Single-Source All-Destinations Shortest Paths With General Weights

- Directed weighted graph.
- Edges may have negative cost.
- No cycle whose cost is < 0.
- Find a shortest path from a given source vertex s to each of the n vertices of the digraph.

Single-Source All-Destinations Shortest Paths With General Weights

• Dijkstra's O(n²) single-source greedy algorithm doesn't work when there are negative-cost edges.

Bellman-Ford Algorithm

- Single-source all-destinations shortest paths in digraphs with negative-cost edges.
- Uses dynamic programming.
- Runs in $O(n^3)$ time when adjacency matrices are used.
- Runs in O(ne) time when adjacency lists are used.

Strategy



- To construct a shortest path from the source to vertex v, decide on the max number of edges on the path and on the vertex that comes just before v.
- Since the digraph has no cycle whose length is < 0, we may limit ourselves to the discovery of cycle-free (acyclic) shortest paths.
- A path that has no cycle has at most n-1 edges.

Cost Function d



- Let d(v,k) (dist^k[v]) be the length of a shortest path from the source vertex to vertex v under the constraint that the path has at most k edges.
- d(v,n-1) is the length of a shortest unconstrained path from the source vertex to vertex v.
- We want to determine d(v,n-1) for every vertex v.

Value Of d(*,0)

• d(v,0) is the length of a shortest path from the source vertex to vertex v under the constraint that the path has at most 0 edges.

S

- d(s,0) = 0.
- d(v,0) = infinity for v != s.

Recurrence For d(*,k), k > 0

- d(v,k) is the length of a shortest path from the source vertex to vertex v under the constraint that the path has at most k edges.
- If this constrained shortest path goes through no more than k-1 edges, then d(v,k) = d(v,k-1).

Recurrence For d(*,k), k > 0

• If this constrained shortest path goes through k edges, then let w be the vertex just before v on this shortest path (note that w may be s).



- We see that the path from the source to w must be a shortest path from the source vertex to vertex w under the constraint that this path has at most k-1 edges.
- d(v,k) = d(w,k-1) + length of edge (w,v).

Recurrence For d(*,k), k > 0

• d(v,k) = d(w,k-1) + length of edge (w,v).

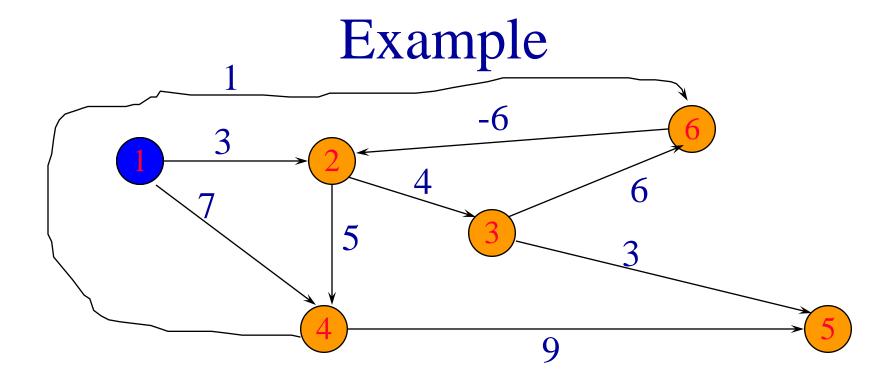


- We do not know what w is.
- We can assert
 - $d(v,k) = min\{d(w,k-1) + length of edge(w,v)\}$, where the min is taken over all w such that (w,v) is an edge of the digraph.
- Combining the two cases considered yields:
 - $d(v,k) = min\{d(v,k-1),$ $min\{d(w,k-1) + length of edge(w,v)\}\}$

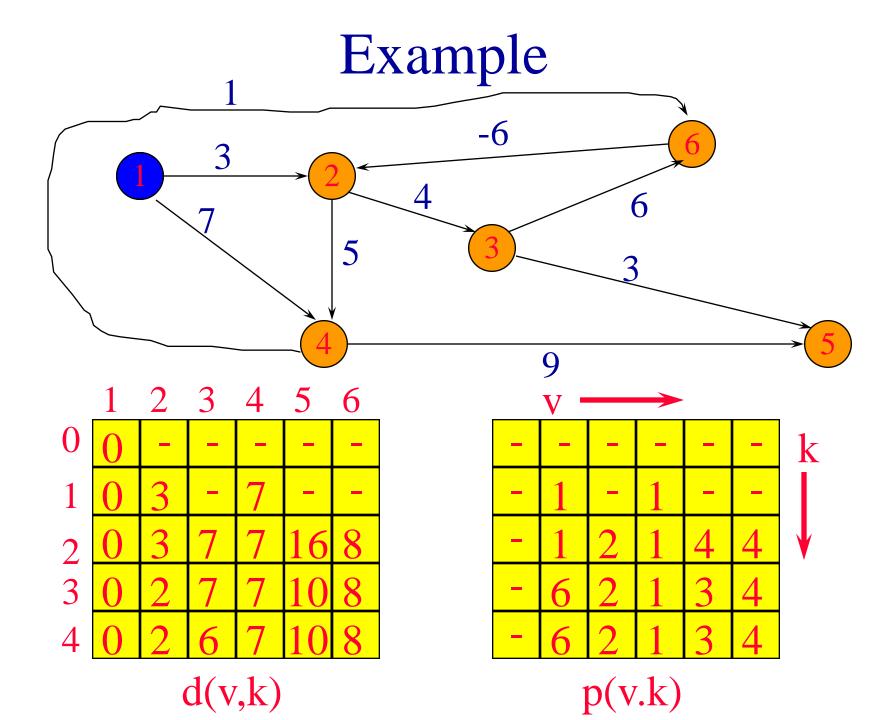
Pseudocode To Compute d(*,*)

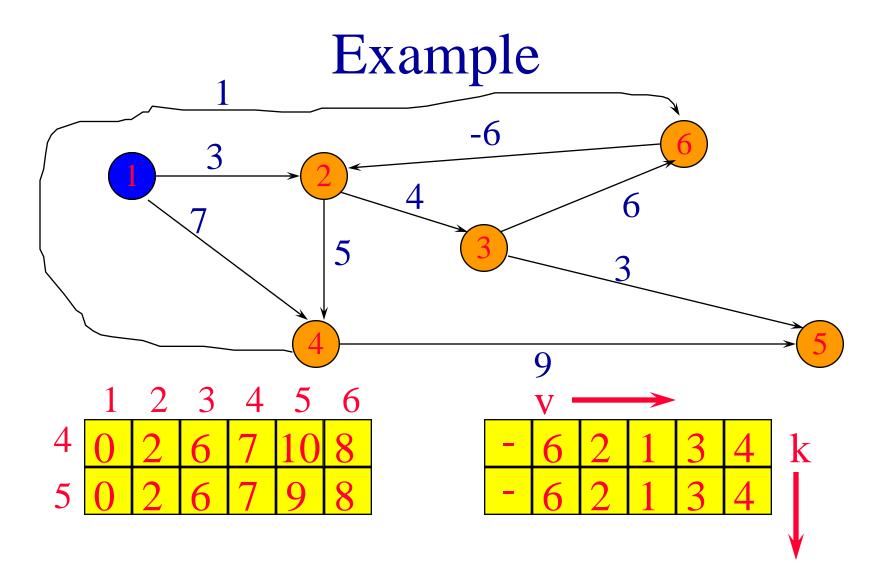
```
// initialize d(*,0)
d(s,0) = 0;
d(v,0) = infinity, v != s;
// compute d(*,k), 0 < k < n
for (int k = 1; k < n; k++)
   d(v,k) = d(v,k-1), 1 \le v \le n;
    for (each edge (u,v))
       d(v,k) = min\{d(v,k), d(u,k-1) + cost(u,v)\}
```

- Let p(v,k) be the vertex just before vertex v on the shortest path for d(v,k).
- p(v,0) is undefined.
- Used to construct shortest paths.



Source vertex is 1.

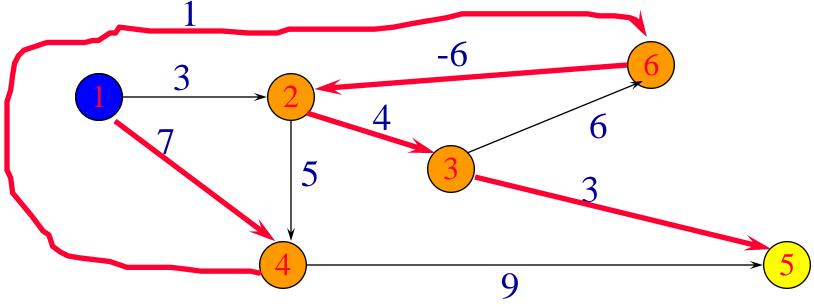


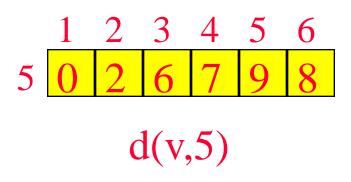


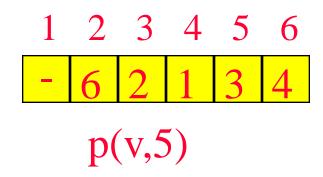
d(v,k)

p(v.k)

Shortest Path From 1 To 5







Observations

- d(v,k) = min{d(v,k-1),
 min{d(w,k-1) + length of edge (w,v)}}
- d(s,k) = 0 for all k.
- If d(v,k) = d(v,k-1) for all v, then d(v,j) = d(v,k-1), for all j >= k-1 and all v.
- If we stop computing as soon as we have a d(*,k) that is identical to d(*,k-1) the run time becomes
 - $O(n^3)$ when adjacency matrix is used.
 - O(ne) when adjacency lists are used.

Observations

The computation may be done in-place.

```
d(v) = min\{d(v), min\{d(w) + length of edge (w,v)\}\}
instead of
d(v,k) = min\{d(v,k-1),
min\{d(w,k-1) + length of edge (w,v)\}\}
```

- Following iteration k, $d(v,k+1) \le d(v) \le d(v,k)$
- On termination d(v) = d(v,n-1).
- Space requirement becomes O(n) for d(*) and p(*).