Breast Cancer Detection



GROUP NO. 3

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PROJECT GUIDE: DR. SATISHKUMAR CHAVAN

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Objectives

- To classify the tumors as Benign and Malignant tumors.
- To detect location of the tumour.
- To automate the process of detection of abnormal tissues.
- To evaluate the performance of various Deep Learning approaches for detection and segmentation of tumours

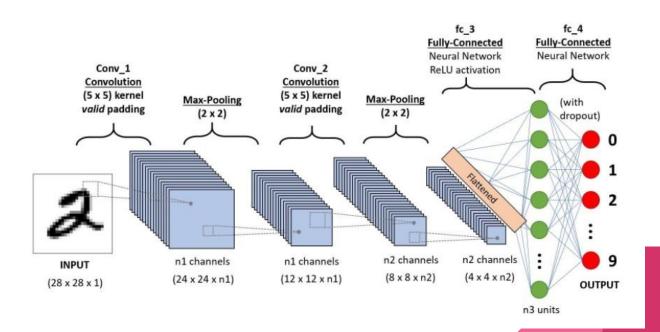
Outcomes

- Software tool which automatically detects cancerous tissues.
- Software will be able to identify location of tumour and detect volume of tumour.
- It will act an an assisting tool to radiologists to classify or choose the abnormal mammogram and prioritise based on level of concern.
- Learning how to write a Technical paper using LaTeX

Problem Statement

To develop an automated detection and segmentation of tumours using mammogram in Cranial-Caudal and Medial-lateral oblique (CC and MLO) views using Deep Learning Techniques

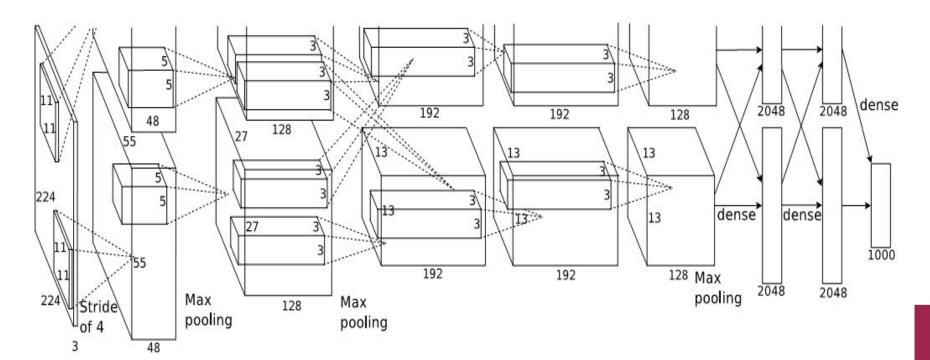
CNN



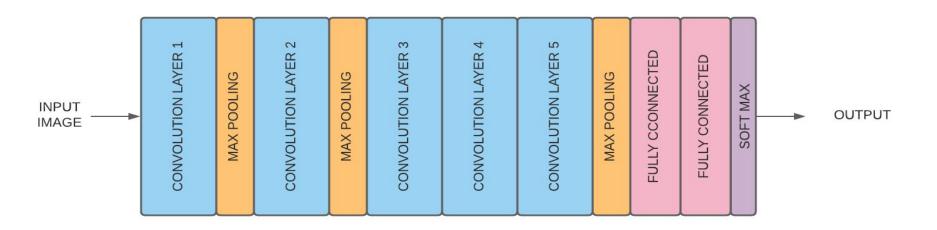
Training Using Alexnet

- 8 layers deep neural network
- A total of 60 million parameters
- 5 Convolutional layers and 3 Fully Connected (dense) layers
- Dataset consisting of 15 million images, over 22,000 categories with variable resolution images so scaled down to fixed resolution 256x256
- Why ReLu Non-linearity?

Architecture of Alexnet



Architecture



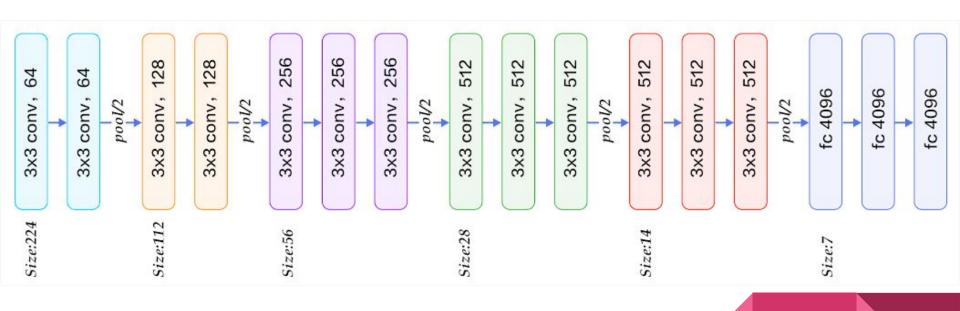
Results of Alexnet

```
+ Code + Text
                                                                                                        Editina
         steps per epoch=int(8000/32),
         epochs=15,
Q
         validation_data=test_set,
         validation steps=200,
Found 20000 images belonging to 2 classes.
        Found 5000 images belonging to 2 classes.
        Epoch 1/5
        /usr/local/lib/python3.6/dist-packages/keras_preprocessing/image/image_data_generator.py:720: UserWarning: This ImageDataGenerator specifies `featurewi
          warnings.warn('This ImageDataGenerator specifies '
        /usr/local/lib/python3.6/dist-packages/keras preprocessing/image/image data generator.py:728: UserWarning: This ImageDataGenerator specifies `featurewi
          warnings.warn('This ImageDataGenerator specifies '
        Epoch 2/5
        250/250 [============= ] - 106s 425ms/step - loss: 0.7112 - accuracy: 0.5010 - val loss: 0.6937 - val accuracy: 0.4994
        Epoch 3/5
        Epoch 4/5
        250/250 [============= ] - 108s 431ms/step - loss: 0.7147 - accuracy: 0.4934 - val loss: 0.6932 - val accuracy: 0.5081
        Epoch 5/5
        [ ] import os
        model_name = 'DogCat.h5'
        save_dir = 'pretrained_model' # pretrained_model # pred_model
        # Save model and weights
        if not os.path.isdir(save_dir):
           os.makedirs(save dir)
                                                                                         ^ □ Æ & ENG
```

Training using VGG-16

- VGGNet consists of 16 convolutional layers with only 3x3 kernels.
- **Input**: VGG takes in a 224x224 pixel RGB image.
- Convolutional Layers: The convolutional layers in VGG use a very small receptive field (3x3, the smallest possible size that still captures left/right and up/down).
- Fully-Connected Layers: VGG has three fully-connected layers: 4096 channels each and the last one has 1000 channels
- **Hidden Layers**: All of VGG's hidden layers use ReLU (a huge innovation from AlexNet that cut training time).

Architecture



Results of VGG-16

```
Epoch 1/10
100/100 [============ ] - 33s 333ms/step - loss: 0.6756 - acc: 0.6855 - val loss: 0.3504 - val acc: 0.8335
Epoch 2/10
100/100 [============= ] - 33s 332ms/step - loss: 0.4837 - acc: 0.7655 - val loss: 0.4827 - val acc: 0.7800
Epoch 3/10
100/100 [============] - 33s 328ms/step - loss: 0.4147 - acc: 0.8110 - val loss: 0.2349 - val acc: 0.8980
Epoch 4/10
100/100 [============= ] - 33s 330ms/step - loss: 0.4037 - acc: 0.8160 - val loss: 0.2329 - val acc: 0.9030
Epoch 5/10
Epoch 6/10
100/100 [============ ] - 33s 326ms/step - loss: 0.3732 - acc: 0.8255 - val loss: 0.2103 - val acc: 0.9070
Epoch 7/10
100/100 [============= ] - 33s 332ms/step - loss: 0.3564 - acc: 0.8420 - val loss: 0.2249 - val acc: 0.9030
Epoch 8/10
Epoch 9/10
100/100 [============ ] - 33s 329ms/step - loss: 0.3583 - acc: 0.8440 - val loss: 0.2276 - val acc: 0.9015
Epoch 10/10
100/100 [============ ] - 33s 331ms/step - loss: 0.3418 - acc: 0.8475 - val loss: 0.2320 - val acc: 0.9045
```

Training using GoogleNet

- 22 layers deep.
- The architecture was designed to keep computational efficiency in mind. The idea behind that the architecture can be run on individual devices even with low computational resources.
- Uses many different methods such as 1x1 convolution and global average pooling that enables it to create a deeper architecture.

Architecture

type	patch size/ stride	output size	depth	#1×1	#3×3 reduce	#3×3	#5×5 reduce	#5×5	pool proj	params	ops
convolution	7×7/2	112×112×64	I							2.7K	34M
max pool	3×3/2	56×56×64	0								
convolution	3×3/1	56×56×192	2		64	192				112K	360M
max pool	3×3/2	28×28×192	0								
inception (3a)		28×28×256	2	64	96	128	16	32	32	159K	128M
inception (3b)		28×28×480	2	128	128	192	32	96	64	380K	304M
max pool	3×3/2	14×14×480	0								
inception (4a)		14×14×512	2	192	96	208	16	48	64	364K	73M
inception (4b)		14×14×512	2	160	112	224	24	64	64	437K	88M
inception (4c)		14×14×512	2	128	128	256	24	64	64	463K	100M
inception (4d)		14×14×528	2	112	144	288	32	64	64	580K	119M
inception (4e)		14×14×832	2	256	160	320	32	128	128	840K	170M
max pool	3×3/2	7×7×832	0						Ī.		
inception (5a)		7×7×832	2	256	160	320	32	128	128	1072K	54M
inception (5b)		7×7×1024	2	384	192	384	48	128	128	1388K	71M
avg pool	7×7/1	1×1×1024	0								
dropout (40%)		1×1×1024	0								
linear		1×1×1000	1							1000K	1M
softmax		1×1×1000	0								

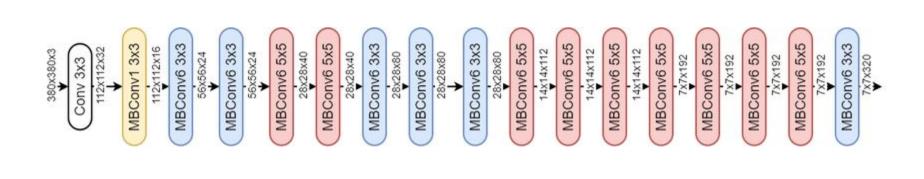
Results of GoogleNet

```
Epoch 1/10
Epoch 2/10
Epoch 3/10
Epoch 4/10
Epoch 5/10
Epoch 6/10
Epoch 7/10
Epoch 8/10
Epoch 9/10
Epoch 10/10
```

EfficientNet

- Alexnet → VGG-16 → Googlenet.
- Process of scaling up CNNs is not well understood; many ways of doing this, mostly arbitrarily chosen.
- Three types of scaling.- width,depth,resolution.
- Efficientnet uses compound scaling.
- Saturation happens if only one type of scaling is done.

EfficientNet



EfficientNet

```
Epoch 1/10
Epoch 2/10
Epoch 3/10
Epoch 4/10
Epoch 5/10
Epoch 6/10
Epoch 7/10
Epoch 8/10
Epoch 9/10
Epoch 10/10
```

Comparing The Four Models

Name of Model	Number of Layers	Accuracy (%)	Validation Accuracy (%)	Loss (%)	Validation Loss (%)
Alex Net	8	49.93	49.69	71.29	69.49
VGG-16	16	84.75	90.45	34.18	23.2
Efficient Net	17	92.9	97.9	32.75	41.17
Google Net	22	91.45	96.2	31.36	13.2

Plan For Remaining Work

- Working on the MIAS dataset with the basic CNN and then proceeding with other models also.
- Trying to increase the accuracy and lower the losses for the MIAS dataset.

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