Introduction to Separation Logic

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Syntax of Separation Logic

- Given a decidable base-theory T, the syntax of separation logic $SL(T)_{Loc,Data}$ is presented
- *Loc* and *Data* represent the type of the address and the values [Srivas: 1. Is T different from Loc, Data? I thought they would be part of T

  2. Data can be Loc too, right otherwise you couldn't express indirection]
- *Loc* and *Data* can be any sorts, but *Loc* should be countably infinite, for the purpose of the decision procedure
- For example, *Loc* and *Data* can be *Int*

$$\begin{aligned} P, Q ::= \ & false \mid P \wedge Q \mid P \vee Q \mid P \rightarrow Q \\ & \mid P * Q \mid P \mathrel{-\!\!*} Q \\ & \mid E = E' \mid E \hookrightarrow E' \mid empty \end{aligned}$$

We use E and E' to denote expressions in the base theory, where heap indirection is not used. This is needed to syntactically rule out formulas like $F : (x \hookrightarrow v_1) = (y \hookrightarrow v_2)$ [Srivas: What are the operators allowed in E? Obviously it scan't have dref(*); can it have arithmetic over Loc? I guess yes; Can it have &; I guess not?]

Semantics of Separation Logic

The model consists of an interpretation (I) and a heap (h)

$$I : \mathrm{Var} \to \mathrm{Loc}$$
$$h : \mathrm{Loc} \to \mathrm{Data}$$

$$\begin{aligned}
I, h &\models \mathit{false} && \text{never satisfied} \\
I, h &\models P \wedge Q && I, h \models P \text{ and } I, h \models Q \\
I, h &\models P \vee Q && I, h \models P \text{ or } I, h \models Q \\
I, h &\models P \to Q && I, h \models P \text{ implies } I, h \models Q \\
I, h &\models E = E' && [\![E]\!]_I = [\![E']\!]_I
\end{aligned}$$

We use $[\![E]\!]_I$, to denote the value of E under the interpretation I. Also, the domain of h should be a <u>finite</u> subset of Loc and it can be a partial function.

Semantics of Separation Logic

Empty heap

$$I, h \models empty$$
$$\text{iff } h = \phi$$

Separating conjunction

$$I, h \models P * Q$$
$$\text{iff } \exists h_1, h_2.(h_1 \# h_2) \wedge (h = h1 \circ h2) \wedge I, h_1 \models P \wedge I, h_2 \models Q$$

Where $h_1 \# h_2$ denotes that the heap domains are disjoint and $h_1 \circ h_2$ means their union.

Separating Implication

$$\begin{gathered} I, h \models P \mathrel{-\!\!*} Q \\ \text{iff } \forall h'.(h \# h') \wedge (I, h' \models P) \rightarrow I, h \circ h' \models Q \end{gathered}$$

Interpretation : If we extend the current heap with a disjoint heap satisfying P, then the new heap satisfies Q. In some ways, we can imagine that our current heap is only missing the records of P, to make it satisfy Q.

Points to

$$\begin{gathered} I, h \models E \hookrightarrow E' \\ \text{iff } h(\llbracket E \rrbracket_I) = \llbracket E' \rrbracket_I \end{gathered}$$

Examples

Points to,

$$
\begin{aligned}
&F : x \hookrightarrow 10\\
&I : \{(x, 0)\}\\
&h : \{(0, 10)\}\\
&I, h \models F
\end{aligned}
$$

Separating conjunction,

$$
\begin{aligned}
&F : x \hookrightarrow 10 * y \hookrightarrow 20\\
&I : \{(x, 0), (y, 1)\}; \quad h : \{(0, 10), (1, 20)\}; \quad I, h \models F\\
&I : \{(x, 0), (y, 1)\}; \quad h' : \{(0, 10), (1, 10)\}; \quad I, h' \models F \ ?
\end{aligned}
$$

Examples

Another example,

$$F : x \hookrightarrow y * y \hookrightarrow x$$

$$I : \{(x,0),(y,1)\} \qquad h : \{(0,1),(1,0)\}$$

$$I, h \models F$$

$$I' : \{(x,0),(y,0)\}$$

$$h' : \{(0,0)\}$$

$$I', h' \not\models F$$

Examples

Separating Implication

$$I, h \models P \mathrel{-\!\!*} Q$$
$$\text{iff } \forall h'.(h \# h') \wedge (I, h' \models P) \rightarrow I, h \circ h' \models Q$$

Example,

$$F : (x \hookrightarrow 10) \mathrel{-\!\!*} (x \hookrightarrow 10 * y \hookrightarrow 20)$$
$$I : \{(x, 0), (y, 1)\}$$
$$h' : \{(0, 10)\}$$
$$h : \{(1, 20)\}$$
$$h \circ h' : \{(0, 10), (1, 20)\}$$
$$I, h \models F$$

[Srivas: Show some negative examples of –* formula that are not satisfiable by a I and H; also does phi*psi =¿ phi -* psi?]

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Translating Separation Logic into Pointer Logic

Points to,

$$I, h \models x \hookrightarrow v$$
$$\Longleftrightarrow$$
$$L, M \models \ {}^{*}x = v$$

Separating conjunction,

$$I, h \models x \hookrightarrow v_1 * y \hookrightarrow v_2$$
$$\Longleftrightarrow$$
$$L, M \models \ {}^{*}x = v_1 \ \wedge \ {}^{*}y = v_2 \wedge x \neq y$$

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Need for inductive predicates

- Most interesting data structures in programs are defined as inductive systems
- For example : linked lists, trees, graphs
- Being able to reason about these in SL is useful
- But inductive predicates introduce quantifiers

This way of specifying a list is quite cumbersome,

$$\begin{gathered} p \hookrightarrow v_1, p_1 \wedge \\ p_1 \hookrightarrow v_2, p_2 \wedge \\ p_2 \hookrightarrow v_3, p_3 \wedge \\ \ldots \end{gathered}$$

Lists in pointer logic

First try at defining lists without explicit quantifiers. We define the following predicates for the i^{th} element of the list,

$$
\begin{aligned}
\text{list-elem}(p, 0) &\equiv p \\
\text{list-elem}(p, i) &\equiv *\text{list-elem}(p, i-1)
\end{aligned}
$$

In this formulation, a null-terminated list would be

$$\text{list-elem}(p, l) = NULL$$

and a cyclic list would be,

$$\text{list-elem}(p, l) = p$$

But the last predicate is also satisfied by an element with length 1.

Lists in pointer logic

To actually get a disjoint list with unique pointer elements, we need to add an extra constraint,

$$
\begin{aligned}
&\mathrm{overlap}(p, q) \equiv p = q \vee p + 1 = q \vee p = q + 1 \\
&\text{list-disjoint}(p, 0) \equiv \mathit{TRUE} \\
&\text{list-disjoint}(p, l) \equiv \text{list-disjoint}(p, l - 1) \wedge \\
&\forall 0 \leq i < l - 1 . \neg\, \mathrm{overlap}(\text{list-elem}(p, i), \text{list-elem}(p, l - 1))
\end{aligned}
$$

The set of clauses grows quadratically upon the quantifier instantiation.

Lists - Try 2

We now try to define a list with inductive predicates,

$$\text{list } 0 \ x \equiv x = nil$$
$$\text{list } n \ x \equiv \exists y.(x \hookrightarrow v, y) \wedge (list \ (n-1) \ y)$$

This is a satisfying assignment for *list* $3 \ x$,

$$I = \{ \ (x, 0), (y, 0), (z, 1), (w, nil) \ \}$$
$$h = \{ \ (0, (v, 1)), (1, (v, w)) \ \}$$

The pointers x and y got aliased to point to z.

$$list \ 3 \ x \equiv$$
$$(x = 0) \hookrightarrow v, 1 \wedge$$
$$(y = 0) \hookrightarrow v, 1 \wedge$$
$$(z = 1) \hookrightarrow v, nil \wedge$$

Lists in Separation Logic

In separation logic, the separating conjunction takes care of ensuring the pointers don't alias.

$$\text{list } 0\ x \equiv x = \mathit{nil}$$
$$\text{list } n\ x \equiv \exists y.(x \hookrightarrow v, y) * (\mathit{list}\ (n-1)\ y)$$

Applications: Hoare Logic

Separation logic has been useful in Hoare logic for program verification. We will have a quick look at Hoare logic.

$$\{P\}S\{Q\}$$
$$P : \text{Logical assertion on states - precondition}$$
$$S : \text{Code section that modifies state}$$
$$Q : \text{Logical assertion on states - postcondition}$$

Example: $\{x = 1\}x := 2\{x = 2\}$

Hoare Triple : holds if "whenever you start in a state that satisfies the precondition and execute the program statement S and terminate then you will be in a state that satisfies the postcondition"

The programs S are defined against a language specification with imperative commands such as skip, loops, variable including pointer assignments.

Strongest Postcondition and Weakest Precondition

Now given a post-condition Q and program S, we want to calculate the set of states, that the program can be in before, to end-up in Q after execution.
Example,

$$\{x > 0\}x := x + 1\{x >= 0\}$$

This is also valid,

$$\{x > 0\}x := x + 1\{x > 0\}$$

$x > 0$ is the *strongest* postcondition for In fact, $(x > -1) \rightarrow (x > 0)$, thus, $(x > -1)$ is weaker. Finding the weakest unique precondition, can then let us reason about all the states, that the program can be in before, to guarantee Q to hold.

The first application of separation logic in Hoare-style verification is to do local reasoning, which is defined as,

$$\frac{\{P\}S\{Q\}}{\{P * R\}S\{Q * R\}}$$

Example,

$$\{\text{root} \hookrightarrow (\text{left}, \text{right}) * \text{tree}(\text{left}) * \text{tree}(\text{right})\}$$
$$\text{deletetree}(\text{left})$$
$$\{\text{root} \hookrightarrow (\text{left}, \text{right}) * \text{emp} * \text{tree}(\text{right})\}$$
$$\text{deletetree}(\text{right})$$
$$\{\text{root} \hookrightarrow (\text{left}, \text{right}) * \text{emp} * \text{emp}\}$$
$$\text{free}(\text{root})$$
$$\{\text{emp} * \text{emp} * \text{emp}\}$$
$$\{\text{emp}\}$$

Applications

Another application is to have an operation similar to modus-ponens for heap predicates.

$$P * (P \twoheadrightarrow Q) \models Q$$

Example,

$$(x \hookrightarrow v_1) * (x \hookrightarrow v_1 \twoheadrightarrow y \hookrightarrow v_2) \models (y \hookrightarrow v_2)$$

Also, this is used in weakest pre-condition computation, where if we have a triple,

$$\{P\}x := 3\{Q\}$$

where the weakest precondition would be,

$$wp(x := 3, Q) \equiv (x \hookrightarrow -) * ((x \hookrightarrow 3) \twoheadrightarrow Q)$$

The trivial case being $P = x \hookrightarrow 3$.