Puppet Pose Capture

IM691 Research Seminar, Anna Maureder

Idea

"Real-Time puppet motion capture for 3D animation purposes"

tracking the motion of joints occlusion by hands



Idea

"Real-Time puppet motion capture for 3D animation purposes"

No motion No occlusion

"3D Puppet Pose Capture"

Pose capture

of articulated objects

3D Reconstruction

capture the shape of real models (3D range data, Shape-from-X)

3D Segmentation

recover rigid parts of a 3D object

Skeleton Extraction

recover joints between rigid parts

Pose capture

of articulated objects

3D Reconstruction

capture the shape of real models (3D range data, Shape-from-X)

3D Segmentation

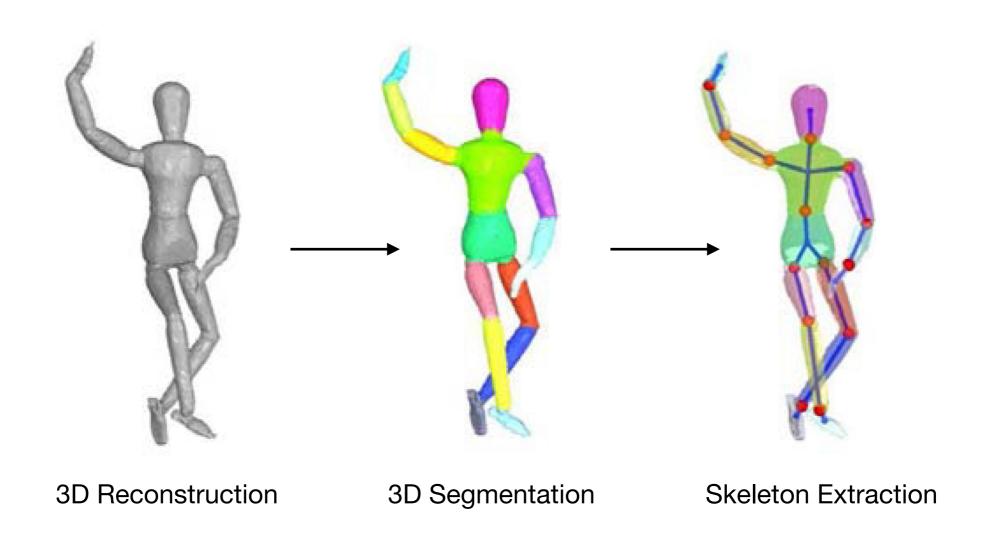
recover rigid parts of a 3D object

Skeleton Extraction

recover joints between rigid parts

Main goal

Recover the skeleton of an unknown articulated object



Non-rigid registration

"deformable template"

"Recovering Articulated Object Models from 3D Scan Data", 2004, Anguelov et al.

• set of meshes of the same object $(D_0 \dots D_N)$



 $D_0 = X$ template mesh

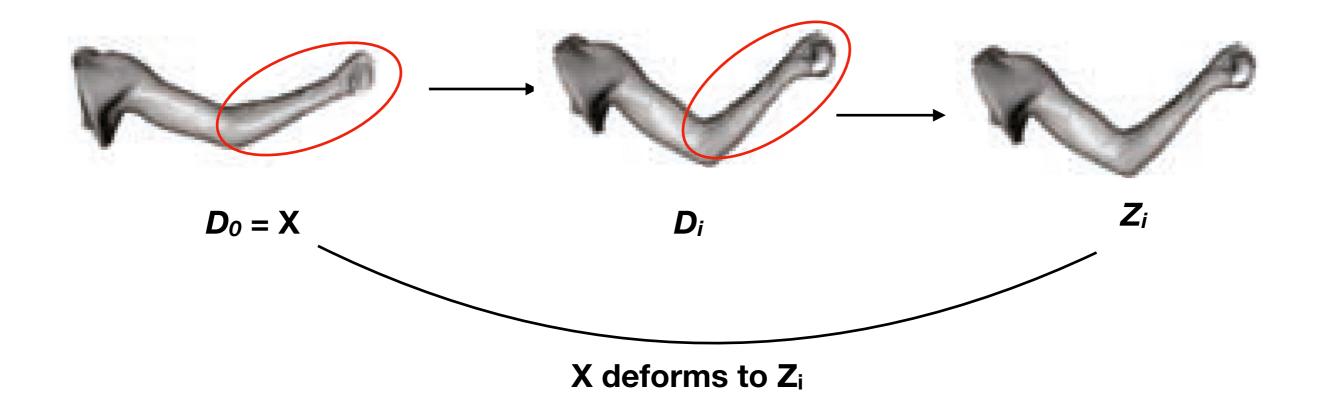


D_{1, ...,} D_N data meshes

Correlated Correspondence

Registration of nonrigid surfaces

- find corresponding points of X and D_i
- find non-rigid transformation to align them



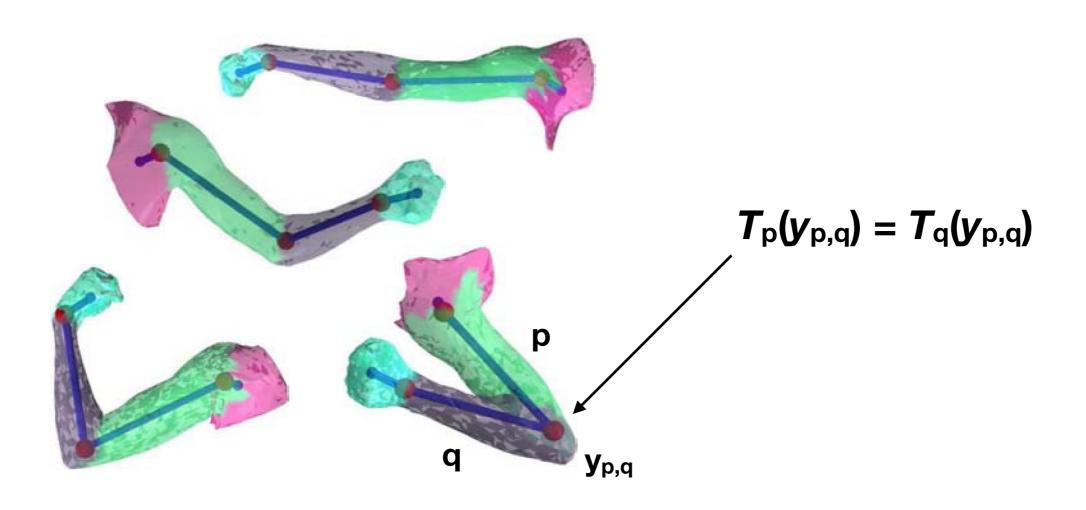
Optimization

performing of Expectation-Maximization algorithm

E-step: assignment of body labels α given estimated T

M-step: improve estimate of T using body labels α (ICP)

Skeleton Estimation



Further work

"Non-rigid registration"

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"Fast and precise kinematic skeleton extraction of 3D dynamic meshes", J. Tierny<sub>1</sub>, J. Vandeborre<sub>1,2</sub> and M. Daoudi, 2008
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"Range Scan Registration Using Reduced Deformable Models", W. Chang, and M. Zwicker, 2009

"Segmenting Animated Objects Into Near-Rigid Components", S. Wuhrer and A. Brunton, 2009

"Robust and Accurate Skeletal Rigging from Mesh Sequences", B. Huy and L. Deng, 2014

Current status

• 3D Data (Kinect Fusion, RecFusion, Online data base)

.pcd/.obj/.ply/.stl

• Library (C++)

VTK, PCL

