# Examples Compendium

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Last edit: approx. January 3, 2021

### Disjoint, non-dominant $\mu$

Example 1.  $\lambda_1 = (1,0,0), \ \lambda_2 = (1,1,0), \ \mu_1 = (0,1,0), \ \mu_2 = (1,0,1).$  Joel:  $\mu = \mu_1 + \mu_2$  determines the blocks we have on the RHS of the BD MVy isomorphism.

$$\begin{bmatrix}
s & A_0 & A_1 \\
0 & 0 & A_2 \\
0 & 0 & s
\end{bmatrix}$$

#### Some multiplicity

Example 2 (Joel's exercise). It would be good to do an example where we will see some multiplicity in the fusion product. I think that the simplest example would be the fusion product of the MV cycles for  $\mathbf{SL}_3$  of weights  $2\alpha_1$  and  $2\alpha_2$ . Following the notation from the mvbasis paper, this would correspond to the following multiplication:

$$x^2y^2 = (xy - z)^2 + 2(xy - z)z + z^2$$
.

For this example, I think we need  $\lambda_1=(2,0,0),\ \lambda_2=(2,2,0),\ \mu_1=(0,2,0),$   $\mu_2=(2,0,2).$  Then

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ -s^2 & 2s & A_0 & A_1 & A_2 & A_3 \\ \hline 0 & 0 & 0 & 1 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & A_4 & A_5 \\ \hline 0 & 0 & 0 & 0 & 0 & 1 \\ \hline 0 & 0 & 0 & 0 & -s^2 & 2s \end{bmatrix}$$

Let's also try

$$\lambda_2 = (4,0,0)$$
  $\lambda_1 = (4,4,0)$   $\lambda = (8,4,0)$   
 $\mu_2 = (2,2,0)$   $\mu_1 = (4,2,2)$   $\mu = (6,4,2)$ 

Then

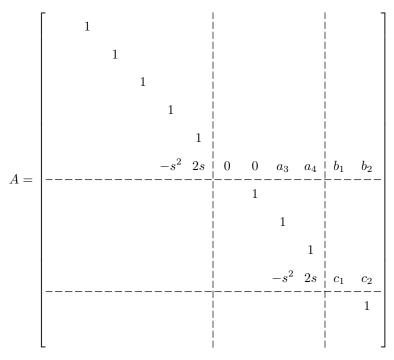
Note that there is only one SSYT of shape  $\lambda_i$  and weight  $\mu_i$ 

$$\tau_2 = \boxed{1 \ | \ 1 \ | \ 2 \ | \ 2} \qquad \tau_1 = \boxed{1 \ | \ 1 \ | \ 1 \ | \ 1} \ 2 \ | \ 3 \ | \ 3}$$

Note also that

$$t^{4}(t-s)^{2} = t^{4}(t^{2} - 2st + s^{2}) = t^{6} - 2st^{5} + s^{2}t^{4}$$
$$t^{2}(t-s)^{2} = t^{4} - 2st^{3} + s^{2}t^{2}$$

Elements of  $\mathbb{T}_{\mu_1,\mu_2}^+$  will take the form



The tableau tells us for each  $1 \le i \le 12$ 

Jordan type of 
$$A\big|_{\operatorname{Span}(e_1,\dots,e_i)\cap E_0}$$
 is shape of  $\tau_1\big|_{\operatorname{first}\ i\ \operatorname{boxes}}$ 

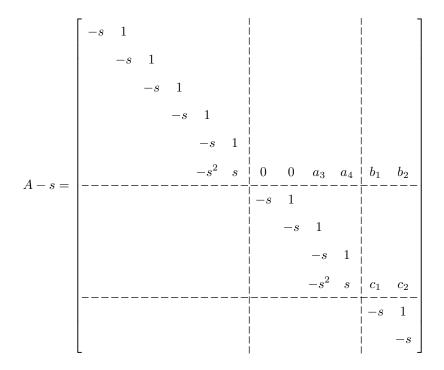
So take i = 10. Then A restricted to  $\mathbb{C}^{10} \cap E_0$  should have Jordan type (4,2). Anne: How to do it box by box? s columns somehow correspond to  $\tau_2$  boxes. Therefore  $a_1 = 0$ . The 4-cycle is obvious. For the 2-cycle we require  $a_2 = 0$ .

$$e_1 \leftarrow e_2 \leftarrow e_3 \leftarrow e_4$$
$$e_7 \leftarrow e_8$$

Now looking at all of A we have continue our 2-cycle to a 4-cycle. Roger found

$$e_{10} - \left(\frac{2s}{c_1} + \frac{s^2c_2}{c_1^2}\right)e_{11} + \frac{s^2}{c_1}e_{12}$$

This requires  $c_1^2 a_4 + c_1 b_2 s^2 - 2sc_1 b_1 - s^2 c_2 = 0$  and  $a_3 c_1 + s^2 b_1 = 0$ . Now looking for the s-eigenspace, we expect  $A - s |_{\mathbb{C}^6 \cap E_s}$  to have Jordan type 2. The kernel is spanned by  $e_1 + se_2 + s^2e_3 + s^3e_4 + s^4e_5 + s^5e_6$ . It is continued to a 2-cycle by/the 2-cycle is generated by  $-\frac{5}{s}e_1-4e_2-3se_3-2s^2e_4-s^3e_5$ . The 3-cycle is maybe  $(1/s^2,-4/s,-8,5s,3s^2,2s^3,-s^2/a_3,-s^3/a_3,-s^4/a_3,-s^5/a_3)$ padded with zeros.



## Simple root weights, things working

Example 3. Let

$$\mu_1 = (3, 1, 1)$$
  $\lambda_1 = (3, 2, 0)$   $\mu = (3, 3, 1)$   
 $\mu_2 = (0, 2, 0)$   $\lambda_2 = (2, 0, 0)$   $\lambda = (5, 2, 0)$ 

and consider the companion matrices of

$$X = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & d & e & f & g \\ \hline 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & -s^2 & 2s & k \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Example 4. Let

$$\lambda_1 = (3, 2, 0)$$
  $\mu_1 = (3, 1, 1)$   
 $\lambda_2 = (2, 0, 0)$   $\mu_2 = (1, 1, 0)$ 

so the first MV cycle  $Z_1 \cong \mathbb{P}^1$  has MV polytope Conv $\{0, \alpha_1\}$  and the second MV cycle  $Z_2 \cong \mathbb{P}^1$  has MV polytope Conv $\{0, \alpha_2\}$ . Their fusion product corresponds to two  $\mathbb{P}^2$ 's intersecting along a  $\mathbb{P}^1$ . That is, we have the fusion product

$$Z_1 * Z_2 = Z_+ + Z_-$$

where  $Z_{+} \cong Z_{-} \cong \mathbb{P}^{2}$ . We have

$$X = \begin{bmatrix} 0 & 1 & & & & & \\ & 0 & 1 & & & & \\ & & 0 & 1 & & & \\ & & & s & a & b & c \\ & & & & 0 & 1 & 0 \\ & & & & 0 & s & d \\ & & & & & 0 \end{bmatrix}$$

The 0-generalized eigenspace  $E_0$  of X is 5-dimensional, containing a 3-cycle and a 2-cycle. The 3-cycle is

$${X^2e_3, Xe_3, e_3} = {e_1, e_2, e_3}.$$

To obtain another vector in ker X, either a=0 or c=d=0, but the latter case cannot give a 2-cycle as  $e_7 \notin \operatorname{im} X$ . Then a=0 and we obtain a 2-cycle

$$\left\{X\left(e_6 - \frac{s}{d}e_7\right), e_6 - \frac{s}{d}e_7\right\} = \left\{e_5, e_6 - \frac{s}{d}e_7\right\}.$$

We also obtain the equations  $b \neq 0$ ,  $d \neq 0$ , and sc - bd = 0 from this.

For the s-generalized eigenspace  $E_s$ , we need  $a+sb\neq 0$  to obtain a 2-cycle, which can be taken as

$$\left\{ (X - sI) \left( e_2 + 2se_3 + 3s^2e_4 + \frac{s^3}{a + sb}e_5 + \frac{s^4}{a + sb}e_6 \right), \\ e_2 + 2se_3 + 3s^2e_4 + \frac{s^3}{a + sb}e_5 + \frac{s^4}{a + sb}e_6 \right\}$$

$$= \left\{ e_1 + se_2 + s^2e_3 + s^3e_4, e_2 + 2se_3 + 3s^2e_4 + \frac{s^3}{a + sb}e_5 + \frac{s^4}{a + sb}e_6 \right\}$$

The minimal polymonial is  $X^3(X - sI)^2$ , which when equated to 0 gives again the equation cs - bd = 0. Thus the defining equations are

$${a = 0, cs - bd = 0}.$$

When we take s = 0, we get the equations

$$\{a=0, bd=0\}$$

which corresponds to two  $\mathbb{A}^2$ 's intersecting along an  $\mathbb{A}^1$ . This is indeed an open subset of  $\mathbb{P}^2 \cup_{\mathbb{P}_1} \mathbb{P}^2$ , as required.

Example 5 (Continued...). The matrix X from the previous example defines (under MVy) the matrix

$$g = \begin{bmatrix} (t-s)t^3 \\ -bt & (t-s)t \\ -c & -d & t \end{bmatrix}$$

in  $G(\mathcal{O})$ . Indeed the various blocks of X are in a precise sense the companion matrices of the polynomial entries of g

In Gr the element g defines the lattice

$$gL_0 = \mathbb{C}[t]\langle (t-s)t^3e_1 - (a+bt)e_2 - ce_3, (t-s)te_2 - de_3, te_3 \rangle$$

and computing the matrix of the action of t on the quotient  $L_0/L$  in the basis

$$\{[e_1], [te_1], [t^2e_1], [t^3e_1], [e_2], [te_2], [e_3]\}$$

recovers X up to a transpose of course.

Now let's see what we get when we invert t and t-s respectively. First let's invert t by considering  $L_2 = L \otimes \mathbb{C}[t-s]$ .

$$L_2 = \mathbb{C}[t, t^{-1}] \langle (t-s)e_1 - \frac{a+bt}{t^3}e_2 - \frac{c}{t^3}e_3, (t-s)e_2 - \frac{d}{t}e_3, e_3 \rangle$$

so in  $L_0/L_2$  we have

$$t[e_1] = s[e_1] + \frac{a+bt}{t^3}[e_2] + \frac{c}{t^3}[e_3]$$
  $t[e_2] = s[e_2] + \frac{d}{t}[e_3]$   $[e_3] = 0$ 

and

$$\begin{bmatrix} t \big|_{L_0/L_2} \end{bmatrix}_{\{[e_1],[e_2]\}} = \begin{bmatrix} s \\ \frac{a+bt}{t^3} & s \end{bmatrix}$$

which upon subtracting sI gives a matrix having block type  $\mu_2$  and Jordan type which apon substacting of gives a matrix having state  $\lambda_2 = (2)$  assuming  $\frac{a+bt}{t^3} \neq 0$ . Next let's invert t-s by considering  $L_1 = L \otimes \mathbb{C}[\![t]\!]$ .

$$L_1 = \mathbb{C}[t, (t-s)^{-1}] \langle t^3 e_1 - \frac{a+bt}{t-s} e_2 - \frac{c}{t-s} e_3, te_2 - \frac{d}{t-s} e_3, te_3 \rangle$$
$$= \langle t^3 e_1 - \frac{a}{t-s} e_2 - \frac{b}{t-s} te_2 - \frac{c}{t-s} e_3, te_2 - \frac{d}{t-s} e_3, te_3 \rangle$$

so in  $L_0/L_1$  we have

$$t[e_1] = [te_1]$$

$$t[te_1] = [t^2e_1]$$

$$t[t^2e_1] = \frac{a}{t-s}[e_2] + \frac{b}{t-s}t[e_2] + \frac{c}{t-s}[e_3]$$

$$= \frac{b}{t-s}\frac{d}{t-s}[e_3] + \frac{c}{t-s}[e_3]$$

$$= \frac{bd + (t-s)c}{(t-s)^2}[e_3]$$

$$= \frac{bd - sc}{(t-s)^2}[e_3] + \frac{c}{(t-s)^2}t[e_3] = 0$$

$$t[e_2] = \frac{d}{t-s}[e_3]$$

$$t[e_3] = 0$$

and

$$\left[t\big|_{L_0/L_1}\right]_{\{[e_1],[te_1],[t^2e_1],[e_2],[e_3]\}} = \begin{bmatrix} 0 & & & \\ 1 & 0 & & \\ 0 & 1 & 0 & \\ & 0 & 0 & \\ & & 0 & \frac{d}{t-s} & 0 \end{bmatrix}$$

taking transpose

$$\begin{bmatrix} 0 & 1 & & & \\ & 0 & 1 & & \\ & & 0 & & \\ & & & 0 & \frac{d}{t-s} \\ & & & & 0 \end{bmatrix}$$

which has block type  $\mu_1$  and Jordan type  $\lambda_1 = (3,2)$  assuming  $d \neq 0$ .

I have used the relations Roger found (and I checked) a=0 and cs-bd=0 in the calculations above.

To sum up, the pair of matrices above should contain the same information as the matrix from the previous example

$$\begin{bmatrix} 0 & 1 & & & & & \\ & 0 & 1 & & & & \\ & & 0 & 1 & & \\ & & s & b & c \\ & & & 0 & 1 & 0 \\ & & & 0 & s & d \\ & & & & 0 \end{bmatrix} \Leftrightarrow \left( \begin{bmatrix} 0 & 1 & & & \\ & 0 & 1 & & \\ & & 0 & 1 & \\ & & & 0 & \frac{d}{t-s} \\ & & & & 0 \end{bmatrix}, \begin{bmatrix} s & \frac{b}{t^2} \\ s \end{bmatrix} \right)$$

**Wish.** Given L in  $\mathcal{G}r_n^{\mathrm{BD}}$  define a map to  $T_{\mu}$  just like MVy by taking  $[t|_{L_0/L}]$  and use the fact that  $[t|_{L_0/L_i}]$  for i=1,2 are companion matrices of the right type, piece together two MVy isomorphisms to make a BD MVy iso.

Equivalent linear algebra question (?): If  $p(t,t-s)=p_1(t)p_2(t-s)$  then how are  $C(p_1),\ C(p_2),$  and C(p) related?

#### Non simple root weights

Example 6 (Anne). Let  $G = \mathbf{SL}_3$  and  $\underline{\mathbf{i}} = 121$ . Take  $n_{\bullet}^1 = (1, 0, 0)$ , and  $n_{\bullet}^2 = (1, 0, 1)$  or (0, 1, 0). So

$$\mu_1 = (2, 2, 1)$$
  $\mu_2 = (1, 1, 1)$   $\mu = (3, 3, 2)$   
 $\lambda_1 = (3, 1, 1)$   $\lambda_2 = (2, 1, 0)$   $\lambda = (5, 2, 1)$ 

Note

Anne: We should show that order does not matter; i.e. swapping indices on  $\lambda$ 's and  $\mu$ 's produces the same result.

 $\mathbb{T}_{\mu_1,\mu_2}^+\cap\mathbb{O}_{\lambda_1,\lambda_2}$  is made up of elements of the form

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & s & A_0 & A_1 & A_2 & A_3 & A_4 \\ \hline 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & s & A_5 & A_6 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & s \end{bmatrix}$$

As usual, denote by  $E_e$  the generalized e-eigenspace of A.  $A|_{\mathbb{C}^3 \cap E_0}$  should have Jordan type (2). The obvious 2-cycle is generated by  $e_2$ :  $\{e_2, Ae_2\}$ .  $A|_{\mathbb{C}^3 \cap E_s}$  should have Jordan type (1). We take  $e_1 + se_2 + s^2e_3 \in \operatorname{Ker}(A - s)$ . Next  $A|_{\mathbb{C}^6 \cap E_0}$  should have Jordan type (3, 1) while  $A|_{\mathbb{C}^6 \cap E_s}$  will have Jordan type (2) or (1, 1). Anne: This example breaks. Why? How should we choose weights?

Take 2: Let's try different weights.

$$\mu_1 = (1, 1, 0) \quad \lambda_1 = (2, 0, 0)$$
  

$$\mu_2 = (1, 1, 1) \quad \lambda_2 = (2, 1, 0)$$
  

$$\mu = (2, 2, 1) \quad \lambda = (4, 1, 0)$$

and

$$\tau(1,0,0) = \boxed{1 \hspace{.1cm} 2} \hspace{.1cm} \tau(1,0,1) = \boxed{1 \hspace{.1cm} 2} \hspace{.1cm} \tau(0,1,0) = \boxed{1 \hspace{.1cm} 3}$$

Then

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & s & A_0 & A_1 & A_2 \\ \hline 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & s & A_3 \\ \hline 0 & 0 & 0 & 0 & s \end{bmatrix}$$

We have  $E_0 \cap \mathbb{C}^2 = \operatorname{Span}(e_1)$ ,  $E_s \cap \mathbb{C}^2 = \operatorname{Span}(e_1 + se_2)$ . Next  $E_0 \cap \mathbb{C}^4$  is spanned by a 2-cycle generated by  $-\frac{A_0}{s}e_2 + e_3$  and  $E_s \cap \mathbb{C}^4$  is spanned by a 2-cycle generated by

$$\frac{s}{A_1 + \frac{A_0}{s}}e_4 + \frac{1}{A_1 + \frac{A_0}{s}}e_3 - \frac{1}{s}e_1$$

or the additional 1-cycle  $e_4 - \frac{A_1}{A_0} e_3$  assuming  $A_0 + sA_1 = 0$ . Finally  $E_s$  is spanned by an additional 1-cycle

$$e_5 - \frac{A_2}{A_1 + \frac{A_0}{s}} e_4 + \frac{1}{s} \frac{A_2}{A_1 + \frac{A_0}{s}} e_3$$

assuming  $A_3=0$ . Or the two 1-cycles are extended to a 2-cycle and a 1-cycle, the 2-cycle generated by  $e_1+\frac{s}{A_2}e_5$  and again assuming  $A_3=0$  in addition to  $A_0+sA_1=0$ . This gives us

$$\boxed{1 \ 2} * \boxed{1 \ 2} = (A_3) \qquad \boxed{1 \ 2} * \boxed{1 \ 3} = (A_0 + sA_1, A_3) \to (A_0, A_3)$$

Does it agree with what is expected on the module/cluster side?

$$S_1 * (1 \rightarrow 2) = S_1 * (1 \leftarrow 2) =$$

Example 7 (Roger). Let

$$\lambda_1 = (2, 0, 0, 0)$$
  $\mu_1 = (1, 1, 0, 0)$   
 $\lambda_2 = (2, 2, 1, 0)$   $\mu_2 = (3, 2, 1, 1)$ 

so  $\lambda_1 - \mu_1 = \alpha_1$  and  $\lambda_2 - \mu_2 = \alpha_2 + \alpha_3$ . We have the following young tableaux:

$$\tau_1 = \boxed{1 \hspace{0.1cm} 2} \hspace{0.1cm} \quad \tau_2 = \boxed{\begin{array}{c|c} 1 \hspace{0.1cm} 1 \\ 2 \hspace{0.1cm} 3 \end{array}} \hspace{0.1cm} \quad \tau_2' = \boxed{\begin{array}{c|c} 1 \hspace{0.1cm} 1 \\ 2 \hspace{0.1cm} 4 \end{array}}$$

where  $\tau_1$  corresponds to the module  $S_1$ ,  $\tau_2$  corresponds to the module  $2 \to 3$ , and  $\tau_2'$  corresponds to the module  $2 \leftarrow 3$ .

The matrix we are considering is

$$X = \begin{bmatrix} 0 & 1 & & & & \\ & 0 & 1 & & & \\ & -s^2 & 2s & a & b & c & d \\ & & & 0 & 1 & & \\ & & & s & e & f \\ & & & & s & g \\ & & & & s \end{bmatrix}$$

such that dim  $E_0=2$ , dim ker X=1, dim  $E_s=5$ , and dim ker (X-sI)=3 where  $E_0$  and  $E_s$  are the 0- and s-generalized eigenspaces.

We see that the two-cycle in  $E_0$  is

$$\left\{ X\left(e_2 + \frac{s^2}{a}e_4\right), e_2 + \frac{s^2}{a}e_4 \right\} = \left\{e_1, e_2 + \frac{s^2}{a}e_4\right\}.$$

As  $\tau_2$  and  $\tau_2'$  both share  $\boxed{\frac{1}{2}}$ , we can find a 2-cycle from just the upper-left  $3\times 3$  block, and an additional vector in  $\ker(X-sI)$  from the upper-left  $5\times 5$ -submatrix. The 2-cycle from the  $3\times 3$  block is

$$\left\{e_1 + se_2 + s^2e_3, -\frac{2}{s}e_1 - e_2\right\}.$$

The additional vector in ker(X - sI) is  $e_4 + se_5$  and this requires a + sb = 0.

Now consider the case that the young diagram we are working with is  $\tau_2$ . Then we have  $e_4 + se_5$  part of a 2-cycle that can be found by looking at the upper-left  $6 \times 6$ -submatrix. We find that the 2-cycle is

$$\left\{e_4 + se_5, -\frac{1}{s}e_4 + \frac{s}{e}e_6\right\}$$

and this requires that  $ae - s^2c = 0$ .

The last vector in ker(X - sI) comes from the entire X - sI and we see it is  $-fe_6 + ee_7$ , which requires g = 0 and ed - cf = 0.

For the case  $\tau'_2$ , we start with find the third vector in  $\ker(X - sI)$  from the upper-left  $6 \times 6$ -submatrix. We see that it is  $e_6$ , which requires c = 0 and e = 0.

For the remaining 2-cycle, we note that  $e_4 + se_5 \notin \operatorname{col}(X - sI)$  but  $e_6 \in \operatorname{col}(X - sI)$  so our 2-cycle is

$$\left\{e_6, \frac{1}{g}e_7\right\}$$

which requires d = 0 and f = 0.

From the minimal polynomial, we have  $X^2(X-sI)^2=0$  which gives us the equations

$$a + sb = cs + eb = bf + cg + ds = esg = 0.$$

Taking  $s \to 0$ , we have the following equations for our two cases of  $\tau_2$  and  $\tau_2'$ :

$$\begin{array}{c|ccc} \tau_2 & \tau_2' \\ \hline a = 0 & a = 0 \\ g = 0 & c = 0 \\ eb = 0 & d = 0 \\ bf = 0 & e = 0 \\ ed - cf = 0 & f = 0 \\ \end{array}$$

For the  $\tau_2$  case, the coordinate ring is

$$\frac{\mathbb{C}[a,b,c,d,e,f,g]}{\langle a,g,eb,bf,ed-cf\rangle}\cong\frac{\mathbb{C}[b,c,d,e,f]}{\langle eb,bf,ed-cf\rangle}=\frac{\mathbb{C}[b,c,d,e,f]}{\langle e,f\rangle\cap\langle b,ed-cf\rangle}$$

Hence the associated algebraic set is reducible with two irreducible components. The component corresponding to the ideal  $\langle e, f \rangle$  is  $\mathbb{A}^3$ , which corresponds to  $\mathbb{P}^3$ , while the ideal  $\langle b, ed-cf \rangle$  corresponds to the toric variety whose toric polytope is a square-based pyramid.

As  $\tau_2$  corresponds to the module  $2 \to 3$ , the irreducible components should correspond to the modules  $P_1 = 1 \to 2 \to 3$  and  $1 \leftarrow 2 \to 3$ . Indeed, the MV cycle corresponding to  $P_1$  is the Grassmannian  $Gr(1,4) \cong \mathbb{P}^3$  and for  $1 \leftarrow 2 \to 3$ , we do get a toric variety with polytope the square-based pyramid.

However for the  $\tau_2'$  case, the coordinate ring is

$$\frac{\mathbb{C}[a, b, c, d, e, f, g]}{\langle a, c, d, e, f \rangle} \cong \mathbb{C}[b, g]$$

which corresponds to  $\mathbb{A}^2$ . Since  $\tau_2'$  corresponds to the module  $2 \leftarrow 3$ , we expect two irreducible components corresponding to the modules  $P_3 = 1 \leftarrow 2 \leftarrow 3$  and  $1 \rightarrow 2 \leftarrow 3$ .  $P_3$  corresponds to the variety  $Gr(3,4) \cong \mathbb{P}^3$  and  $1 \rightarrow 2 \leftarrow 3$  also corresponds to a toric variety whose polytope is a square-based pyramid (?).