

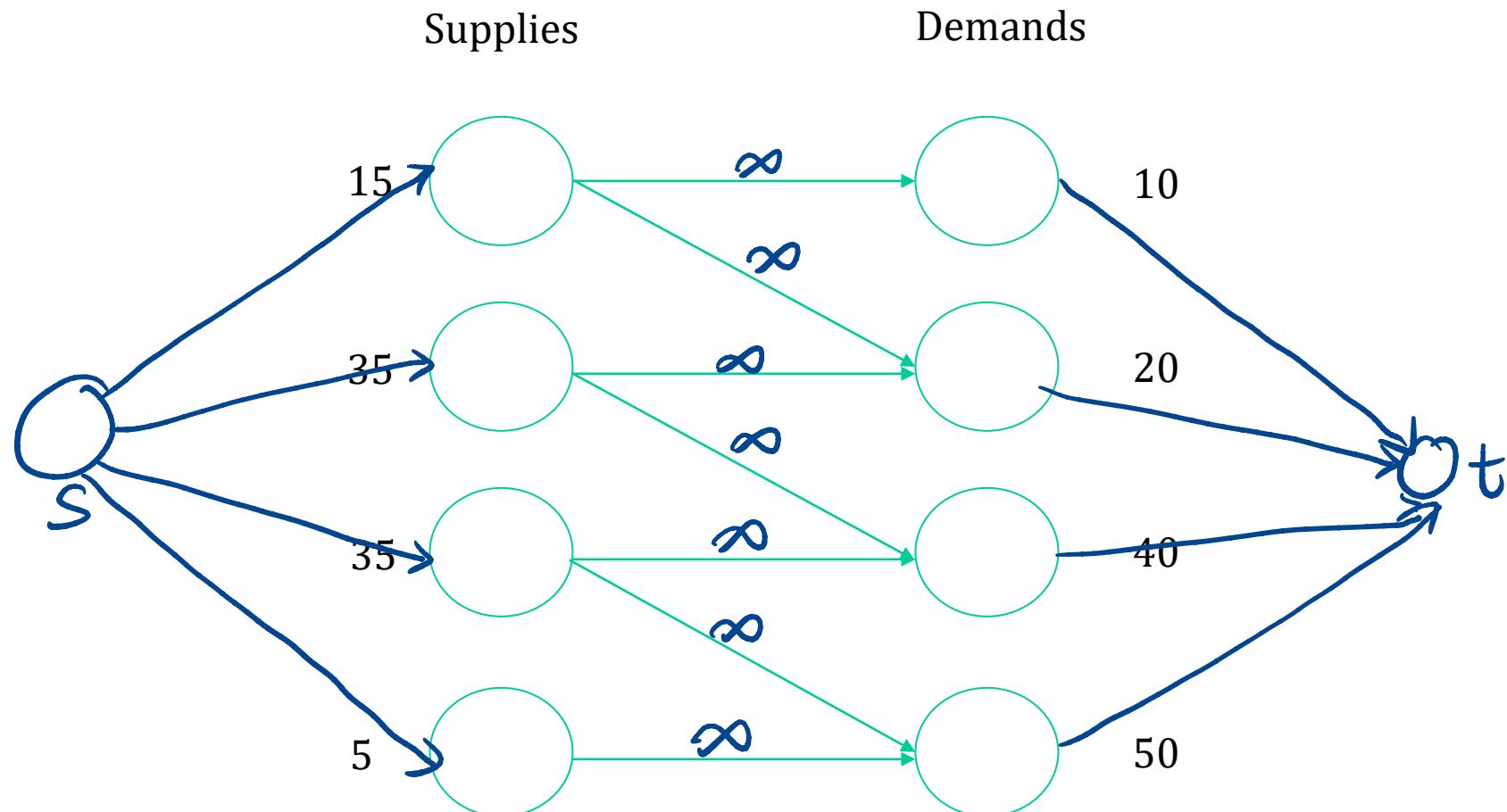
LEC011 Maximum Flow and Linear Program

VG441 SS2021

Cong Shi
Industrial & Operations Engineering
University of Michigan

Max Flow Applications

matching problem



Linear Programming

- Comparison to systems of linear equations

$$\begin{aligned} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n &= b_1 & Ax = b \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n &= b_2 \\ &\vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n &= b_m \end{aligned}$$

$$\min c^T x$$

$$Ax \leq b$$

Linear Programming

- Ingredients of a Linear Program

1. Decision variables $x_1, \dots, x_n \in \mathbb{R}$
2. Linear constraints, each of the form

$$\sum_{j=1}^n a_{ij}x_j \stackrel{(*)}{=} b_i$$

where (*) could be \leq, \geq , or $=$

3. A linear objective function, of the form

$$\max \sum_{j=1}^n c_j x_j \quad \text{or} \quad \min \sum_{j=1}^n c_j x_j$$

A Simple Example

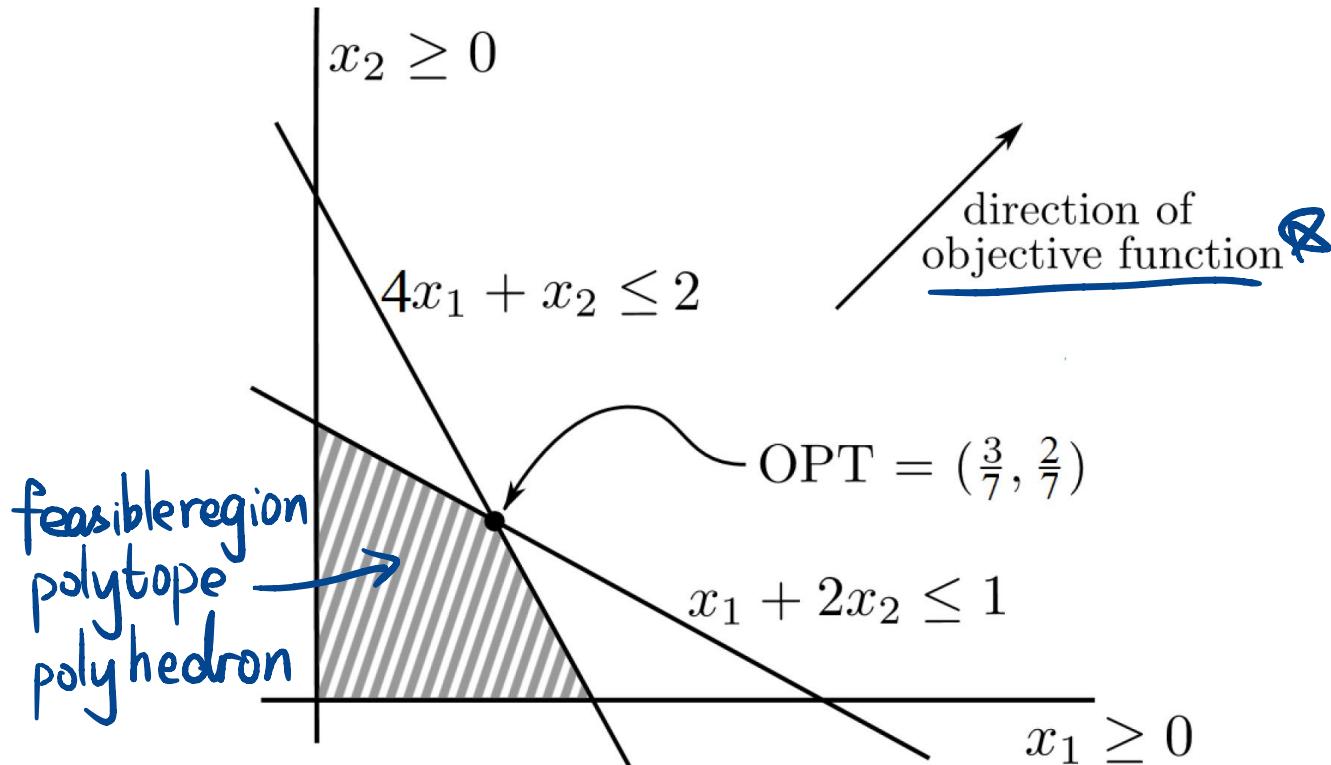
$$\max \quad x_1 + x_2$$

$$\text{s.t.} \quad 4x_1 + x_2 \leq 2$$

$$x_1 + 2x_2 \leq 1$$

$$x_1, x_2 \geq 0$$

$$x_1 + x_2 = (1 \ 1) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$



Python + Gurobi Time!

1. Excel Add-in Tools
2. small scale problem → Excel



MaxFlow is a LP

- Decision variables

$$\{f_e\}_{e \in E}$$

- Constraints ($2m + n - 2$)

$$\underbrace{\sum_{e \in \delta^-(v)} f_e}_{\text{flow in}} - \underbrace{\sum_{e \in \delta^+(v)} f_e}_{\text{flow out}} = 0$$

$$f_e \leq u_e$$

- Objectives

$$f_e \geq 0$$

$$\max \sum_{e \in \delta^+(s)} f_e$$

Generalization of MaxFlow \rightarrow simple

\downarrow
F-F algorithm
(fast)

- Min-Cost MaxFlow

$$\min \sum_{e \in E} c_e f_e$$

$\max flow \geq 0$
add additional constraints

- Easy to change the LP formulation!

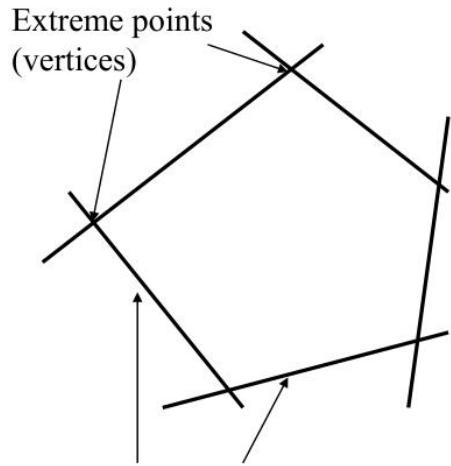
LP优点: customize

Solution Approaches(LP)

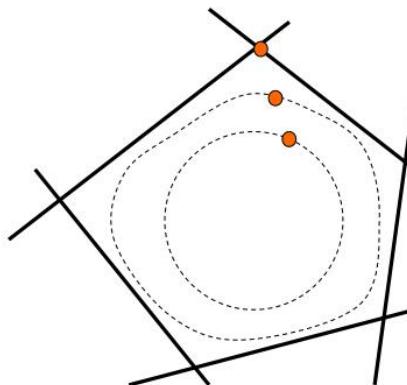
- Simplex methods
- Interior point methods

start of every vertex, check neighbours, stop when no neighbour is better (已找到 local optimization)
polytope : feasible region \uparrow Grobi

Interior point methods



Simplex: search from vertex to vertex along the edges



barrier-function.

Interior-point methods: go through the inside of the feasible space

CVX (develop by stanford) solve this by
interior



Primal LP \Leftrightarrow Dual LP LP Duality 二重性

- Question: given a feasible solution, how can we know whether it is optimal or close to optimal? *can we actually get the upper bound of solution*

$$\begin{aligned} \max \quad & x_1 + x_2 \\ \text{s.t.} \quad & 4x_1 + x_2 \leq 2 \\ & x_1 + 2x_2 \leq 1 \\ & x_1, x_2 \geq 0 \end{aligned}$$

$$\underbrace{x_1 + x_2}_{\text{objective}} \leq 4x_1 + x_2 \leq \underbrace{2}_{\text{upper bound}}$$

$$\underbrace{x_1 + x_2}_{\text{objective}} \leq x_1 + 2x_2 \leq \underbrace{1}_{\text{upper bound}}$$

how can I make sure that I have the best upper bound

Can we get an even better upper bound?

$$x_1 + x_2 \leq \frac{1}{7} \underbrace{(4x_1 + x_2)}_{\leq 2 \text{ by (2)}} + \frac{3}{7} \underbrace{(x_1 + 2x_2)}_{\leq 1 \text{ by (3)}} \leq \frac{1}{7} \cdot 2 + \frac{3}{7} \cdot 1 = \frac{5}{7}$$

better upper bound

$$x_1^* = \frac{3}{7} \quad x_2^* = \frac{2}{7} \quad \text{obj}^* = \frac{5}{7}$$

Deriving the Dual LP

Compact form

$$\begin{array}{ll} \max & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & \mathbf{A}\mathbf{x} \leq \mathbf{b} \\ & \mathbf{x} \geq 0 \end{array}$$

\max

$$\sum_{j=1}^n c_j x_j$$

s.t.

$$\sum_{j=1}^n a_{1j} x_j \leq b_1$$

“Multipliers”

$$y_1 \geq 0$$

$$\sum_{j=1}^n a_{2j} x_j \leq b_2$$

$$y_2 \geq 0$$

$$\vdots \leq \vdots$$

$$\sum_{j=1}^n a_{mj} x_j \leq b_m$$

$$y_m \geq 0$$

$$x_1, \dots, x_n \geq 0$$

The idea is to “dominates the objective coefficients”:

$$\sum_{i=1}^m y_i a_{ij} \geq c_j$$

More compactly,

Find $\mathbf{y} \geq 0$ such that $\mathbf{A}^T \mathbf{y} \geq \mathbf{c}$

mixing all the constraints

Deriving the Dual LP

$$\begin{array}{ll} \max & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & \mathbf{A}\mathbf{x} \leq \mathbf{b} \\ & \mathbf{x} \geq 0 \end{array}$$

Find $\mathbf{y} \geq 0$ such that $\mathbf{A}^T \mathbf{y} \geq \mathbf{c}$

clever thing to do:

$$\begin{array}{l} \min \mathbf{y}^T \mathbf{b} \\ \mathbf{A}^T \mathbf{y} \geq \mathbf{c} \\ \mathbf{y} \geq 0 \end{array}$$

dual LP

$$\begin{aligned} \sum_{j=1}^n c_j x_j &\leq \sum_{j=1}^n \left(\sum_{i=1}^m y_i a_{ij} \right) x_j && \text{dominant } c \\ &= \sum_{i=1}^m y_i \cdot \left(\sum_{j=1}^n a_{ij} x_j \right) && \leq b_i \forall i \\ &\leq \underbrace{\sum_{i=1}^m y_i b_i}_{\text{upper bound}} && \text{把第 } i \text{ 项弄得更 general - } \Rightarrow \end{aligned}$$

More compactly,

$$\mathbf{c}^T \mathbf{x} \leq (\mathbf{A}^T \mathbf{y})^T \mathbf{x} = \mathbf{y}^T (\mathbf{A}\mathbf{x}) \leq \mathbf{y}^T \mathbf{b}$$

Deriving the Dual LP

$$\begin{array}{ll}\max & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & \mathbf{A} \mathbf{x} \leq \mathbf{b} \\ & \mathbf{x} \geq 0\end{array}$$

weak duality
 $\text{OPT}(P) \leq \text{OPT}(D)$

Find $\mathbf{y} \geq 0$ such that $\mathbf{A}^T \mathbf{y} \geq \mathbf{c}$

$$\mathbf{c}^T \mathbf{x} \leq (\mathbf{A}^T \mathbf{y})^T \mathbf{x} = \mathbf{y}^T (\mathbf{A} \mathbf{x}) \leq \mathbf{y}^T \mathbf{b}$$

$$\begin{array}{ll}\min & \mathbf{b}^T \mathbf{y} \\ \text{s.t.} & \mathbf{A}^T \mathbf{y} \geq \mathbf{c} \\ & \mathbf{y} \geq 0\end{array}$$

strong duality:
 $\text{OPT}(P) = \text{OPT}(D)$
proof is non-trivial:
hyperplane separation
Farkas' Lemma

A Simple Example

Primal problem

$$\begin{array}{ll} \max & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & \mathbf{A}\mathbf{x} \leq \mathbf{b} \\ & \mathbf{x} \geq 0 \end{array}$$

$$\mathbf{c} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\mathbf{A} = \begin{pmatrix} 4 & 1 \\ 1 & 2 \end{pmatrix}$$

$$\mathbf{b} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

Dual Problem

$$\begin{array}{ll} \min & \mathbf{b}^T \mathbf{y} \\ \text{s.t.} & \mathbf{A}^T \mathbf{y} \geq \mathbf{c} \\ & \mathbf{y} \geq 0 \end{array}$$

$$\begin{array}{ll} \max & x_1 + x_2 \\ \text{s.t.} & 4x_1 + x_2 \leq 2 \\ & x_1 + 2x_2 \leq 1 \\ & x_1, x_2 \geq 0 \end{array}$$

$$\begin{array}{ll} \min & 2y_1 + y_2 \\ \text{s.t.} & 4y_1 + y_2 \geq 1 \\ & y_1 + 2y_2 \geq 1 \\ & y_1, y_2 \geq 0 \end{array}$$

$$x_1^* = 3/7, x_2^* = 2/7$$

$$y_1^* = 1/7, y_2^* = 3/7$$

Optimal objectives are the same!

Weak and Strong Duality

$$\begin{aligned} \max \quad & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} \quad & \mathbf{A}\mathbf{x} \leq \mathbf{b} \\ & \mathbf{x} \geq 0 \end{aligned}$$

$$\begin{aligned} \min \quad & \mathbf{b}^T \mathbf{y} \\ \text{s.t.} \quad & \mathbf{A}^T \mathbf{y} \geq \mathbf{c} \\ & \mathbf{y} \geq 0 \end{aligned}$$

We have

$$\text{OPT}(P) \leq \text{OPT}(D)$$

- Weak Duality $\underline{\mathbf{c}^T \mathbf{x} \leq \mathbf{b}^T \mathbf{y}}$ for any feasible solutions \mathbf{x} and \mathbf{y}
- Strong Duality $\underline{\mathbf{OPT}(P) = \text{OPT}(D)}$
 $\mathbf{c}^T \mathbf{x}^* = \mathbf{b}^T \mathbf{y}^*$ at optimality

Proof = Separating hyperplane theorem + Farkas's Lemma

More General Form

Primal	Dual
variables x_1, \dots, x_n	n constraints
m constraints	variables y_1, \dots, y_m
objective function \mathbf{c}	right-hand side \mathbf{c}
right-hand side \mathbf{b}	objective function \mathbf{b}
$\max \mathbf{c}^T \mathbf{x}$	$\min \mathbf{b}^T \mathbf{y}$
constraint matrix \mathbf{A}	constraint matrix \mathbf{A}^T
i-th constraint is “ \leq ”	$y_i \geq 0$
i-th constraint is “ \geq ”	$y_i \leq 0$
i-th constraint is “ $=$ ”	$y_i \in \mathbb{R}$
$x_j \geq 0$	j-th constraint is “ \geq ”
$x_j \leq 0$	j-th constraint is “ \leq ”
$x_j \in \mathbb{R}$	j-th constraint is “ $=$ ”

constraint \longleftrightarrow variable
 variable \longleftrightarrow constraints

Back to MaxFlow

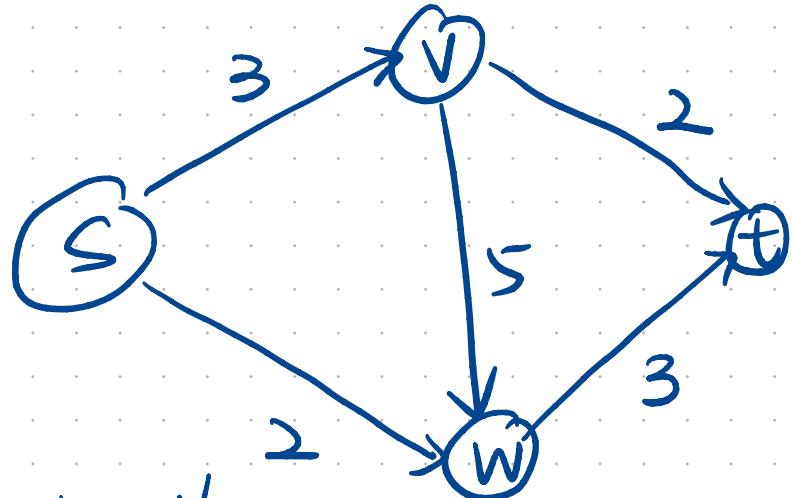
- Let the decision variable be flow on an s-t path

Primal

$$\max \quad \sum_{P \in \mathcal{P}} f_P$$

$$\text{s.t.} \quad \underbrace{\sum_{P \in \mathcal{P}: e \in P} f_P}_{\text{total flow on } e} \leq u_e \text{ for all } e \in E$$
$$f_P \geq 0 \text{ for all } P \in \mathcal{P}$$

Question: how to write its dual and what is its interpretation?



s-t path:

$$P_1: S \rightarrow V \rightarrow T \quad f_{P_1} = 2$$

$$P_2: S \rightarrow V \rightarrow W \rightarrow T \quad f_{P_2} = 1$$

$$P_3: S \rightarrow W \rightarrow T \quad f_{P_3} = 2$$

$$\begin{aligned} & \max \sum_{P \in P} f_P \\ \text{st. } & \sum_{P \in P: e \in P} f_P \leq u_e, \forall e \in E \\ & f_P \geq 0 \quad \forall P \in P \end{aligned}$$

convert into
↓ matrix notation

$$\begin{aligned} & \max \mathbf{1}^T \mathbf{f} \\ & A\mathbf{f} \leq \mathbf{u} \\ & \mathbf{f} \geq 0 \end{aligned}$$