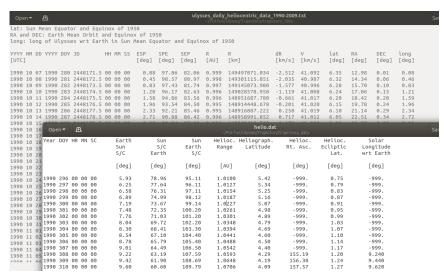
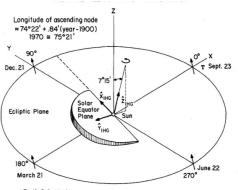
#### Data from the ULYSSES FINAL ARCHIVE



#### **Coordinate Systems**

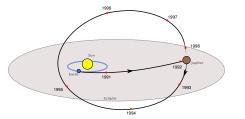
There seem to be two options for coordinate systems:

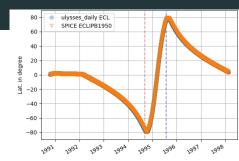
- · Heliocentric Inertial (HCI) system
- Heliocentric Aries Ecliptic (HAE) system

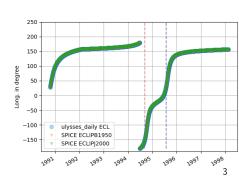


≠ Earth Spin Vector

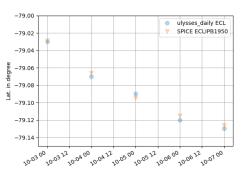
## Ulysses' 1st Orbit

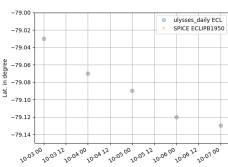




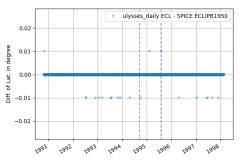


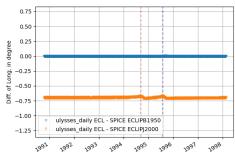
#### Ecliptic System - Latitude





### **Ecliptic System – Differences**

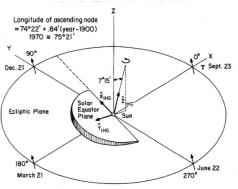




#### **Equatorial System**

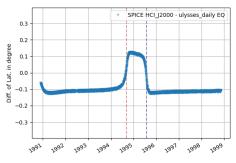
There seem to be two options for coordinate systems:

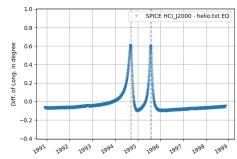
- · Heliocentric Inertial (HCI) system
- Heliocentric Aries Ecliptic (HAE) system



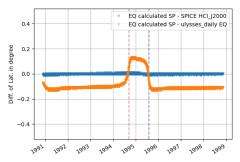
≠ Earth Spin Vector

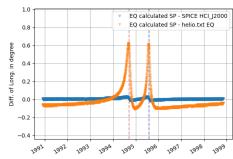
### **Equatorial System**



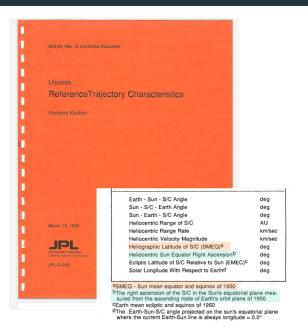


## Equatorial System – calculated

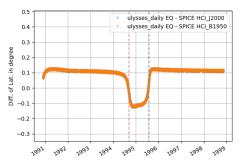


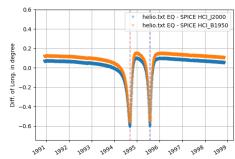


#### **Equatorial System**

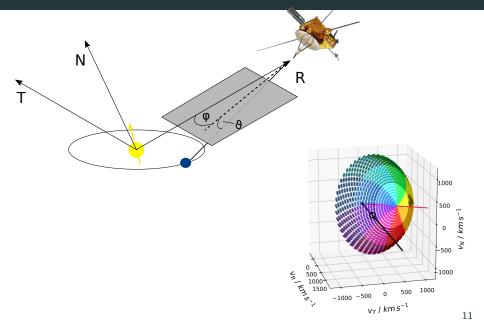


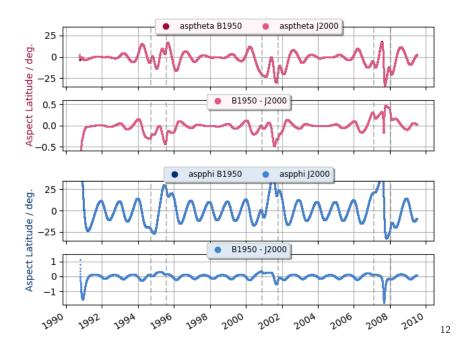
#### Equatorial System - B1950 vs. J2000





# Aspect Angle





#### SPICE Reference Frame Kernel

Heliocentric Inertial (HCI) Frame

Definition of the Heliocentric Inertial frame:



#### Two-Vector Frame Concepts - 3

Navigation and Ancillary Information Facility

- · Secondary Vector
  - A specified positive or negative axis of the two-vector frame is aligned with the component of the secondary vector orthogonal to the primary vector.
    - » The frame kernel creator associates with this vector one of the axis designations (+X, -X, +Y, -Y, +Z, -Z), where the axis is orthogonal to that associated with the primary vector.

All vectors are geometric: no aberration corrections are used.

The solar rotation axis is the primary vector: the Z axis points in the solar north direction (IAU SUN frozen at J2000 epoch).

The ascending node on the ecliptic of J2000 of the IAU\_SUN equator forms the X axis. \*\*\* N.B this is accomplished by using the +Z axis of the ecliptic of J2000 as the secondary vector and HCI +Y as the secondary axis

The Y axis is Z cross X, completing the right-handed reference frame

#### \begindata

```
FRAME HCI
                               1810420
FRAME 1810420 NAME
                               'HCI'
FRAME 1810420 CLASS
FRAME 1810420 CLASS ID
                             = 1810420
FRAME 1810420 CENTER
FRAME 1810420 RELATIVE
                             = '.12000'
FRAME 1810420 DEF STYLE
                               'PARAMETERTZED'
FRAME 1810420 FAMILY
                             = 'TWO-VECTOR'
FRAME 1810420 FREEZE EPOCH
                             = |a2000-JAN-01/12:00:00
FRAME 1810420 PRI AXIS
FRAME 1810420 PRI VECTOR DEF = 'CONSTANT'
FRAME 1810420 PRI FRAME
                             = 'IAU SUN'
FRAME 1810420 PRI SPEC
                             = 'RECTANGULAR'
FRAME 1810420 PRI VECTOR
                             = (0, 0, 1)
FRAME 1810420 SEC AXIS
                             = 'Y'
FRAME 1810420 SEC VECTOR DEF = 'CONSTANT'
FRAME 1810420 SEC FRAME
                             = 'ECLIPJ2000'
FRAME 1810420 SEC SPEC
                             = 'RECTANGULAR'
FRAME 1810420 SEC VECTOR
                             = (0.0.1)
```