# Anna Cao

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#### **EDUCATION**

# **Electrical Engineering, Bachelor of Applied Science,**

University of British Columbia

2021 - 2026 | Vancouver, Canada

#### **SKILLS**

#### **Embedded**

Microcontrollers, Communication Protocols, Git, PlatformIO, STM32CubeIDE, STM32\_HAL, ESP-IDF, FPGAs, Quartus, ModelSim

#### **Electrical**

Altium, LTSpice, Circuit Analysis/Design, Soldering/SMT Soldering, Allegro System Capture & **PCB Editor** 

## Languages

C/C++, Python, Verilog/System Verilog, MATLAB

#### **TECHNICAL EXPERIENCE**

## **Hardware Design Engineer, Intel**

09/2024 - present

- Designing a central I2C interface board for streamline debugging using Allegro Schematic Capture / PCB Editor
- Full stack development in Python for a CLI and GUI I2C debug tool, implementing communication with downstream devices to help support ongoing validation efforts.
- Set up and validated an on-board FTDI chip using UART and PuTTY.
- Gaining exposure to computer/system architecture, board-level digital circuitry, and validation processes.

#### **Electrical Product Designer,** *Dometic Marine*

04/2024 - 08/2024

- Performed PCBA debugging by reading electrical schematics, analyzing circuit behavior, and using an oscilloscope to evaluate signals like PWM and CAN.
- Diagnosed and resolved a motor calibration failure by studying datasheets and comparing expected vs. actual signal behavior, leading to successful circuit correction.
- Designed and built a reverse polarity protection circuit following ISO standards using Altium and LTSpice, ensuring compliance with safety standards and increasing the system's operational lifespan.

## **Sensors and Communications Lead,** *UBC AeroDesign ⊗*

05/2023 - present

- Leading a 9-member team to build a sensing and data communication system for an aircraft.
- Designing firmware system architecture, utilizing C/C++ and reading datasheets to write sensor drivers and integrate sensors using SPI, I2C, UART, and CAN.
- Designed STM32-based sensor hardware optimized for signal integrity, carefully evaluating design options, and marking the team's first year implementing a custom sensor system.
- Teaching skills like PCB design and firmware development to members and presenting design reviews.

# Academic Assistant - Junior Developer, UBC Okanagan

05/2023 - 08/2023

- Collaborated in developing an open-source bank of nearly 900 questions 

  Ø in introductory physics.
- Worked with a team to create scripts; converting existing academic resources to Markdown, Python, and HTML, testing them through Docker and using **Git** with a **Branch and Pull Request** method to review contributions.

## **Power and Controls Member,** *UBC AeroDesign ⊗*

09/2022 - 05/2023

- Conducted wind-tunnel tests on motors-propeller combinations using Arduino and Python for thrust and current draw measurements to validate designs, resulting in up to 12 pounds of thrust.
- Spearheaded the setup of the plane's **telemetry** system and LiPo batteries in test flights.

# **PROJECTS**

# Aircraft Sensor System, C, Circuit Design, Altium

- Developed aircraft sensor software in PlatformIO using C for STM32F1, integrating barometer, IMU, airspeed, and GNSS modules using **freeRTOS** to provide **real-time** sensor readings and data logging to a micro SD card for post-flight analysis.
- Implemented a robust calibration process, including an IMU calibration ISR executed upon a button press.
- Utilized **Altium** to design and construct a compact 4-layer PCB development board with integrated sensors, optimizing component placement and adhering to design rules - successfully collected data during this year's competition.
- Troubleshooted board issues by reviewing schematics, analyzing circuit behavior using an oscilloscope, and using a DLA for debugging serial communication.

## 2-DOF Laser Projector, Circuit Design, Altium, C

- Designed the circuit, selected PCB components, and developed a 2-DOF laser projector PCBA featuring the STM32H7, that drives two encoded DC motors and a laser to project reflected images.
- Aided hardware/software integration by validating PWM and UART using C for precise motor control.
- Researched, prototyped, and validated a motor driver circuit with an H-bridge, achieving bi-directional motor control at 50kHz while optimizing propagation delay and rise time.
- Designed a power system with a 12V-to-5V buck converter and a 5V-to-3V3 regulator, meeting the electronics power requirements.