

The Macroeconomy as a Random Forest

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Final Destination

Modeling *flexibly* macro relationships without assuming what flexible means first. Take something fundamental: a Phillips' curve.

$$u_t^{\text{gap}} \rightarrow \pi_t$$

The statistical characterization of " \rightarrow " has forecasting, policy and theoretical (!) implications. Better get it right.

One way out is getting " \rightarrow " from off-the-shelf nonparametric Machine Learning (ML) techniques. **But:**

- Likely too flexible and wildly inefficient for the short *time series* we have.
- No obvious parameter(s) to look at — interpretation is fuzzy.

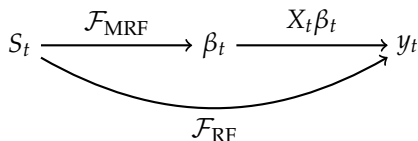
Another is assuming $\pi_t = \beta_t u_t^{\text{gap}} + \text{stuff}_t$. **But:**

- Rigid
- In-sample fit notoriously don't translate in out-of-sample gains.

Solution: *Generalized Time-Varying Parameters* via Random Forests.

(Machine) Learning β_t 's

- I propose *Macroeconomic Random Forests* (MRF): fix the linear part X_t and let the coefficients β_t vary through time according to a Random Forest.

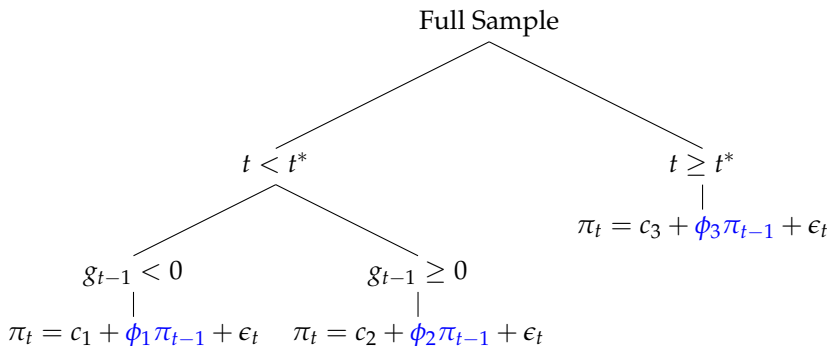


- The core "mechanical" modification wrt plain RF is fitting an ensemble of trees which have a linear model in each leaf rather than a constant.
- MRF is nice "meeting halfway"
 - ⇒ Brings macro closer to ML by squashing many popular nonlinearities (structural change/breaks, thresholds, regime-switching, etc.) into an arbitrarily large S_t , handled easily by RF.
 - ⇒ The core output are β_t 's, *Generalized Time-Varying Parameters* (GTVPs).
 - ⇐ Brings ML closer to macro by adapting RF to the reality of economic time series. $\text{MRF} \succ \text{RF}$ if the linear part is pervasive (like in a (V)AR).

Generalized Time-Varying Parameters

Why Trees Make Sense (in Macro/Finance)

- Let π_t be inflation at time t .
- t^* is inflation targeting implementation date.
- Let g_t be some measure of output gap.



Generalized Time-Varying Parameters

- The general model is

$$\begin{aligned}y_t &= X_t \beta_t + \epsilon_t \\ \beta_t &= \mathcal{F}(S_t)\end{aligned}$$

where S_t are the state variables that determine time-variation.

- If we know the threshold variables ($S_t = [t, g_{t-1}]$) and values ($c = [t^*, 0]$): run OLS on subsamples.
- But we don't.** So we need an algorithm to find out:

$$\min_{j \in \mathcal{J}^-, c \in \mathbb{R}} \left[\min_{\beta_1} \sum_{\{t \in I | S_{j,t} \leq c\}} (y_t - X_t \beta_1)^2 + \lambda \|\beta_1\|_2 \right. \\ \left. + \min_{\beta_2} \sum_{\{t \in I | S_{j,t} > c\}} (y_t - X_t \beta_2)^2 + \lambda \|\beta_2\|_2 \right].$$

Generalized Time-Varying Parameters

3 ingredients to go from a single tree to a forest

For each tree:

1. **Let the trees run deep:** even though that would surely imply overfitting for a single tree, let each tree run until leafs contain very few observations (usually < 5).

Diversifying the Portfolio (i.e., creating the ensemble)

2. **Bagging:** Create B nonparametric bootstrap samples of the data. That is, we are picking $[y_t \ X_t]$ pairs with replacement.
3. **De-correlated trees:** At each splitting point, we only consider a subset of all predictors ($\mathcal{J}^- \subset \mathcal{J}$) for the split.

(M)RF prediction is the simple average of all the B tree predictions.

Why does it not overfit? See *To Bag is to Prune*, a spin-off paper.

Generalized Time-Varying Parameters

Useful Addition: Random Walk Regularization

- The above implements the prior $\beta_t \sim \mathcal{N}(0, .)$.
- However, $\beta_t \sim \mathcal{N}(\beta_{t-1}, .)$, i.e., time-smoothness, makes more sense.
- I implement it via WLS with rudimentary egalitarian Olympic podium weights $w(t; \zeta)$, where $\zeta < 1$ is a tuning parameter.
- The splitting rule becomes

$$\min_{j \in \mathcal{J}^-, c \in \mathbb{R}} \left[\min_{\beta_1} \sum_{t \in l_1^{RW}(j, c)} w(t; \zeta) (y_t - X_t \beta_1)^2 + \lambda \|\beta_1\|_2 \right. \\ \left. + \min_{\beta_2} \sum_{t \in l_2^{RW}(j, c)} w(t; \zeta) (y_t - X_t \beta_2)^2 + \lambda \|\beta_2\|_2 \right].$$

Generalized Time-Varying Parameters

Inference

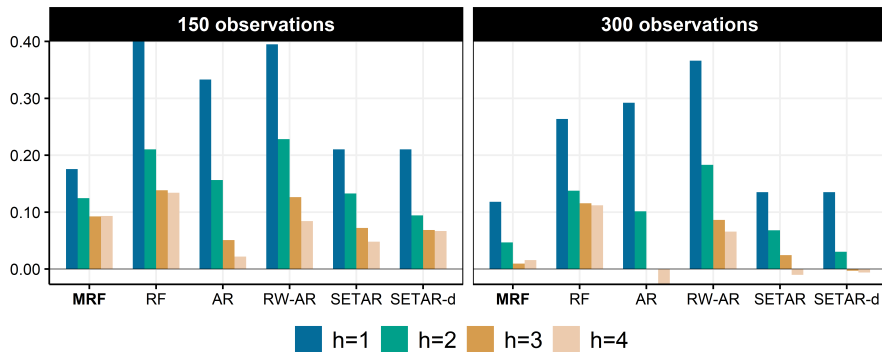
- Following (Taddy et al., 2015), *interpret* \mathcal{F} as a the posterior mean of tree \mathcal{T} which posterior distribution was obtained by (Rubin, 1981)'s Bayesian Bootstrap.
- Crucial advantage: no additional computations required, quantiles computed straight from the "bag" of trees.
- (Taddy et al., 2015)'s approach requires *iid* data: the bayesian model is multinomial with Dirichlet conjugate prior.
- I propose to rather use a Block Bayesian Bootstrap (BBB)

Simulations

DGP 3: Persistent SETAR

$$y_t = \phi_{0,t} + \phi_{1,t}y_{t-1} + \phi_{2,t}y_{t-2} + \epsilon_t, \quad \epsilon_t \sim N(0, 0.5^2)$$

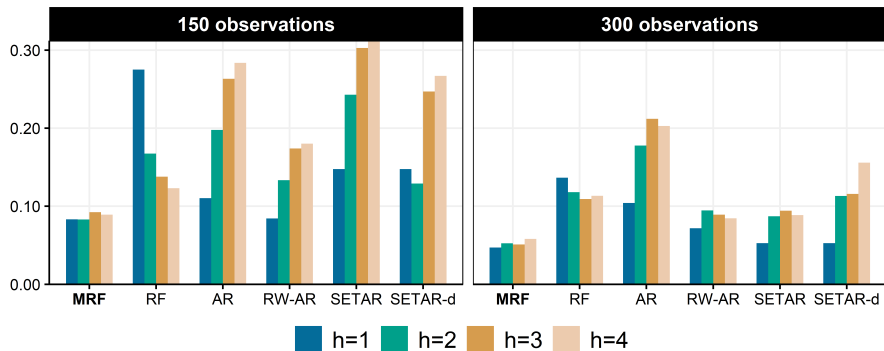
$$\beta_t = [\phi_{0,t} \ \phi_{1,t} \ \phi_{2,t}] = \begin{cases} [2 \ 0.8 \ -0.2], & \text{if } y_{t-1} \geq 0 \\ [0.25 \ 1.1 \ -0.4], & \text{otherwise} \end{cases}$$



Simulations

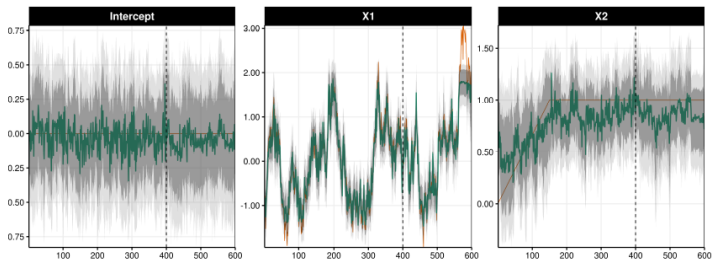
DGP 6: SETAR that morphs instantly in AR(2)

$$\text{DGP 6} = \begin{cases} \text{SETAR}, & \text{if } t < T/2 \\ \text{Plain AR(2)}, & \text{otherwise} \end{cases}$$

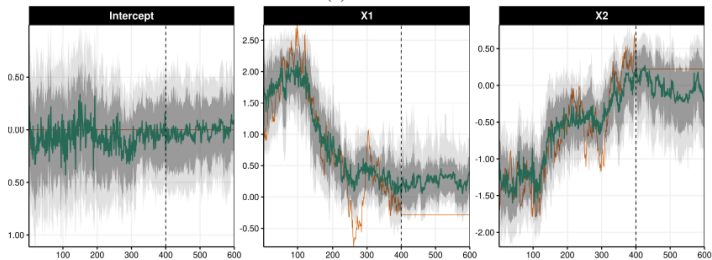


Simulations

A look at GTVPs under Different Contexts, when S_t is large



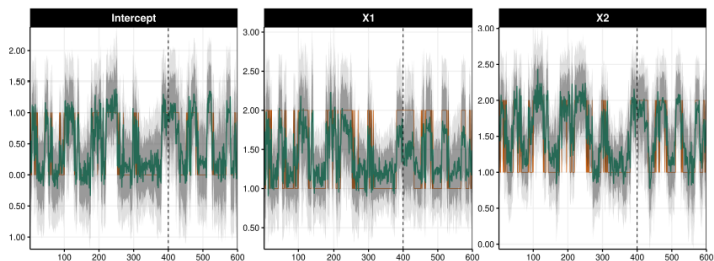
(d) DGP 4



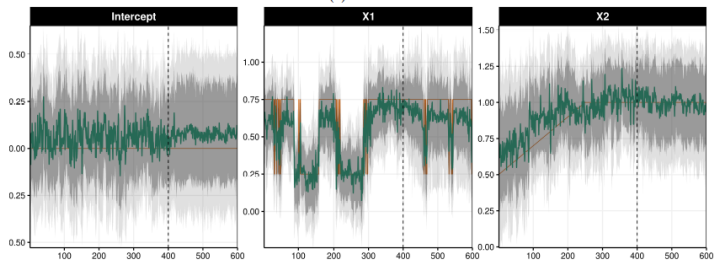
(e) DGP 5

Simulations

A look at GTVPs under Different Contexts, when S_t is large



(a) DGP 1



(b) DGP 2

Forecasting

Setup

- Data: FRED-QD, the SW data set update by (McCracken and Ng, 2016), 260 series
- POOS period starts on 2002Q1 and ends 2014Q1. *Expanding* window estimation from 1959Q3.
- Horizons: $h \in \{1, 2, 4, 6, 8\}$ quarters
- 6 variables of interest: GDP growth, Unemployment Rate (UNRATE) growth, Interest Rate (GS1), Inflation ($\Delta \log(\text{CPIAUCSL})$), Housing Starts (HOUST) and some spread (T10YFFM).
- Evaluation metric is $RMSPE_{v,h,m} = \sqrt{\sum_{t \in \text{OOS}} (y_t^v - \hat{y}_{t-h}^{v,h,m})^2}$

Forecasting

About the composition of S_t

1. 8 lags of y_t
2. t for structural breaks/exogenous time-variation
3. 2 lags of all variables in FRED
4. F to summarize the cross-section variation: 8 lags of 5 factors extracted from FRED by PCA

Most importantly

5. For each variable j , I generate two $\text{MAF}_{t,j}$ (Moving Average Factors) summarizing the information contained in its distributed lags.
 - Bypasses the need to penalize explicitly a nonexistent lag polynomial.
 - Done by PCA on 8 lags.
 - Further studied for many ML models (along with other transformations) in (Goulet Coulombe et al., 2020).

Forecasting

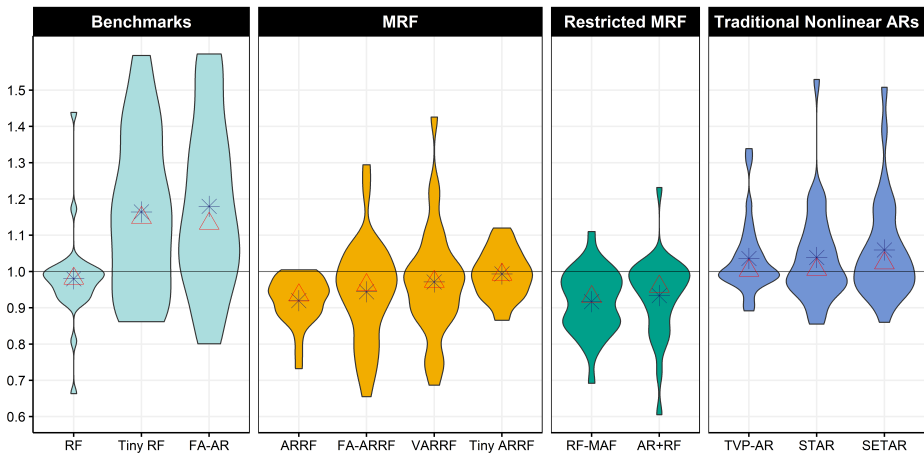
Main Models

Table: Wild Horses

Acronym	Linear Part (X_t^m)	RF part
AR	$[1, y_{t-\{1:4\}}]$	\emptyset
FA-AR	$[1, y_{t-\{1:4\}}, F_{1,t-\{1:2\}}, F_{2,t-\{1:2\}}]$	\emptyset
RF	\emptyset	8 lags of all raw data
Tiny RF	\emptyset	$[y_{t-\{1:8\}}, t]$
RF-MAF	\emptyset	S_t
AR+RF	Filter y_t first with an AR(4)	S_t
ARRF	$[1, y_{t-\{1:2\}}]$	S_t
Tiny ARRF	$[1, y_{t-\{1:2\}}]$	$[y_{t-\{1:8\}}, t]$
FAARRF	$[1, y_{t-\{1:2\}}, F_{1,t-1}, F_{2,t-1}]$	S_t
VARRF	$[1, y_{t-\{1:2\}}, GDP_{t-1}, IR_{t-1}, INF_{t-1}]$	S_t

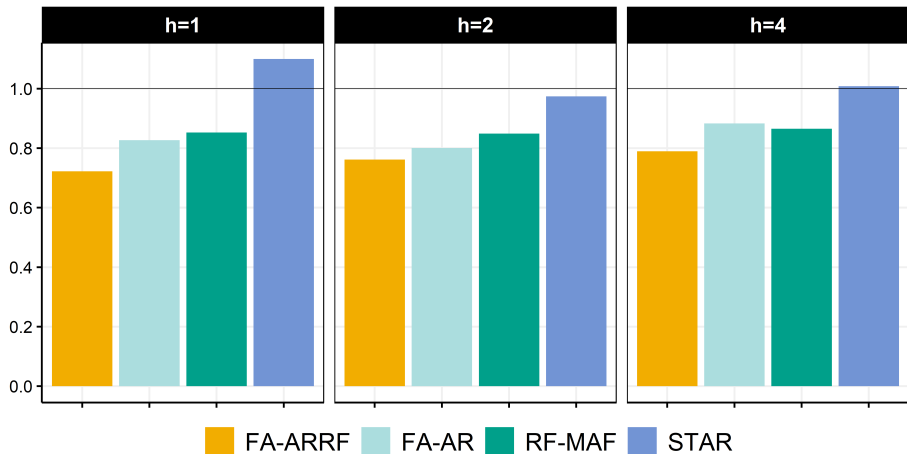
Forecasting

Visualizing the distribution of $RMSPE_{v,h,m} / RMSPE_{v,h,AR}$



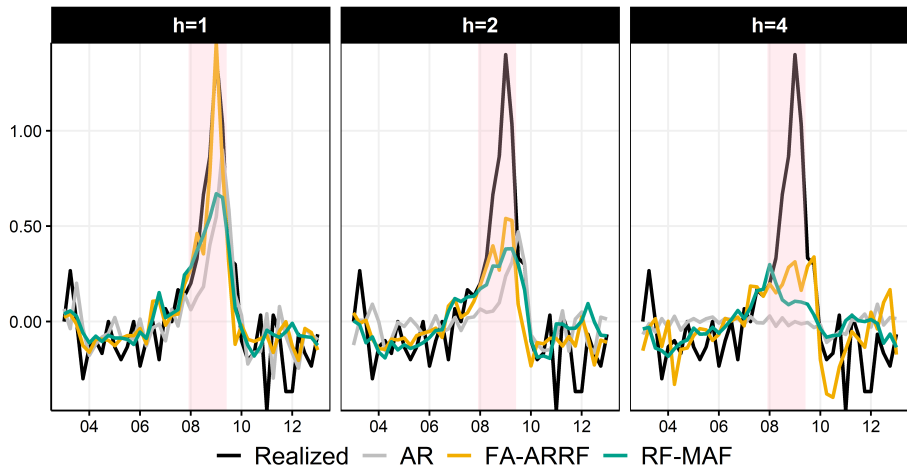
Forecasting

$RMSPE_{UR,h,m} / RMSPE_{UR,h,AR}$ in more detail



Forecasting

What do forecasts look like for UR? $\rightarrow R^2_{OOS}$ 80% for $h = 1$



GTVPs of the one-quarter ahead UR forecast

$$\Delta UR_{t+1} = \mu_t + \phi_t^1 y_t + \phi_t^2 y_{t-1} + \gamma_t^1 F_t^1 + \gamma_t^2 F_t^2 + e_{t+1}.$$

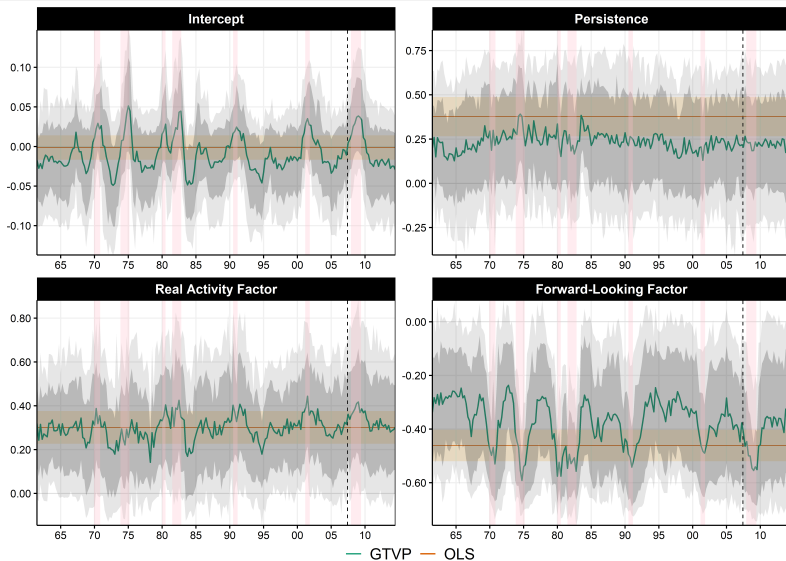


Figure: GTVPs of the one-quarter ahead UR forecast. The grey bands are the 68% and 90% credible region. The pale orange region is the OLS coefficient \pm one standard error. The vertical dotted blue line is the end of the training sample. Pink shading corresponds to NBER recessions.

Dynamic β_t Learning

$$\Delta UR_{t+1} = \mu_t + \phi_t^1 y_t + \phi_t^2 y_{t-1} + \gamma_t^1 F_t^1 + \gamma_t^2 F_t^2 + e_{t+1}.$$

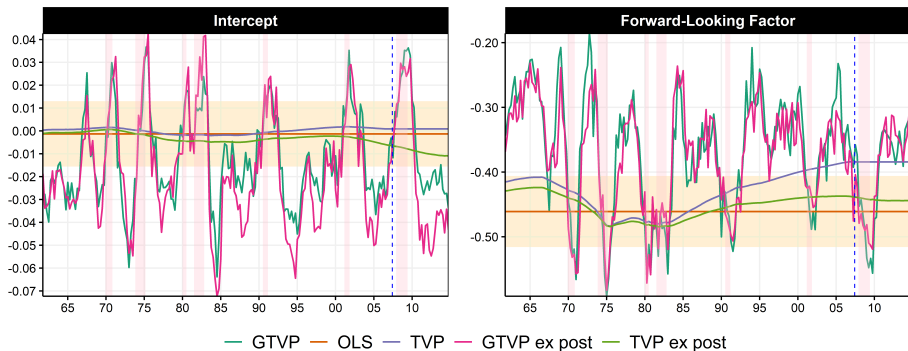
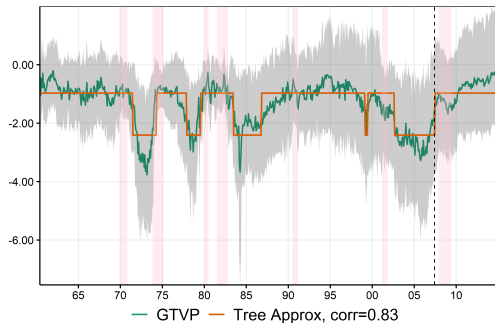


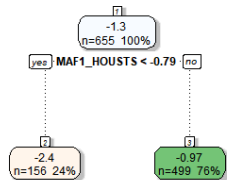
Figure: Comparing TVPs and GTVPs, ex-ante and ex-post.

An Interesting Observation for (monthly) *Inflation*

$$\pi_{t+1} = \mu_t + \phi_t^1 y_t + \phi_t^2 y_{t-1} + \gamma_t^1 F_t^1 + \gamma_t^2 F_t^2 + e_{t+1}.$$



(a) Surrogate Model Replication

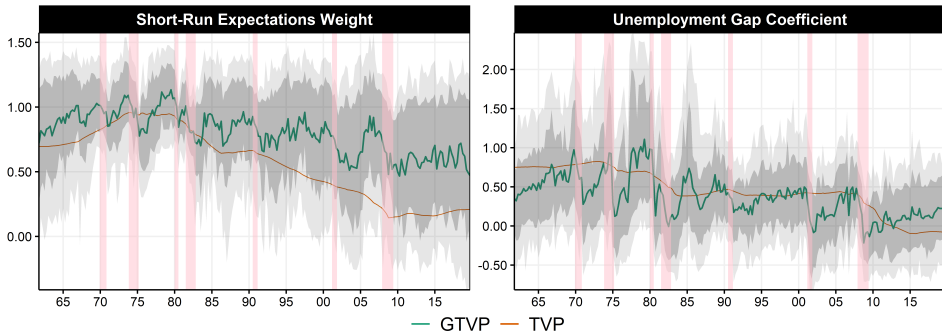


(b) Corresponding Tree

A more traditional Phillips' Curve

À la (Blanchard et al., 2015) and many others

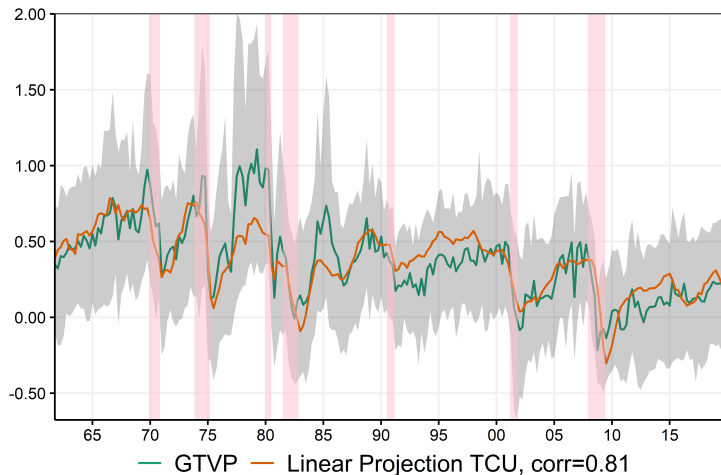
$$\pi_t = \mu_t + \beta_{1,t}\hat{\pi}_t^{SR} + \beta_{2,t}u_t^{GAP} + \beta_{3,t}\pi_t^{IMP} + \varepsilon_t$$



A more traditional Phillips' Curve

$\beta_{2,t}$ looks like Total Capacity Utilization (TCU)

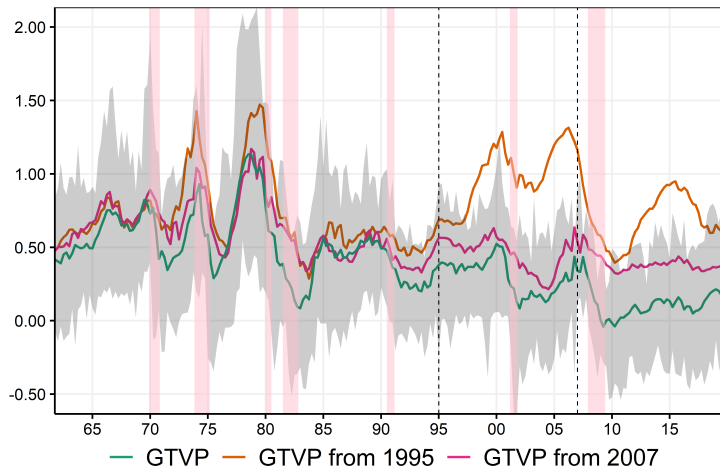
$$\pi_t = \mu_t + \beta_{1,t}\hat{\pi}_t^{SR} + \beta_{2,t}u_t^{GAP} + \beta_{3,t}\pi_t^{IMP} + \varepsilon_t$$



Dynamic Phillips' Curve Learning

Comparing "out-of-sample" predictions of GTVPs at different points in time

$$\pi_t = \mu_t + \beta_{1,t}\hat{\pi}_t^{SR} + \beta_{2,t}u_t^{GAP} + \beta_{3,t}\pi_t^{IMP} + \varepsilon_t$$



Conclusion

I proposed a new time series model that

1. works;
2. is interpretable;
3. is highly versatile;
4. off-the-shelf (R `package` is available);

Extensions/applications:

- VARs
- Conditional CAPM
- HAR volatility
- DSGEs?
- Anything goes

Try it with your favorite X_t *today*!

Appendix

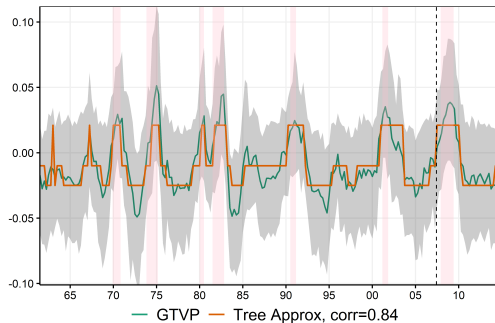
Appendix

Misc

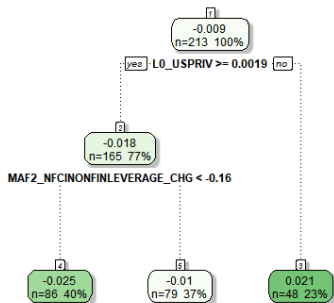
1. GTVPs \succ Random Walk TVPs since it implies an *adaptive* kernel rather than a fixed one
 - The intercept itself is a RF rather than a RW (e.i., a bad X_t choice can be rescued)
 - Less reliant (or not all) on $t \rightarrow$ less boundary problems (or none) when forecasting.
2. Compress lag polynomials $S_{t,j}^{1:P}$ ex-ante with Moving Average Factors
 - Get MAFs by running PCA on the panel $[S_{t-1,j} \dots S_{t-P,j}]$ of P lags of variable j .
 - Boost splits' meaningfulness (not wasting splits on 12 individual lags)
 - Reduce computing time

Appendix

Cutting Down the Forest, One Tree at a Time ($\mu_t^{UR,h=1}$)



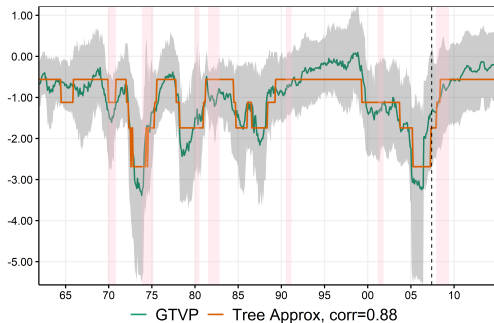
(a) Surrogate Model Replication



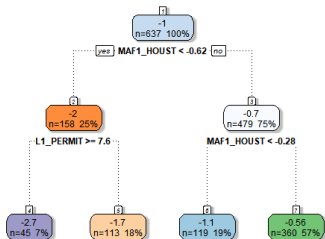
(b) Corresponding Tree

Appendix

Cutting Down the Forest, One Tree at a Time ($\gamma_{t,F_1}^{INF,h=12}$, monthly)



(a) Surrogate Model Replication



(b) Corresponding Tree