Anna Cao

Q Vancouver, BC **■** anna.shuqi@gmail.com

annascao.github.io

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EDUCATION

Electrical Engineering, Bachelor of Applied Science,

University of British Columbia

2021 - 2026 | Vancouver, Canada

SKILLS

Embedded

Microcontrollers, Communication Protocols, Git, PlatformIO, STM32CubeIDE, STM32_HAL, ESP-IDF, FPGAs, Quartus, ModelSim

Electrical

Altium, LTSpice, Circuit Analysis/Design, Soldering/SMT Soldering, Allegro System Capture & PCB Editor

Languages

C/C++, Python, Verilog/System Verilog, **MATLAB**

TECHNICAL EXPERIENCE

Hardware Design Engineering Intern, Intel

09/2024 - present

- Designing a central I2C interface board for streamline debugging using Allegro Schematic Capture / PCB Editor.
- Full stack development in Python to support validation efforts of Integrated Circuits and products, including making a CLI and GUI I2C debug tool.
- Testing board hardware, including the validation of an FTDI chip using UART communication and PuTTY.
- Gaining exposure to computer/system architecture, board-level digital circuitry, and validation processes.

Electrical Product Design Intern, Dometic Marine

04/2024 - 08/2024

- Performed PCBA debugging for marine electronics by reading electrical schematics, analyzing circuit behavior, and using an oscilloscope to evaluate signals such as PWM and CAN.
- Diagnosed and resolved a motor calibration failure by studying datasheets and comparing expected vs. actual signal behavior, leading to successful circuit correction.
- Designed and built a reverse polarity protection circuit following ISO standards using Altium and LTSpice, ensuring compliance with safety standards and increasing the system's operational lifespan.

Sensors and Communications Lead, *UBC AeroDesign ⊘*

- Leading a 9-member team in developing an avionics system for an aircraft, with the goal of competing in the annual SAE Aero Design Competition.
- Designing firmware system architecture, utilizing C/C++ and reading datasheets to write sensor drivers and integrate sensors using SPI, I2C, UART, and CAN.
- Designed STM32-based sensor hardware optimized for signal integrity, carefully evaluating design options, and marking the team's first year implementing a custom sensor system.
- Teaching skills like PCB design and firmware development to members and presenting design reviews.

Academic Assistant - Junior Developer, UBC Okanagan

05/2023 - 08/2023

- Collaborated in developing an open-source bank of nearly 900 questions

 Ø in introductory physics.
- · Worked with a team to create scripts; converting existing academic resources to Markdown, Python, and HTML, testing them through Docker and using **Git** with a **Branch and Pull Request** method to review contributions.

Power and Controls Member, *UBC AeroDesign ⊗*

09/2022 - 05/2023

- Conducted wind-tunnel tests on motors-propeller combinations using Arduino and Python for thrust and current draw measurements to validate designs, resulting in up to 12 pounds of thrust.
- Spearheaded the setup of the plane's telemetry system and LiPo batteries in test flights.

PROJECTS

Aircraft Sensor System, C, Circuit Design, Altium

- Developed aircraft sensor software in PlatformIO using C for STM32F1, integrating barometer, IMU, airspeed, and GNSS modules using **freeRTOS** to provide **real-time** sensor readings and data logging to a micro SD card for post-flight analysis.
- Utilized Altium to design and construct a compact 4-layer PCB development board with integrated sensors, optimizing component placement and adhering to design rules - successfully collected data during this year's competition.
- Troubleshooted board issues by reviewing schematics, analyzing circuit behavior using an oscilloscope, and using a DLA for debugging serial communication.

2-DOF Laser Projector, Circuit Design, Altium, C

- Designed the circuit, selected PCB components, and developed a 2-DOF laser projector PCBA featuring the STM32H7, that drives two encoded DC motors and a laser to project reflected images.
- Aided hardware/software integration by validating PWM and UART using C for precise motor control.
- Researched, prototyped, and validated a **motor driver** circuit with an **H-bridge**, achieving bi-directional motor control at 50kHz while optimizing propagation delay and rise time.