
(Iteration 445 / 1170) loss: 33.659680
(Iteration 446 / 1170) loss: 33.403771
(Iteration 447 / 1170) loss: 33.404118
(Iteration 448 / 1170) loss: 33.638741
(Iteration 449 / 1170) loss: 33.799630
(Iteration 450 / 1170) loss: 34.285606
(Iteration 451 / 1170) loss: 33.811048
(Iteration 452 / 1170) loss: 33.785121
(Iteration 453 / 1170) loss: 33.615105
(Iteration 454 / 1170) loss: 34.206907
(Iteration 455 / 1170) loss: 33.898393
(Iteration 456 / 1170) loss: 33.121223
(Iteration 457 / 1170) loss: 33.159011
(Iteration 458 / 1170) loss: 33.523095
(Iteration 459 / 1170) loss: 33.094843
(Iteration 460 / 1170) loss: 33.655474
(Iteration 461 / 1170) loss: 33.348471
(Iteration 462 / 1170) loss: 33.158638
(Iteration 463 / 1170) loss: 33.153592
(Iteration 464 / 1170) loss: 33.303603
(Iteration 465 / 1170) loss: 33.292811
(Iteration 466 / 1170) loss: 33.542595
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(Iteration 467 / 1170) loss: 33.698990
(Iteration 468 / 1170) loss: 33.563057
(Iteration 469 / 1170) loss: 32.714531
(Iteration 470 / 1170) loss: 32.950740
(Iteration 471 / 1170) loss: 32.751261
(Iteration 472 / 1170) loss: 32.717498
(Iteration 473 / 1170) loss: 33.434564
(Iteration 474 / 1170) loss: 33.193851
(Iteration 475 / 1170) loss: 33.190127
(Iteration 476 / 1170) loss: 33.353590
(Iteration 477 / 1170) loss: 32.795355
(Iteration 478 / 1170) loss: 33.320396
(Iteration 479 / 1170) loss: 33.200352
(Iteration 480 / 1170) loss: 33.020380
(Iteration 481 / 1170) loss: 33.332993
(Iteration 482 / 1170) loss: 32.960230
(Iteration 483 / 1170) loss: 33.187581
(Iteration 484 / 1170) loss: 32.623760
(Iteration 485 / 1170) loss: 32.893347
(Iteration 486 / 1170) loss: 32.509182
(Iteration 487 / 1170) loss: 33.603365
(Iteration 488 / 1170) loss: 33.370716
(Iteration 489 / 1170) loss: 33.279617
(Iteration 490 / 1170) loss: 33.327044
(Iteration 491 / 1170) loss: 32.930262
(Iteration 492 / 1170) loss: 32.619970
(Iteration 493 / 1170) loss: 33.139073
(Iteration 494 / 1170) loss: 32.908674
(Iteration 495 / 1170) loss: 32.352402
(Iteration 496 / 1170) loss: 32.433681
(Iteration 497 / 1170) loss: 32.626423
(Iteration 498 / 1170) loss: 32.801581
(Iteration 499 / 1170) loss: 33.067539
(Iteration 500 / 1170) loss: 33.079359
(Iteration 501 / 1170) loss: 32.756391
(Iteration 502 / 1170) loss: 32.939887
(Iteration 503 / 1170) loss: 33.116890
(Iteration 504 / 1170) loss: 32.735933
(Iteration 505 / 1170) loss: 32.379567
(Iteration 506 / 1170) loss: 32.675950
(Iteration 507 / 1170) loss: 32.241672
(Iteration 508 / 1170) loss: 32.359516
(Iteration 509 / 1170) loss: 32.896862
(Iteration 510 / 1170) loss: 32.512261
(Iteration 511 / 1170) loss: 32.999227
(Iteration 512 / 1170) loss: 32.645263
(Iteration 513 / 1170) loss: 32.379482
(Iteration 514 / 1170) loss: 32.954073
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(Iteration 515 / 1170) loss: 32.149876
(Iteration 516 / 1170) loss: 32.225248
(Iteration 517 / 1170) loss: 32.857355
(Iteration 518 / 1170) loss: 32.158181
(Iteration 519 / 1170) loss: 31.657619
(Iteration 520 / 1170) loss: 32.681091
(Iteration 521 / 1170) loss: 32.874352
(Iteration 522 / 1170) loss: 32.513895
(Iteration 523 / 1170) loss: 32.371625
(Iteration 524 / 1170) loss: 32.389979
(Iteration 525 / 1170) loss: 32.732699
(Iteration 526 / 1170) loss: 32.414199
(Iteration 527 / 1170) loss: 32.162697
(Iteration 528 / 1170) loss: 32.658137
(Iteration 529 / 1170) loss: 32.756132
(Iteration 530 / 1170) loss: 32.481291
(Iteration 531 / 1170) loss: 32.160260
(Iteration 532 / 1170) loss: 32.545895
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(Iteration 535 / 1170) loss: 32.295389
(Iteration 536 / 1170) loss: 32.827657
(Iteration 537 / 1170) loss: 31.879670
(Iteration 538 / 1170) loss: 32.823324
(Iteration 539 / 1170) loss: 32.425885
(Iteration 540 / 1170) loss: 32.333622
(Iteration 541 / 1170) loss: 32.068654
(Iteration 542 / 1170) loss: 31.691115
(Iteration 543 / 1170) loss: 32.427284
(Iteration 544 / 1170) loss: 32.157501
(Iteration 545 / 1170) loss: 32.810479
(Iteration 546 / 1170) loss: 32.004972
(Iteration 547 / 1170) loss: 32.011385
(Iteration 548 / 1170) loss: 32.757092
(Iteration 549 / 1170) loss: 32.218461
(Iteration 550 / 1170) loss: 32.442353
(Iteration 551 / 1170) loss: 32.030827
(Iteration 552 / 1170) loss: 32.189922
(Iteration 553 / 1170) loss: 32.216837
(Iteration 554 / 1170) loss: 31.570212
(Iteration 555 / 1170) loss: 31.931412
(Iteration 556 / 1170) loss: 31.990476
(Iteration 557 / 1170) loss: 31.971198
(Iteration 558 / 1170) loss: 31.213170
(Iteration 559 / 1170) loss: 32.091260
(Iteration 560 / 1170) loss: 32.419030
(Iteration 561 / 1170) loss: 32.174844
(Iteration 562 / 1170) loss: 32.333550
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(Iteration 563 / 1170) loss: 31.784384
(Iteration 564 / 1170) loss: 32.042295
(Iteration 565 / 1170) loss: 31.845305
(Iteration 566 / 1170) loss: 32.639774
(Iteration 567 / 1170) loss: 31.881697
(Iteration 568 / 1170) loss: 32.425990
(Iteration 569 / 1170) loss: 32.038801
(Iteration 570 / 1170) loss: 31.942124
(Iteration 571 / 1170) loss: 32.178334
(Iteration 572 / 1170) loss: 32.944392
(Iteration 573 / 1170) loss: 32.210219
(Iteration 574 / 1170) loss: 32.003747
(Iteration 575 / 1170) loss: 31.911046
(Iteration 576 / 1170) loss: 31.528676
(Iteration 577 / 1170) loss: 31.871120
(Iteration 578 / 1170) loss: 31.586415
(Iteration 579 / 1170) loss: 32.020349
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(Iteration 583 / 1170) loss: 31.651657
(Iteration 584 / 1170) loss: 32.208650
(Iteration 585 / 1170) loss: 31.868022
(Iteration 586 / 1170) loss: 31.803422
(Iteration 587 / 1170) loss: 31.954733
(Iteration 588 / 1170) loss: 31.435778
(Iteration 589 / 1170) loss: 31.613750
(Iteration 590 / 1170) loss: 31.438791
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(Iteration 592 / 1170) loss: 31.737930
(Iteration 593 / 1170) loss: 31.320335
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(Iteration 595 / 1170) loss: 31.922990
(Iteration 596 / 1170) loss: 31.909592
(Iteration 597 / 1170) loss: 31.410951
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(Iteration 601 / 1170) loss: 31.450883
(Iteration 602 / 1170) loss: 31.149214
(Iteration 603 / 1170) loss: 32.082070
(Iteration 604 / 1170) loss: 31.331303
(Iteration 605 / 1170) loss: 31.235649
(Iteration 606 / 1170) loss: 31.593371
(Iteration 607 / 1170) loss: 31.650304
(Iteration 608 / 1170) loss: 32.436133
(Iteration 609 / 1170) loss: 31.482398
(Iteration 610 / 1170) loss: 31.337651
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(Iteration 612 / 1170) loss: 31.622641
(Iteration 613 / 1170) loss: 30.899109
(Iteration 614 / 1170) loss: 31.828537
(Iteration 615 / 1170) loss: 31.486409
(Iteration 616 / 1170) loss: 31.652059
(Iteration 617 / 1170) loss: 32.001517
(Iteration 618 / 1170) loss: 31.565428
(Iteration 619 / 1170) loss: 31.192610
(Iteration 620 / 1170) loss: 31.512387
(Iteration 621 / 1170) loss: 31.272529
(Iteration 622 / 1170) loss: 31.000339
(Iteration 623 / 1170) loss: 31.262548
(Iteration 624 / 1170) loss: 31.453422
(Iteration 625 / 1170) loss: 31.239857
(Iteration 626 / 1170) loss: 31.392993
(Iteration 627 / 1170) loss: 31.261834
(Iteration 628 / 1170) loss: 31.299854
(Iteration 629 / 1170) loss: 30.697519
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(Iteration 632 / 1170) loss: 31.284192
(Iteration 633 / 1170) loss: 30.677539
(Iteration 634 / 1170) loss: 31.001599
(Iteration 635 / 1170) loss: 31.727386
(Iteration 636 / 1170) loss: 31.343166
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(Iteration 638 / 1170) loss: 31.204257
(Iteration 639 / 1170) loss: 31.062858
(Iteration 640 / 1170) loss: 31.190932
(Iteration 641 / 1170) loss: 31.053907
(Iteration 642 / 1170) loss: 31.498789
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(Iteration 645 / 1170) loss: 31.031574
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(Iteration 648 / 1170) loss: 31.355442
(Iteration 649 / 1170) loss: 30.823586
(Iteration 650 / 1170) loss: 30.412247
(Iteration 651 / 1170) loss: 31.539554
(Iteration 652 / 1170) loss: 31.234986
(Iteration 653 / 1170) loss: 30.846187
(Iteration 654 / 1170) loss: 31.564078
(Iteration 655 / 1170) loss: 30.939418
(Iteration 656 / 1170) loss: 31.244746
(Iteration 657 / 1170) loss: 30.782312
(Iteration 658 / 1170) loss: 31.424211
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(Iteration 659 / 1170) loss: 31.200938
(Iteration 660 / 1170) loss: 30.994386
(Iteration 661 / 1170) loss: 31.064688
(Iteration 662 / 1170) loss: 30.568168
(Iteration 663 / 1170) loss: 30.940868
(Iteration 664 / 1170) loss: 30.321513
(Iteration 665 / 1170) loss: 30.519844
(Iteration 666 / 1170) loss: 30.706499
(Iteration 667 / 1170) loss: 30.766145
(Iteration 668 / 1170) loss: 30.926961
(Iteration 669 / 1170) loss: 31.691334
(Iteration 670 / 1170) loss: 30.628253
(Iteration 671 / 1170) loss: 31.260639
(Iteration 672 / 1170) loss: 30.667350
(Iteration 673 / 1170) loss: 30.696374
(Iteration 674 / 1170) loss: 30.651947
(Iteration 675 / 1170) loss: 30.741168
(Iteration 676 / 1170) loss: 31.035634
(Iteration 677 / 1170) loss: 30.803979
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(Iteration 679 / 1170) loss: 30.575737
(Iteration 680 / 1170) loss: 30.934694
(Iteration 681 / 1170) loss: 30.417181
(Iteration 682 / 1170) loss: 30.030339
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(Iteration 684 / 1170) loss: 30.557240
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(Iteration 687 / 1170) loss: 30.615136
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(Iteration 692 / 1170) loss: 31.011963
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(Iteration 695 / 1170) loss: 30.278503
(Iteration 696 / 1170) loss: 30.489433
(Iteration 697 / 1170) loss: 30.556171
(Iteration 698 / 1170) loss: 30.770118
(Iteration 699 / 1170) loss: 30.477635
(Iteration 700 / 1170) loss: 31.123422
(Iteration 701 / 1170) loss: 30.911183
(Iteration 702 / 1170) loss: 30.083101
(Iteration 703 / 1170) loss: 30.732318
(Iteration 704 / 1170) loss: 30.466698
(Iteration 705 / 1170) loss: 30.942748
(Iteration 706 / 1170) loss: 30.977583
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(Iteration 708 / 1170) loss: 30.824954
(Iteration 709 / 1170) loss: 30.274673
(Iteration 710 / 1170) loss: 30.544743
(Iteration 711 / 1170) loss: 30.617080
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(Iteration 715 / 1170) loss: 29.647310
(Iteration 716 / 1170) loss: 30.258734
(Iteration 717 / 1170) loss: 30.663590
(Iteration 718 / 1170) loss: 30.415042
(Iteration 719 / 1170) loss: 30.611797
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(Iteration 725 / 1170) loss: 30.084793
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(Iteration 727 / 1170) loss: 30.364411
(Iteration 728 / 1170) loss: 30.480105
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(Iteration 743 / 1170) loss: 29.736850
(Iteration 744 / 1170) loss: 30.046070
(Iteration 745 / 1170) loss: 30.106753
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(Iteration 749 / 1170) loss: 30.097480
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(Iteration 752 / 1170) loss: 29.865327
(Iteration 753 / 1170) loss: 30.452962
(Iteration 754 / 1170) loss: 29.800002
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(Iteration 756 / 1170) loss: 30.305423
(Iteration 757 / 1170) loss: 29.924702
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(Iteration 791 / 1170) loss: 30.237704
(Iteration 792 / 1170) loss: 29.633130
(Iteration 793 / 1170) loss: 29.446157
(Iteration 794 / 1170) loss: 29.795023
(Iteration 795 / 1170) loss: 29.397883
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(Iteration 800 / 1170) loss: 29.691524
(Iteration 801 / 1170) loss: 29.611999
(Iteration 802 / 1170) loss: 29.543875
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(Iteration 804 / 1170) loss: 29.706596
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(Iteration 807 / 1170) loss: 29.694111
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(Iteration 814 / 1170) loss: 29.280775
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(Iteration 844 / 1170) loss: 29.264774
(Iteration 845 / 1170) loss: 29.420155
(Iteration 846 / 1170) loss: 29.656248
(Iteration 847 / 1170) loss: 29.314509
(Iteration 848 / 1170) loss: 29.969110
(Iteration 849 / 1170) loss: 29.518102
(Iteration 850 / 1170) loss: 29.437379
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(Iteration 852 / 1170) loss: 29.958328
(Iteration 853 / 1170) loss: 30.013861
(Iteration 854 / 1170) loss: 29.415234
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(Iteration 887 / 1170) loss: 29.087414
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(Iteration 889 / 1170) loss: 28.969185
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(Iteration 893 / 1170) loss: 28.844422
(Iteration 894 / 1170) loss: 29.550295
(Iteration 895 / 1170) loss: 29.303578
(Iteration 896 / 1170) loss: 29.228292
(Iteration 897 / 1170) loss: 28.423250
(Iteration 898 / 1170) loss: 29.308155
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(Iteration 899 / 1170) loss: 29.058048
(Iteration 900 / 1170) loss: 28.896022
(Iteration 901 / 1170) loss: 28.873905
(Iteration 902 / 1170) loss: 29.333270
(Iteration 903 / 1170) loss: 28.999651
(Iteration 904 / 1170) loss: 29.349183
(Iteration 905 / 1170) loss: 29.021035
(Iteration 906 / 1170) loss: 29.204844
(Iteration 907 / 1170) loss: 28.813579
(Iteration 908 / 1170) loss: 29.191886
(Iteration 909 / 1170) loss: 29.038770
(Iteration 910 / 1170) loss: 28.988775
(Iteration 911 / 1170) loss: 29.041550
(Iteration 912 / 1170) loss: 29.494369
(Iteration 913 / 1170) loss: 28.721753
(Iteration 914 / 1170) loss: 29.275927
(Iteration 915 / 1170) loss: 28.741681
(Iteration 916 / 1170) loss: 29.086756
(Iteration 917 / 1170) loss: 29.408208
(Iteration 918 / 1170) loss: 28.774981
(Iteration 919 / 1170) loss: 28.982913
(Iteration 920 / 1170) loss: 28.694968
(Iteration 921 / 1170) loss: 29.193428
(Iteration 922 / 1170) loss: 28.577763
(Iteration 923 / 1170) loss: 28.887023
(Iteration 924 / 1170) loss: 28.941964
(Iteration 925 / 1170) loss: 28.724439
(Iteration 926 / 1170) loss: 29.481298
(Iteration 927 / 1170) loss: 28.984663
(Iteration 928 / 1170) loss: 29.205435
(Iteration 929 / 1170) loss: 29.315587
(Iteration 930 / 1170) loss: 29.388203
(Iteration 931 / 1170) loss: 28.876854
(Iteration 932 / 1170) loss: 28.632212
(Iteration 933 / 1170) loss: 28.997329
(Iteration 934 / 1170) loss: 29.022588
(Iteration 935 / 1170) loss: 28.904659
(Iteration 936 / 1170) loss: 28.674420
(Iteration 937 / 1170) loss: 29.151163
(Iteration 938 / 1170) loss: 29.308904
(Iteration 939 / 1170) loss: 29.001241
(Iteration 940 / 1170) loss: 28.967791
(Iteration 941 / 1170) loss: 29.231370
(Iteration 942 / 1170) loss: 28.937086
(Iteration 943 / 1170) loss: 29.109665
(Iteration 944 / 1170) loss: 29.713266
(Iteration 945 / 1170) loss: 28.334617
(Iteration 946 / 1170) loss: 28.775995
```

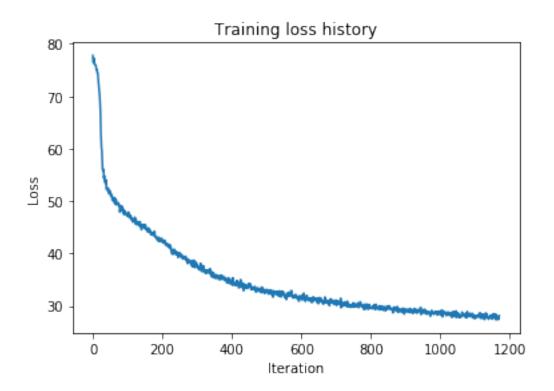
```
(Iteration 947 / 1170) loss: 29.232653
(Iteration 948 / 1170) loss: 29.115159
(Iteration 949 / 1170) loss: 28.616220
(Iteration 950 / 1170) loss: 28.965920
(Iteration 951 / 1170) loss: 28.701441
(Iteration 952 / 1170) loss: 28.798769
(Iteration 953 / 1170) loss: 29.322617
(Iteration 954 / 1170) loss: 29.350177
(Iteration 955 / 1170) loss: 29.022612
(Iteration 956 / 1170) loss: 28.597863
(Iteration 957 / 1170) loss: 29.242333
(Iteration 958 / 1170) loss: 28.732268
(Iteration 959 / 1170) loss: 29.137053
(Iteration 960 / 1170) loss: 28.787869
(Iteration 961 / 1170) loss: 28.745462
(Iteration 962 / 1170) loss: 28.367417
(Iteration 963 / 1170) loss: 28.904983
(Iteration 964 / 1170) loss: 28.719763
(Iteration 965 / 1170) loss: 28.908716
(Iteration 966 / 1170) loss: 28.532066
(Iteration 967 / 1170) loss: 28.935602
(Iteration 968 / 1170) loss: 28.511464
(Iteration 969 / 1170) loss: 28.452648
(Iteration 970 / 1170) loss: 28.664457
(Iteration 971 / 1170) loss: 28.713876
(Iteration 972 / 1170) loss: 28.034597
(Iteration 973 / 1170) loss: 28.469428
(Iteration 974 / 1170) loss: 28.909980
(Iteration 975 / 1170) loss: 28.846037
(Iteration 976 / 1170) loss: 29.155126
(Iteration 977 / 1170) loss: 28.632205
(Iteration 978 / 1170) loss: 28.676081
(Iteration 979 / 1170) loss: 28.913345
(Iteration 980 / 1170) loss: 28.578561
(Iteration 981 / 1170) loss: 28.613226
(Iteration 982 / 1170) loss: 28.369245
(Iteration 983 / 1170) loss: 28.622429
(Iteration 984 / 1170) loss: 28.725235
(Iteration 985 / 1170) loss: 28.684964
(Iteration 986 / 1170) loss: 28.844841
(Iteration 987 / 1170) loss: 28.972614
(Iteration 988 / 1170) loss: 28.634971
(Iteration 989 / 1170) loss: 28.618245
(Iteration 990 / 1170) loss: 28.777486
(Iteration 991 / 1170) loss: 28.716851
(Iteration 992 / 1170) loss: 28.281896
(Iteration 993 / 1170) loss: 28.949652
(Iteration 994 / 1170) loss: 28.427868
```

```
(Iteration 995 / 1170) loss: 28.289375
(Iteration 996 / 1170) loss: 28.440379
(Iteration 997 / 1170) loss: 28.737136
(Iteration 998 / 1170) loss: 28.970435
(Iteration 999 / 1170) loss: 28.585170
(Iteration 1000 / 1170) loss: 28.537002
(Iteration 1001 / 1170) loss: 28.853405
(Iteration 1002 / 1170) loss: 29.061061
(Iteration 1003 / 1170) loss: 28.239023
(Iteration 1004 / 1170) loss: 29.000617
(Iteration 1005 / 1170) loss: 29.135170
(Iteration 1006 / 1170) loss: 28.551154
(Iteration 1007 / 1170) loss: 27.920559
(Iteration 1008 / 1170) loss: 29.080961
(Iteration 1009 / 1170) loss: 28.593395
(Iteration 1010 / 1170) loss: 28.380071
(Iteration 1011 / 1170) loss: 28.559377
(Iteration 1012 / 1170) loss: 28.807022
(Iteration 1013 / 1170) loss: 28.904998
(Iteration 1014 / 1170) loss: 28.504866
(Iteration 1015 / 1170) loss: 28.719703
(Iteration 1016 / 1170) loss: 28.441040
(Iteration 1017 / 1170) loss: 28.676281
(Iteration 1018 / 1170) loss: 28.121957
(Iteration 1019 / 1170) loss: 28.628628
(Iteration 1020 / 1170) loss: 28.781378
(Iteration 1021 / 1170) loss: 28.425756
(Iteration 1022 / 1170) loss: 28.672018
(Iteration 1023 / 1170) loss: 28.333944
(Iteration 1024 / 1170) loss: 28.816378
(Iteration 1025 / 1170) loss: 28.234842
(Iteration 1026 / 1170) loss: 28.326254
(Iteration 1027 / 1170) loss: 28.500720
(Iteration 1028 / 1170) loss: 28.616619
(Iteration 1029 / 1170) loss: 28.139319
(Iteration 1030 / 1170) loss: 28.466767
(Iteration 1031 / 1170) loss: 28.304872
(Iteration 1032 / 1170) loss: 28.304780
(Iteration 1033 / 1170) loss: 28.742356
(Iteration 1034 / 1170) loss: 27.788925
(Iteration 1035 / 1170) loss: 28.178090
(Iteration 1036 / 1170) loss: 28.502421
(Iteration 1037 / 1170) loss: 28.184158
(Iteration 1038 / 1170) loss: 28.943661
(Iteration 1039 / 1170) loss: 28.355858
(Iteration 1040 / 1170) loss: 28.099197
(Iteration 1041 / 1170) loss: 28.421258
(Iteration 1042 / 1170) loss: 28.206057
```

```
(Iteration 1043 / 1170) loss: 28.677556
(Iteration 1044 / 1170) loss: 27.917520
(Iteration 1045 / 1170) loss: 28.776106
(Iteration 1046 / 1170) loss: 29.035018
(Iteration 1047 / 1170) loss: 28.320558
(Iteration 1048 / 1170) loss: 27.795305
(Iteration 1049 / 1170) loss: 28.242135
(Iteration 1050 / 1170) loss: 28.684234
(Iteration 1051 / 1170) loss: 28.017025
(Iteration 1052 / 1170) loss: 28.617441
(Iteration 1053 / 1170) loss: 27.915142
(Iteration 1054 / 1170) loss: 28.417297
(Iteration 1055 / 1170) loss: 28.184423
(Iteration 1056 / 1170) loss: 28.234795
(Iteration 1057 / 1170) loss: 27.771163
(Iteration 1058 / 1170) loss: 28.016220
(Iteration 1059 / 1170) loss: 27.763667
(Iteration 1060 / 1170) loss: 28.084024
(Iteration 1061 / 1170) loss: 28.222109
(Iteration 1062 / 1170) loss: 28.207939
(Iteration 1063 / 1170) loss: 28.810936
(Iteration 1064 / 1170) loss: 28.620083
(Iteration 1065 / 1170) loss: 28.137360
(Iteration 1066 / 1170) loss: 28.469947
(Iteration 1067 / 1170) loss: 28.240817
(Iteration 1068 / 1170) loss: 28.195230
(Iteration 1069 / 1170) loss: 28.395139
(Iteration 1070 / 1170) loss: 28.260399
(Iteration 1071 / 1170) loss: 27.894241
(Iteration 1072 / 1170) loss: 28.459563
(Iteration 1073 / 1170) loss: 28.466285
(Iteration 1074 / 1170) loss: 28.000565
(Iteration 1075 / 1170) loss: 28.528651
(Iteration 1076 / 1170) loss: 27.713833
(Iteration 1077 / 1170) loss: 27.870103
(Iteration 1078 / 1170) loss: 28.905975
(Iteration 1079 / 1170) loss: 28.506766
(Iteration 1080 / 1170) loss: 28.037633
(Iteration 1081 / 1170) loss: 28.502402
(Iteration 1082 / 1170) loss: 28.280396
(Iteration 1083 / 1170) loss: 28.022912
(Iteration 1084 / 1170) loss: 28.444705
(Iteration 1085 / 1170) loss: 28.305708
(Iteration 1086 / 1170) loss: 28.542622
(Iteration 1087 / 1170) loss: 28.522181
(Iteration 1088 / 1170) loss: 27.890638
(Iteration 1089 / 1170) loss: 28.381683
(Iteration 1090 / 1170) loss: 28.189118
```

```
(Iteration 1091 / 1170) loss: 28.368537
(Iteration 1092 / 1170) loss: 28.574107
(Iteration 1093 / 1170) loss: 28.481975
(Iteration 1094 / 1170) loss: 28.182890
(Iteration 1095 / 1170) loss: 27.715921
(Iteration 1096 / 1170) loss: 28.338725
(Iteration 1097 / 1170) loss: 28.129565
(Iteration 1098 / 1170) loss: 27.984473
(Iteration 1099 / 1170) loss: 27.612157
(Iteration 1100 / 1170) loss: 27.539009
(Iteration 1101 / 1170) loss: 27.875686
(Iteration 1102 / 1170) loss: 28.157067
(Iteration 1103 / 1170) loss: 27.916055
(Iteration 1104 / 1170) loss: 28.104660
(Iteration 1105 / 1170) loss: 27.860556
(Iteration 1106 / 1170) loss: 28.159342
(Iteration 1107 / 1170) loss: 27.953799
(Iteration 1108 / 1170) loss: 27.888603
(Iteration 1109 / 1170) loss: 28.002741
(Iteration 1110 / 1170) loss: 28.275730
(Iteration 1111 / 1170) loss: 28.347819
(Iteration 1112 / 1170) loss: 28.446450
(Iteration 1113 / 1170) loss: 28.089102
(Iteration 1114 / 1170) loss: 28.127514
(Iteration 1115 / 1170) loss: 28.686746
(Iteration 1116 / 1170) loss: 27.638460
(Iteration 1117 / 1170) loss: 28.304120
(Iteration 1118 / 1170) loss: 28.131632
(Iteration 1119 / 1170) loss: 28.362445
(Iteration 1120 / 1170) loss: 27.633282
(Iteration 1121 / 1170) loss: 28.073806
(Iteration 1122 / 1170) loss: 28.044797
(Iteration 1123 / 1170) loss: 28.375480
(Iteration 1124 / 1170) loss: 27.677307
(Iteration 1125 / 1170) loss: 27.814703
(Iteration 1126 / 1170) loss: 28.359944
(Iteration 1127 / 1170) loss: 28.001617
(Iteration 1128 / 1170) loss: 27.384863
(Iteration 1129 / 1170) loss: 28.181642
(Iteration 1130 / 1170) loss: 28.403436
(Iteration 1131 / 1170) loss: 28.191006
(Iteration 1132 / 1170) loss: 28.650015
(Iteration 1133 / 1170) loss: 28.089381
(Iteration 1134 / 1170) loss: 28.377556
(Iteration 1135 / 1170) loss: 27.724679
(Iteration 1136 / 1170) loss: 28.013137
(Iteration 1137 / 1170) loss: 27.693455
(Iteration 1138 / 1170) loss: 27.961595
```

```
(Iteration 1139 / 1170) loss: 27.907114
(Iteration 1140 / 1170) loss: 27.443694
(Iteration 1141 / 1170) loss: 27.968376
(Iteration 1142 / 1170) loss: 27.841702
(Iteration 1143 / 1170) loss: 27.846533
(Iteration 1144 / 1170) loss: 28.111039
(Iteration 1145 / 1170) loss: 27.837913
(Iteration 1146 / 1170) loss: 28.237898
(Iteration 1147 / 1170) loss: 27.659699
(Iteration 1148 / 1170) loss: 27.706018
(Iteration 1149 / 1170) loss: 28.220831
(Iteration 1150 / 1170) loss: 27.795767
(Iteration 1151 / 1170) loss: 27.472485
(Iteration 1152 / 1170) loss: 28.357459
(Iteration 1153 / 1170) loss: 27.775586
(Iteration 1154 / 1170) loss: 28.361578
(Iteration 1155 / 1170) loss: 28.505262
(Iteration 1156 / 1170) loss: 28.079944
(Iteration 1157 / 1170) loss: 27.727539
(Iteration 1158 / 1170) loss: 28.288190
(Iteration 1159 / 1170) loss: 27.729254
(Iteration 1160 / 1170) loss: 28.437921
(Iteration 1161 / 1170) loss: 27.352448
(Iteration 1162 / 1170) loss: 27.378884
(Iteration 1163 / 1170) loss: 28.022717
(Iteration 1164 / 1170) loss: 27.830514
(Iteration 1165 / 1170) loss: 27.779283
(Iteration 1166 / 1170) loss: 28.005814
(Iteration 1167 / 1170) loss: 27.377732
(Iteration 1168 / 1170) loss: 27.470774
(Iteration 1169 / 1170) loss: 27.504349
(Iteration 1170 / 1170) loss: 28.120129
```



```
LSTM score:
Average BLEU score for train: 0.175831
Average BLEU score for val: 0.168395
My model score:
Average BLEU score for train: 0.316566
Average BLEU score for val: 0.307564
In [ ]: print("My model score:")
        evaluate_model(my_lstm_model)
In [17]: for split in ['train', 'val']:
             minibatch = sample_coco_minibatch(my_data, split=split, batch_size=2)
             gt_captions, features, urls = minibatch
             gt_captions = decode_captions(gt_captions, data['idx_to_word'])
             sample_captions = my_lstm_model.sample(features)
             sample_captions = decode_captions(sample_captions, data['idx_to_word'])
             for gt_caption, sample_caption, url in zip(gt_captions, sample_captions, urls):
                 plt.imshow(image_from_url(url))
                 plt.title('%s\n%s\nGT:%s' % (split, sample_caption, gt_caption))
                 plt.axis('off')
                 plt.show()
```

train
a dog is sitting on a bench with a <UNK> <END>
GT:<START> a <UNK> kitten walks in the grass around <UNK> foot <END>



train
a kitchen with a sink and a refrigerator <END>
GT:<START> a desk sitting next to a refrigerator microwave oven and mirror <END>



val
a bathroom with a toilet and a mirror in the mirror <END>
GT:<START> a small sink in a cabinet lies in a <UNK> <END>



val
a cat laying on top of a couch <END>
GT:<START> a cat sleeping on a bed with <UNK> <UNK> on top of him <END>



- 2.3 Transformer Classification
- 2.3.1 Ipython notebook

Transformer_Classification

October 23, 2019

1 Sentence Classification with Transformers

In this exercise you will implement a Transformer and use it to judge the grammaticality of English sentences.

A quick note: if you receive the following TypeError "super(type, obj): obj must be an instance or subtype of type", try restarting your kernel and re-running all cells. Once you have finished making changes to the model constuctor, you can avoid this issue by commenting out all of the model instantiations after the first (e.g. lines starting with "model = ClassificationTransformer").

```
In [1]: import numpy as np
    import csv
    import torch

from gt_7643.transformer import ClassificationTransformer

# for auto-reloading external modules
    # see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
    %load_ext autoreload
    %autoreload 2
```

1.1 The Corpus of Linguistic Acceptability (CoLA)

The Corpus of Linguistic Acceptability (CoLA) in its full form consists of 10657 sentences from 23 linguistics publications, expertly annotated for acceptability (grammaticality) by their original authors. Native English speakers consistently report a sharp contrast in acceptability between pairs of sentences. Some examples include:

```
What did Betsy paint a picture of? (Correct)
What was a picture of painted by Betsy? (Incorrect)
```

You can read more info about the dataset here. This is a binary classification task (predict 1 for correct grammar and 0 otherwise).

Can we train a neural network to accurately predict these human acceptability judgements? In this assignment, we will implement the forward pass of the Transformer architecture discussed in class. The general intuitive notion is that we will *encode* the sequence of tokens in the sentence, and then predict a binary output based on the final state that is the output of the model.

1.2 Load the preprocessed data

We've appended a "CLS" token to the beginning of each sequence, which can be used to make predictions. The benefit of appending this token to the beginning of the sequence (rather than the end) is that we can extract it quite easily (we don't need to remove paddings and figure out the length of each individual sequence in the batch). We'll come back to this.

We've additionally already constructed a vocabulary and converted all of the strings of tokens into integers which can be used for vocabulary lookup for you. Feel free to explore the data here.

```
In [2]: train_inxs = np.load('./gt_7643/datasets/train_inxs.npy')
        val_inxs = np.load('./gt_7643/datasets/val_inxs.npy')
        train_labels = np.load('./gt_7643/datasets/train_labels.npy')
        val_labels = np.load('./gt_7643/datasets/val_labels.npy')
        # load dictionary
        word_to_ix = {}
        with open("./gt_7643/datasets/word_to_ix.csv", "r") as f:
            reader = csv.reader(f)
            for line in reader:
                word_to_ix[line[0]] = line[1]
        print("Vocabulary Size:", len(word_to_ix))
        print(train_inxs.shape) # 7000 training instances, of (maximum/padded) length 43 words
        print(val_inxs.shape) # 1551 validation instances, of (maximum/padded) length 43 words
        print(train_labels.shape)
        print(val_labels.shape)
        # load checkers
        d1 = torch.load('./gt_7643/datasets/d1.pt')
        d2 = torch.load('./gt_7643/datasets/d2.pt')
        d3 = torch.load('./gt_7643/datasets/d3.pt')
        d4 = torch.load('./gt_7643/datasets/d4.pt')
Vocabulary Size: 1542
(7000, 43)
(1551, 43)
(7000,)
(1551,)
```

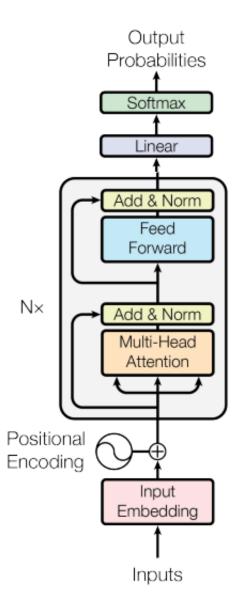
1.3 Transformers

We will be implementing a one-layer Transformer **encoder** which, similar to an RNN, can encode a sequence of inputs and produce a final output state for classification. This is the architecture:

You can refer to the original paper for more details.

Instead of using numpy for this model, we will be using Pytorch to implement the forward pass. You will not need to implement the backward pass for the various layers in this assignment.

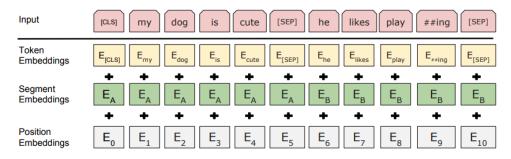
The file gt_7643/transformer.py contains the model class and methods for each layer. This is where you will write your implementations.



imgs/encoder.png

1.4 Deliverable 1: Embeddings

We will format our input embeddings similarly to how they are constructed in BERT (source of figure). Recall from lecture that unlike a RNN, a Transformer does not include any positional information about the order in which the words in the sentence occur. Because of this, we need to append a positional encoding token at each position. (We will ignore the segment embeddings and [SEP] token here, since we are only encoding one sentence at a time). We have already appended the [CLS] token for you in the previous step.



Your first task is to implement the embedding lookup, including the addition of positional encodings. Open the file gt_7643/transformer.py and complete all code parts for Deliverable 1.

Difference: 0.0017998494440689683

1.5 Deliverable 2: Multi-head Self-Attention

Attention can be computed in matrix-form using the following formula:

$$\operatorname{Attention}(Q, K, V) = \operatorname{softmax}(\frac{QK^T}{\sqrt{d_k}})V$$

We want to have multiple self-attention operations, computed in parallel. Each of these is called a *head*. We concatenate the heads and multiply them with the matrix attention_head_projection to produce the output of this layer.

$$FFN(x) = \max(0, xW_1 + b_1)W_2 + b_2$$

imgs/ffn.png

After every multi-head self-attention and feedforward layer, there is a residual connection + layer normalization. Make sure to implement this, using the following formula:

LayerNorm(x + Sublayer(x))

Open the file gt_7643/transformer.py and implement the multihead_attention function. We have already initialized all of the layers you will need in the constructor.

1.6 Deliverable 3: Element-Wise Feed-forward Layer

Open the file gt_7643/transformer.py and complete code for Deliverable 3: the element-wise feed-forward layer consisting of two linear transformers with a ReLU layer in between.

1.7 Deliverable 4: Final Layer

Open the file gt_7643/transformer.py and complete code for Deliverable 4, to produce binary classification scores for the inputs based on the output of the Transformer.

```
try:
    print("Difference:", torch.sum(torch.pairwise_distance(scores, d4)).item()) # shou
except Exception as e:
    print(e)
    print("NOT IMPLEMENTED")
```

Difference: 0.432945191860199

1.8 Deliverable 5: Putting it all together

Open the file gt_7643/transformer.py and complete the method forward, by putting together all of the methods you have developed in the right order to perform a full forward pass.

```
In [7]: inputs = train_inxs[0:2]
    inputs = torch.LongTensor(inputs)

outputs = model.forward(inputs)

try:
    print("Difference:", torch.sum(torch.pairwise_distance(outputs, scores)).item()) #
except:
    print("NOT IMPLEMENTED")
```

Difference: 1.999999949504854e-06

Great! We've just implemented a Transformer forward pass for text classification. One of the big perks of using PyTorch is that with a simple training loop, we can rely on automatic differentation (autograd) to do the work of the backward pass for us. This is not required for this assignment, but you can explore this on your own.

Make sure when you submit your PDF for this assignment to also include a copy of transformer.py converted to PDF as well.

2.3.2 Python code

```
2
3
4
   mport numpy as np
5
   import torch
6
   rom torch import nn
7
8
   mport random
9
10
11
12
   class ClassificationTransformer(nn.Module):
13
14
15
16
17
18
19
20
21
22
       def __init__(self, word_to_ix, hidden_dim=128, num_heads=2, dim_feedforward=2048, dim_k
23
       =96, dim_v=96, dim_q=96,
24
                    max_length=43):
25
26
27
28
29
30
31
32
33
           super(ClassificationTransformer, self).__init__()
34
           assert hidden_dim % num_heads == 0
35
36
           self.num_heads = num_heads
37
38
           self.word_embedding_dim = hidden_dim
           self.hidden_dim = hidden_dim
39
40
           self.dim_feedforward = dim_feedforward
           self.max_length = max_length
41
42
           self.vocab_size = len(word_to_ix)
43
44
           self.dim_k = dim_k
           self.dim_v = dim_v
45
           self.dim_q = dim_q
46
47
           seed torch(0)
48
49
50
51
52
53
           self.embedding_voc = nn.Embedding(num_embeddings=self.vocab_size, embedding_dim=self
54
       .hidden_dim)
           self.embedding_pos = nn.Embedding(num_embeddings=self.max_length, embedding_dim=self
55
       .hidden_dim)
           self.sqrt_dim_k = torch.sqrt(torch.Tensor([self.dim_k]))
56
57
58
59
60
61
62
```

```
63
64
65
66
            self.k1 = nn.Linear(self.hidden_dim, self.dim_k)
67
            self.v1 = nn.Linear(self.hidden_dim, self.dim_v)
68
            self.q1 = nn.Linear(self.hidden_dim, self.dim_q)
69
70
71
            self.k2 = nn.Linear(self.hidden_dim, self.dim_k)
72
            self.v2 = nn.Linear(self.hidden_dim, self.dim_v)
73
            self.q2 = nn.Linear(self.hidden_dim, self.dim_q)
74
75
            self.softmax = nn.Softmax(dim=2)
76
            self.attention_head_projection = nn.Linear(self.dim_v * self.num_heads, self.
77
       hidden dim)
            self.norm_mh = nn.LayerNorm(self.hidden_dim)
78
79
80
81
82
83
            self.relu = nn.ReLU()
84
            self.ff_transform1 = nn.Linear(self.hidden_dim, self.dim_feedforward)
85
            self.ff_transform2 = nn.Linear(self.dim_feedforward, self.hidden_dim)
86
            self.norm_ff = nn.LayerNorm(self.hidden_dim)
87
88
89
90
91
92
93
94
            self.sigmoid = nn.Sigmoid()
95
            self.output_layer = nn.Linear(self.hidden_dim * self.max_length, 1)
96
97
98
99
100
        def forward(self, inputs):
104
106
107
108
109
110
111
112
113
114
115
116
            outputs = self.final_layer(self.feedforward_layer(self.multi_head_attention(self.
        embed(inputs))))
117
118
119
            return outputs
120
121
       def embed(self, inputs):
122
123
124
125
126
127
```

```
130
            embeddings = self.embedding_voc(inputs)
            N, T = inputs.shape
134
135
            r = torch.arange(T).reshape((1, T))
            c = torch.ones((N, 1), dtype=torch.long)
136
            p = torch.mm(c, r)
137
            embeddings += self.embedding_pos(p)
138
139
140
141
            return embeddings
142
143
       def multi_head_attention(self, inputs):
144
145
146
147
148
149
151
152
154
155
156
            head1 = self.softmax(self.q1(inputs) @ self.k1(inputs).transpose(1, 2) / self.
157
        sqrt_dim_k) @ self.v1(inputs)
            head2 = self.softmax(self.q2(inputs) @ self.k2(inputs).transpose(1, 2) / self.
158
        sqrt_dim_k) @ self.v2(inputs)
            attention = self.attention_head_projection(torch.cat((head1, head2), 2))
            outputs = self.norm_mh(inputs + attention)
160
161
162
163
            return outputs
164
165
        def feedforward_layer(self, inputs):
166
167
168
169
170
171
173
174
175
176
177
            outputs = self.norm_ff(inputs + self.ff_transform2(self.relu(self.ff_transform1()))
178
        inputs))))
179
180
181
            return outputs
182
183
       def final_layer(self, inputs):
184
185
186
187
188
189
190
191
192
193
```

```
outputs = self.sigmoid(self.output_layer(inputs.reshape((inputs.shape[0], -1))))
194
         195
196
197
         return outputs
198
199
200
   lef seed_torch(seed=0):
201
      random.seed(seed)
202
      np.random.seed(seed)
203
      torch.manual_seed(seed)
204
      torch.cuda.manual_seed(seed)
205
      torch.backends.cudnn.benchmark = False
206
207
      torch.backends.cudnn.deterministic = True
```