Working title: Mirković-Vybornov fusion in Beilinson-Drinfeld Grassmannian

October 2020

1 Introduction

The BD Grassmannian. The convolution Grassmannian. Distinguished orbits and slices. Connections to Mirković–Vybornov [?, ?], Cautis–Kamnitzer [?], Anderson–Kogan [?].

Address limitations outside of type A?

2 Notation

In ordinary Gr we have the following lattice descriptions valid only in type A. Given $\mu \in X^{\bullet}(T)$, write t^{μ} for its image in $G(\mathcal{K})$ and L_{μ} for its image in

$$\operatorname{Gr} = G(\mathcal{K})/G(\mathcal{O}) \stackrel{A}{=} \{ L \subset_{\text{rank } m}^{\text{free}} \mathcal{O}^m : tL \subset L \}$$

Example: $L_{\mu} = \operatorname{Span}_{\mathcal{O}}(e_i t^j : 0 \leq j < \mu_i)$. Fact: $\operatorname{Gr}^T = X^{\bullet}(T)$ and other distinguished subsets (needed for the definition of MV cycles and later open subset thereof) are all orbits of fixed points

$$\begin{aligned} \operatorname{Gr}^{\lambda} &= G(\mathcal{O})L_{\lambda} &= \{L \in \operatorname{Gr} : t \big|_{\mathcal{O}^m/L} \text{ has Jordan type } \lambda \} \\ \operatorname{Gr}_{\mu} &= G_1[t^{-1}]L_{\mu} &= \{L \in \operatorname{Gr} : L = \operatorname{Span}_{\mathcal{O}}(v_1, \dots, v_m) \text{ such that} \\ &\qquad \qquad v_j = t^{\mu_j}e_j + \sum p_{ij}e_i \text{ with } \deg p_{ij} < \mu_j \} \\ S_-^{\mu} &= U_-(\mathcal{K})L_{\mu} &= \{L \in \operatorname{Gr}_{\mu} : \dim(\mathcal{O}^k/L \cap \mathcal{O}^k) = \mu_1 + \dots + \mu_k \} \end{aligned}$$

Let Gr denote the ordinary affine Grassmannian $G^{\vee}(\mathcal{K})/G^{\vee}(\mathcal{O})$, $\mathcal{G}r_n^{\mathrm{BD}}$ the Beilinson–Drinfeld affine Grassmannian, and Gr_n the convolution affine Grassmannian.

Definition 1. The BD Grassmannian is the set

$$\{(V,\sigma): V \text{ is a rank } m \text{ vector bundle on } \mathbb{P}^1$$

and $\sigma: V \dashrightarrow \mathscr{O}^m_{\mathbb{P}^1}$ is a trivialization (1)
defined away from finitely many points in $\mathbb{A}^1\}$

The rank of the m in the definition of $\mathcal{G}r_n^{\mathrm{BD}}$ is the dimension of the maximal torus of G^{\vee} . For $G^{\vee} = \mathbf{GL}_m = G$.

More generally, one can define a BD grassmannian of \mathbf{GL}_m over any smooth curve C as the reduced ind-scheme $\mathcal{G}_{n,C}^{\mathrm{BD}}$ fibered over a finite symmetric power of $C-C^{(n)}$ — such that the fibre over the point $\vec{p}=(p_1,\ldots,p_n)\in C^n$ is a collection of rank m vector bundles V over C which are trivial away from \vec{p} viewed also as a subset — $\{p_1,\ldots,p_n\}$ — of C. Trivial means $\mathscr{O}_C^m\cong V$.

Joel: Careful: you can define it over C^n or $C^{(n)}$, these are two different things.

To quote [?] the BD Grassmannian is a relative version of the affine Grassmannian where the base is the space of effective divisors on a smooth curve C. The choice $C=\mathbb{A}^1$ "amply satisfies our needs and offers three advantages: there is a natural global coordinate it, every G-torsor on it is trivializable, and the monodromy of any local system is trivial. Formally, $\mathcal{G}r_n^{\mathrm{BD}}$ is the functor on the category of commutative \mathbb{C} -algebras that assigns to an algebra R the set of isomorphism classes of triples (\vec{p}, V, σ) where $\vec{p} \in \mathbb{A}^n(R)$, V is a G^{\vee} -torsor over \mathbb{A}^1_R and σ is a trivialization of V away from \vec{p} ." Joel: Yes, G-torsor is the same thing as a principal G-bundle.

They denote by π the fibration $\mathcal{G}r_n^{\mathrm{BD}} \to \mathbb{A}^n$ (forgetting V and σ). Their simplified description is: it's the set of pairs $(\vec{p}, [\sigma])$ where $\vec{p} \in \mathbb{C}^n$ and $[\sigma]$ is an element of the homogeneous space

$$G^{\vee}(\mathbb{C}[z,(z-p_1)^{-1},\ldots,(z-p_n)^{-1}])/G^{\vee}(\mathbb{C}[z])$$

Their example, (almost) our setting:

Example 1. When $G = \mathbf{GL}_m\mathbb{C}$ the datum of $[\sigma]$ is equivalent to the datum of the $\mathbb{C}[z]$ -lattice $\sigma(L_0)$ in $\mathbb{C}(z)^m$ with $L_0 = \mathbb{C}[z]^m$ denoting the **standard lattice**. Set $f_{\vec{p}} = (z - p_1) \cdots (z - p_n)$. Then a lattice L is of the form $\sigma(L_0)$ if and only if there exists a positive integer k such that $f_{\vec{p}}^k(L_0) \subseteq L \subseteq f_{\vec{p}}^{-k}(L_0)$ and for each k they denote by $\mathcal{G}_n^{\text{BD}}$ the subset of $\mathcal{G}_n^{\text{BD}}$ consisting of pairs (\vec{p}, L) such that this sandwhich condition holds. They identify $\mathbb{C}[z]/(f_{\vec{p}}^{2k})$ with the vector space of polynomials of degree strictly less than 2kn, and $L_0/f_{\vec{p}}^{2k}L_0$ with its Nth product. Then

$$\mathcal{G}_{r_{n}}^{\mathrm{BD}} \overset{\mathrm{Zariski\ closed}}{\subset} \mathbb{C}^{n} \times \bigcup_{d=0}^{2knN} G_{d}(L_{0}/f_{\vec{p}}^{2k}L_{0})$$

where $G_d(?)$ denotes the ordinary Grassmann manifold of d-planes in the argument.

Our setting is $G = \mathbf{GL}_m$ and n = 2.

Definition 2. The **deformed convolution Grassmannian** is [not needed?] pairs $(\vec{p}, [\vec{\sigma}])$ where $\vec{p} \in \mathbb{C}^n$ and $\vec{\sigma}$ is in

$$G^{\vee}(\mathbb{C}[z,(z-p_1)^{-1}])\times^{G^{\vee}(\mathbb{C}[z])}\cdots\times^{G^{\vee}(\mathbb{C}[z])}G^{\vee}(\mathbb{C}[z,(z-p_n)^{-1}])/G^{\vee}(\mathbb{C}[z])$$

with a map down to $\mathcal{G}r_n^{\mathrm{BD}}$ defined by $(\vec{p}, [\vec{\sigma}]) \mapsto (\vec{p}, [\sigma_1 \cdots \sigma_n])$.

i.e. principal G bundle?

To steal the follow-up example in \cite{black} where the above definition is also copied from. . .

Example 2. When $G = \mathbf{GL}_m\mathbb{C}$ this deformation is described by the datum of $\vec{p} \in \mathbb{C}^n$ and a sequence (L_1, \ldots, L_n) of $\mathbb{C}[z]$ -lattices in $\boxed{\mathbb{C}(z)^m}$ such that for some $k \in \mathbb{Z}$ and for all $j \in \{1 \ldots n\}$

Why Laurent polynomials for the convolution?

$$(z-p_j)^k L_{j-1} \subset L_j \subset (z-p_j)^{-k} L_{j-1}$$

where again $L_0 = \mathbb{C}[z]^m$ denotes the standard lattice, while $L_j = (\sigma_1 \cdots \sigma_j)(L_0)$. Very nice. Very concrete. They can partition the deformation into **cells** by specifying the **relative positions** of the pairs (L_{j-1}, L_j) in terms of **invariant factors**.

To be continued: [?] go on to describe the fibres of the composition

Not to $\mathbb{C}^{(n)}$? Or to \mathbb{C} ?

$$\operatorname{Gr}_n \to \mathcal{G}r_n^{\operatorname{BD}} \to \mathbb{C}^n = \mathbb{A}^n_{\mathbb{C}}$$

their description may be helpful.

For $\mu \in P$ and $p \in \mathbb{C}$ they define

$$\tilde{S}_{\mu|p} = (z-p)^{\mu} N^{\vee}(\mathbb{C}[z,(z-p)^{-1}]) = N^{\vee}(\mathbb{C}[z,(z-p)^{-1}])(z-p)^{\mu}$$

They note that $\mathbb{C}((z-p))$ is the completion of $\mathbb{C}(z)$ at "the place defined by p" and identify $\mathbb{C}[z-p]$ with $\mathbb{C}[z]$ and $\mathbb{C}((z-p))$ with $\mathbb{C}((z))$.

They claim that

$$N^{\vee}(\mathbb{C}[z,(z-p)^{-1}])/N^{\vee}(\mathbb{C}[z]) \to N^{\vee}(\mathbb{C}(\!(z-p)\!))/N^{\vee}(\mathbb{C}[\![z-p]\!]) \cong N^{\vee}(\mathcal{K})/N^{\vee}(\mathcal{O})$$

is bijective, and that mapping Gr and multiplying by $(z-p)^{\mu}$ one gets

$$\tilde{S}_{\mu|p}/N^{\vee}(\mathbb{C}[z]) \cong S_{\mu}$$

They go on to describe the fusion product (section 5.3) a probably worthwhile read.

Going forward, we'll use t to denote the coordinate on $\mathbb{A}^1_{\mathbb{C}} = \mathbb{C}$ instead of z. Then by $t^{\mu} \in G^{\vee}(\mathcal{K})$ we'll denote the point defined by the coweight $\mu \in \operatorname{Hom}(\mathbb{C}^{\times}, T^{\vee}) = T^{\vee}(\mathcal{K})$ and by L_{μ} its image $t^{\mu}G^{\vee}(\mathcal{O})$ in Gr.

Definition 3. Given μ_1, μ_2 such that $\mu = \mu_1 + \mu_2$ is a partition of N we define $T_{\mu_1,\mu_2} \subset \operatorname{Mat}_N$ to be the set of $\mu \times \mu$ block matrices that are zero everywhere except possibly in the last $\min(\mu_i,\mu_j)$ columns of the last row of the $\mu_i \times \mu_j$ th block plus the block diagonal matrix whose $\mu_i \times \mu_i$ diagonal block is the companion matrix of $t^{\mu_{1,i}}(t-s)^{\mu_{2,i}}$ for each $i \in \{1,2,\ldots,m\}$. We call this set name.

Remark 1. While we limit ourselves to the case of dominant partitions, the definition above makes sense for arbitrary partitions.

Remark 2. Speak to whether or not this slice appears in [?]. We don't think it does. But its "lift" might.

Definition 4. Given λ_1, λ_2 such that $\lambda = \lambda_1 + \lambda_2$ is a partition of N we define $\mathbb{O}_{\lambda_1, \lambda_2}$ to be the set of $N \times N$ **semi-nilpotent** matrices X with spectrum in $\{0, s\}$ for some $s \in \mathbb{C}^{\times}$ such that $X|_{E_0} \in \mathbb{O}_{\lambda_1}$ and $(X - s)|_{E_S} \in \mathbb{O}_{\lambda_2}$ meaning TODO

Cute

Correspondingly we have

- $W_{\mu_1,\mu_2}=G_1^{\vee}[t^{-1},(t-s)^{-1}]t^{\mu_1}(t-s)^{\mu_2}G^{\vee}(\mathcal{O})$ as a subset of $\mathcal{G}r_2^{\mathrm{BD}}$ where recall the subscript 2 records the fact that we are fixing two points $0,s\in\mathbb{C}$
- Does $\mathcal{G}r_2^{\mathrm{BD}\lambda_1,\lambda_2}$ admit such an orbit description? As a fibration it is pairs (V,σ) such that is trivialized away from (0,s) by σ and σ has type (λ_1,λ_2) the data of the trivialization is equivalent to the data of pairs of lattices (L_1,L_2) such that $L_i\in\mathrm{Gr}^{\lambda_i}$ away from 0 and $L_1=L_2\in\mathrm{Gr}^{\lambda}$ at 0?
- In the deformed convolution Gr we have the subset $\operatorname{Gr}_2^{\lambda_1,\lambda_2}$ of pairs $((0,s),[\sigma_1,\sigma_2])$ (really want arbitrary (p_1,p_2) in place of (0,s) which is the specialization that we make when we work in $\mathcal{G}r_2^{\operatorname{BD}}$ sort of?) with $\sigma_i \in G^{\vee}(\mathbb{C}[t])(t-p_i)^{\lambda_i}G^{\vee}(\mathbb{C}[z])$ but this is not important?

Question 1. Can we describe $W_{\mu_1,\mu_2} \cap \overline{\operatorname{Gr}^{\lambda_1,\lambda_2}}$ as the set of lattices L such that

$$t^{\lambda_{1,1}}(t-s)^{\lambda_{2,1}}L_0 \subset L \subset t^{-\lambda_{1,1}}(t-s)^{-\lambda_{2,1}}L_0$$

and $\lim_{s\to 0} \rho^{\vee}(s) \cdot L = L_{\mu}$

Joel: This is not correct since, you don't use all information in λ_1, λ_2 . You need to describe the Jordan type of the quotients, or something equivalent.

Definition 5. Say μ_1 and μ_2 are **disjoint** if $(\mu_1)_i \neq 0 \Rightarrow (\mu_2)_i = 0$ and $(\mu_2)_i \neq 0 \Rightarrow (\mu_1)_i = 0$.

3 Main results

Claim 1. $\widetilde{T}_x^a \to \pi^{-1}(\overline{\operatorname{Gr}^{\lambda}} \cap \operatorname{Gr}_{\mu})$ (this does depend on b! we get something like a springer fibre where the action of [what] on either side has eigenvalues a permutation of b.)

Claim 2. Let $\mathcal{W}^{\mu}_{BD} = G_1((t^{-1}))t^{\mu}$. Then $S^{\mu_1 + \mu_2}$ is contained in \mathcal{W}^{μ}_{BD} if μ is dominant. Joel: And μ_1 , μ_2 are dominant also? Anne: Roger has a proof.

Claim 3. Let a=(0,s) and suppose μ_1 and μ_2 are disjoint "transverse" Let $\mu=\mu_1+\mu_2$. Then $X\in\widetilde{T_x^a}$ is a $\mu\times\mu$ block matrix, with $(\mu_1)_k\times(\mu_1)_k$ diagonal block conjugate to a $(\mu_1)_k$ Jordan block and $(\mu_2)_k\times(\mu_2)_k$ diagonal block conjugate to $(\mu_2)_k$ Jordan block plus sI.

Question 2. If μ_i is not a permutation of λ_i and λ_i are not "homogeneous" how do we proceed? E.g. if $\mu_1 = (3,0,2)$, $\mu_2 = (0,2,0)$ and $\lambda_1 = (4,1)$, $\lambda_2 = (2,0,0)$. Question 3. If μ_1 and μ_2 are not disjoint how do we proceed? E.g. if $\mu_1 = (2,2,0)$, $\mu_2 = (1,0,2)$; $\mu_1 = (2,2,1)$, $\mu_2 = (1,0,1)$.

Joel: I think that we figured this out. We just need to take the matrix corresponding to $z^{\mu_1}(z-s)^{\mu_2}$ under the MVy isomorphism.

Convolution vs BD

Fix $G = \mathbf{GL}(U) \cong \mathbf{GL}_m\mathbb{C}$ and $\{e_1, \dots, e_m\}$ a basis of U. Recall $Gr = \mathbf{GL}(U)$ $G(\mathcal{K})/G(\mathcal{O})$ where $\mathcal{K}, \mathcal{O}...$

Definition 6 (Beilinson–Drinfeld loop Grassmannians). Denoted $\mathcal{G}r_{n-C^{(n)}}^{\mathrm{BD}}$ with C a smooth curve (or formal neighbourhood of a finite subset thereof) and $C^{(n)}$ its nth symmetric power. It is a reduced ind-scheme $\mathcal{G}_n^{\mathrm{BD}}{}_{C^{(n)}} \to C^{(n)}$ with fibres of C-lattices $\mathcal{G}r_n^{\mathrm{BD}}{}_b = \{(b,\mathcal{L}) : b \in C^{(n)}\}$ made up of vector bundles such that $\mathcal{L} \cong U \otimes \mathcal{O}_C$ off b (i.e. over $C - \underline{b}$). The standard lattice is the pair $(\varnothing, \mathcal{L}_0)$ with $\mathcal{L}_0 = U \otimes \mathcal{O}_C$.

The case n = 1. Fix $b \in C$ and t a choice of formal parameter. Then

 $\mathcal{G}\!r_n^{\mathrm{BD}}{}_b \cong \mathrm{Gr}.$ Furthermore, in this case, C-lattices (b,\mathcal{L}) are identified with \mathcal{O} -submodules $L = \Gamma(\hat{b}, \mathcal{L})$ of $U_{\mathcal{K}} = U \otimes \mathcal{K}$ such that $L \otimes_{\mathcal{O}} \mathcal{K} \cong U_{\mathcal{K}}$.

Under this identification, we associate to a given $\lambda \in \mathbb{Z}^m$ the lattice (a priori a \mathcal{O} -submodule) $L_{\lambda} = \bigoplus_{i=1}^{m} t^{\lambda_i} e_i \mathcal{O}$. Nb. our lattices will be contained in the standard lattice L_0 whereas MVy's lattices contain.

Connected components of Gr are

 $G(\mathcal{O})$ -orbits are indexed by coweights $\lambda = (\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_n)$ of G. In terms of lattices

$$\operatorname{Gr}^{\lambda} = \left\{ L \supset L_0 \left| t \right|_{L/L_0} \in \mathbb{O}_{\lambda} \right\}$$
 (2)

in the connected component Gr_N are indexed

[?] define a map

$$\mathcal{G}r_n^{\mathrm{BD}} \to \mathrm{Gr}_n$$
 (3)

- Their slice T_x or T_λ
- Their embedding $T_x \to \mathfrak{G}_N$
- N-dim D
- The map $\tilde{\mathbf{m}}: \tilde{\mathfrak{g}}^n \to \operatorname{End}(D)$
- The map $\mathbf{m}: \tilde{\mathcal{N}}^n \to \mathcal{N}$ sending (x, F_{\bullet}) to x
- The map $\pi: \tilde{\mathfrak{G}}^n \to \mathfrak{G}$ sending \mathcal{L}_{\bullet} to \mathcal{L}_n

The special case $b = \vec{0}$. In this case 0 in the affine quiver variety goes to the point L_{λ} in the affine Grassmannian, and the preimage of zero in the smooth quiver variety (= the core?) is identified with the preimage of L_{λ} in the BD Grassmannian.

$$\begin{array}{ccc} \mathfrak{L}(\vec{v}, \vec{w}) & \longrightarrow & \pi^{-1}(L_{\lambda}) \\ \downarrow & & \downarrow \\ 0 & \longrightarrow & L_{\lambda} \end{array}$$

Not sure what \mathcal{O}_C Notation

Why is this called "its group-theoretic realization"

MVy write: "we believe that one should be able to generalize this to arbitrary b" and that's where we come in!

Recall the Mirković-Vybornov immersion [?, Theorems 1.2 and 5.3].

Theorem 1. ([?, Theorem 1.2 and 5.3]) There exists an algebraic immersion $\tilde{\psi}$

$$\widetilde{\mathbf{m}}^{-1}(T_{\lambda}) \cap \widetilde{\mathfrak{g}}^{n,a,E,\tilde{\mu}} \xrightarrow{\widetilde{\psi}} \widetilde{\mathfrak{G}}_{b}^{n,a}(P)$$

5 Statements and Proofs of Results

Anne: Maybe split for now into a Notation section and a Proofs section Define

$$S_{\mu_1,\mu_2} = N((t^{-1}))t^{\mu_1}(t-s)^{\mu_2}$$

and

$$W_{\mu} = G_1[[t^{-1}]]t^{\mu}.$$

Let $|\lambda| = |\lambda_1 + \lambda_2|$ and $|\mu| = |\mu_1 + \mu_2|$.

Anne: Why not $\lambda = \lambda_1 + \lambda_2$ and recall $|\nu|$ in general.

Lemma 1 (Proof in Proposition 2.6 of KWWY). Suppose μ is dominant. Then

$$N((t^{-1}))t^{\mu} = N_1[[t^{-1}]]t^{\mu}.$$

Lemma 2. For dominant μ_1, μ_2 , we have

$$S_{\mu_1,\mu_2} \subset W_{\mu_1+\mu_2}.$$

Proof. We have

$$S_{\mu_{1},\mu_{2}} = N((t^{-1}))t^{\mu_{1}}(t-s)^{\mu_{2}}$$

$$\subset T_{1}[[t^{-1}]]N((t^{-1}))t^{\mu_{1}}(t-s)^{\mu_{2}}$$

$$= T_{1}[[t^{-1}]]N_{1}[[t^{-1}]]t^{\mu_{1}}(t-s)^{\mu_{2}}$$

$$= B_{1}[[t^{-1}]]t^{\mu_{1}}(t-s)^{\mu_{2}}$$

$$= B_{1}[[t^{-1}]]t^{\mu_{1}+\mu_{2}}$$

$$\subset G_{1}[[t^{-1}]]t^{\mu_{1}+\mu_{2}}$$

$$= W_{\mu_{1}+\mu_{2}}$$

where $B_1[[t^{-1}]]t^{\mu_1}(t-s)^{\mu_2} = B_1[[t^{-1}]]t^{\mu_1+\mu_2}$ since

$$\frac{t}{t-s} = 1 + \frac{s}{t} + \frac{s^2}{t^2} + \dots \in B_1[[t^{-1}]].$$

Define $Gr^{\lambda_1,\lambda_2} \subset Gr_{BD}$ to be the family with generic fibre $Gr^{\lambda_1} \times Gr^{\lambda_2}$ and 0-fibre $Gr^{\lambda_1+\lambda_2}$.

Define $\mathbb{O}_{\lambda_1,\lambda_2}$ to be matrices X of size $|\lambda| \times |\lambda|$ such that

$$X\big|_{E_0} \in \mathbb{O}_{\lambda_1} \text{ and } (X - sI)\big|_{E_s} \in \mathbb{O}_{\lambda_2}$$

Let

$$\mu = (\mu^{(1)}, \mu^{(2)}, ..., \mu^{(n)}).$$

Define \mathbb{T}_{μ_1,μ_2} to be $|\mu| \times |\mu|$ matrices X such that X consists of block matrices where the size of the i-th diagonal block is $|\mu^{(i)}| \times |\mu^{(i)}|$, for $1 \le i \le n$. Each diagonal block is the companion matrix for $t^{\mu_1}(t-s)^{\mu_2}$. Each off-diagonal block is zero everywhere except possibly in the last $\min(\mu_i, \mu_j)$ columns of the last row.

Theorem 2. We have an isomorphism

$$\overline{\mathrm{Gr}^{\lambda_1,\lambda_2}} \cap S_{\mu_1,\mu_2} \cong \overline{\mathbb{O}_{\lambda_1,\lambda_2}} \cap \mathbb{T}_{\mu_1,\mu_2} \cap \mathfrak{n}.$$

Anne: Rather, corollary?

Proof. We will prove this similarly to how the usual Mirković–Vybornov isomorphism is proven.

Step 1: Define a map $\mathbb{T}_{\mu_1,\mu_2} \cap \mathcal{N} \to G_1[t^{-1},(t-s)^{-1}]t^{\mu_1}(t-s)^{\mu_2}$.

$$A \mapsto t^{\mu_1}(t-s)^{\mu_2} + a(t,t-s) \mapsto (L_1 \subset L_2) : (t-s)\big|_{L_2/L_1} = A\big|_{E_s}, t\big|_{L_1/L_0} = A\big|_{E_0}$$

Question: 1. is the middle matrix similar to a block matrix? 2. is the composition of these maps some intermediate level of MVy's ψ 's

BD Gr as lattices? $(L_1, L_2) \in \operatorname{Gr} \times \operatorname{Gr}$ corresponds to L such that $L \otimes \mathbb{C}[\![t]\!] \cong L_1 \otimes \mathbb{C}[\![t]\!]$ and $L \otimes \mathbb{C}[\![t-s]\!] \cong L_2 \otimes \mathbb{C}[\![t-s]\!]$ where $\otimes = \otimes_{\mathbb{C}[t]}$ or $\otimes_{\mathbb{C}[t-s]}$ respectively even though Roger believes $\mathbb{C}[t] = \mathbb{C}[t-s]$.

Proof of Step 1: Let $\mu_1 = (\mu_{1,1}, \mu_{1,2}, ..., \mu_{1,n}), \ \mu_2 = (\mu_{2,1}, ..., \mu_{2,n}), \ \text{and} \ \mu = (\mu^{(1)}, \mu^{(2)}, ..., \mu^{(n)}).$ Consider the matrix where C_i is the $\mu^{(i)} \times \mu^{(i)}$ companion matrix of $t^{\mu_{1,i}}(t-s)^{\mu_{2,i}}$. We send this matrix to the matrix

$$\begin{bmatrix} t^{\mu_{1,1}}(t-s)^{\mu_{2,1}} \\ -\sum_{k=1}^{\mu^{(2)}} a_{12}^k t^{k-1} & t^{\mu_{1,2}}(t-s)^{\mu_{2,2}} \\ \vdots & \ddots & \ddots \\ -\sum_{k=1}^{\mu^{(n)}} a_{1n}^k t^{k-1} & \cdots & -\sum_{k=1}^{\mu^{(n)}} a_{n-1,n}^k t^{k-1} & t^{\mu_{1,n}}(t-s)^{\mu_{2,n}} \end{bmatrix}$$

$$= \begin{bmatrix} 1 & & & & \\ p_{1,2}(t) & 1 & & & \\ \vdots & \ddots & \ddots & & \\ p_{1,n}(t) & \cdots & p_{n-1,n}(t) & 1 \end{bmatrix} \begin{bmatrix} t^{\mu_{1,1}}(t-s)^{\mu_{2,1}} & & & \\ & \ddots & & & \\ & & t^{\mu_{1,n}}(t-s)^{\mu_{2,n}} \end{bmatrix}$$

where

$$p_{i,j}(t) = \frac{-\sum_{k=1}^{\mu^{(j)}} a_{i,j}^k t^{k-1}}{t^{\mu_{1,i}} (t-s)^{\mu_{2,i}}}$$

As μ_1 and μ_2 are dominant, we have $p_{i,j}(t)\to 0$ as $t\to\infty$ so this matrix is indeed in $G_1[t^{-1},(t-s)^{-1}]t^{\mu_1}(t-s)^{\mu_2}$.

Step 2: If $A \in \mathbb{T}_{\mu_1,\mu_2} \cap \mathfrak{n}$ then A is sent to $(N_-)_1[t^{-1},(t-s)^{-1}]t^{\mu_1}(t-s)^{\mu_2}$. Anne: Requires MVyBD!

Step 3: Conversely, given $L \in W_{\mu_1 + \mu_2}$, want to show surjectivity.

Last meeting's todos:

- make sure that the image of our map is in the G_1 orbit
- more generally, define the map, check that the map is well-defined
- Anne: say what little a is, i.e. insert the MVy theorem as stated in CK, or thesis
- Roger: check it

8

article basic

Examples Compendium Roger Bai, Anne Dranowski Last edit: approx. January 22, 2021

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Let Z be the MV cycle of weight α_3 with Lusztig datum (000, 00, 1) and Z' the MV cycle of weight $\alpha_{1,2}$ with Lusztig datum (010, 00, 0).

In terms of tableax the fusion Z * Z' can be encoded as

$$S_3 * (1 \leftarrow 2) = (1 \leftarrow 2 \rightarrow 3) + P_3$$
 (5)

$$(000, 00, 1) * (010, 00, 0) = (010, 00, 1) + (001, 00, 0)$$

$$(6)$$

$$= (A_0, A_5, A_1A_4 - A_2A_3) \sqcup (A_0, A_1, A_3)$$
 (7)

where the ideals in line 3 are given in coordinates on matrices of the form

$$\begin{bmatrix} 0 & A_0 & A_1 & A_2 \\ \hline 0 & 0 & A_3 & A_4 \\ \hline 0 & 0 & s & A_5 \\ \hline 0 & 0 & 0 & 0 \end{bmatrix}$$

Check that

$$E_0 = \{\vec{\mathbf{e}}_1, \vec{\mathbf{e}}_2, \vec{\mathbf{e}}_4 - \frac{1}{s} A_5 \vec{\mathbf{e}}_3\} \to \{\vec{\mathbf{e}}_1, \vec{\mathbf{e}}_2, -A_5 \vec{\mathbf{e}}_3\}$$

$$E_s = \{\vec{\mathbf{e}}_3 + \frac{1}{s} A_3 \vec{\mathbf{e}}_2 + \frac{1}{s} A_1 \vec{\mathbf{e}}_1\} \to \{A_3 \vec{\mathbf{e}}_2 + A_1 \vec{\mathbf{e}}_1\}$$

The equations imposed by the factor tableaux also degenerate.

$$(A_0, sA_2 - A_1A_5, sA_4 - A_3A_5) \rightarrow (A_0, A_1A_5, A_3A_5) = (A_0, A_5) \sqcup (A_0, A_1, A_3)$$

Need to supplement $A_5 = 0$ case with $\operatorname{col}_3 \wedge \operatorname{col}_4 = 0$ or $A_1 A_4 - A_2 A_3 = 0$ in order that $\dim \ker A = 3$.

Remark 3. If we take $s \to \infty$ in E_0 , E_s we get the spanning set $\{\vec{\mathbf{e}}_1, \vec{\mathbf{e}}_2, \vec{\mathbf{e}}_4\} \sqcup \{\vec{\mathbf{e}}_3\}$. Does this have any significance?

Next let Z be the MV cycle of weight $\alpha_{1,3}$ having Lusztig datum (100,01,0) and Z' the MV cycle of weight α_2 having Lusztig datum (000,10,0).

Again, in terms of tableaux, Z * Z' is given by

$$(1 \to 2 \leftarrow 3) * S_2 = P_2 + (2 \leftarrow 3) \oplus (1 \to 2)$$
 (9)

$$(100,01,0) * (000,10,0) = (010,01,0) + (100,11,0)$$

$$(10)$$

$$= (A_5, A_0) \sqcup (A_3, A_0 A_4 + A_1 A_5) \tag{11}$$

Let's verify with MVy. Consider

$$A = \begin{bmatrix} s & A_0 & A_1 & A_2 \\ 0 & 0 & A_3 & A_4 \\ 0 & 0 & s & A_5 \\ 0 & 0 & 0 & 0 \end{bmatrix} \qquad A - s = \begin{bmatrix} 0 & A_0 & A_1 & A_2 \\ 0 & -s & A_3 & A_4 \\ 0 & 0 & 0 & A_5 \\ 0 & 0 & 0 & -s \end{bmatrix}$$

Then

$$E_0 = \{ s\vec{\mathbf{e}}_2 - A_0\vec{\mathbf{e}}_1, \tag{12}$$

$$sA_0\vec{\mathbf{e}}_4 - A_0A_5\vec{\mathbf{e}}_3 + A_1A_5\vec{\mathbf{e}}_2 - A_0A_1\vec{\mathbf{e}}_1 \text{ if } sA_4 - A_3A_5 = 0\}$$
 (13)

$$\rightarrow \{\vec{\mathbf{e}}_1, -A_0 A_5 \vec{\mathbf{e}}_3 + A_1 A_5 \vec{\mathbf{e}}_2 - A_0 A_1 \vec{\mathbf{e}}_1 \text{ if } A_3 A_5 = 0\}$$
 (14)

$$E_s = \{\vec{\mathbf{e}}_1, \tag{15}$$

$$s\vec{\mathbf{e}}_3 + A_3\vec{\mathbf{e}}_2 \text{ if } sA_1 + A_0A_3 = 0$$
 (16)

$$\to \{\vec{\mathbf{e}}_1, \vec{\mathbf{e}}_2 \text{ if } A_0 A_3 = 0\} \tag{17}$$

From this we see that Z * Z' is contained in

$$(A_3A_5, A_0A_3) = (A_3) \sqcup (A_5, A_0)$$

Expected dimension is 4+3-2-1=4 hence the first ideal is not big enough. Indeed the case $A_3=0$ and $A_5\neq 0$ has to be supplemented with $A\big|_{s=0}^2=0$ since the total Jordan type is (1,1)+(1,1)=(2,2). This adds the condition $A_0A_4+A_1A_5=0$.

Now take Z to be the MV cycle of weight $\alpha_{1,3}$ with Lusztig datum (010,00,1) and leave Z' as above. Then

$$(1 \leftarrow 2 \rightarrow 3) * S_2 = (2 \rightarrow 3) \oplus (1 \leftarrow 2) + P_2$$
 (19)

$$(010, 00, 1) * (000, 10, 0) = (010, 10, 1) + (010, 01, 0)$$
(20)

Verifying. Consider

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -s^2 & 2s & A_0 & A_1 & A_2 & A_3 & A_4 \\ \hline 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & s & A_5 & A_6 & A_7 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & s & A_8 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

and

$$A - s = \begin{bmatrix} -s & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -s & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -s^2 & s & A_0 & A_1 & A_2 & A_3 & A_4 \\ \hline 0 & 0 & 0 & -s & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & A_5 & A_6 & A_7 \\ \hline 0 & 0 & 0 & 0 & 0 & -s & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & A_8 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & -s \end{bmatrix}$$

Then

$$E_0 = \{\vec{\mathbf{e}}_1, \tag{21}$$

$$\vec{\mathbf{e}}_4 \text{ if } A_0 = 0, \tag{22}$$

$$s\vec{\mathbf{e}}_6 - A_5\vec{\mathbf{e}}_5 + c\vec{\mathbf{e}}_2 \text{ if } A_2 = 0,$$
 (23)

$$A_5\vec{\mathbf{e}}_8 - A_7\vec{\mathbf{e}}_6 \text{ if } A_4, A_8 = 0\} \tag{24}$$

$$\rightarrow \{\vec{\mathbf{e}}_1, \vec{\mathbf{e}}_4, -A_5 \vec{\mathbf{e}}_5 + c \vec{\mathbf{e}}_2, A_5 \vec{\mathbf{e}}_8 - A_7 \vec{\mathbf{e}}_6 \tag{25}$$

if
$$A_0, A_2, A_4, A_8 = 0$$
 (26)

$$E_s = \{s^2 \vec{\mathbf{e}}_3 + s \vec{\mathbf{e}}_2 + \vec{\mathbf{e}}_1, s \vec{\mathbf{e}}_3 - \frac{1}{s} \vec{\mathbf{e}}_1,$$
 (27)

$$s\vec{\mathbf{e}}_5 + \vec{\mathbf{e}}_4 \text{ if } A_1 = 0, \tag{28}$$

$$s\vec{\mathbf{e}}_7 + \vec{\mathbf{e}}_6 + \vec{\mathbf{e}}_5 \text{ if } A_5 + (A_6 - 1)s = 0$$
 (29)

$$\rightarrow \{\vec{\mathbf{e}}_1, \vec{\mathbf{e}}_4, \vec{\mathbf{e}}_6 + \vec{\mathbf{e}}_5 \text{ if } A_1, A_5 = 0\}$$
 (30)

In line ?? I don't think $A_3=0$ because we can probably add some combination $a\vec{\bf e}_1+b\vec{\bf e}_2+c\vec{\bf e}_3$ so that $\vec{\bf e}_7$ maps to both 1-cycles (the 2-d kernel) determined so far

Thus Z * Z' is contained in $(A_0, A_2, A_4, A_8, A_1, A_5)$ Also computed:

$$\frac{1}{2} * \frac{1}{3} = \frac{1}{2} = \frac{1}{2} + \frac{1}{2} = \frac{1}{3} = \frac{1}{3} + \frac{1}{2} = \frac{1}{3}$$
(31)

$$(000, 00, 1) * (100, 10, 0) = (100, 01, 0) + (100, 10, 1)$$
(32)

$$S_3 * (1 \to 2) = (1 \to 2 \leftarrow 3) + (1 \to 2 \to 3)$$
 (33)

$$= (A_0, A_5, A_4, A_2) \sqcup (A_0, A_5, A_4, A_6)$$
 (34)

in

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & s & A_0 & A_1 & A_2 & A_3 \\ \hline 0 & 0 & 0 & 1 & 0 & 0 \\ \hline 0 & 0 & 0 & s & A_4 & A_5 \\ \hline 0 & 0 & 0 & 0 & s & A_6 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

TODO: add explanation, double check the ideals.

Finally, we guess that the fusion $2\alpha_1*2\alpha_2$ is encoded by the tableau equation

$$\boxed{2 \mid 2} * \boxed{\frac{1 \mid 1}{3 \mid 3}} = \boxed{\frac{1 \mid 1 \mid 2 \mid 2}{3 \mid 3}} + \boxed{\frac{1 \mid 1 \mid 2 \mid 3}{2 \mid 3}} + \boxed{\frac{1 \mid 1 \mid 3 \mid 3}{2 \mid 2}}$$

This is checked below.

7 Disjoint, non-dominant weight

Example 3. $\lambda_1 = (1, 0, 0), \ \lambda_2 = (1, 1, 0), \ \mu_1 = (0, 1, 0), \ \mu_2 = (1, 0, 1).$ Joel: $\mu = \mu_1 + \mu_2$ determines the blocks we have on the RHS of the BD MVy isomorphism.

$$\begin{bmatrix} s & A_0 & A_1 \\ \hline 0 & 0 & A_2 \\ \hline 0 & 0 & s \end{bmatrix}$$

8 Some multiplicity

Example 4 (Joel's exercise). It would be good to do an example where we will see some multiplicity in the fusion product. I think that the simplest example would be the fusion product of the MV cycles for SL_3 of weights $2\alpha_1$ and $2\alpha_2$.

Following the notation from the mvbasis paper, this would correspond to the following multiplication:

$$x^2y^2 = (xy - z)^2 + 2(xy - z)z + z^2$$
.

Take $\lambda_1=(2,0,0),\ \lambda_2=(2,2,0),\ \mu_1=(0,2,0),\ \mu_2=(2,0,2).$ Note that there is only one tableau of weight μ_i and type λ_i for each i.

Consider

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ -s^2 & 2s & A_0 & A_1 & A_2 & A_3 \\ \hline 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & A_4 & A_5 \\ \hline 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & -s^2 & 2s \end{bmatrix}$$

Then

$$E_s = \{\vec{\mathbf{e}}_1 + s\vec{\mathbf{e}}_2, \vec{\mathbf{e}}_1 + (s+1)\vec{\mathbf{e}}_2$$
 (35)

$$\vec{\mathbf{e}}_5 + s\vec{\mathbf{e}}_6 + \frac{1}{s}(A_4 + A_5s)\vec{\mathbf{e}}_4 + \frac{1}{s^2}(A_4 + A_5s)\vec{\mathbf{e}}_3$$
 (36)

if
$$(A_0 + A_1 s)(A_4 + A_5 s) + (A_2 + A_3 s)s^2 = 0,$$
 (37)

$$\vec{\mathbf{e}}_1 + (s+a)\vec{\mathbf{e}}_2 + \vec{\mathbf{e}}_6 + \frac{1}{s}\vec{\mathbf{e}}_5 + \frac{1}{s}A_5\vec{\mathbf{e}}_4 - \frac{1}{s^3}A_4\vec{\mathbf{e}}_3\}$$
 (38)

if
$$-2A_3s^3 - A_2s^2 + A_0A_4 - A_5s = 0$$
 (39)

$$E_0 = \{ A_0 \vec{\mathbf{e}}_1 + s^2 \vec{\mathbf{e}}_3, A_0 \vec{\mathbf{e}}_2 + s^2 \vec{\mathbf{e}}_4 + \frac{A_1}{A_0} \vec{\mathbf{e}}_1 - 2s \vec{\mathbf{e}}_3 \}$$
 (40)

Taking $s \to 0$ we get

$$E_{s=0} = \{\vec{\mathbf{e}}_1, \vec{\mathbf{e}}_1 + \vec{\mathbf{e}}_2, \vec{\mathbf{e}}_3 \text{ if } A_0 A_4 = 0\}$$
(41)

$$E_0 = \{\vec{\mathbf{e}}_1, A_0^2 \vec{\mathbf{e}}_2 + A_1 \vec{\mathbf{e}}_1\}$$
(42)

So Z*Z' is contained in (A_0A_4) . If we look at $(A|_{s=0})^4$, which must be zero since $\lambda=(4,2)$, we pick up the additional equation $A_1A_4+A_0A_5$. Therefore the ideal of Z*Z' is

$$(A_0 A_4, A_1 A_4 + A_0 A_5) \subset \mathbb{C}[A_0 ... A_5] \tag{43}$$

which decomposes as $(A_4, A_5) \sqcup (A_0, A_1) \sqcup (A_0, A_4)$. Since

$$\mathbb{C}[x,y]/(xy,x+y) \cong \mathbb{C}[z]/(z^2)$$

the component (A_0, A_4) occurs with multiplicity 2 as expected! Localize at, or colon out (A_1, A_5) .

Note that these ideals correspond to expected tableaux as follows.

$$= (A_4, A_5) + \frac{2?}{(A_0, A_4)} + (A_0, A_1) \tag{45}$$

$$= (20,2) + \frac{2?}{(11,1)} + (02,0) \tag{46}$$

$$= (11 \to 22) + \frac{2?}{(1 \to (1 \leftarrow 2))} \to 2) + (11 \leftarrow 22) \tag{47}$$

$$= (xy - z)^{2} + 2(xy - z)z + z^{2}$$
(48)

Question 4. How do we tell from the tableaux that an ideal is occurring with multiplicity?

9 Simple root weights, things working

Example 5. Let

$$\mu_1 = (3, 1, 1)$$
 $\lambda_1 = (3, 2, 0)$ $\mu = (3, 3, 1)$

$$\mu_2 = (0, 2, 0)$$
 $\lambda_2 = (2, 0, 0)$ $\lambda = (5, 2, 0)$

and consider the companion matrices of

$$p_1(t) = t^3$$
 $p_2(t) = t(t-s)^2 = t^3 - 2st^2 + s^2t$ $p_3(t) = t$

$$X = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & d & e & f & g \\ \hline 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & -s^2 & 2s & k \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Example 6. Let

$$\lambda_1 = (3, 2, 0)$$
 $\mu_1 = (3, 1, 1)$
 $\lambda_2 = (2, 0, 0)$ $\mu_2 = (1, 1, 0)$

so the first MV cycle $Z_1 \cong \mathbb{P}^1$ has MV polytope Conv $\{0, \alpha_1\}$ and the second MV cycle $Z_2 \cong \mathbb{P}^1$ has MV polytope Conv $\{0, \alpha_2\}$. Their fusion product corresponds to two \mathbb{P}^2 's intersecting along a \mathbb{P}^1 . That is, we have the fusion product

$$Z_1 * Z_2 = Z_+ + Z_-$$

where $Z_+ \cong Z_- \cong \mathbb{P}^2$. We have

$$X = \begin{bmatrix} 0 & 1 & & & & \\ & 0 & 1 & & & \\ & & 0 & 1 & & \\ & & & s & a & b & c \\ & & & & 0 & 1 & 0 \\ & & & & 0 & s & d \\ & & & & & 0 \end{bmatrix}$$

The 0-generalized eigenspace E_0 of X is 5-dimensional, containing a 3-cycle and a 2-cycle. The 3-cycle is

$${X^2e_3, Xe_3, e_3} = {e_1, e_2, e_3}.$$

To obtain another vector in ker X, either a=0 or c=d=0, but the latter case cannot give a 2-cycle as $e_7 \notin \operatorname{im} X$. Then a=0 and we obtain a 2-cycle

$$\left\{X\left(e_6 - \frac{s}{d}e_7\right), e_6 - \frac{s}{d}e_7\right\} = \left\{e_5, e_6 - \frac{s}{d}e_7\right\}.$$

We also obtain the equations $b \neq 0$, $d \neq 0$, and sc - bd = 0 from this. For the s-generalized eigenspace E_s , we need $a + sb \neq 0$ to obtain a 2-cycle, which can be taken as

$$\left\{ (X - sI) \left(e_2 + 2se_3 + 3s^2e_4 + \frac{s^3}{a + sb}e_5 + \frac{s^4}{a + sb}e_6 \right), \\ e_2 + 2se_3 + 3s^2e_4 + \frac{s^3}{a + sb}e_5 + \frac{s^4}{a + sb}e_6 \right\}$$

$$= \left\{ e_1 + se_2 + s^2e_3 + s^3e_4, e_2 + 2se_3 + 3s^2e_4 + \frac{s^3}{a + sb}e_5 + \frac{s^4}{a + sb}e_6 \right\}$$

The minimal polymonial is $X^3(X - sI)^2$, which when equated to 0 gives again the equation cs - bd = 0. Thus the defining equations are

$${a = 0, cs - bd = 0}.$$

When we take s = 0, we get the equations

$${a = 0, bd = 0}$$

which corresponds to two \mathbb{A}^2 's intersecting along an \mathbb{A}^1 . This is indeed an open subset of $\mathbb{P}^2 \cup_{\mathbb{P}_1} \mathbb{P}^2$, as required.

Example 7 (Continued...). The matrix X from the previous example defines (under MVy) the matrix

$$g = \begin{bmatrix} (t-s)t^3 \\ -bt & (t-s)t \\ -c & -d & t \end{bmatrix}$$

in $G(\mathcal{O})$. Indeed the various blocks of X are in a precise sense the companion matrices of the polynomial entries of q

In Gr the element q defines the lattice

$$gL_0 = \mathbb{C}[t]\langle (t-s)t^3e_1 - (a+bt)e_2 - ce_3, (t-s)te_2 - de_3, te_3 \rangle$$

and computing the matrix of the action of t on the quotient L_0/L in the basis

$$\{[e_1], [te_1], [t^2e_1], [t^3e_1], [e_2], [te_2], [e_3]\}$$

recovers X up to a transpose of course.

Now let's see what we get when we invert t and t-s respectively. First let's invert t by considering $L_2 = L \otimes \mathbb{C}[[t-s]]$.

$$L_2 = \mathbb{C}[t, t^{-1}] \langle (t-s)e_1 - \frac{a+bt}{t^3}e_2 - \frac{c}{t^3}e_3, (t-s)e_2 - \frac{d}{t}e_3, e_3 \rangle$$

so in L_0/L_2 we have

$$t[e_1] = s[e_1] + \frac{a+bt}{t^3}[e_2] + \frac{c}{t^3}[e_3]$$
 $t[e_2] = s[e_2] + \frac{d}{t}[e_3]$ $[e_3] = 0$

and

$$\left[t\big|_{L_0/L_2}\right]_{\{[e_1],[e_2]\}} = \begin{bmatrix} s \\ \frac{a+bt}{t^3} & s \end{bmatrix}$$

which upon subtracting sI gives a matrix having block type μ_2 and Jordan type $\lambda_2 = (2)$ assuming $\frac{a+bt}{t^3} \neq 0$. Next let's invert t-s by considering $L_1 = L \otimes \mathbb{C}[\![t]\!]$.

$$L_1 = \mathbb{C}[t, (t-s)^{-1}] \langle t^3 e_1 - \frac{a+bt}{t-s} e_2 - \frac{c}{t-s} e_3, te_2 - \frac{d}{t-s} e_3, te_3 \rangle$$
$$= \langle t^3 e_1 - \frac{a}{t-s} e_2 - \frac{b}{t-s} te_2 - \frac{c}{t-s} e_3, te_2 - \frac{d}{t-s} e_3, te_3 \rangle$$

so in L_0/L_1 we have

$$t[e_{1}] = [te_{1}]$$

$$t[te_{1}] = [t^{2}e_{1}]$$

$$t[t^{2}e_{1}] = \frac{a}{t-s}[e_{2}] + \frac{b}{t-s}t[e_{2}] + \frac{c}{t-s}[e_{3}]$$

$$= \frac{b}{t-s}\frac{d}{t-s}[e_{3}] + \frac{c}{t-s}[e_{3}]$$

$$= \frac{bd + (t-s)c}{(t-s)^{2}}[e_{3}]$$

$$= \frac{bd - sc}{(t-s)^{2}}[e_{3}] + \frac{c}{(t-s)^{2}}t[e_{3}] = 0$$

$$t[e_{2}] = \frac{d}{t-s}[e_{3}]$$

$$t[e_{3}] = 0$$

and

$$\left[t\big|_{L_0/L_1}\right]_{\{[e_1],[te_1],[t^2e_1],[e_2],[e_3]\}} = \begin{bmatrix} 0 & & & \\ 1 & 0 & & \\ 0 & 1 & 0 & \\ & 0 & 0 & \\ & & 0 & \frac{d}{t-s} & 0 \end{bmatrix}$$

taking transpose

$$\begin{bmatrix} 0 & 1 & & & & \\ & 0 & 1 & & & \\ & & 0 & & & \\ & & & 0 & \frac{d}{t-s} \\ & & & & 0 \end{bmatrix}$$

which has block type μ_1 and Jordan type $\lambda_1 = (3,2)$ assuming $d \neq 0$.

I have used the relations Roger found (and I checked) a = 0 and cs - bd = 0in the calculations above.

To sum up, the pair of matrices above should contain the same information as the matrix from the previous example

$$\begin{bmatrix} 0 & 1 & & & & & \\ & 0 & 1 & & & & \\ & & 0 & 1 & & & \\ & & & s & b & c \\ & & & 0 & 1 & 0 \\ & & & 0 & s & d \\ & & & & 0 \end{bmatrix} \Leftrightarrow \left(\begin{bmatrix} 0 & 1 & & & & \\ & 0 & 1 & & & \\ & & 0 & 1 & & \\ & & & 0 & \frac{d}{t-s} & \\ & & & & 0 \end{bmatrix}, \begin{bmatrix} s & \frac{b}{t^2} \\ & s \end{bmatrix} \right)$$

Wish. Given L in $\mathcal{G}r_n^{\mathrm{BD}}$ define a map to T_μ just like MVy by taking $[t\big|_{L_0/L}]$ and use the fact that $[t\big|_{L_0/L_i}]$ for i=1,2 are companion matrices of the right type, piece together two MVy isomorphisms to make a BD MVy iso.

Equivalent linear algebra question(?): If $p(t, t - s) = p_1(t)p_2(t - s)$ then how are $C(p_1)$, $C(p_2)$, and C(p) related?

10 Non simple root weights

Example 8 (Anne). Let $G = \mathbf{SL}_3$ and $\underline{\mathbf{i}} = 121$. Take $n^1_{\bullet} = (1, 0, 0)$, and $n^2_{\bullet} = (1, 0, 1)$ or (0, 1, 0). So

$$\mu_1 = (2, 2, 1)$$
 $\mu_2 = (1, 1, 1)$ $\mu = (3, 3, 2)$
 $\lambda_1 = (3, 1, 1)$ $\lambda_2 = (2, 1, 0)$ $\lambda = (5, 2, 1)$

Note

Anne: We should show that order does not matter; i.e. swapping indices on λ 's and μ 's produces the same result.

 $\mathbb{T}_{\mu_1,\mu_2}^+\cap\mathbb{O}_{\lambda_1,\lambda_2}$ is made up of elements of the form

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & s & A_0 & A_1 & A_2 & A_3 & A_4 \\ \hline 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & s & A_5 & A_6 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & s \end{bmatrix}$$

As usual, denote by E_e the generalized e-eigenspace of A. $A|_{\mathbb{C}^3 \cap E_0}$ should have Jordan type (2). The obvious 2-cycle is generated by e_2 : $\{e_2, Ae_2\}$. $A|_{\mathbb{C}^3 \cap E_s}$ should have Jordan type (1). We take $e_1 + se_2 + s^2e_3 \in \operatorname{Ker}(A - s)$. Next $A|_{\mathbb{C}^6 \cap E_0}$ should have Jordan type (3, 1) while $A|_{\mathbb{C}^6 \cap E_s}$ will have Jordan type (2) or (1, 1). Anne: This example breaks. Why? How should we choose weights?

Take 2: Let's try different weights.

$$\mu_1 = (1, 1, 0)$$
 $\lambda_1 = (2, 0, 0)$
 $\mu_2 = (1, 1, 1)$ $\lambda_2 = (2, 1, 0)$
 $\mu = (2, 2, 1)$ $\lambda = (4, 1, 0)$

and

$$\tau(1,0,0) = \boxed{1 \hspace{.1cm} 2} \hspace{.1cm} \tau(1,0,1) = \boxed{1 \hspace{.1cm} 2} \hspace{.1cm} \tau(0,1,0) = \boxed{1 \hspace{.1cm} 3}$$

Then

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & s & A_0 & A_1 & A_2 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & s & A_3 \\ \hline 0 & 0 & 0 & 0 & s \end{bmatrix}$$

We have $E_0 \cap \mathbb{C}^2 = \operatorname{Span}(e_1)$, $E_s \cap \mathbb{C}^2 = \operatorname{Span}(e_1 + se_2)$. Next $E_0 \cap \mathbb{C}^4$ is spanned by a 2-cycle generated by $-\frac{A_0}{s}e_2 + e_3$ and $E_s \cap \mathbb{C}^4$ is spanned by a 2-cycle generated by

$$\frac{s}{A_1 + \frac{A_0}{s}} e_4 + \frac{1}{A_1 + \frac{A_0}{s}} e_3 - \frac{1}{s} e_1$$

or the additional 1-cycle $e_4 - \frac{A_1}{A_0} e_3$ assuming $A_0 + sA_1 = 0$. Finally E_s is spanned by an additional 1-cycle

$$e_5 - \frac{A_2}{A_1 + \frac{A_0}{s}} e_4 + \frac{1}{s} \frac{A_2}{A_1 + \frac{A_0}{s}} e_3$$

assuming $A_3 = 0$. Or the two 1-cycles are extended to a 2-cycle and a 1-cycle, the 2-cycle generated by $-\frac{1}{s}e_1 + \frac{s}{A_2}e_5$. This gives us

$$\boxed{1 \ 2} * \boxed{1 \ 2} = (A_3) \qquad \boxed{1 \ 2} * \boxed{1 \ 3} = (A_0 + sA_1) \to (A_0)$$

Does it agree with what is expected on the module/cluster side?

$$S_1 * (1 \rightarrow 2) = S_1 \oplus (1 \rightarrow 2)$$
 $S_1 * (1 \leftarrow 2) = S_1 \oplus (1 \leftarrow 2)$

The MV cycle of $\boxed{1\ 2}$ is a \mathbb{P}^1 : via MVy it has an open subset comprised of matrices

$$\begin{bmatrix} 0 & A_0 \\ 0 & 0 \end{bmatrix} : A_0 \neq 0$$

The MV cycles of the other two tableaux are made up of matrices of the form

$$\begin{bmatrix} 0 & A_0 & A_1 \\ 0 & 0 & A_2 \\ 0 & 0 & 0 \end{bmatrix} : \begin{cases} A_0 \neq 0 \text{ and } A_2 = 0 & \tau = \boxed{1 & 2} \\ A_0 = 0 \text{ and } A_2 \neq 0 & \tau = \boxed{1 & 3} \\ A_0 = 0 \text{ and } A_2 \neq 0 & \tau = \boxed{2} \end{cases}$$

both \mathbb{C}^2 's. Anne: How do the coordinates relate?

Example 9 (Roger). Let

$$\lambda_1 = (2, 0, 0, 0)$$
 $\mu_1 = (1, 1, 0, 0)$
 $\lambda_2 = (2, 2, 1, 0)$ $\mu_2 = (3, 2, 1, 1)$

so $\lambda_1 - \mu_1 = \alpha_1$ and $\lambda_2 - \mu_2 = \alpha_2 + \alpha_3$. We have the following young tableaux:

$$\tau_1 = \boxed{1 \hspace{0.1cm} 2} \hspace{0.1cm} \quad \tau_2 = \boxed{\begin{array}{c|c} 1 \hspace{0.1cm} 1} \\ 2 \hspace{0.1cm} 3 \end{array}} \hspace{0.1cm} \quad \tau_2' = \boxed{\begin{array}{c|c} 1 \hspace{0.1cm} 1} \\ 2 \hspace{0.1cm} 4 \end{array}}$$

where τ_1 corresponds to the module S_1 , τ_2 corresponds to the module $2 \to 3$, and τ_2' corresponds to the module $2 \leftarrow 3$.

The matrix we are considering is

$$X = \begin{bmatrix} 0 & 1 & & & & \\ & 0 & 1 & & & \\ & -s^2 & 2s & a & b & c & d \\ & & & 0 & 1 & & \\ & & & s & e & f \\ & & & & s & g \\ & & & & s \end{bmatrix}$$

such that dim $E_0 = 2$, dim ker X = 1, dim $E_s = 5$, and dim ker (X - sI) = 3 where E_0 and E_s are the 0- and s-generalized eigenspaces.

We see that the two-cycle in E_0 is

$$\left\{ X\left(e_2 + \frac{s^2}{a}e_4\right), e_2 + \frac{s^2}{a}e_4 \right\} = \left\{e_1, e_2 + \frac{s^2}{a}e_4\right\}.$$

As τ_2 and τ_2' both share $\boxed{\frac{1}{2}}$, we can find a 2-cycle from just the upper-left 3×3 block, and an additional vector in $\ker(X-sI)$ from the upper-left 5×5 -submatrix. The 2-cycle from the 3×3 block is

$$\left\{e_1 + se_2 + s^2e_3, -\frac{2}{s}e_1 - e_2\right\}.$$

The additional vector in ker(X - sI) is $e_4 + se_5$ and this requires a + sb = 0.

Now consider the case that the young diagram we are working with is τ_2 . Then we have $e_4 + se_5 + x(e_1 + se_2 + s^2e_3)$ part of a 2-cycle that can be found by looking at the upper-left 6×6 -submatrix. We find that the 2-cycle is

$$\left\{e_4 + se_5 + x(e_1 + se_2 + s^2e_3), -\frac{2x}{s}e_1 - xe_2 - \frac{1}{s}e_4 + \frac{s}{e}e_6\right\}$$

and this requires that $ae - s^2c = 0$.

The last vector in ker(X - sI) comes from the entire X - sI and we see it is $-fe_6 + ee_7$, which requires g = 0 and ed - cf = 0.

For the case τ'_2 , we start with find the third vector in $\ker(X - sI)$ from the upper-left 6×6 -submatrix. We see that it is e_6 , which requires c = 0 and e = 0.

For the remaining 2-cycle, we want it to end with $x(e_1 + se_2 + s^2e_3) + (e_4 + se_5) + ye_6$ so our 2-cycle is

$$\left\{x(e_1 + se_2 + s^2e_3) + (e_4 + se_5) + ye_6, -\frac{2x}{s}e_1 - xe_2 - \frac{1}{s}e_4 + \frac{s}{f}e_7\right\}$$

which requires $af - ds^2 = 0$ and fy - sg = 0. As y is free, the last equation is not really a restriction on f and g.

From the minimal polynomial, we have $X^2(X-sI)^2=0$ which gives us the equations

$$a + sb = cs + eb = bf + cq + ds = esq = 0.$$

Taking $s \to 0$, we have the following equations for our two cases of τ_2 and τ_2' :

$$\begin{array}{c|ccc} \tau_2 & \tau_2' \\ \hline a = 0 & a = 0 \\ g = 0 & c = 0 \\ eb = 0 & e = 0 \\ bf = 0 & bf = 0 \\ ed - cf = 0 & \end{array}$$

For the τ_2 case, the coordinate ring is

$$\frac{\mathbb{C}[a,b,c,d,e,f,g]}{\langle a,g,eb,bf,ed-cf\rangle}\cong\frac{\mathbb{C}[b,c,d,e,f]}{\langle eb,bf,ed-cf\rangle}=\frac{\mathbb{C}[b,c,d,e,f]}{\langle e,f\rangle\cap\langle b,ed-cf\rangle}$$

Hence the associated algebraic set is reducible with two irreducible components. The component corresponding to the ideal $\langle e, f \rangle$ is \mathbb{A}^3 , which corresponds to \mathbb{P}^3 , while the ideal $\langle b, ed-cf \rangle$ corresponds to the toric variety whose toric polytope is a square-based pyramid.

As τ_2 corresponds to the module $2 \to 3$, the irreducible components should correspond to the modules $P_1 = 1 \to 2 \to 3$ and $1 \leftarrow 2 \to 3$. Indeed, the MV cycle corresponding to P_1 is the Grassmannian $Gr(1,4) \cong \mathbb{P}^3$ and for $1 \leftarrow 2 \to 3$, we do get a toric variety with polytope the square-based pyramid.

However for the τ_2' case, the coordinate ring is

$$\frac{\mathbb{C}[a,b,c,d,e,f,g]}{\langle a,c,e,df\rangle}\cong\frac{\mathbb{C}[b,d,f,g]}{\langle df\rangle}$$

which corresponds to $\mathbb{A}^3 \cup \mathbb{A}^3$. Since τ_2' corresponds to the module $2 \leftarrow 3$, we expect two irreducible components corresponding to the modules $P_3 = 1 \leftarrow 2 \leftarrow 3$ and $1 \rightarrow 2 \leftarrow 3$. P_3 corresponds to the variety $Gr(3,4) \cong \mathbb{P}^3$ and $1 \rightarrow 2 \leftarrow 3$ also corresponds to a toric variety whose polytope is a square-based pyramid (?).

Example 10 (Above example redone). In $\mathbb{C}[A_0..A_6]$ where

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & -s^2 & 2s & A_0 & A_1 & A_2 & A_3 \\ \hline 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & s & A_4 & A_5 \\ \hline 0 & 0 & 0 & 0 & 0 & s & A_6 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & s \end{bmatrix}$$

we have

$$\begin{array}{c|c}
\hline 1 & 1 \\
\hline 2 & 3 \\
\hline 4
\end{array} = (A_6, A_2A_5 - A_3A_4, A_1A_4 + A_2s, A_1s + A_0) \\
= (A_6, A_2A_5 - A_3A_4, A_1A_4, A_0) \text{ at } s = 0 \\
= (A_0, A_4, A_5, A_6) \sqcup (A_0, A_1, A_6, A_2A_5 - A_3A_4) \sqcup (A_0, A_2, A_4, A_6)
\end{array}$$

while

$$\begin{array}{c|c}
\hline
1 & 1 \\
\hline
2 & 4 \\
\hline
3
\end{array} = (sA_0A_5 + (1+s^2)A_1A_5 + sA_3, A_2, A_4, A_1s + A_0) \\
= (A_1A_5, A_2, A_4, A_0) \text{ at } s = 0 \\
= (A_0, A_2, A_4, A_5) \sqcup (A_0, A_1, A_2, A_4)
\end{array}$$

Cycles are

$$\frac{A_0}{s^2}e_2 + e_4 \xrightarrow{A} e_1$$

and, in the $\boxed{\frac{1}{2} \ket{1}}$ case,

$$e_2 + 2se_3 \xrightarrow{A-s} e_1 + se_2 + s^2 e_3$$
$$(sA_4e_4 + (1+s^2)A_4e_5 + se_6)/(sA_4) \xrightarrow{A-s} (e_4 + se_5)/s$$

while in the $\begin{bmatrix} 1 & 1 \\ 2 & 1 \end{bmatrix}$ case,

$$e_6 \xrightarrow{A-s} 0$$
 $e_4 + (1/s + s)e_5 + (1/A_5)e_7 \xrightarrow{A-s} (1/s)e_4 + e_5 + *e_6$