Introduction to Separation Logic

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Syntax of Separation Logic

- Given a decidable base-theory T, the syntax of separation logic $SL(T)_{Loc,Data}$ is presented
- Loc and Data represent the type of the address and the values [Srivas: 1. Is T different from Loc, Data? I thought they would be part of T
 - 2. Data can be Loc too, right otherwise you couldn't express indirection
- Loc and Data can be any sorts, but Loc should be countably infinite, for the purpose of the decision procedure
- For example, Loc and Data can be Int

$$P, Q ::= false \mid P \land Q \mid P \lor Q \mid P \rightarrow Q$$

$$\mid P * Q \mid P \twoheadrightarrow Q$$

$$\mid E = E' \mid E \hookrightarrow E' \mid empty$$

We use E and E' to denote expressions in the base theory, where heap indirection is not used. This is needed to syntactically rule out formulas like $F:(x\hookrightarrow v_1)=(y\hookrightarrow v_2)$ [Srivas: What are the operators allowed in E? Obviously it scan't have

Semantics of Separation Logic

The model consists of an interpretation (I) and a heap (h)

$$I: \operatorname{Var} \to \operatorname{Loc}$$

 $h: \operatorname{Loc} \to \operatorname{Data}$

$$\begin{array}{ll} I,h\models \mathit{false} & \text{never satisfied} \\ I,h\models P\wedge Q & I,h\models P \text{ and } I,h\models Q \\ I,h\models P\vee Q & I,h\models P \text{ or } I,h\models Q \\ I,h\models P\to Q & I,h\models P \text{ implies } I,h\models Q \\ I,h\models E=E' & \llbracket E\rrbracket_I=\llbracket E'\rrbracket_I \end{array}$$

We use $[E]_I$, to denote the value of E under the interpretation I. Also, the domain of h should be a finite subset of Loc and it can be a partial function.

Semantics of Separation Logic

Empty heap

$$I, h \models empty$$
 iff $h = \phi$

Separating conjunction

$$I, h \models P * Q$$
iff $\exists h_1, h_2.(h_1 \# h_2) \land (h = h1 \circ h2) \land I, h_1 \models P \land I, h_2 \models Q$

Where $h_1 \# h_2$ denotes that the heap domains are disjoint and $h_1 \circ h_2$ means their union.

Semantics of Separation Logic

Separating Implication

$$I, h \models P \twoheadrightarrow Q$$
iff $\forall h'.(h\#h') \land (I, h' \models P) \rightarrow I, h \circ h' \models Q$

Interpretation: If we extend the current heap with a disjoint heap satisfying P, then the new heap satisfies Q. In some ways, we can imagine that our current heap is only missing the records of P, to make it satisfy Q.

Points to

$$I, h \models E \hookrightarrow E'$$
 iff $h(\llbracket E \rrbracket_I) = \llbracket E' \rrbracket_I$

Examples

Points to,

$$F: x \hookrightarrow 10$$

$$I: \{(x,0)\}$$

$$h: \{(0,10)\}$$

$$I, h \models F$$

Separating conjunction,

$$F: x \hookrightarrow 10 * y \hookrightarrow 20$$

$$I: \{(x,0), (y,1)\}$$

$$h: \{(0,10), (1,20)\}$$

$$I, h \models F$$



Examples

Another example,

$$F: x \hookrightarrow y * y \hookrightarrow x$$

 $I: \{(x,0), (y,1)\}$
 $h: \{(0,1), (1,0)\}$
 $I, h \models F$

Examples

Separating Implication

$$I,h \models P \twoheadrightarrow Q$$
 iff $\forall h'.(h\#h') \land (I,h' \models P) \rightarrow I, h \circ h' \models Q$

Example,

$$F: (x \hookrightarrow 10) \twoheadrightarrow (x \hookrightarrow 10 * y \hookrightarrow 20)$$

$$I: \{(x,0), (y,1)\}$$

$$h': \{(0,10)\}$$

$$h: \{(1,20)\}$$

$$h \circ h': \{(0,10), (1,20)\}$$

$$I, h \models F$$

Separation logic has been useful in Hoare logic for program verification. We will have a quick look at Hoare logic.

[Srivas: This is strongest post condition and must be introduced as such]

 $\{P\}S\{Q\}$

P : Logical assertion on states - precondition

S: Code section that modifies state

 \boldsymbol{Q} : Logical assertion on states - postcondition

Example,

$${x = 1}x := 2{x = 2}$$

The programs S are defined against a language specification with imperative commands such as skip, loops, variable and pointer assignments.

Now given a post-condition Q and program S, we want to calculate the set of states, that the program can be in before, to end-up in Q after execution.

Example,

$${x > 0}x := x + 1{x >= 0}$$

Srivas: This is correct as a ordinary triple; but strongest post condition would be x > 0This is also valid,

$${x > -1}x := x + 1{x >= 0}$$

In fact, $(x > -1) \rightarrow (x > 0)$, thus, (x > -1) is weaker. Finding the weakest unique precondition, can then let us reason about all the states, that the program can be in before, to guarantee Q to hold. Srivas: This can

be confusing; first introduce SP, then formally define WP in a slide after this and talk about it before you show the next to next slide

The first application of separation logic in Hoare-style verification is to do local reasoning, which is defined as,

$$\frac{\{P\}S\{Q\}}{\{P*R\}S\{Q*R\}}$$

Example,

```
\{ \text{root} \hookrightarrow (\text{left}, \text{right}) * \text{tree}(\text{left}) * \text{tree}(\text{right}) \}
\text{deletetree}(\text{left})
\{ \text{root} \hookrightarrow (\text{left}, \text{right}) * \text{emp} * \text{tree}(\text{right}) \}
\text{deletetree}(\text{right})
\{ \text{root} \hookrightarrow (\text{left}, \text{right}) * \text{emp} * \text{emp} \}
\text{free}(\text{root})
\{ \text{emp} * \text{emp} * \text{emp} \}
\{ \text{emp} \}
```

Another application is to have an operation similar to modus-ponens for heap predicates.

Example,

$$(x \hookrightarrow v_1) * (x \hookrightarrow v_1 \twoheadrightarrow y \hookrightarrow v_2) \models (y \hookrightarrow v_2)$$

Also, this is used in weakest pre-condition computation, where if we have a triple,

$$\{P\}x := 3\{Q\}$$

where the weakest precondition would be,

$$wp(x := 3, Q) \equiv (x \hookrightarrow -) * ((x \hookrightarrow 3) \twoheadrightarrow Q)$$

The trivial case being $P = x \hookrightarrow 3$.

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Translating Separation Logic into Pointer Logic

Points to,

$$I, h \models x \hookrightarrow v$$

$$\iff$$

$$L, M \models *x = v$$

Separating conjunction,

$$I, h \models x \hookrightarrow v_1 * y \hookrightarrow v_2$$

$$\iff$$

$$L, M \models *x = v_1 \land *y = v_2 \land x \neq y$$

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Inductive predicates

Need for inductive predicates

- Most interesting data structures in programs are defined as inductive systems
- For example : linked lists, trees, graphs
- Being able to reason about these in SL is useful
- But inductive predicates introduce quantifiers

This way of specifying a list is quite cumbersome,

$$p \hookrightarrow v_1, p_1 \land$$
 $p_1 \hookrightarrow v_2, p_2 \land$
 $p_2 \hookrightarrow v_3, p_3 \land$

Lists in pointer logic

First try at defining lists without explicit quantifiers. We define the following predicates for the i^{th} element of the list,

list-elem
$$(p, 0) \equiv p$$

list-elem $(p, i) \equiv *$ list-elem $(p, i - 1)$

In this formulation, a null-terminated list would be

$$list-elem(p, I) = NULL$$

and a cyclic list would be,

$$list-elem(p, I) = p$$

But the last predicate is also satisfied by an element with length 1.

Lists in pointer logic

To actually get a disjoint list with unique pointer elements, we need to add an extra constraint,

$$\operatorname{overlap}(p,q) \equiv p = q \lor p + 1 = q \lor p = q + 1$$

 $\operatorname{list-disjoint}(p,0) \equiv TRUE$
 $\operatorname{list-disjoint}(p,l) \equiv \operatorname{list-disjoint}(p,l-1) \land \forall 0 \leq i < l-1. \neg \operatorname{overlap}(\operatorname{list-elem}(p,i),\operatorname{list-elem}(p,l-1))$

The set of clauses grows quadratically upon the quantifier instantiation.

Lists - Try 2

We now try to define a list with inductive predicates,

list
$$0 \times \equiv x = nil$$

list $n \times \equiv \exists y.(x \hookrightarrow v, y) \land (list (n-1) y)$

This is a satisfying assignment for list 3x,

$$I = \{ (x,0), (y,0), (z,1), (w, nil) \}$$

$$h = \{ (0, (v,1)), (1, (v,w)) \}$$

The pointers x and y got aliased to point to z.

list
$$3 \times \equiv$$

 $(x = 0) \hookrightarrow v, 1 \land$
 $(y = 0) \hookrightarrow v, 1 \land$
 $(z = 1) \hookrightarrow v, nil \land$

Lists in Separation Logic

In separation logic, the separating conjunction takes care of ensuring the pointers don't alias.

list
$$0 \times \equiv x = nil$$

list $n \times \equiv \exists y.(x \hookrightarrow v, y) * (list (n-1) y)$