

## UNION-FIND

- ▶ *union by size*
- ▶ *link-by-rank*
- ▶ *path compression*
- ▶ *link-by-rank with path compression*
- ▶ *context*

Lecture slides by Kevin Wayne

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<http://www.cs.princeton.edu/~wayne/kleinberg-tardos>

Last updated on Sep 8, 2013 7:01 AM

## Disjoint sets data type

**Goal.** Support two operations on a set of elements:

- MAKE-SET( $x$ ). Create a new set containing only element  $x$ .
- FIND( $x$ ). Return a canonical element in the set containing  $x$ .
- UNION( $x, y$ ). Merge the sets containing  $x$  and  $y$ .

**Dynamic connectivity.** Given an initial empty graph  $G$  on  $n$  nodes, support the following queries:

- ADD-EDGE( $u, v$ ). Add an edge between nodes  $u$  and  $v$ . ← 1 union operation
- IS-CONNECTED( $u, v$ ). Is there a path between  $u$  and  $v$ ? ← 2 find operations

## Disjoint sets data type: applications

**Original motivation.** Compiling EQUIVALENCE, DIMENSION, and COMMON statements in Fortran.

### An Improved Equivalence Algorithm

BERNARD A. GALLER AND MICHAEL J. FISHER  
University of Michigan, Ann Arbor, Michigan

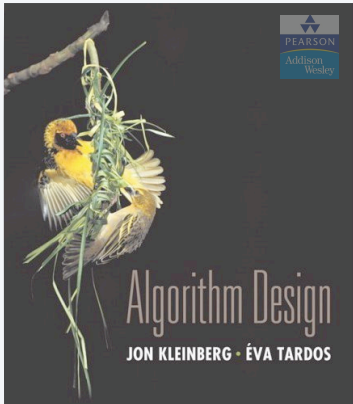
An algorithm for assigning storage on the basis of EQUIVALENCE, DIMENSION and COMMON declarations is presented. The algorithm is based on a tree structure, and has reduced computation time by 40 percent over a previously published algorithm by identifying all equivalence classes with one scan of the EQUIVALENCE declarations. The method is applicable in any problem in which it is necessary to identify equivalence classes, given the element pairs defining the equivalence relation.

**Note.** This 1964 paper also introduced key data structure for problem.

## Disjoint sets data type: applications

### Applications.

- Percolation.
- Kruskal's algorithm.
- Connected components.
- Computing LCAs in trees.
- Computing dominators in digraphs.
- Equivalence of finite state automata.
- Checking flow graphs for reducibility.
- Hoshen-Kopelman algorithm in physics.
- Hinley-Milner polymorphic type inference.
- Morphological attribute openings and closings.
- Matlab's BW-LABEL() function for image processing.
- Compiling EQUIVALENCE, DIMENSION and COMMON statements in Fortran.
- ...



## SECTION 4.6

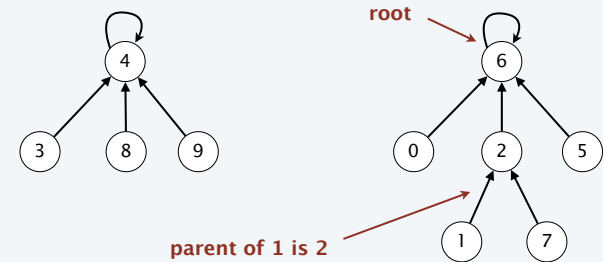
### UNION-FIND

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- ▶ *context*

### Disjoint-sets data structure

**Representation.** Represent each set as a tree of elements.

- Each element has a parent pointer in the tree.
- The root serves as the canonical element.
- $\text{FIND}(x)$ . Find the root of the tree containing  $x$ .
- $\text{UNION}(x, y)$ . Make the root of one tree point to root of other tree.



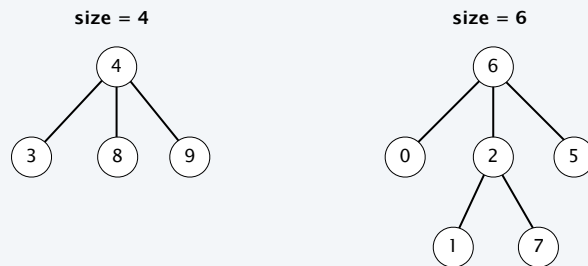
**Note.** For brevity, we suppress arrows and self loops in figures.

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### Link-by-size

**Link-by-size.** Maintain a subtree count for each node, initially 1. Link root of smaller tree to root of larger tree (breaking ties arbitrarily).

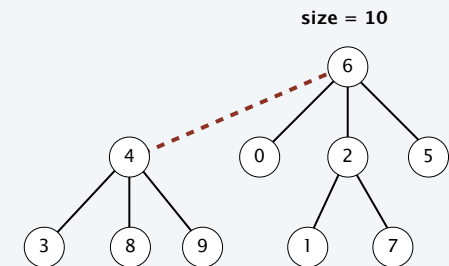
**union(7, 3)**



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**union(7, 3)**



## Link-by-size

**Link-by-size.** Maintain a subtree count for each node, initially 1.  
Link root of smaller tree to root of larger tree (breaking ties arbitrarily).

**MAKE-SET** ( $x$ )

$\text{parent}(x) \leftarrow x.$

$\text{size}(x) \leftarrow 1.$

**FIND** ( $x$ )

**WHILE** ( $x \neq \text{parent}(x)$ )

$x \leftarrow \text{parent}(x).$

**RETURN**  $x.$

**UNION-BY-SIZE** ( $x, y$ )

$r \leftarrow \text{FIND}(x).$

$s \leftarrow \text{FIND}(y).$

**IF** ( $r = s$ ) **RETURN.**

**ELSE IF** ( $\text{size}(r) > \text{size}(s)$ )

$\text{parent}(s) \leftarrow r.$

$\text{size}(r) \leftarrow \text{size}(r) + \text{size}(s).$

**ELSE**

$\text{parent}(r) \leftarrow s.$

$\text{size}(s) \leftarrow \text{size}(r) + \text{size}(s).$

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## Link-by-size: analysis

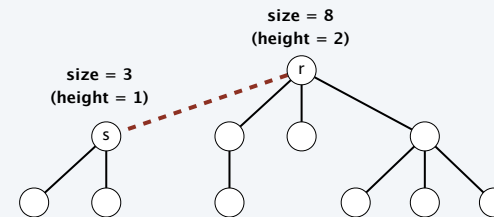
**Property.** Using link-by-size, for every root node  $r$ ,  $\text{size}(r) \geq 2^{\text{height}(r)}$ .

**Pf.** [ by induction on number of links ]

- Base case: singleton tree has size 1 and height 0.
- Inductive hypothesis: assume true after first  $i$  links.
- Tree rooted at  $r$  changes only when a smaller tree rooted at  $s$  is linked into  $r$ .
- Case 1. [  $\text{height}(r) > \text{height}(s)$  ]  $\text{size}'(r) \geq \text{size}(r)$

$$\geq 2^{\text{height}(r)} \quad \leftarrow \text{inductive hypothesis}$$

$$= 2^{\text{height}'(r)}.$$



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## Link-by-size: analysis

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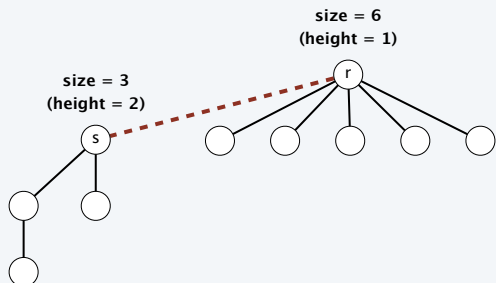
- Base case: singleton tree has size 1 and height 0.
- Inductive hypothesis: assume true after first  $i$  links.
- Tree rooted at  $r$  changes only when a smaller tree rooted at  $s$  is linked into  $r$ .
- Case 2. [  $\text{height}(r) \leq \text{height}(s)$  ]  $\text{size}'(r) = \text{size}(r) + \text{size}(s)$

$$\geq 2 \text{size}(s) \quad \leftarrow \text{link-by-size}$$

$$\geq 2 \cdot 2^{\text{height}(s)} \quad \leftarrow \text{inductive hypothesis}$$

$$= 2^{\text{height}(s) + 1}$$

$$= 2^{\text{height}'(r)}. \quad \blacksquare$$



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## Link-by-size: analysis

**Theorem.** Using link-by-size, any UNION or FIND operations takes  $O(\log n)$  time in the worst case, where  $n$  is the number of elements.

**Pf.**

- The running time of each operation is bounded by the tree height.
- By the previous property, the height is  $\leq \lceil \lg n \rceil$ . ■

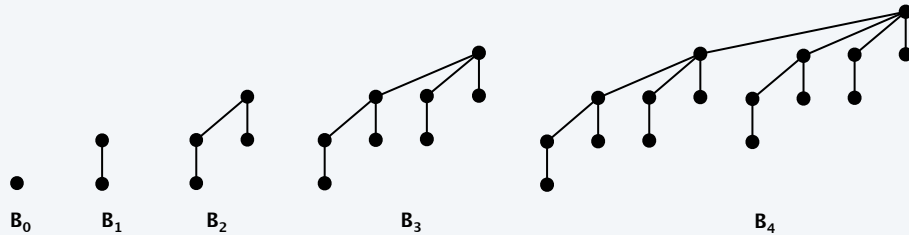
$$\uparrow \\ \lg n = \log_2 n$$

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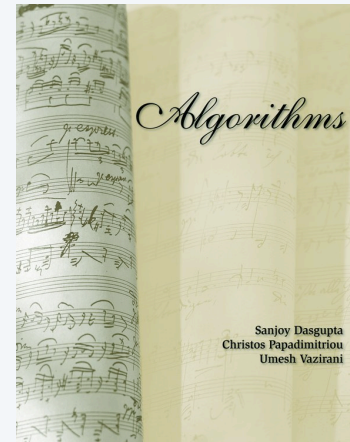
## A matching lower bound

**Theorem.** Using link-by-size, a tree with  $n$  nodes can have height  $= \lg n$ .  
**Pf.**

- Arrange  $2^k - 1$  calls to UNION to form a binomial tree of order  $k$ .
- An order- $k$  binomial tree has  $2^k$  nodes and height  $k$ . ▀



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SECTION 5.1.4

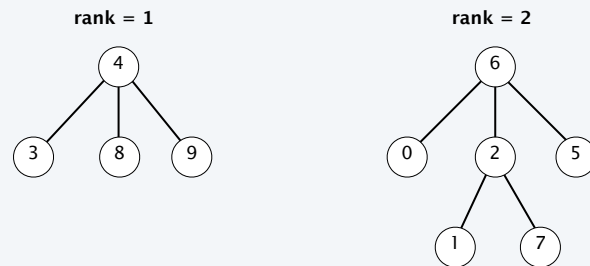
## UNION-FIND

- ▶ link-by-size
- ▶ link-by-rank
- ▶ path compression
- ▶ link-by-rank with path compression
- ▶ context

## Link-by-rank

**Link-by-rank.** Maintain an integer rank for each node, initially 0. Link root of smaller rank to root of larger rank; if tie, increase rank of new root by 1.

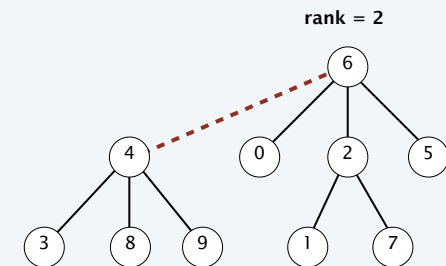
**union(7, 3)**



**Note.** For now, rank = height.

## Link-by-rank

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**Note.** For now, rank = height.

## Link-by-rank

**Link-by-rank.** Maintain an integer rank for each node, initially 0. Link root of smaller rank to root of larger rank; if tie, increase rank of new root by 1.

### MAKE-SET ( $x$ )

```
parent( $x$ )  $\leftarrow x$ .
rank( $x$ )  $\leftarrow 0$ .
```

### FIND ( $x$ )

```
WHILE  $x \neq \text{parent}(x)$ 
   $x \leftarrow \text{parent}(x)$ .
RETURN  $x$ .
```

### UNION-BY-RANK ( $x, y$ )

```
 $r \leftarrow \text{FIND}(x)$ .
 $s \leftarrow \text{FIND}(y)$ .
IF ( $r = s$ ) RETURN.
ELSE IF rank( $r$ ) > rank( $s$ )
  parent( $s$ )  $\leftarrow r$ .
ELSE IF rank( $r$ ) < rank( $s$ )
  parent( $r$ )  $\leftarrow s$ .
ELSE
  parent( $r$ )  $\leftarrow s$ .
  rank( $s$ )  $\leftarrow \text{rank}(s) + 1$ .
```

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## Link-by-rank: properties

**Property 1.** If  $x$  is not a root node, then  $\text{rank}(x) < \text{rank}(\text{parent}(x))$ .

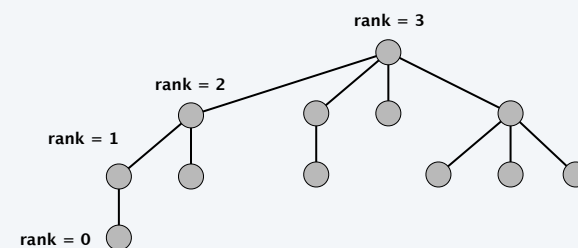
**Pf.** A node of rank  $k$  is created only by merging two roots of rank  $k-1$ . ■

**Property 2.** If  $x$  is not a root, then  $\text{rank}(x)$  will never change again.

**Pf.** Rank changes only for roots; a nonroot never becomes a root. ■

**Property 3.** If  $\text{parent}(x)$  changes, then  $\text{rank}(\text{parent}(x))$  strictly increases.

**Pf.** The parent can change only for a root, so before linking  $\text{parent}(x) = x$ ; After  $x$  is linked-by-rank to new root  $r$  we have  $\text{rank}(r) > \text{rank}(x)$ . ■



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## Link-by-rank: properties

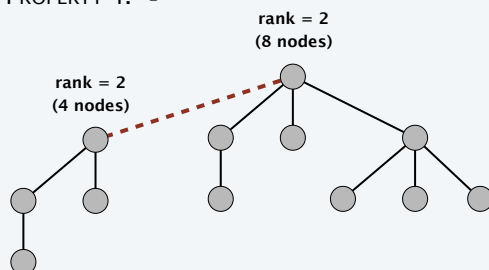
**Property 4.** Any root node of rank  $k$  has  $\geq 2^k$  nodes in its tree.

**Pf.** [ by induction on  $k$  ]

- Base case: true for  $k=0$ .
- Inductive hypothesis: assume true for  $k-1$ .
- A node of rank  $k$  is created only by merging two roots of rank  $k-1$ .
- By inductive hypothesis, each subtree has  $\geq 2^{k-1}$  nodes  
 $\Rightarrow$  resulting tree has  $\geq 2^k$  nodes. ■

**Property 5.** The highest rank of a node is  $\leq \lceil \lg n \rceil$ .

**Pf.** Immediate from PROPERTY 1 and PROPERTY 4. ■



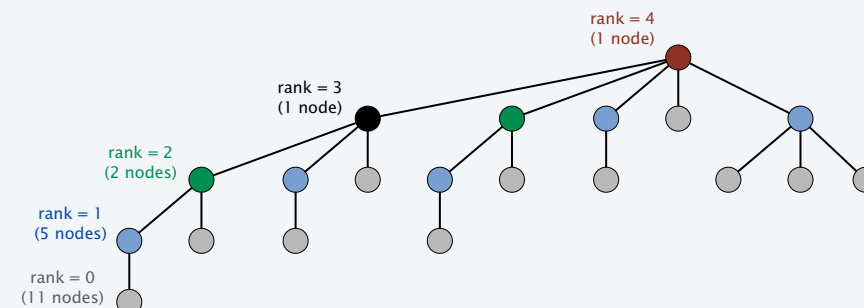
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## Link-by-rank: properties

**Property 6.** For any integer  $r \geq 0$ , there are  $\leq n / 2^r$  nodes with rank  $r$ .

**Pf.**

- Any root node of rank  $k$  has  $\geq 2^k$  descendants. [PROPERTY 4]
- Any nonroot node of rank  $k$  has  $\geq 2^k$  descendants because:
  - it had this property just before it became a nonroot [PROPERTY 4]
  - its rank doesn't change once it becomes a nonroot [PROPERTY 2]
  - its set of descendants doesn't change once it became a nonroot
- Different nodes of rank  $k$  can't have common descendants. [PROPERTY 1] ■



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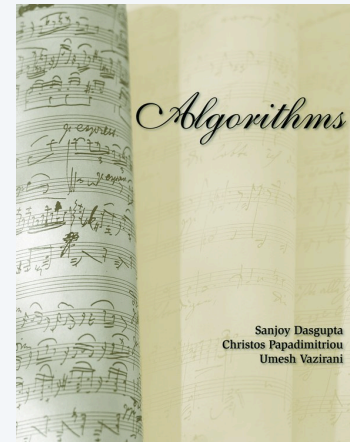
## Link-by-rank: analysis

**Theorem.** Using link-by-rank, any UNION or FIND operations takes  $O(\log n)$  time in the worst case, where  $n$  is the number of elements.

**Pf.**

- The running time of each operation is bounded by the tree height.
- By the PROPERTY 5, the height is  $\leq \lceil \lg n \rceil$ . ▀

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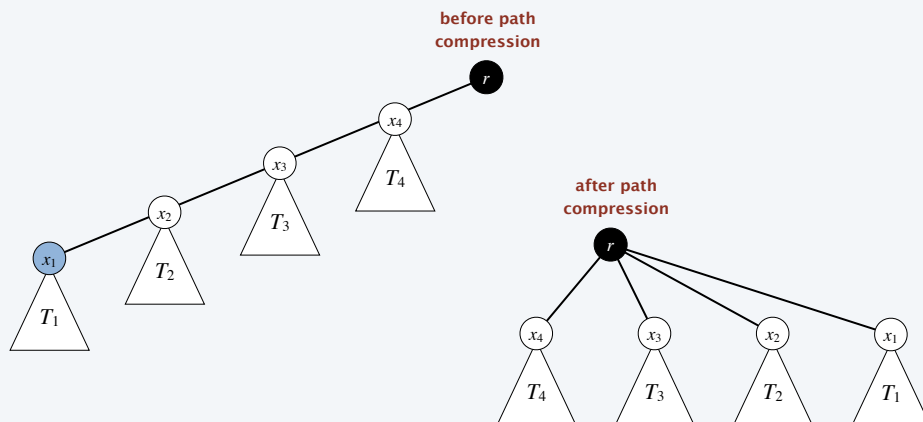
SECTION 5.1.4

## UNION-FIND

- ▶ link-by-size
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- ▶ path compression
- ▶ link-by-rank with path compression
- ▶ context

## Path compression

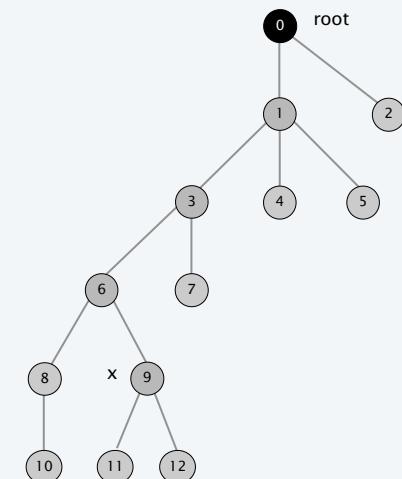
**Path compression.** After finding the root  $r$  of the tree containing  $x$ , change the parent pointer of all nodes along the path to point directly to  $r$ .



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## Path compression

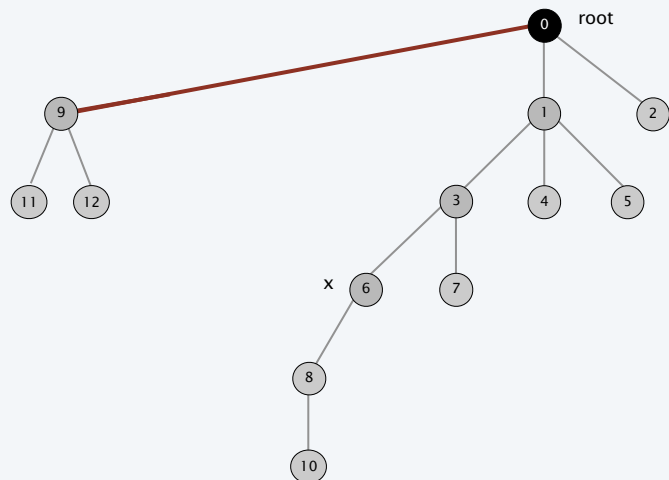
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## Path compression

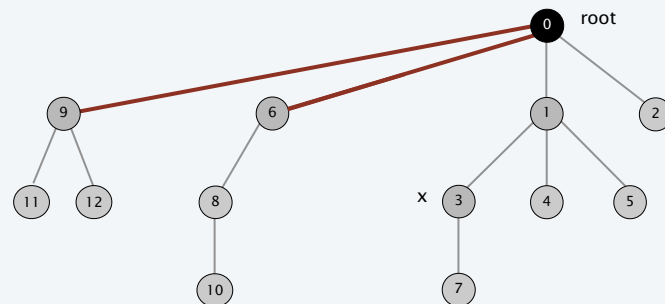
**Path compression.** After finding the root  $r$  of the tree containing  $x$ , change the parent pointer of all nodes along the path to point directly to  $r$ .



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## Path compression

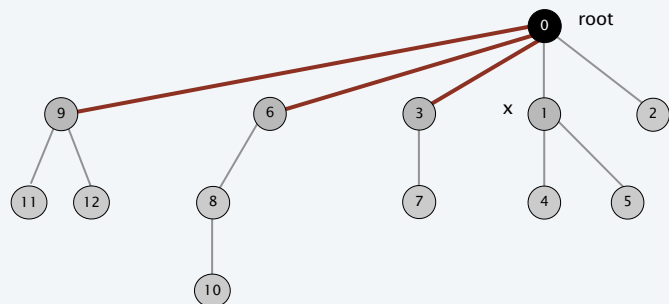
**Path compression.** After finding the root  $r$  of the tree containing  $x$ , change the parent pointer of all nodes along the path to point directly to  $r$ .



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## Path compression

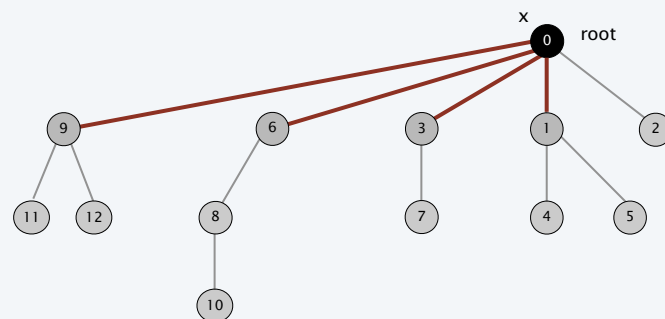
**Path compression.** After finding the root  $r$  of the tree containing  $x$ , change the parent pointer of all nodes along the path to point directly to  $r$ .



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## Path compression

**Path compression.** After finding the root  $r$  of the tree containing  $x$ , change the parent pointer of all nodes along the path to point directly to  $r$ .



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## Path compression

**Path compression.** After finding the root  $r$  of the tree containing  $x$ , change the parent pointer of all nodes along the path to point directly to  $r$ .

```
FIND( $x$ )  
IF  $x \neq \text{parent}(x)$   
     $\text{parent}(x) \leftarrow \text{FIND}(\text{parent}(x)).$   
RETURN  $\text{parent}(x).$ 
```

**Note.** Path compression does not change the rank of a node; so  $\text{height}(x) \leq \text{rank}(x)$  but they are not necessarily equal.

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## Path compression

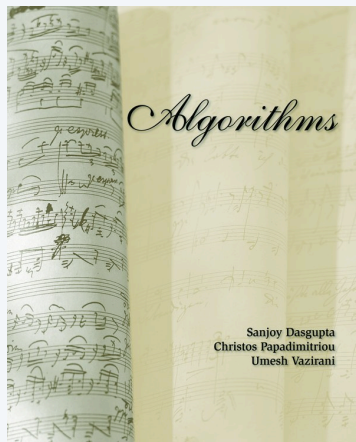
**Fact.** Path compression (with naive linking) can require  $\Omega(n)$  time to perform a single UNION or FIND operation, where  $n$  is the number of elements.

**Pf.** The height of the tree is  $n - 1$  after the sequence of union operations: UNION(1, 2), UNION(2, 3), ..., UNION( $n - 1$ ,  $n$ ). ■

**Theorem.** [Tarjan-van Leeuwen 1984] Starting from an empty data structure, path compression (with naive linking) performs any intermixed sequence of  $m \geq n$  find and  $n - 1$  union operations in  $O(m \log n)$  time.

**Pf.** Nontrivial but omitted.

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### SECTION 5.1.4

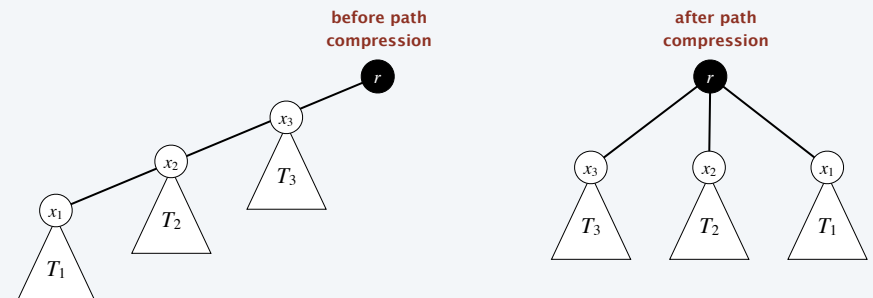
## UNION-FIND

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## Link-by-rank with path compression: properties

**Property.** The tree roots, node ranks, and elements within a tree are the same with or without path compression.

**Pf.** Path compression does not create new roots, change ranks, or move elements from one tree to another. ■



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## Link-by-rank with path compression: properties

**Property.** The tree roots, node ranks, and elements within a tree are the same with or without path compression.

**Corollary.** PROPERTY 2, 4–6 hold for link-by-rank with path compression.

**Property 1.** If  $x$  is not a root node, then  $\text{rank}(x) < \text{rank}(\text{parent}(x))$ .

**Property 2.** If  $x$  is not a root, then  $\text{rank}(x)$  will never change again.

**Property 3.** If  $\text{parent}(x)$  changes, then  $\text{rank}(\text{parent}(x))$  strictly increases.

**Property 4.** Any root node of rank  $k$  has  $\geq 2^k$  nodes in its tree.

**Property 5.** The highest rank of a node is  $\leq \lfloor \lg n \rfloor$ .

**Property 6.** For any integer  $r \geq 0$ , there are  $\leq n / 2^r$  nodes with rank  $r$ .

**Bottom line.** PROPERTY 1–6 hold for link-by-rank with path compression. (but we need to recheck PROPERTY 1 and PROPERTY 3)

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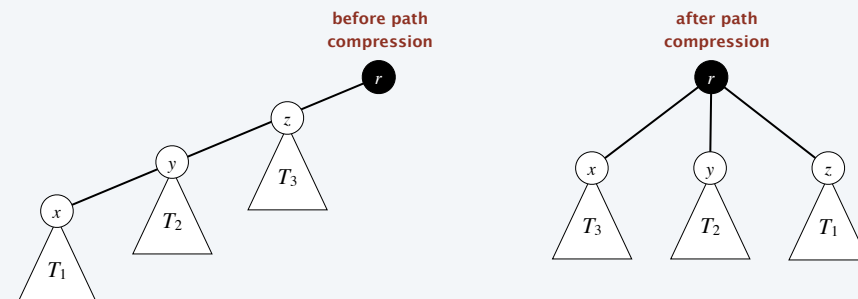
## Link-by-rank with path compression: properties

**Property 1.** If  $x$  is not a root node, then  $\text{rank}(x) < \text{rank}(\text{parent}(x))$ .

**Pf.** Path compression only increases rank of parent.

**Property 3.** If  $\text{parent}(x)$  changes, then  $\text{rank}(\text{parent}(x))$  strictly increases.

**Pf.** Path compression can only make  $x$  point to an ancestor of  $\text{parent}(x)$ .



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## Iterated logarithm function

**Def.** The **iterated logarithm** function is defined by:

$$\lg^* n = \begin{cases} 1 & \text{if } n \leq 1 \\ 1 + \lg^*(\lg n) & \text{otherwise} \end{cases}$$

$n$	$\lg^* n$
1	0
2	1
(3, 4]	2
[5, 16]	3
[17, 65536]	4
[65537, 2 <sup>65536</sup> ]	5

iterated lg function

**Note.** We have  $\lg^* n \leq 5$  unless  $n$  exceeds the # atoms in the universe.

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## Analysis

Divide nonzero ranks into the following groups:

- $\{1\}$
- $\{2\}$
- $\{3, 4\}$
- $\{5, 6, \dots, 16\}$
- $\{17, 18, \dots, 2^{16}\}$
- $\{65537, 65538, \dots, 2^{65536}\}$
- ...

**Property 7.** Every nonzero rank falls within one of the first  $\lg^* n$  groups.

**Pf.** The rank is between 0 and  $\lfloor \lg n \rfloor$ . [PROPERTY 5]

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## Creative accounting

**Credits.** A node receives credits as soon as it ceases to be a root. If its rank is in the interval  $\{k+1, k+2, \dots, 2^k\}$ , we give it  $2^k$  credits.

group k

**Proposition.** Number of credits disbursed to all nodes is  $\leq n \lg^* n$ .  
**Pf.**

- By PROPERTY 6, the number of nodes with rank  $\geq k+1$  is at most

$$\frac{n}{2^{k+1}} + \frac{n}{2^{k+2}} + \dots \leq \frac{n}{2^k}$$

- Thus, nodes in group  $k$  need at most  $n$  credits in total.
- There are  $\leq \lg^* n$  groups. [PROPERTY 7] ■

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## Running time of find

**Running time of find.** Bounded by number of parent pointers followed.

- Recall: the rank strictly increases as you go up a tree. [PROPERTY 1]
- Case 0:  $\text{parent}(x)$  is a root  $\Rightarrow$  only happens for one link per FIND.
- Case 1:  $\text{rank}(\text{parent}(x))$  is in a higher group than  $\text{rank}(x)$ .
- Case 2:  $\text{rank}(\text{parent}(x))$  is in the same group as  $\text{rank}(x)$ .

**Case 1.** At most  $\lg^* n$  nodes on path can be in a higher group. [PROPERTY 7]

**Case 2.** These nodes are charged 1 credit to follow parent pointer.

- Each time  $x$  pays 1 credit,  $\text{rank}(\text{parent}(x))$  strictly increases. [PROPERTY 1]
- Therefore, if  $\text{rank}(x)$  is in the group  $\{k+1, \dots, 2^k\}$ , the rank of its parent will be in a higher group before  $x$  pays  $2^k$  credits.
- Once  $\text{rank}(\text{parent}(x))$  is in a higher group than  $\text{rank}(x)$ , it remains so because:
  - $\text{rank}(x)$  does not change once it ceases to be a root. [PROPERTY 2]
  - $\text{rank}(\text{parent}(x))$  does not decrease. [PROPERTY 3]
  - thus,  $x$  has enough credits to pay until it becomes a Case 1 node. ■

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## Link-by-rank with path compression

**Theorem.** Starting from an empty data structure, link-by-size with path compression performs any intermixed sequence of  $m \geq n$  FIND and  $n-1$  UNION operations in  $O(m \log^* n)$  time.

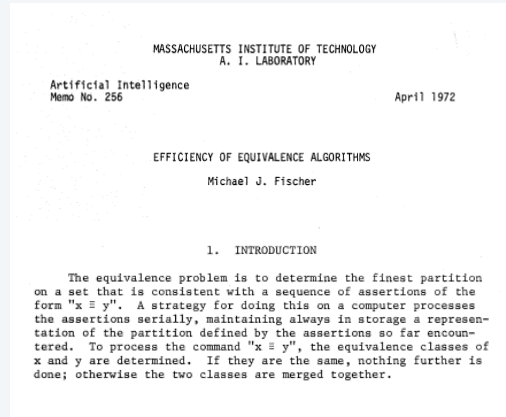
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## UNION-FIND

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## Link-by-size with path compression

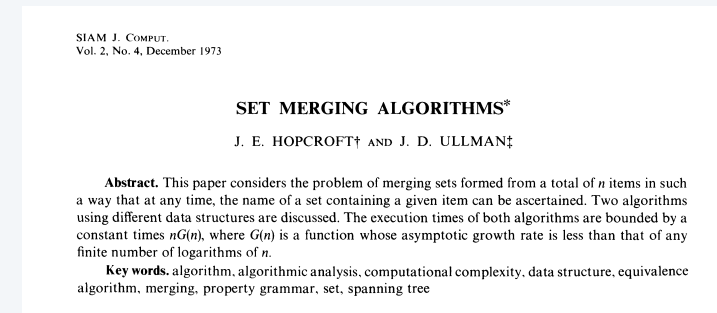
**Theorem.** [Fischer 1972] Link-by-size with path compression performs any intermixed sequence of  $m \geq n$  FIND and  $n - 1$  UNION operations in  $O(m \log \log n)$  time.



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## Link-by-size with path compression

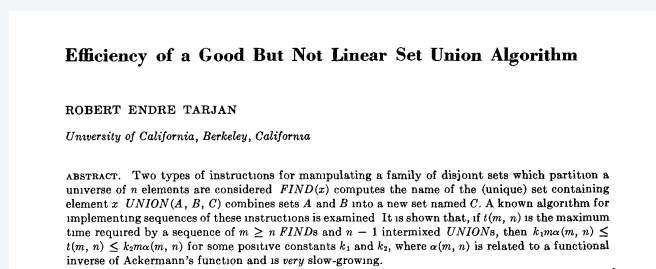
**Theorem.** [Hopcroft-Ullman 1973] Link-by-size with path compression performs any intermixed sequence of  $m \geq n$  FIND and  $n - 1$  UNION operations in  $O(m \log^* n)$  time.



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## Link-by-size with path compression

**Theorem.** [Tarjan 1975] Link-by-size with path compression performs any intermixed sequence of  $m \geq n$  FIND and  $n - 1$  UNION operations in  $O(m \alpha(m, n))$  time, where  $\alpha(m, n)$  is a functional inverse of the Ackermann function.

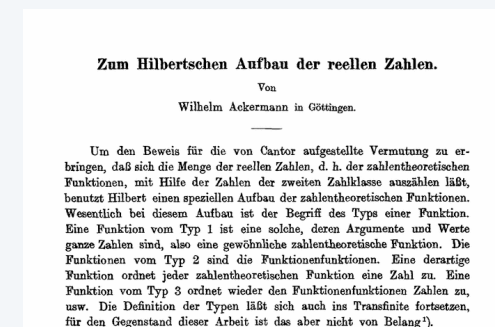


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## Ackermann function

**Ackermann function.** A computable function that is **not** primitive recursive.

$$A(m, n) = \begin{cases} n + 1 & \text{if } m = 0 \\ A(m - 1, 1) & \text{if } m > 0 \text{ and } n = 0 \\ A(m - 1, A(m, n - 1)) & \text{if } m > 0 \text{ and } n > 0 \end{cases}$$



**Note.** There are many inequivalent definitions.

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**Inverse Ackermann function.**

$$\alpha(m, n) = \min\{i \geq 1 : A(i, \lfloor m/n \rfloor) \geq \log_2 n\}$$

“I am not smart enough to understand this easily.”

— Raymond Seidel



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## Inverse Ackermann function

**Definition.**

$$\alpha_k(n) = \begin{cases} 1 & \text{if } n = 1 \\ \lceil n/2 \rceil & \text{if } k = 1 \\ 1 + \alpha_k(\alpha_{k-1}(n)) & \text{otherwise} \end{cases}$$

**Ex.**

- $\alpha_1(n) = \lceil n/2 \rceil$ .
- $\alpha_2(n) = \lceil \lg n \rceil$  = # of times we **divide n by two**, until we reach 1.
- $\alpha_3(n) = \lg^* n$  = # of times we apply the **lg function to n**, until we reach 1.
- $\alpha_4(n)$  = # of times we apply the **iterated lg function to n**, until we reach 1.

$$2 \uparrow 65536 = 2^{2^{2^{\cdot^{\cdot^{\cdot^2}}}}} \text{ (65536 times)}$$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	...	2 <sup>16</sup>	...	2 <sup>65536</sup>	...	2 ↑ 65536
α <sub>1</sub> (n)	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	8	...	2 <sup>15</sup>	...	2 <sup>65535</sup>	...	huge
α <sub>2</sub> (n)	1	1	2	2	3	3	3	3	4	4	4	4	4	4	4	4	...	16	...	65536	...	2 ↑ 65535
α <sub>3</sub> (n)	1	1	2	2	3	3	3	3	3	3	3	3	3	3	3	3	...	4	...	5	...	65536
α <sub>4</sub> (n)	1	1	2	2	3	3	3	3	3	3	3	3	3	3	3	3	...	3	...	3	...	4

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## Inverse Ackermann function

**Definition.**

$$\alpha_k(n) = \begin{cases} 1 & \text{if } n = 1 \\ \lceil n/2 \rceil & \text{if } k = 1 \\ 1 + \alpha_k(\alpha_{k-1}(n)) & \text{otherwise} \end{cases}$$

**Property.** For every  $n \geq 5$ , the sequence  $\alpha_1(n), \alpha_2(n), \alpha_3(n), \dots$  converges to 3.

**Ex.**  $[n = 9876!]$   $\alpha_1(n) \geq 10^{35163}$ ,  $\alpha_2(n) = 116812$ ,  $\alpha_3(n) = 6$ ,  $\alpha_4(n) = 4$ ,  $\alpha_5(n) = 3$ .

**One-parameter inverse Ackermann.**  $\alpha(n) = \min \{k : \alpha_k(n) \leq 3\}$ .

**Ex.**  $\alpha(9876!) = 5$ .

**Two-parameter inverse Ackermann.**  $\alpha(m, n) = \min \{k : \alpha_k(n) \leq 3 + m/n\}$ .

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## A matching lower bound

**Theorem.** [Fredman-Saks 1989] Any CPROBE(log n) algorithm for the disjoint set union problem requires  $\Omega(m \alpha(m, n))$  time to perform an intermixed sequence of  $m \geq n$  FIND and  $n - 1$  UNION operations in the worst case.

**Cell probe model.** [Yao 1981] Count only number of words of memory accessed; all other operations are free.

The Cell Probe Complexity of Dynamic Data Structures

Michael L. Fredman<sup>1</sup>

Bellcore and  
U.C. San Diego

Michael E. Saks<sup>2</sup>

U.C. San Diego,  
Bellcore and  
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**1. Summary of Results**

Dynamic data structure problems involve the representation of data in memory in such a way as to permit certain types of modifications of the data (updates) and certain types of questions about the data (queries). This paradigm encompasses many fundamental problems in computer science.

The purpose of this paper is to prove new lower and upper bounds on the time per operation to implement solutions to some familiar dynamic data structure problems including list representation, subset ranking, partial sums, and the set union problem. The main features of our lower bounds are:

(1) They hold in the *cell probe* model of computation (A. Yao

register size from  $\log n$  to  $\text{poly}(\log n)$  only reduces the time complexity by a constant factor. On the other hand, decreasing the register size from  $\log n$  to 1 increases time complexity by a  $\log n$  factor for one of the problems we consider and only a  $\log \log n$  factor for some other problems.

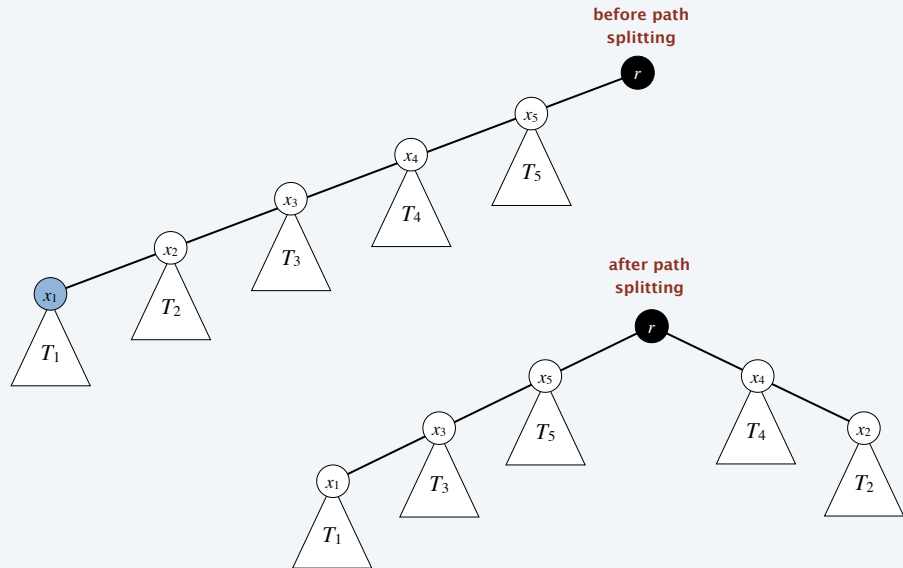
The first two specific data structure problems for which we obtain bounds are:

**List Representation.** This problem concerns the representation of an ordered list of at most  $n$  (not necessarily distinct) elements from the universe  $U = \{1, 2, \dots, n\}$ . The operations to be supported are *report*( $k$ ), which returns the  $k^{\text{th}}$  element of the list, *insert*( $k, a$ ) which inserts element  $a$  into the list between the

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## Path compaction variants

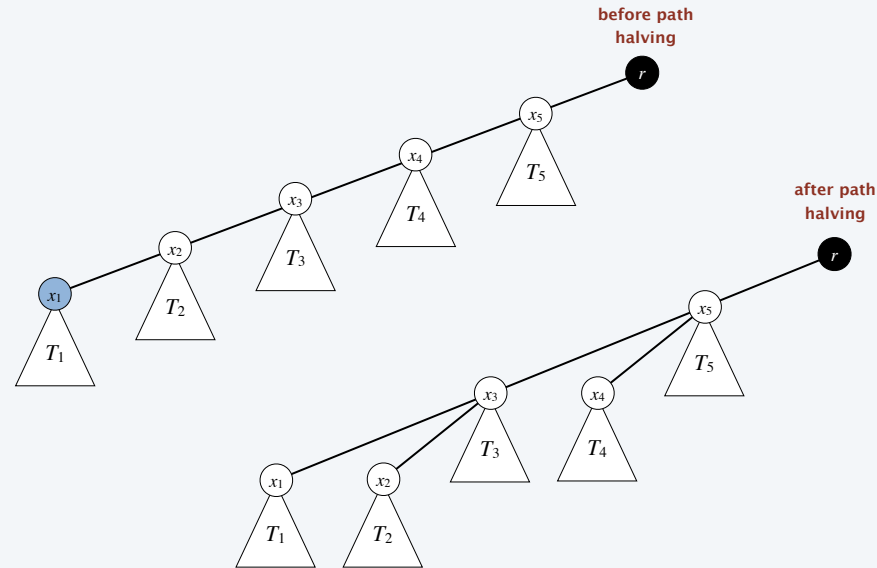
**Path splitting.** Make every node on path point to its grandparent.



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## Path compaction variants

**Path halving.** Make every other node on path point to its grandparent.



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## Linking variants

**Link-by-size.** Number of nodes in tree.

**Link-by-rank.** Rank of tree.

**Link-by-random.** Label each element with a random real number between 0.0 and 1.0. Link root with smaller label into root with larger label.

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## Disjoint set union algorithms

**Theorem.** [Tarjan-van Leeuwen 1984] Link-by- { size, rank } combined with { path compression, path splitting, path halving } performs any intermixed sequence of  $m \geq n$  find and  $n - 1$  union operations in  $O(m \alpha(m, n))$  time.

### Worst-Case Analysis of Set Union Algorithms

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**Abstract.** This paper analyzes the asymptotic worst-case running time of a number of variants of the well-known method of path compression for maintaining a collection of disjoint sets under union. We show that two one-pass methods proposed by van Leeuwen and van der Weide are asymptotically optimal, whereas several other methods, including one proposed by Rem and advocated by Dijkstra, are slower than the best methods.

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