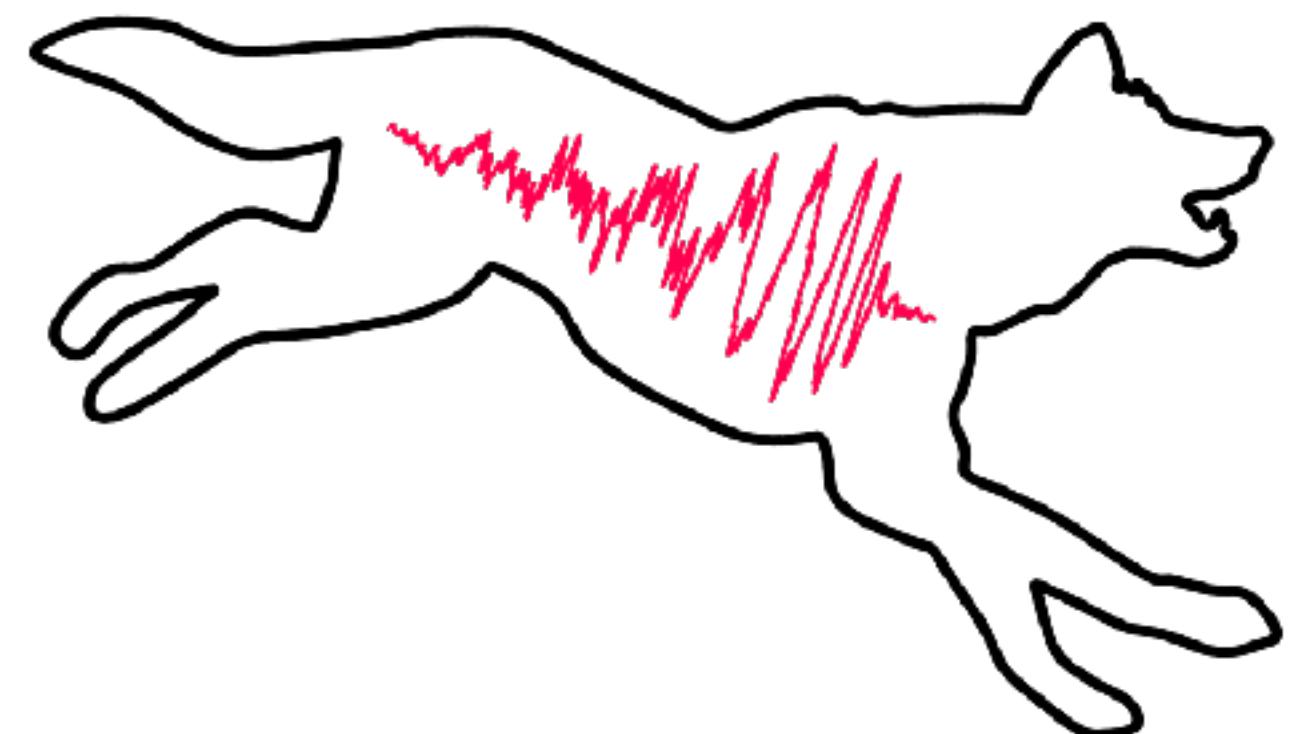


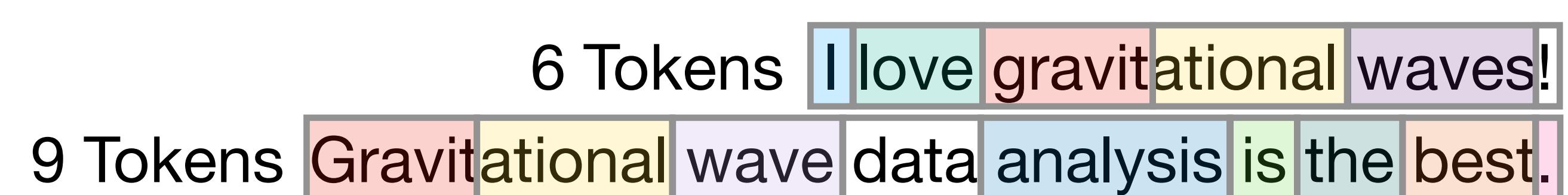
Flexible Gravitational-Wave Parameter Estimation with Transformers

Annalena Kofler, 18.12.2025
ML Algorithms Group, LIGO



Transformers for GW data

- Increasing number of papers that use transformers:
 - Denoising Previous talk!
 - Detection Jiang & Luo ICPR 2022, Chatterjee et al. arXiv 2025, Joshi & Prix arXiv 2025
 - Glitch classification Chatterjee et al. arXiv 2025
 - Waveform generation Shi et al., PRD 2024
 - Parameter estimation Papalini et al. Class. Quantum Grav. 2025
- Strength of transformers: **Variable sequence length**
 - Flexible parameter estimation

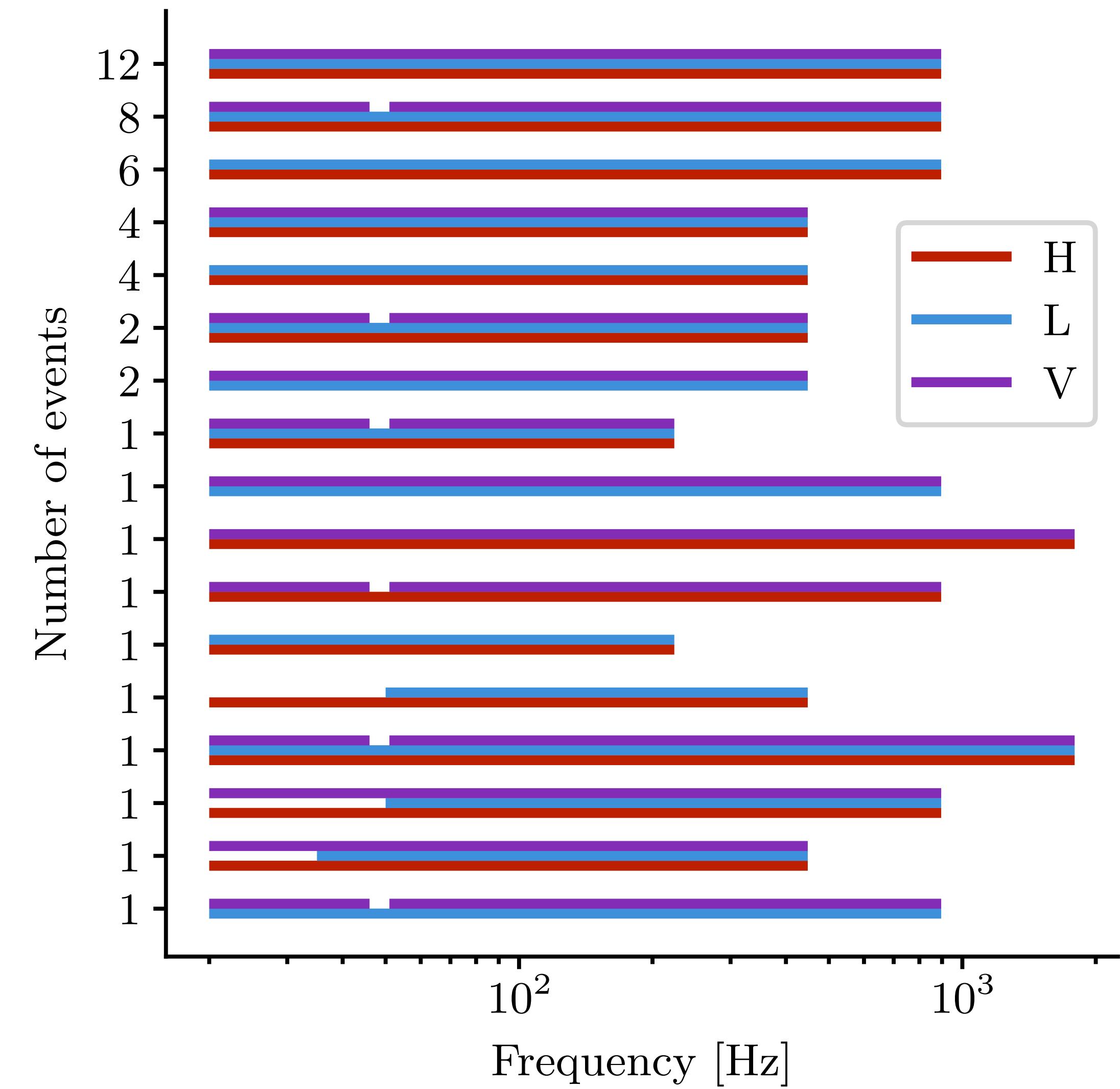


Why do we need flexible parameter estimation?

Example: Official O3 LVK analysis

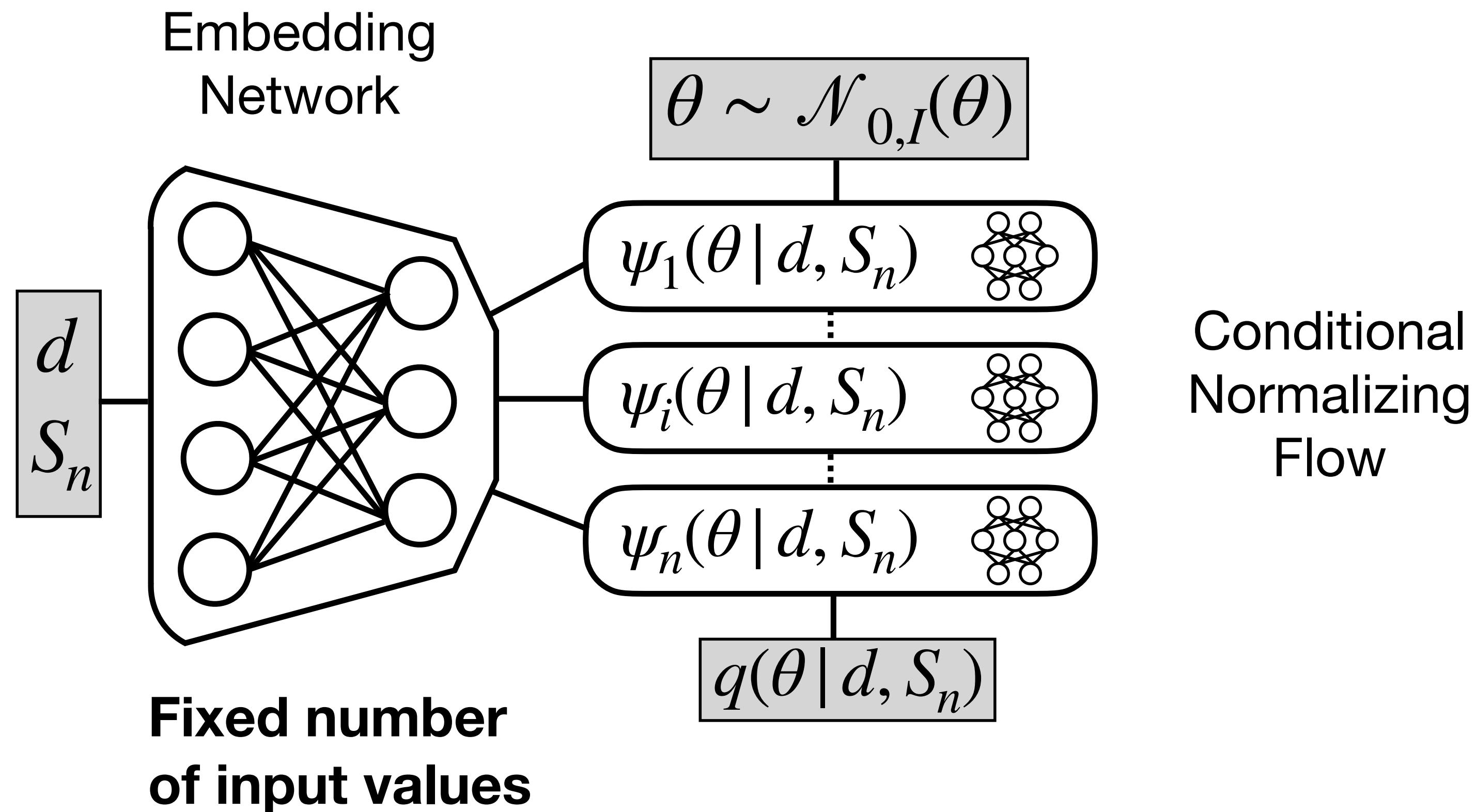
- 48 events with 17 different data configurations
 - Different detectors
 - Different frequency ranges

Problem:
Amortized ML approaches like DINGO¹ cannot deal with changing inputs!



Why is the DINGO architecture not flexible?

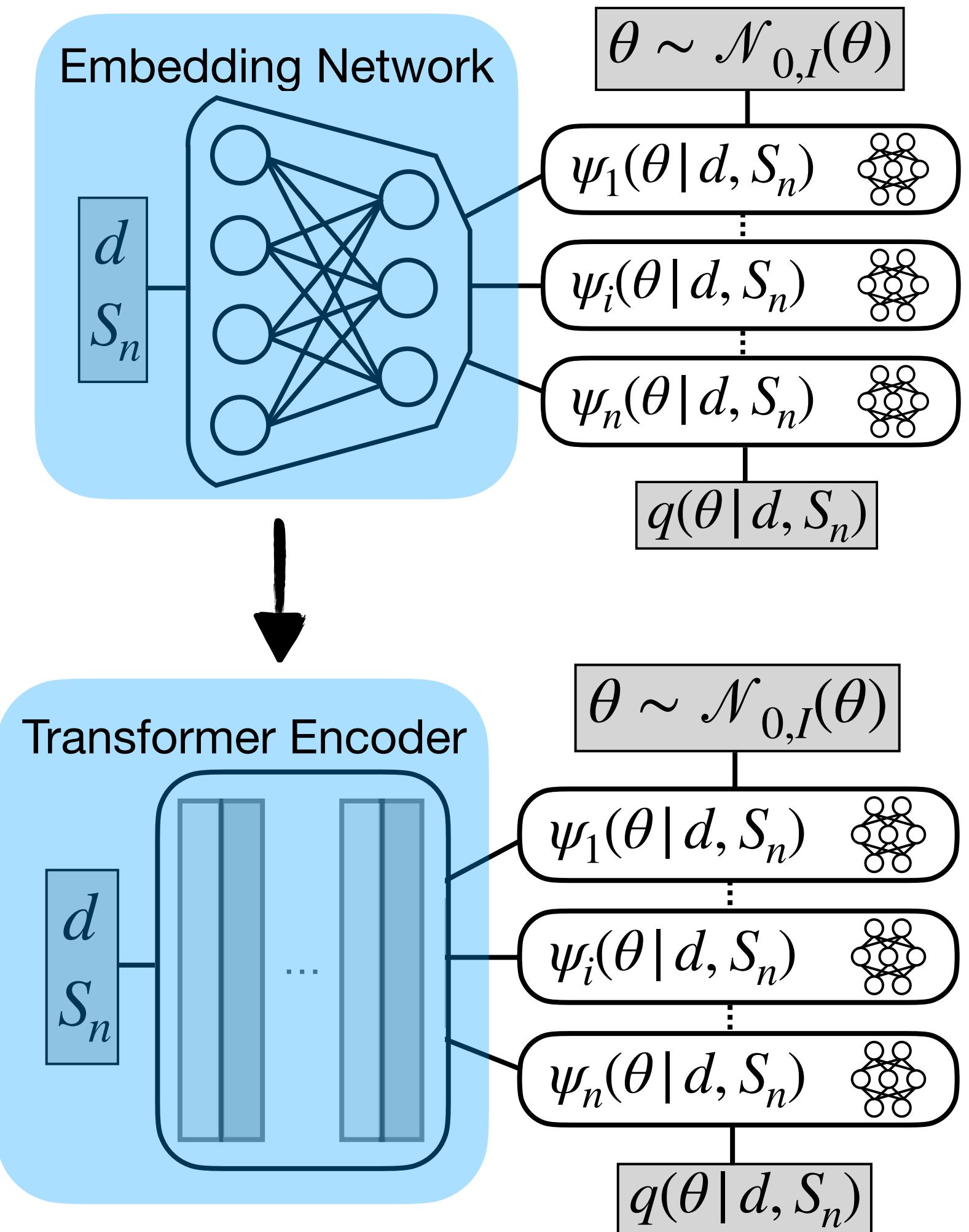
- Compress data d and noise PSD S_n via embedding network
- Train with negative log-likelihood loss $\mathcal{L} = \mathbb{E}_{p(\theta), p(S_n), p(d|\theta, S_n)} [-\log q(\theta | d, S_n)]$



How do we make DINGO flexible?

- Replace fixed embedding network with transformer encoder²
- Train with signals of varying shapes
- Adjust exact data analysis settings at inference time

→ **DINGO-T1** (Transformer version 1)

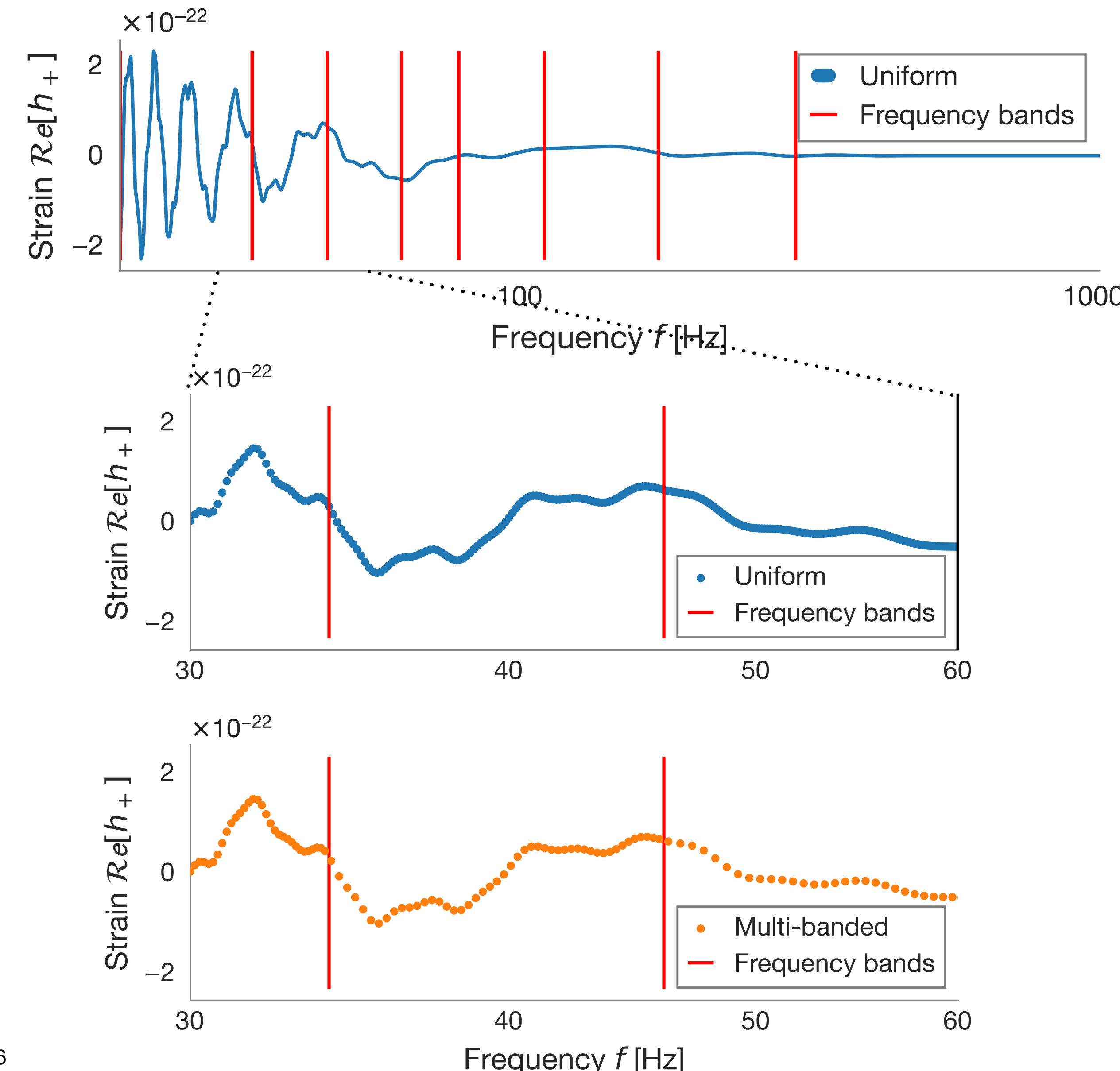


Previous work (relevant for this talk)

- **Conditioning** on measured ASD
Dax+ PRL 2021, ICLR 2022
- **Importance sampling** to validate model & reweigh samples towards true posterior
Dax+ PRL 2023

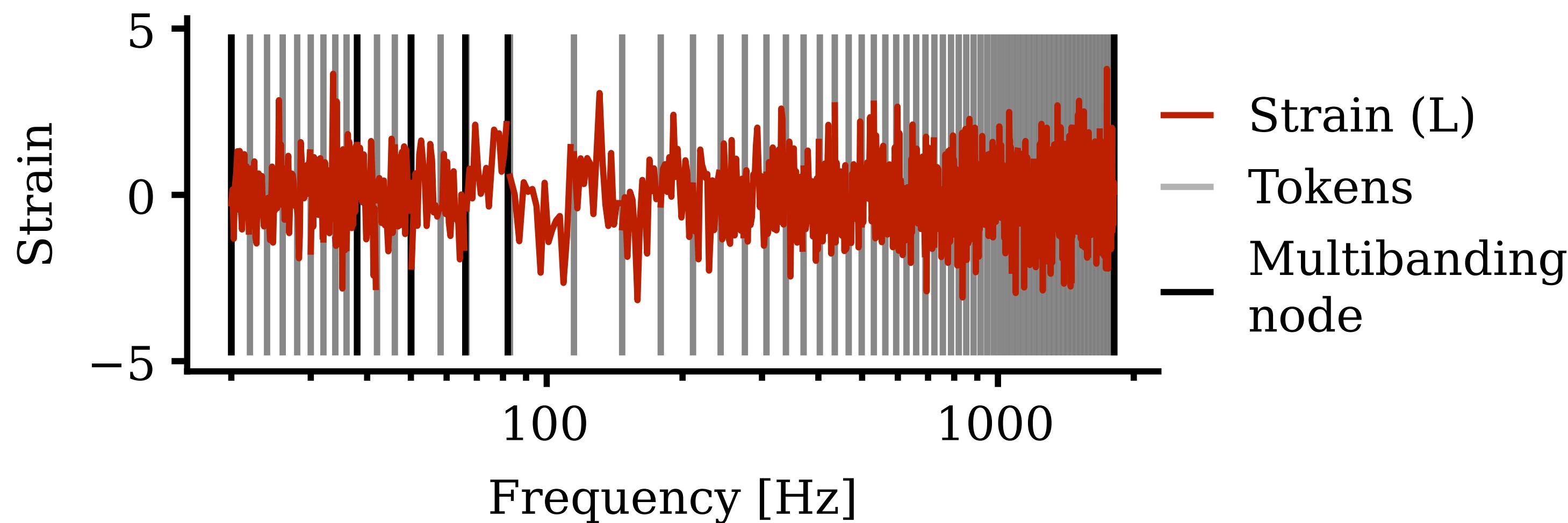
$$\text{Efficiency: } \epsilon = \frac{N_{\text{eff}}}{N}$$

- **“Multibanding”**: Data compression
Dax+ Nature 2025



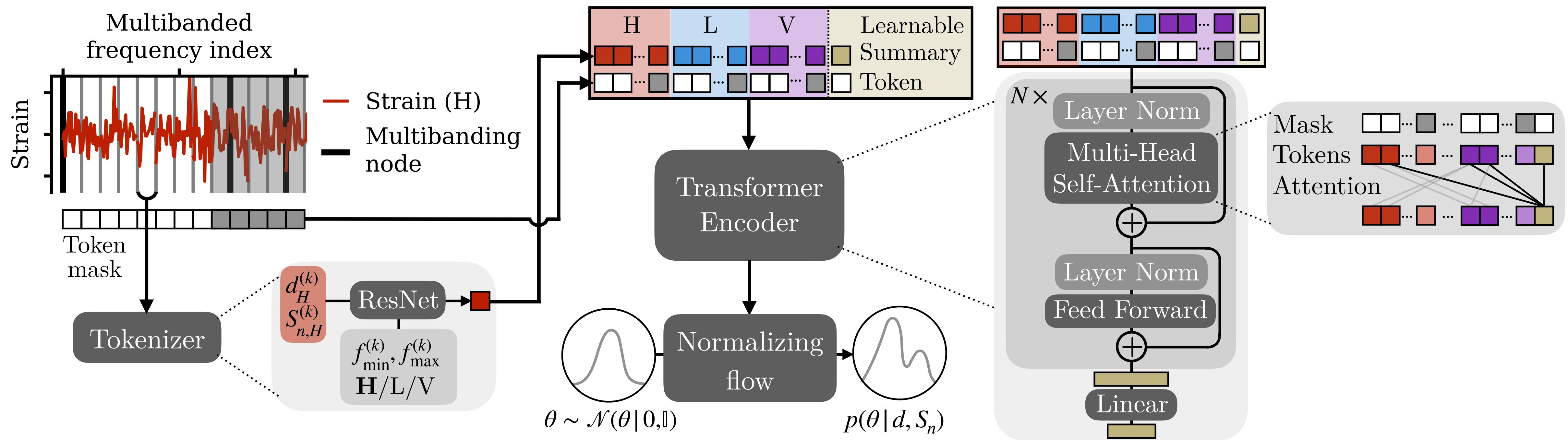
Preparing token segments

- Extend multibanding:
 - Resolution should be consistent within a token segment
 - Tokens should have same number of strain values
 - Nodes of multibanded frequency domain should align with token boundaries



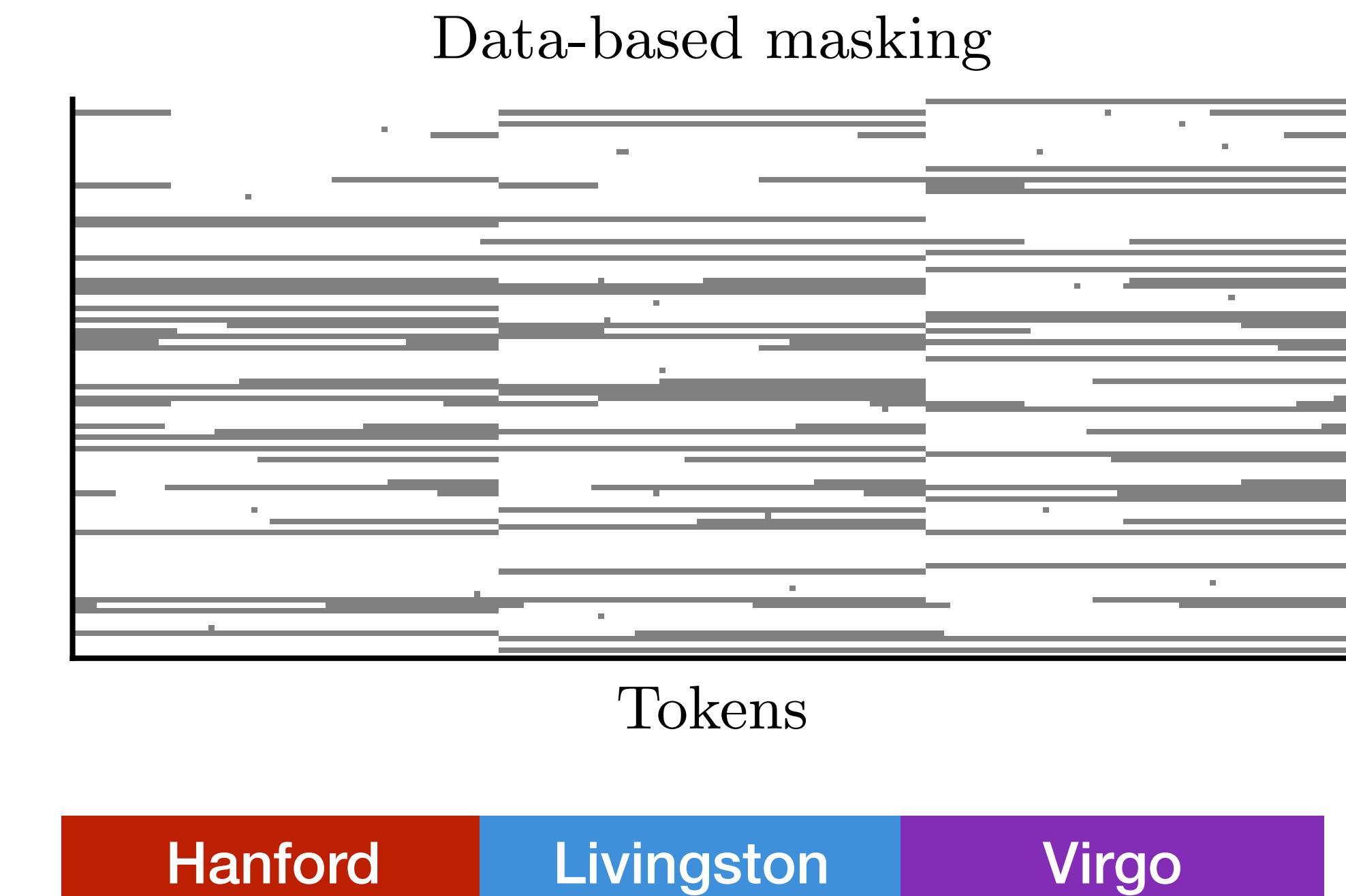
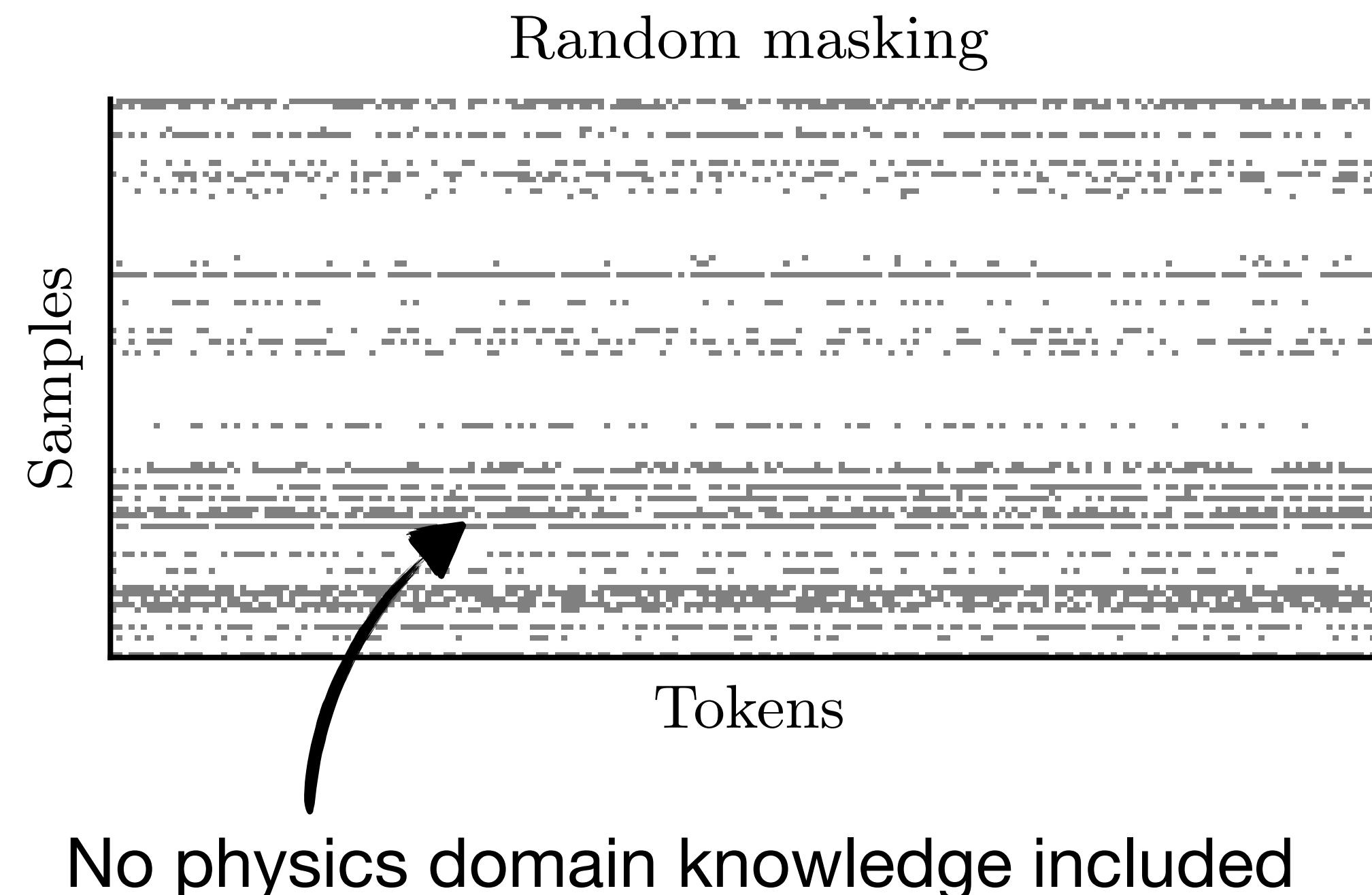
DINGO-T1 Architecture

- Shared tokenizer across detector and frequencies
- Extract information via summary token
- End-to-end training



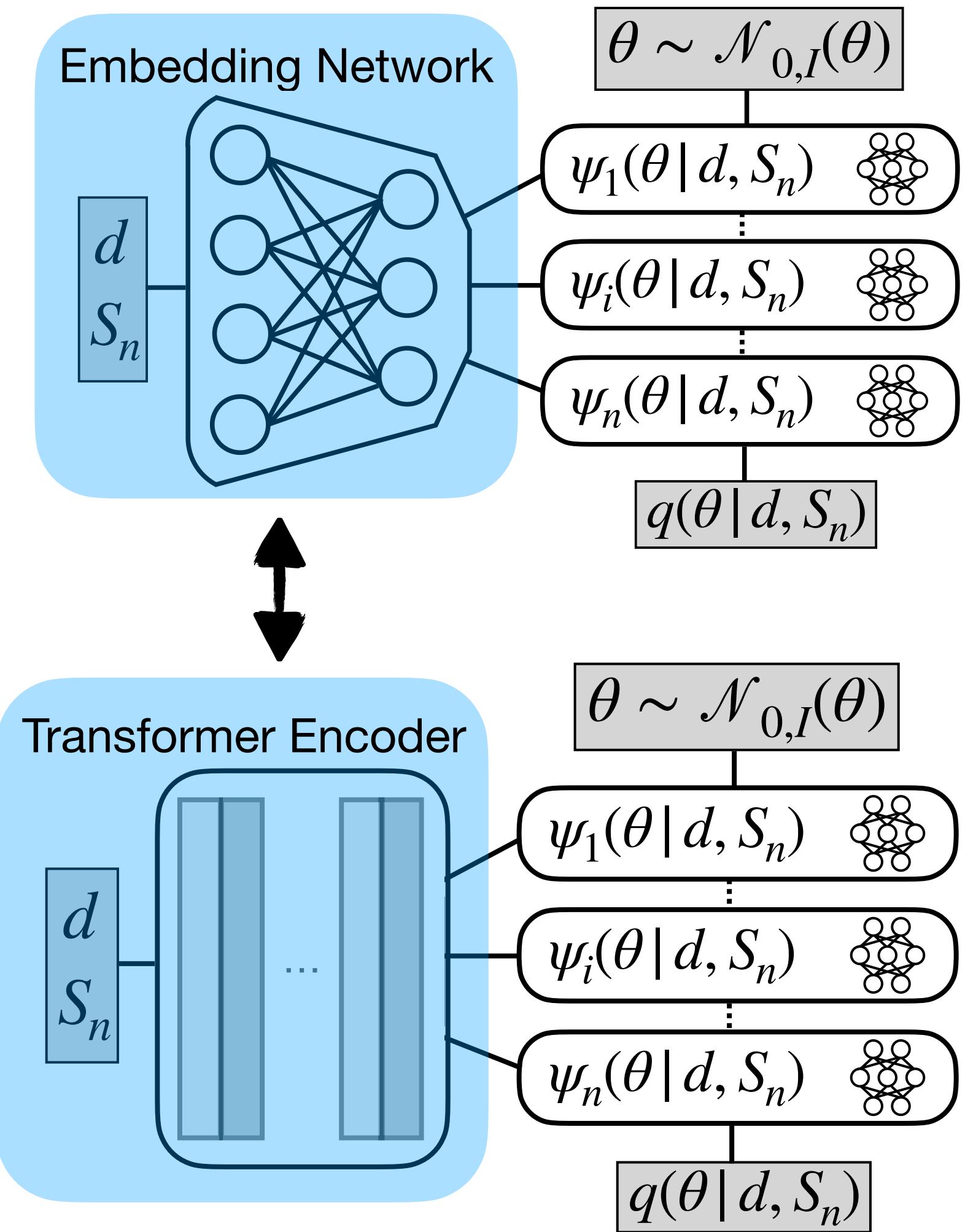
Training a flexible model

- Loss: $\mathcal{L} = \mathbb{E}_{p(\theta)p(S_n)p(d|\theta, S_n)p(m)} \left[-\log q(\theta | m(d), m(S_n)) \right]$
- Two masking strategies $m \sim p(m)$:



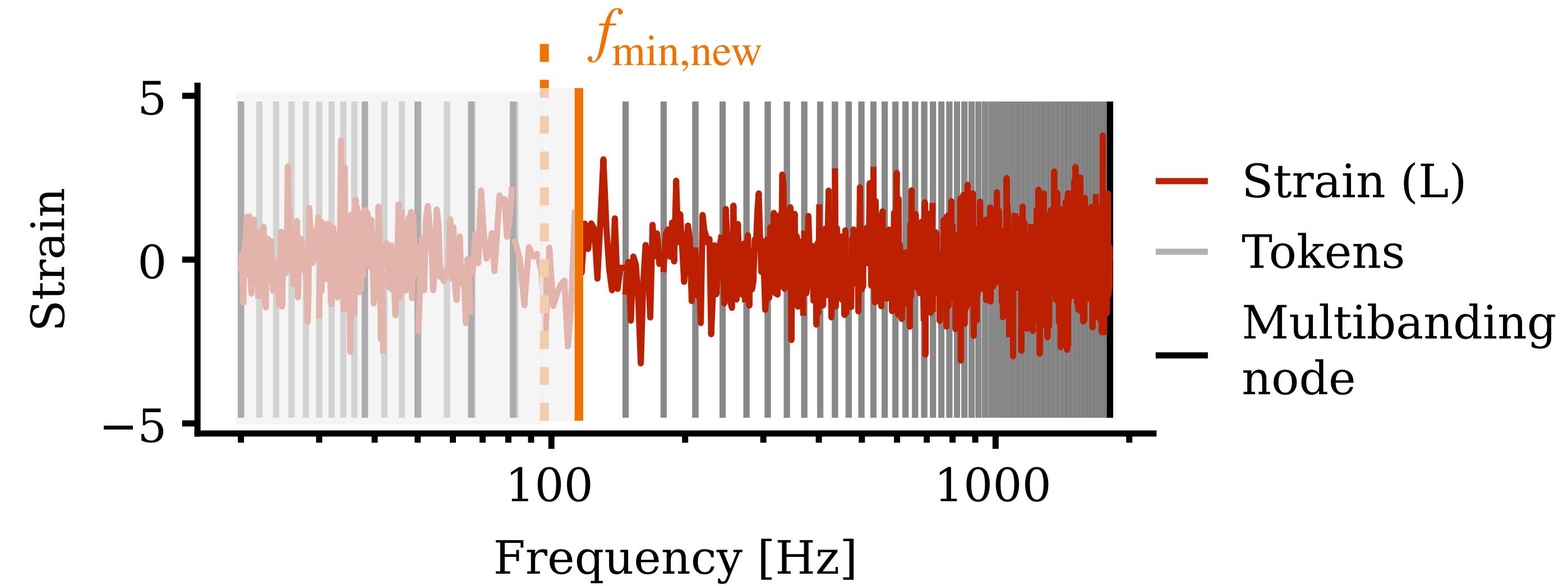
Training a flexible model

- Train with $2.5 \cdot 10^7$ IMRPhenomXPHM waveforms and $\sim 10^3$ noise curves
- Distributed data-parallel training on 8 A100 GPUs
 $\rightarrow \sim 8$ days
- Baseline: NPE with ResNet embedding network



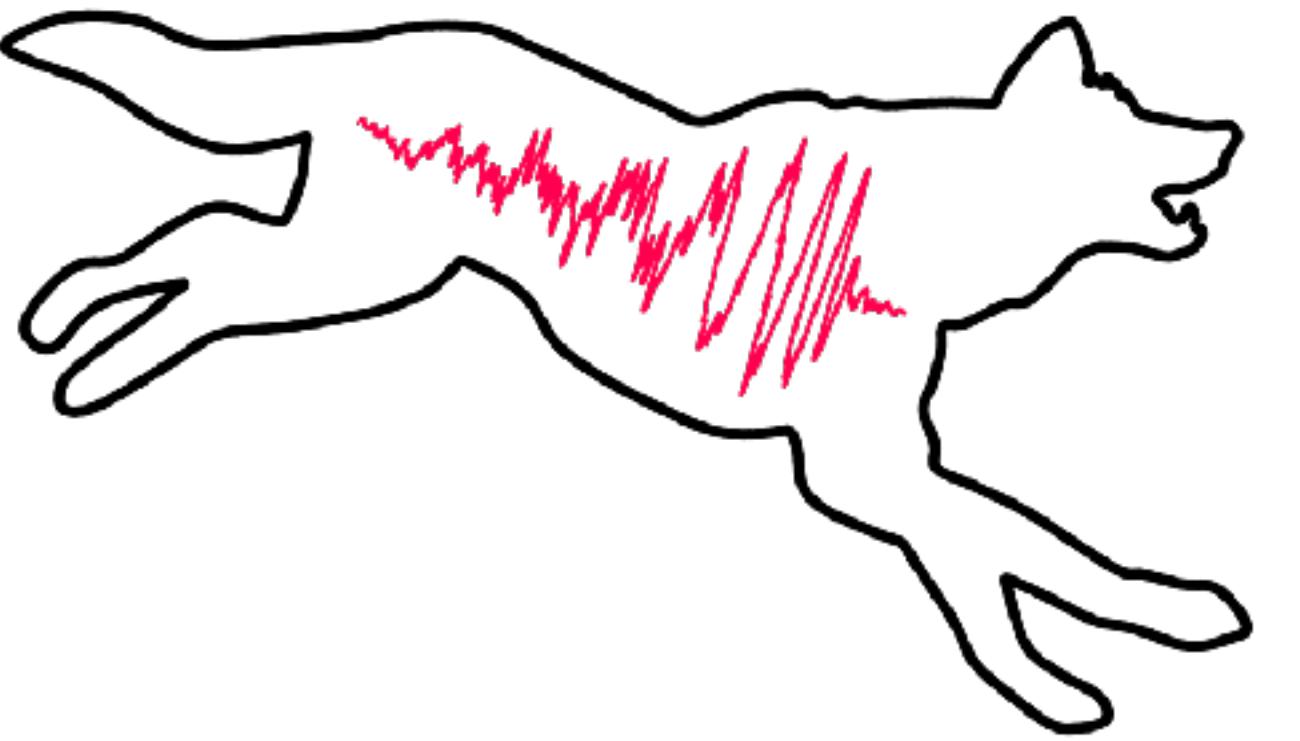
Data analysis settings during inference

- Remove token inclusively by masking unwanted tokens
- Perform importance sampling on uniform frequency domain



- Result independent of multi-banding and masking
- Correct for potential information loss

Results

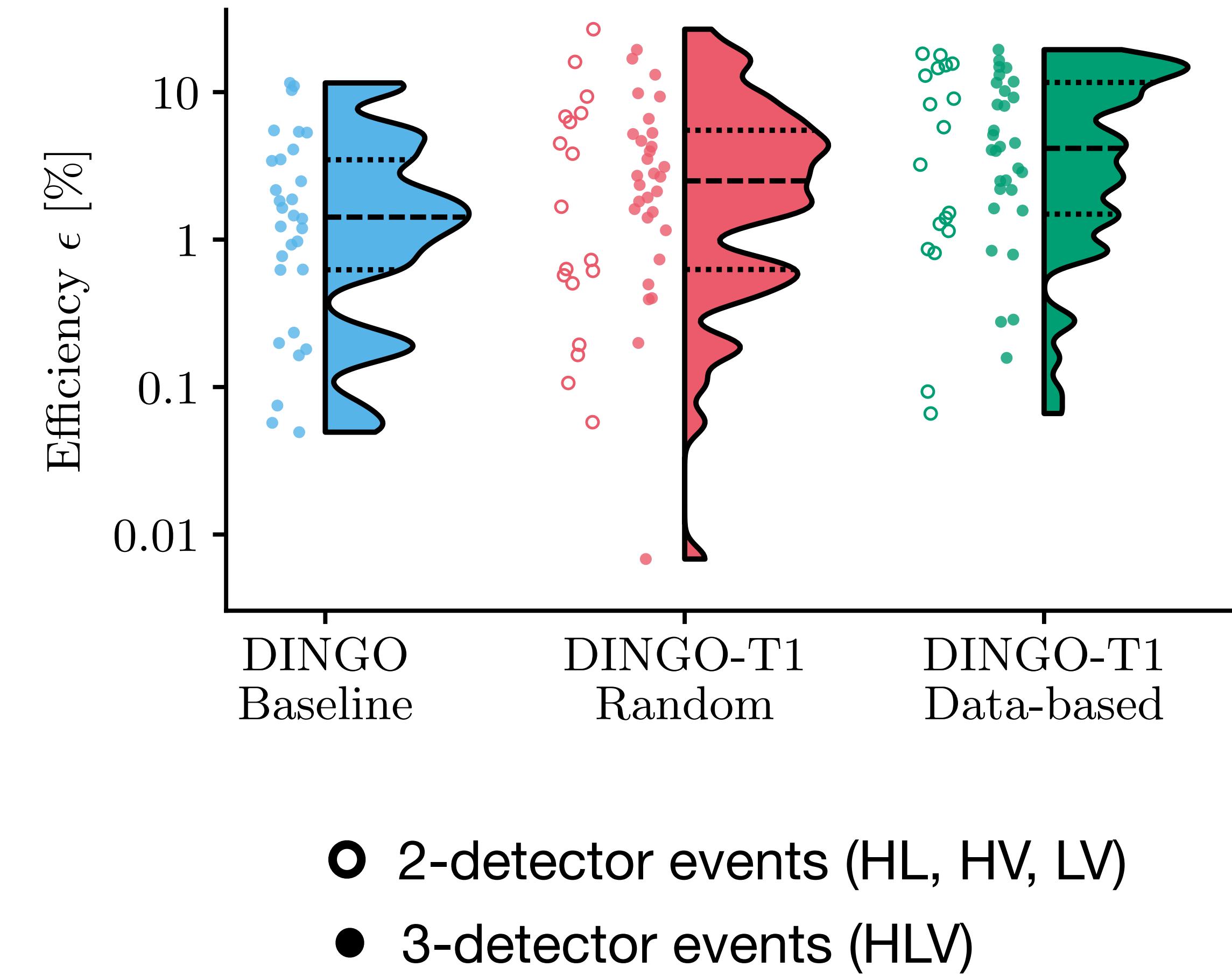


- What masking strategy works best?
- What can we do with a flexible model?

Comparing masking strategies

- 48 O3 events with 17 different data analysis settings
- Distribution over sample efficiencies:

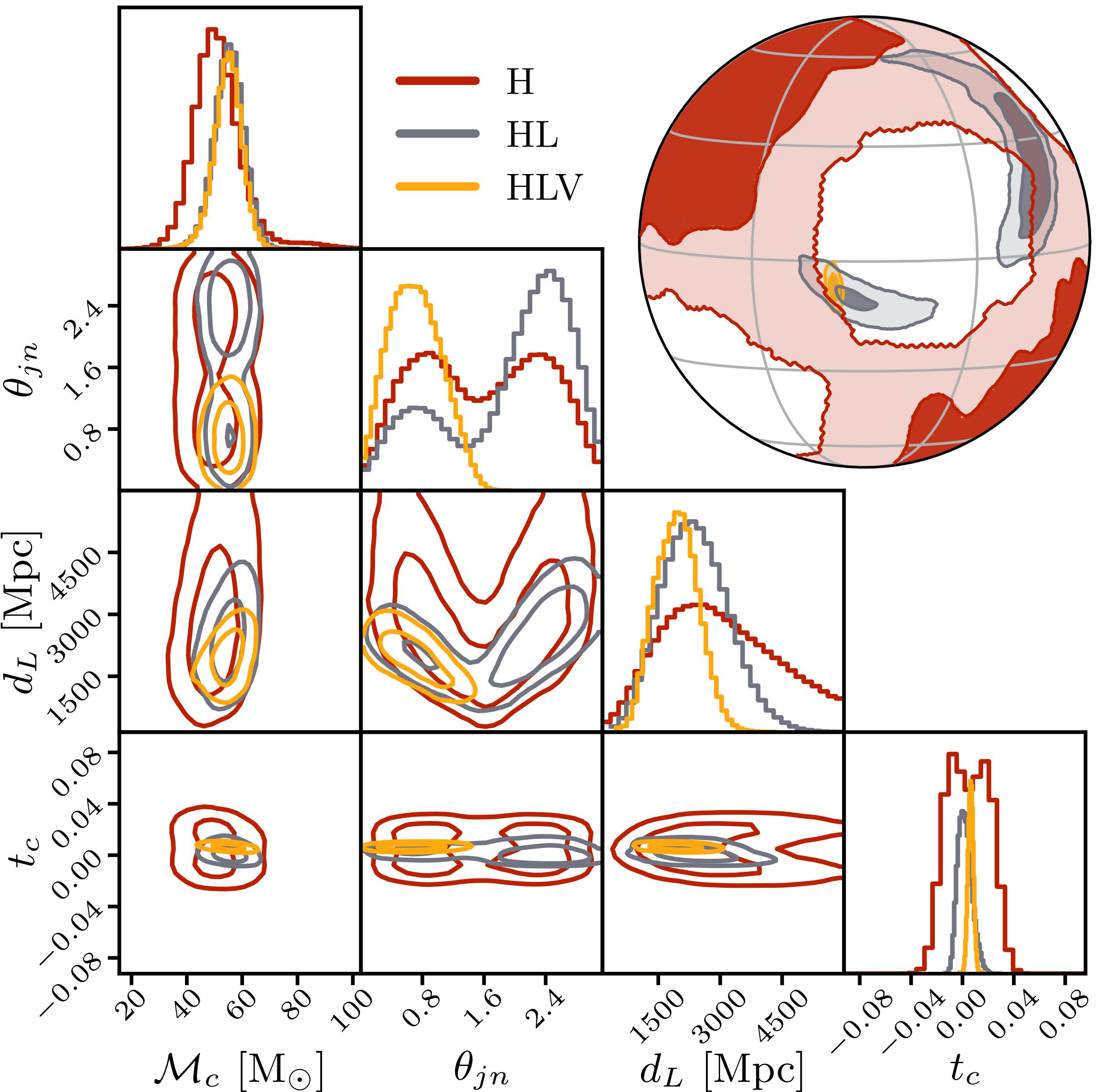
Median efficiency	2-detector	3-detector
DINGO-T1 Random	1.2%	2.7%
DINGO-T1 Data-based	4.5%	4.2%



Conclusion: Data-based masking wins ⇒ DINGO-T1

Applications: Posteriors under different detectors

- How is the posterior affected when analyzing an event in different detectors?
- Example: GW190701_203306
- Sky position changes a lot (expected)



Applications: Posteriors under different detectors

- Inference with DINGO-T1:
 - Initial sampling < 10s
 - Importance sampling: 5 - 10min
- Analyze all events in different detectors (264 individual PE runs)
- Computationally infeasible with standard samplers

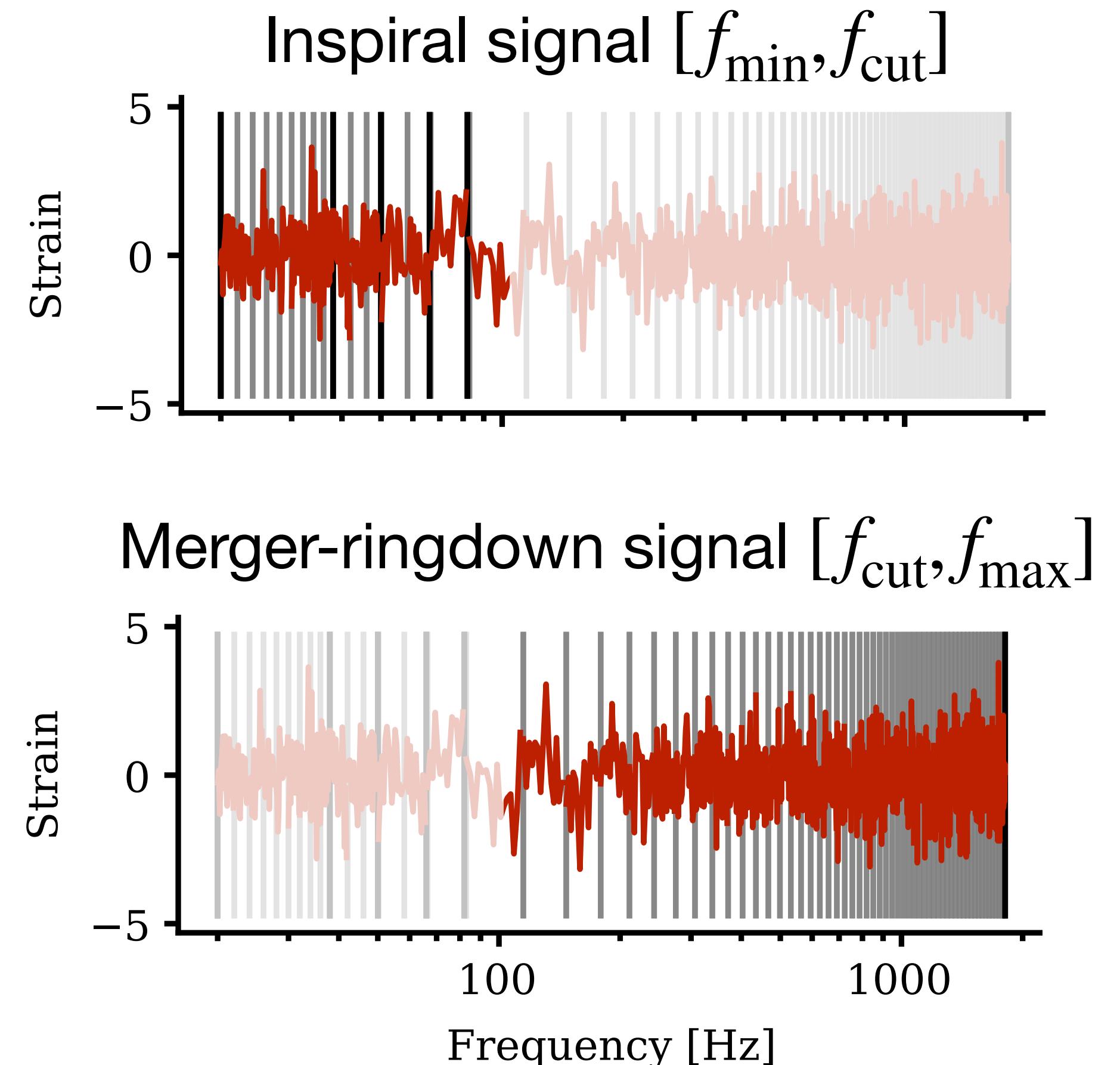
Event	Detectors	HLV	HL	HV	LV	H	L	V
GW190408_181802	HLV	8.07 %	8.28 %	0.64 %	1.35 %	2.79 %	6.71 %	62.23 %
GW190413_052954	HLV	11.77 %	9.52 %	2.41 %	0.74 %	9.5 %	18.61 %	37.48 %
GW190413_134308 ^{*L}	HLV	4.52 %	7.84 %	8.29 %	1.36 %	21.16 %	11.78 %	32.2 %
GW190426_190642	HLV	0.79 %	2.27 %	7.41 %	0.0 %	29.53 %	0.04 %	49.52 %
GW190503_185404 ^{*L}	IILV	1.57 %	1.31 %	1.0 %	0.41 %	17.09 %	2.14 %	60.85 %
GW190513_205428 ^{*L}	HLV	0.16 %	0.52 %	4.19 %	2.04 %	11.74 %	4.17 %	22.9 %
GW190517_055101	HLV	2.17 %	4.28 %	1.79 %	0.27 %	1.36 %	0.36 %	13.06 %
GW190519_153544	HLV	4.26 %	0.85 %	3.71 %	4.88 %	3.38 %	9.09 %	59.66 %
GW190602_175927	HLV	13.09 %	13.18 %	28.09 %	5.4 %	27.24 %	15.95 %	26.58 %
GW190701_203305 ^{*L}	HLV	14.83 %	14.05 %	9.13 %	5.45 %	31.43 %	5.93 %	38.78 %
GW190706_222641	HLV	2.49 %	5.65 %	13.73 %	6.21 %	0.1 %	10.14 %	27.66 %
GW190727_060333 ^L	HLV	0.84 %	17.6 %	2.95 %	3.29 %	5.09 %	0.45 %	23.71 %
GW190803_022701	IILV	16.39 %	28.23 %	19.48 %	9.04 %	28.74 %	7.89 %	42.92 %
GW190828_063405	HLV	3.99 %	17.35 %	8.7 %	7.11 %	24.58 %	9.26 %	64.41 %
GW190915_235702	HLV	8.23 %	13.56 %	0.89 %	5.24 %	1.9 %	14.02 %	42.52 %
GW190916_200658	HLV	19.41 %	20.19 %	5.16 %	18.13 %	11.2 %	27.25 %	42.29 %
GW190926_050336	HLV	1.63 %	4.25 %	11.17 %	12.38 %	16.39 %	19.97 %	53.75 %
GW190929_012149	HLV	3.04 %	4.74 %	10.61 %	0.0 %	24.68 %	0.01 %	50.24 %
GW191127_050227 ^{*H}	HLV	0.28 %	0.97 %	8.21 %	5.15 %	16.13 %	28.83 %	6.04 %
GW191215_223052	HLV	4.05 %	5.79 %	5.13 %	1.25 %	6.55 %	2.02 %	56.09 %
GW191230_180458	IILV	14.61 %	8.4 %	2.68 %	16.51 %	7.79 %	16.88 %	58.75 %
GW200129_065458 ^{*L}	HLV	0.29 %	0.29 %	2.16 %	0.01 %	14.15 %	0.07 %	2.66 %
GW200208_130117	HLV	11.58 %	12.15 %	5.17 %	5.99 %	32.27 %	8.9 %	17.75 %
GW200208_222617	HLV	2.86 %	2.47 %	4.73 %	0.05 %	5.55 %	18.82 %	18.48 %
GW200209_085452	HLV	2.52 %	11.06 %	3.55 %	16.62 %	9.66 %	34.08 %	41.28 %
GW200216_220804	HLV	2.2 %	12.56 %	12.41 %	7.44 %	21.27 %	10.96 %	52.1 %
GW200219_094415	HLV	5.12 %	7.36 %	3.27 %	2.77 %	11.76 %	11.09 %	1.9 %
GW200220_061928	HLV	10.17 %	18.1 %	6.07 %	7.68 %	8.67 %	11.95 %	61.93 %
GW200224_222234	IILV	5.49 %	7.18 %	1.65 %	6.85 %	10.2 %	20.89 %	4.01 %
GW200311_115853	HLV	9.2 %	5.56 %	11.57 %	4.81 %	7.71 %	4.23 %	3.64 %
GW190421_213856	HL	-	17.8 %	-	-	10.08 %	17.4 %	-
GW190514_065410 ^{*L}	IIL	-	15.22 %	-	-	19.48 %	4.83 %	-
GW190521_074359	HL	-	1.28 %	-	-	7.24 %	1.26 %	-
GW190527_092055	HL	-	0.04 %	-	-	2.95 %	5.56 %	-
GW190719_215514	HL	-	14.56 %	-	-	17.56 %	0.05 %	-
GW190731_140936	HL	-	18.22 %	-	-	38.6 %	4.69 %	-
GW191109_010717 ^{*HL}	HL	-	1.52 %	-	-	0.11 %	5.15 %	-
GW191204_110529	HL	-	0.07 %	-	-	19.49 %	13.28 %	-
GW191222_033537	HL	-	15.61 %	-	-	6.84 %	16.18 %	-
GW200128_022011	HL	-	8.28 %	-	-	38.87 %	18.79 %	-
GW200220_124850	HL	-	12.94 %	-	-	23.86 %	15.56 %	-
GW200306_093714	HL	-	0.09 %	-	-	6.0 %	0.08 %	-
GW190925_232845	HV	-	-	0.86 %	-	8.16 %	-	16.97 %
GW200302_015811	HV	-	-	1.4 %	-	2.25 %	-	31.8 %
GW190620_030421	LV	-	-	-	0.81 %	-	1.5 %	55.53 %
GW190630_185205	LV	-	-	-	1.15 %	-	7.98 %	16.08 %
GW190910_112807	LV	-	-	-	3.22 %	-	4.2 %	19.1 %
GW200112_155838	LV	-	-	-	5.79 %	-	16.7 %	20.93 %

Applications: Testing general relativity

- Inspiral-merger-ringdown (IMR) consistency tests
- Do we obtain the same M_f & χ_f from different parts of the signal?
- Quantify as deviation:

$$\frac{\Delta M_f}{\bar{M}_f} = 2 \frac{M_f^{\text{insp}} - M_f^{\text{postinsp}}}{M_f^{\text{insp}} + M_f^{\text{postinsp}}}$$

$$\frac{\Delta \chi_f}{\bar{\chi}_f} = 2 \frac{\chi_f^{\text{insp}} - \chi_f^{\text{postinsp}}}{\chi_f^{\text{insp}} + \chi_f^{\text{postinsp}}}$$

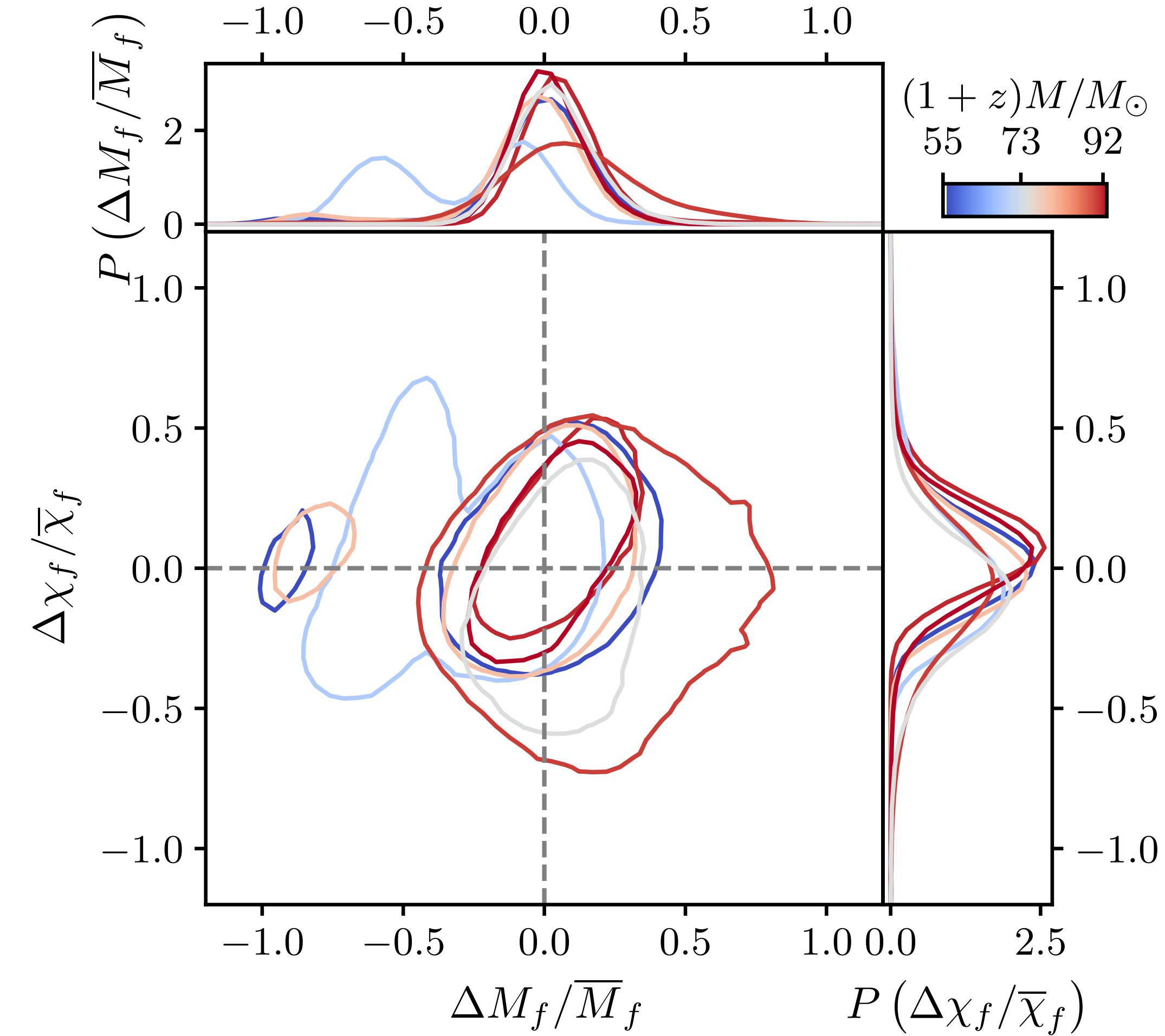


Applications: Testing general relativity

- 7 O3 events:

Event	Color	Frequency ranges [Hz]	
		Inspiral	Postinspiral
GW190408_181802	—	[20, 164]	[164, 896]
GW190521_074359	—	[20, 105]	[105, 224]
GW190630_185205	—	[20, 135]	[135, 896]
GW190828_063205	—	[20, 132]	[132, 896]
GW200208_130117	—	[20, 98]	[98, 448]
GW200224_222234	—	[20, 107]	[107, 448]
GW200311_115853	—	[20, 122]	[102, 896]

- Theory consistent with data
→ peak at (0,0)



Summary: DINGO-T1

- Flexibility of DINGO-T1 allows us to do ...
 - ... large scale PE analysis
 - ... fast re-analysis with different data analysis settings
 - ... IMR consistency tests
- All analyses in this paper would have required training
94 separate DINGO models!

Further resources

- Preprint on arXiv: <https://arxiv.org/abs/2512.02968>
- Model publicly available on Zenodo:

November 26, 2025 (v1) Model Open

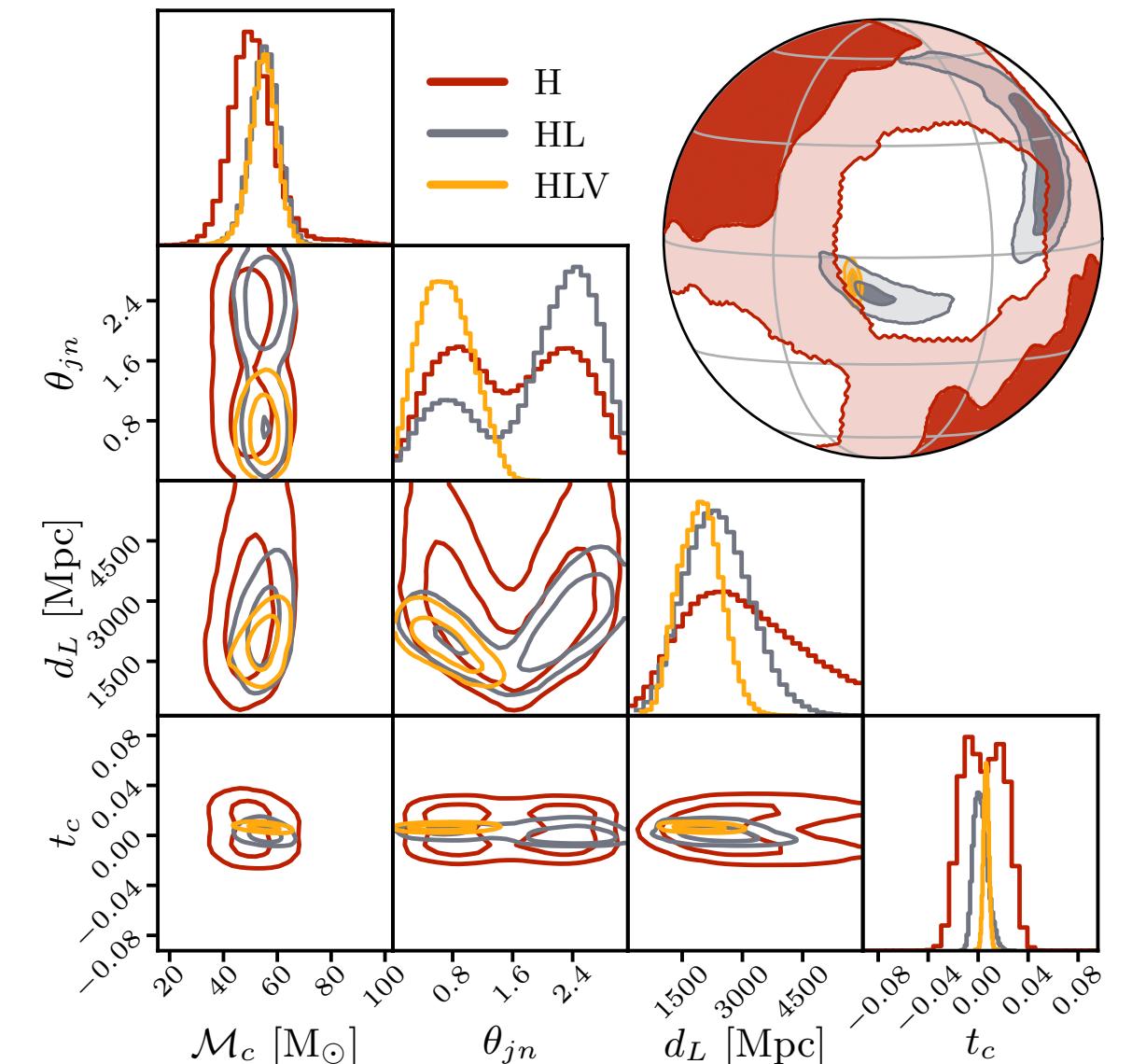
DINGO-T1 model for "Flexible Gravitational-Wave Parameter Estimation with Transformers"

Kofler, Annalena ; Dax, Maximilian ; Green, Stephen R. ; and 6 others

DINGO-T1 and DINGO NPE baseline models for the paper "Flexible Gravitational-Wave Parameter Estimation with Transformers". How to download all files from this page If you would like to download all files on this page, you can use zenodo_get: pip install zenodo_get zenodo_get RECORD_ID_OR_DOI where the record ID for the most recent version of this page is 17726076. How to perform inference with the...

- Tutorial online: <https://github.com/dingo-gw/dingo-T1>

Make this plot yourself!



The Dingo Pack



Maximilian Dax



Stephen Green



Annalena Kofler



Nihar Gupte



Michael Pürer



Alex Roussopoulos



Samuel Clyne



Ashwin Girish



Cecilia Fabbri



Jonas Wildberger



Vincent Berenz



Jonathan Gair



Jakob Macke



Bernhard Schölkopf



Alessandra Buonanno

Do you have any questions?



References

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- Dax+, Group Equivariant Neural Posterior Estimation, ICLR 2022
- Dax+, Neural Importance Sampling for Rapid and Reliable Gravitational Wave Inference, PRL 130, 2023
- Wildberger+, Adapting to noise distribution shifts in flow-based gravitational-wave inference, PRD 107, 2023
- Wildberger+, Flow Matching for Scalable Simulation-Based Inference, NeurIPS 2023
- Gupte+, Evidence for eccentricity in the population of binary black holes observed by LIGO-Virgo-KAGRA, arXiv:2404.14286v1, 2024
- Dax+, Real-time Gravitational-Wave Inference for Binary Neutron Stars using Machine Learning, Nature, 2025
- Kofler+, Flexible Gravitational-Wave Parameter Estimation with Transformers, 2025

