Introduction to Separation Logic

Heavily borrows from slides by Cristiano Calcagno, Imperial College London

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Syntax of Separation Logic

- Given a decidable base-theory T, the syntax of separation logic $SL(T)_{Loc,Data}$ is presented
- Loc and $Data$ represent the type of the address and the values
- Loc and $Data$ can be any sorts, but Loc should be countably infinite, for the purpose of the decision procedure
- For example, Loc and $Data$ can be Int

$$
\begin{aligned}
P, Q ::= \ & \mathit{false} \mid P \wedge Q \mid P \vee Q \mid P \rightarrow Q \\
& \mid P * Q \mid P \mathrel{-\!\!*} Q \\
& \mid E = E' \mid E \hookrightarrow E' \mid \mathit{empty}
\end{aligned}
$$

We use E and E' to denote expressions in the base theory, where heap indirection is not used. This is needed to syntactically rule out formulas like $F : (x \hookrightarrow v_1) = (y \hookrightarrow v_2)$

Semantics of Separation Logic

The model consists of an interpretation (I) and a heap (h)

$$I : \text{Var} \to \text{Loc}$$
$$h : \text{Loc} \to \text{Data}$$

$I, h \models \mathit{false}$	never satisfied
$I, h \models P \wedge Q$	$I, h \models P$ and $I, h \models Q$
$I, h \models P \vee Q$	$I, h \models P$ or $I, h \models Q$
$I, h \models P \to Q$	$I, h \models P$ implies $I, h \models Q$
$I, h \models E = E'$	$[\![E]\!]_I = [\![E']\!]_I$

We use $[\![E]\!]_I$, to denote the value of E under the interpretation I. Also, the domain of h should be a subset of Loc and it can be a partial function.

Semantics of Separation Logic

Empty heap

$$I, h \models \mathit{empty}$$
$$\text{iff } h = \phi$$

Separating conjunction

$$I, h \models P * Q$$
$$\text{iff } \exists h_1, h_2.(h_1 \# h_2) \wedge (h = h1 \circ h2) \wedge I, h_1 \models P \wedge I, h_2 \models Q$$

Where $h_1 \# h_2$ denotes that the heap domains are disjoint and $h_1 \circ h_2$ means their union.

Semantics of Separation Logic

Separating Implication

$$I, h \models P \mathrel{-\!\!*} Q$$
$$\text{iff } \forall h'.(h \# h') \wedge (I, h' \models P) \rightarrow I, h \circ h' \models Q$$

Interpretation : If we extend the current heap with a disjoint heap satisfying P, then the new heap satisfies Q. In some ways, we can imagine that our current heap is only missing the records of P, to make it satisfy Q.

Points to

$$I, h \models E \hookrightarrow E'$$
$$\text{iff } h([\![E]\!]_I) = [\![E']\!]_I$$

Examples

Points to,

$$F : x \hookrightarrow 10$$
$$I : \{(x, 0)\}$$
$$h : \{(0, 10)\}$$
$$I, h \models F$$

Separating conjunction,

$$F : x \hookrightarrow 10 * y \hookrightarrow 20$$
$$I : \{(x, 0), (y, 1)\}$$
$$h : \{(0, 10), (1, 20)\}$$
$$I, h \models F$$

Examples

Another example,

$$F : x \hookrightarrow y * y \hookrightarrow x$$
$$I : \{(x, 0), (y, 1)\}$$
$$h : \{(0, 1), (1, 0)\}$$
$$I, h \models F$$

Examples

Separating Implication

$$I, h \models P \mathrel{-\!\!*} Q$$
$$\text{iff } \forall h'.(h \# h') \wedge (I, h' \models P) \rightarrow I, h \circ h' \models Q$$

Example,

$$F : (x \hookrightarrow 10) \mathrel{-\!\!*} (x \hookrightarrow 10 * y \hookrightarrow 20)$$
$$I : \{(x, 0), (y, 1)\}$$
$$h' : \{(0, 10)\}$$
$$h : \{(1, 20)\}$$
$$h \circ h' : \{(0, 10), (1, 20)\}$$
$$I, h \models F$$

Applications

Separation logic has been useful in Hoare logic for program verification. We will have a quick look at Hoare logic.

$$\{P\}S\{Q\}$$

P : Logical assertion on states - precondition

S : Code section that modifies state

Q : Logical assertion on states - postcondition

Example,

$$\{x = 1\}x := 2\{x = 2\}$$

The programs S are defined against a language specification with imperative commands such as skip, loops, variable and pointer assignments.

Applications

Now given a post-condition Q and program S, we want to calculate the set of states, that the program can be in before, to end-up in Q after execution.
Example,

$$\{x > 0\}x := x + 1\{x >= 0\}$$

This is also valid,

$$\{x > -1\}x := x + 1\{x >= 0\}$$

In fact, $(x > -1) \rightarrow (x > 0)$, thus, $(x > -1)$ is weaker. Finding the weakest unique precondition, can then let us reason about all the states, that the program can be in before, to guarantee Q to hold.

Applications

The first application of separation logic in Hoare-style verification is to do local reasoning, which is defined as,

$$\frac{\{P\}S\{Q\}}{\{P * R\}S\{Q * R\}}$$

Example,

$$\{\text{root} \hookrightarrow (\text{left}, \text{right}) * \text{tree(left)} * \text{tree(right)}\}$$
$$\text{deletetree(left)}$$
$$\{\text{root} \hookrightarrow (\text{left}, \text{right}) * \text{emp} * \text{tree(right)}\}$$
$$\text{deletetree(right)}$$
$$\{\text{root} \hookrightarrow (\text{left}, \text{right}) * \text{emp} * \text{emp}\}$$
$$\text{free(root)}$$
$$\{\text{emp} * \text{emp} * \text{emp}\}$$
$$\{\text{emp}\}$$

Applications

Another application is to have a modus-ponens similar operation for heaps.

$$P * (P \mathrel{-\!\!*} Q) \models Q$$

Example,

$$(x \hookrightarrow v_1) * (x \hookrightarrow v_1 \mathrel{-\!\!*} y \hookrightarrow v_2) \models (y \hookrightarrow v_2)$$

Also, this is used in weakest pre-condition computation, where if we have a triple,

$$\{P\}x := 3\{Q\}$$

where the weakest precondition would be,

$$wp(x := 3, Q) \equiv (x \hookrightarrow -) * ((x \hookrightarrow 3) \mathrel{-\!\!*} Q)$$

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Translating Separation Logic into Pointer Logic

Points to,

$$I, h \models x \hookrightarrow v$$
$$\Longleftrightarrow$$
$$L, M \models {}^*x = v$$

Separating conjunction,

$$I, h \models x \hookrightarrow v_1 * y \hookrightarrow v_2$$
$$\Longleftrightarrow$$
$$L, M \models {}^*x = v_1 \ \wedge \ {}^*y = v_2 \wedge x \neq y$$

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Need for inductive predicates

- Most interesting data structures in programs are defined as inductive systems
- For example : linked lists, trees, graphs
- Being able to reason about these in SL is useful
- But inductive predicates introduce quantifiers

This way of specifying a list is quite cumbersome,

$$p \hookrightarrow v_1, p_1 \wedge$$
$$p_1 \hookrightarrow v_2, p_2 \wedge$$
$$p_2 \hookrightarrow v_3, p_3 \wedge$$
$$\ldots$$

Lists in pointer logic

First try at defining lists without explicit quantifiers. We define the following predicates for the i^{th} element of the list,

$$\text{list-elem}(p, 0) \equiv p$$
$$\text{list-elem}(p, i) \equiv *\text{list-elem}(p, i-1)$$

In this formulation, a null-terminated list would be

$$\text{list-elem}(p, l) = \mathit{NULL}$$

and a cyclic list would be,

$$\text{list-elem}(p, l) = p$$

But the last predicate is also satisfied by an element with length 1.

Lists in pointer logic

To actually get a disjoint list with unique pointer elements, we need to add an extra constraint,

$$\text{overlap}(p, q) \equiv p = q \vee p + 1 = q \vee p = q + 1$$
$$\text{list-disjoint}(p, 0) \equiv \mathit{TRUE}$$
$$\text{list-disjoint}(p, l) \equiv \text{list-disjoint}(p, l - 1) \wedge$$
$$\forall 0 \leq i < l - 1. \neg\, \text{overlap}(\text{list-elem}(p, i), \text{list-elem}(p, l - 1))$$

The set of clauses grows quadratically upon the quantifier instantiation.

Lists - Try 2

We use inductive predicates to define lists,

$$\text{list } 0\ x \equiv \mathit{empty} \wedge x = \mathit{nil}$$
$$\text{list } n\ x \equiv \exists y.(x \hookrightarrow n, y) * (\mathit{list}\ (n-1)\ y)$$

- This defines a linked-list rooted at x
- Base case : empty list where heap is empty and root pointer is null
- Inductive case : the root points to a struct which has a value and the pointer for the remaining list
- Separately, the next pointer points to a list. Prevents pointer aliasing, each pointer is different