

1. Gauss-Jordan elimination (rank of rows = rank of columns) 110611103

$$A = \begin{bmatrix} 1 & 3 & 2 & 1 \\ 2 & 0 & 1 & -1 \\ -1 & 1 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 3 & 2 & 1 \\ 0 & 2 & 1 & 1 \\ 0 & 4 & 2 & 2 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 3 & 2 & 1 \\ 0 & 2 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

row echelon form

$$\rightarrow \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & 2 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & \frac{1}{2} & -\frac{1}{2} \\ 0 & 1 & \frac{1}{2} & \frac{1}{2} \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

rank = 2

2.

$$AB \Rightarrow m \times m$$

Let λ be an eigenvalue of AB
eigenvalues $\det(AB - \lambda I) = 0$

$$BA \Rightarrow n \times n$$

non-zero v

$$ABv = \lambda v$$

$$BABv = \lambda Bv$$

$$\Rightarrow (BA)(Bv) = \lambda(Bv)$$

non-zero eigenvalues

$$\Rightarrow \lambda \neq 0$$

同理 let λ be an non-zero eigenvalue of BA
non-zero v

$$BAv = \lambda v$$

$$ABAv = \lambda Av$$

$$\Rightarrow (AB)(Av) = \lambda(Av)$$

$$Bv \neq 0 \text{ 否则 } ABv = \lambda v = 0 \rightarrow \lambda = 0$$

\Rightarrow hence λ is a non-zero eigenvalue of BA (不合假设)

$\Rightarrow AB$ & BA have the same non-zero eigenvalues.

$$Av \neq 0 \text{ 否则 } BAv = \lambda v = 0 \rightarrow \lambda = 0 \text{ (不合)}$$

\Rightarrow hence λ is a non zero eigenvalue of AB

3.

a) $\begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 2 & 4 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ rank = 2
nullity = 1

basis for range $\rightarrow \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

basis for null space

$$A\vec{x} = \vec{0}$$

$$\left[\begin{array}{ccc|c} 1 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$x_1 + 2x_2 = 0$$

$$x_3 = 0$$

$$x_2 = t \in \mathbb{R}$$

$$\Rightarrow x_1 = -2t \in \mathbb{R}$$

$$\begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}$$

basis
of
null
space

b) $\begin{bmatrix} 1 & -1 \\ 0 & 1 \\ 4 & 0 \\ 1 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ rank = 2
nullity = 0
4x2 2x1

$$x_1 = 0$$

$$x_2 = 0$$

$$\text{null}(A) = \vec{0}$$

↑
僅有 zero vector

basis for range

$$\begin{bmatrix} 1 \\ 0 \\ 4 \\ 1 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

basis for
null space

$$\begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \\ -4 \end{bmatrix}$$

c) $\begin{bmatrix} 1 & 0 & 4 & 1 \\ -1 & 1 & 0 & 0 \end{bmatrix}$

rank = 2

nullity = 2

$$(4-2=2)$$

basis for range

$$\begin{bmatrix} 1 \\ -1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 4 & 1 \\ -1 & 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

2x1

$$-(t + 4s) = x_4$$

$$x_1 + 4x_3 + x_4 = 0$$

$$x_3 = s \in \mathbb{R}$$

$$-x_1 + x_2 = 0 \rightarrow x_1 = x_2 = t \in \mathbb{R}$$

3. d)

$$\begin{bmatrix} 0 & 0 & 4 & 0 \\ 0 & 1 & 0 & 0 \\ 11 & 0 & 0 & 0 \end{bmatrix}$$

$$\text{rank} = 3$$

$$\text{nullity} = 1$$

$$\text{basis for range} = \left\{ \begin{bmatrix} 0 \\ 0 \\ 11 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 4 \\ 0 \\ 0 \end{bmatrix} \right\}$$

↓

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \quad \text{basis for nullity} = \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

$3 \times 4 \quad 4 \times 1$

5. 矩阵对角化 → 用 eigenvectors (basis) 来做 similar transform

a) $\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$

$$\det \begin{pmatrix} 1-\lambda & 2 \\ 2 & 4-\lambda \end{pmatrix} = 0 \Rightarrow (1-\lambda)(4-\lambda) - 4 = 0$$

$$\lambda = 0 \text{ or } 5$$

$$A\vec{x} = \lambda\vec{x} \rightarrow (A - \lambda I)\vec{x} = 0$$

$$\lambda = 0 \Rightarrow \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$x_1 + 2x_2 = 0 \Rightarrow \vec{v}_1 = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

$$\lambda = 5 \Rightarrow \begin{bmatrix} -4 & 2 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \vec{v}_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$2x_1 - x_2 = 0$$

2D, 2 eigenvectors \Rightarrow good eigen basis
(diagonalizable)

$$D = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 5 \end{bmatrix}$$

$$T = \begin{bmatrix} \vec{v}_1 & \vec{v}_2 \\ 2 & 1 \\ -1 & 2 \end{bmatrix}$$

$$AT = TD$$

$$\Rightarrow A = TDT^{-1}$$

↓

$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$$

(SVD)

b)

$$\begin{bmatrix} 3 & 2 \\ -1 & 0 \end{bmatrix}$$

$$(A - \lambda I)\vec{x} = 0$$

$$\begin{vmatrix} 3-\lambda & 2 \\ -1 & 0-\lambda \end{vmatrix} = 0 \quad (3-\lambda)(-\lambda) + 2 = 0$$

$$\lambda = 1 \vee 2$$

$$D = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

$\Rightarrow D$ 且 2 个 eigenvector
 \Rightarrow diagonalizable

$$A = TDT^{-1}$$

$$\begin{bmatrix} 3 & 2 \\ -1 & 0 \end{bmatrix}$$

$$T = \begin{bmatrix} 1 & -2 \\ -1 & 1 \end{bmatrix}$$

$$\lambda = 1 \Rightarrow \begin{bmatrix} 2 & 2 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\vec{v}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\lambda = 2 \Rightarrow \begin{bmatrix} 1 & 2 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\vec{v}_2 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$

c)

$$\begin{bmatrix} \boxed{\begin{matrix} 1 & 2 \\ 2 & 4 \end{matrix}} & \begin{matrix} 0 & 0 \\ 0 & 0 \end{matrix} \\ \begin{matrix} 0 & 0 \\ 0 & 0 \end{matrix} & \boxed{\begin{matrix} 3 & -1 \\ 2 & 0 \end{matrix}} \end{bmatrix}$$

\hookrightarrow 2 个 block 分别做 左上同 a) $\Rightarrow D = \begin{bmatrix} 0 & 0 \\ 0 & 5 \end{bmatrix}$

$\begin{bmatrix} 3 & -1 \\ 2 & 0 \end{bmatrix}$ 为 b) 之 transpose, 而计算后 characteristic eqn 不改变 $\Rightarrow D = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$

$$\Rightarrow J = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 5 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$

d) $\begin{bmatrix} 2 & 11 \\ 0 & 2 \end{bmatrix}$ 已为上三角 matrix $\rightarrow \lambda = 2, 2$ algebraic multiplicity = 2

$$\begin{bmatrix} 0 & 11 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$\Rightarrow x_2 = 0 \quad \vec{v}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ NOT diagonalizable

\rightarrow Jordan form
geometric multiplicity = 1
即 $p.m.(A-2I)$
 $\hookrightarrow = 1$
2 个 $\lambda=2$
1 个 eigenvector

$$J = \begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix}$$

generalized eigenvector

$$\begin{bmatrix} 0 & 11 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \Rightarrow x_2 = \frac{1}{11} \Rightarrow \vec{v}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$T = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

6. $M = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$ max column sum

a) $\|M\|_{1/1}$ column sum 看哪几 column 有和之 max.
 $\Rightarrow \text{col 1} \quad \text{col 2} \quad \text{col 3} \Rightarrow \|M\|_{1/1} = 9$
 $1+4=5 \quad 2+5=7 \quad 3+6=9$

b) 贴在附件.

d)

c) $\|M\|_{\infty/\infty}$ $\xrightarrow{\text{max row sum}}$
 $\text{row 1} \Rightarrow 1+2+3=6 \Rightarrow \|M\|_{\infty/\infty} = 15$
 $\text{row 2} \Rightarrow 4+5+6=15$

7. Show $\frac{1}{n} \|V\|_1 \leq \|V\|_2 \leq \|V\|_1$

1) upper bound

$$\|V\|_2 \leq \|V\|_1$$

由柯西不等式 $\|\vec{a} \cdot \vec{b}\| \leq \|\vec{a}\| \|\vec{b}\|$

$$\sum_i |v_i \cdot v_i^T| \leq \left(\sum_i |v_i| \right) \left(\sum_i |v_i| \right)$$

$$\|V\|_2 = \sqrt{\sum_{i=1}^n |v_i|^2} = \sqrt{\sum_{i=1}^n |v_i \cdot v_i^T|} \leq \sum_{i=1}^n |v_i| = \|V\|_1$$

$$\Rightarrow \|V\|_2 \leq \|V\|_1$$

2) lower bound

$$\frac{1}{n} \|V\|_1 \leq \frac{1}{\sqrt{n}} \|V\|_1 \leq \|V\|_2$$

AM-QM mean inequality

$$\left(\sum_{i=1}^n x_i \right)^2 \leq \sum_{i=1}^n x_i^2 \sum_{i=1}^n 1^2 = n \sum_{i=1}^n x_i^2$$

$$\Rightarrow \left(\frac{\sum_{i=1}^n x_i}{n} \right)^2 \leq \frac{\sum_{i=1}^n x_i^2}{n}$$

$$\frac{1}{n} \sum_{i=1}^n |v_i|^2 \geq \left(\frac{1}{n} \sum_{i=1}^n |v_i| \right)^2$$

show

\Rightarrow 则 $\frac{1}{n} \|V\|_1 \leq \|V\|_2$ 成立

\Rightarrow 故命题成立

$$\Rightarrow \sum_{i=1}^n |v_i|^2 \geq \frac{1}{n} \left(\sum_{i=1}^n |v_i| \right)^2 \Rightarrow \sqrt{\sum_{i=1}^n |v_i|^2} \geq \frac{1}{\sqrt{n}} \sum_{i=1}^n |v_i| = \frac{1}{\sqrt{n}} \|V\|_1$$

$$\Rightarrow \|V\|_2 \geq \frac{1}{\sqrt{n}} \|V\|_1 \geq \frac{1}{n} \|V\|_1$$

8.

a)

find state eqns

controllable canonical form

$$G(s) = \frac{2s+3}{s^2+5s+6} + 0$$

$D=0$

$$A = \begin{bmatrix} 0 & 1 \\ -a_0 & -a_1 \end{bmatrix}$$

$$= \frac{Y(s)}{U(s)}$$

$$\Rightarrow Y(s)(s^2+5s+6) = (2s+3)U(s)$$

$b = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

$C = [b_0 \ b_1], D=0$

$$\Rightarrow y'' + 5y' + 6y(t) = 2u'(t) + 3u(t)$$

let $x_1 = y$

$x_2 = y'$

$\Rightarrow y'' = \dot{x}_2$

$$y'' = 2u' + 3u - 5y' - 6y$$

$$= 2u' + 3u - 5x_2 - 6x_1$$

$$= \dot{x}_2$$

$$\dot{x}_1 = y' = x_2$$

$$\Rightarrow \begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = -6x_1 - 5x_2 + 2u' + 3u \end{cases}$$

$$\Rightarrow \begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = -6x_1 - 5x_2 + 2u' + 3u \end{cases}$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -6 & -5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$$

A B

$$y = \begin{bmatrix} 3 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + 0 \cdot u$$

C D

$D=0$

no direct feedthrough term

$$sX_1(s) = (2U - 5X_1) + X_2(s)$$

$$sX_2(s) = 3U - 6X_1 + X_1(s)$$

$$\Rightarrow \begin{cases} \dot{x}_1(t) = 2u - 5x_1(t) + x_2(t) \\ \dot{x}_2(t) = 3u - 6x_1(t) + x_1(t) \end{cases}$$

$$\Rightarrow \begin{cases} \dot{x}_1(t) = 2u - 5x_1(t) + x_2(t) \\ \dot{x}_2(t) = 3u - 6x_1(t) + x_1(t) \end{cases}$$

$$\begin{cases} X_1(s) = Y(s) \\ X_2(s) = \frac{1}{s}(3U - 6Y) \end{cases}$$

$$X_2(s) = \frac{1}{s}(3U - 6Y)$$

$$\Rightarrow x_1(t) = y(t)$$

$$\dot{x}_2(t) = 3u(t) - 6y(t)$$

$$= \frac{1}{s} ((2U - 5Y) + \frac{1}{s}(3U - 6Y))$$

$\hookrightarrow X_1(s)$

b) observable form

$$\frac{Y(s)}{U(s)} = G(s) = \frac{\frac{2}{s} + \frac{3}{s^2}}{1 + \frac{5}{s} + \frac{6}{s^2}}$$

$$\Rightarrow Y(s) \left(1 + \frac{5}{s} + \frac{6}{s^2} \right) = U(s) \left(\frac{2}{s} + \frac{3}{s^2} \right)$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} -5 & 1 \\ -6 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 2 \\ 3 \end{bmatrix} u$$

$$y = [1 \ 0] \vec{x}$$

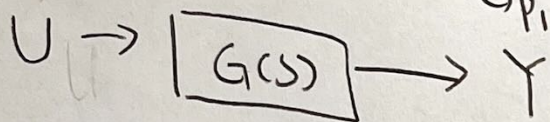
$$\Rightarrow Y(s) = -\frac{5}{s} Y(s) - \frac{6}{s^2} Y + \frac{2}{s} U + \frac{3}{s^2} U = \frac{1}{s} (2U - 5Y) + \frac{1}{s^2} (3U - 6Y)$$

8. c) diagonal canonical form

$$G(s) = \frac{2s+3}{s^2+5s+6} = \frac{2s+3}{(s+3)(s+2)} \quad \leftarrow \text{poles at } +3 \text{ \& } -2 \text{ not repeat}$$

$$= \frac{+3 \overset{k_1}{\swarrow}}{s+3} + \frac{-1 \overset{k_2}{\swarrow}}{s+2}$$

$\swarrow p_1 \qquad \swarrow p_2$

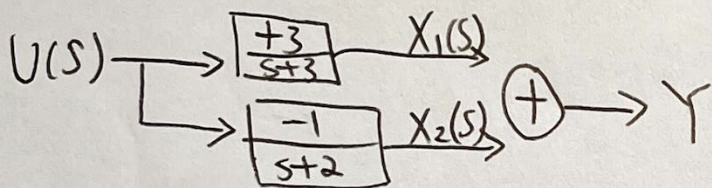


$$A = \begin{bmatrix} p_1 & 0 \\ 0 & p_2 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$C = \begin{bmatrix} k_1 & k_2 \end{bmatrix} \quad D=0$$

$\downarrow \qquad \downarrow$
3 -1



$$\frac{X_1}{U} = \frac{+3}{s+3} \Rightarrow (s+3)X_1 = +3U \Rightarrow sX_1 = +3U - 3X_1$$

$$\frac{X_2}{U} = \frac{-1}{s+2} \Rightarrow (s+2)X_2 = -U \Rightarrow sX_2 = -U - 2X_2$$

$$\downarrow \begin{cases} \dot{X}_1 = +3u(t) - 3X_1 \\ \dot{X}_2 = -u - 2X_2 \end{cases}$$

$$\begin{bmatrix} \dot{X}_1 \\ \dot{X}_2 \end{bmatrix} = \begin{bmatrix} -3 & 0 \\ 0 & -2 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \end{bmatrix} u$$

和公式解等效

$$y = \begin{bmatrix} 3 & -1 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \end{bmatrix}$$

(有四种表示法)

$$\begin{bmatrix} \dot{X}_1 \\ \dot{X}_2 \end{bmatrix} = \begin{bmatrix} -3 & 0 \\ 0 & -2 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} + \begin{bmatrix} +3 \\ -1 \end{bmatrix} u$$

$$y = \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \end{bmatrix}$$