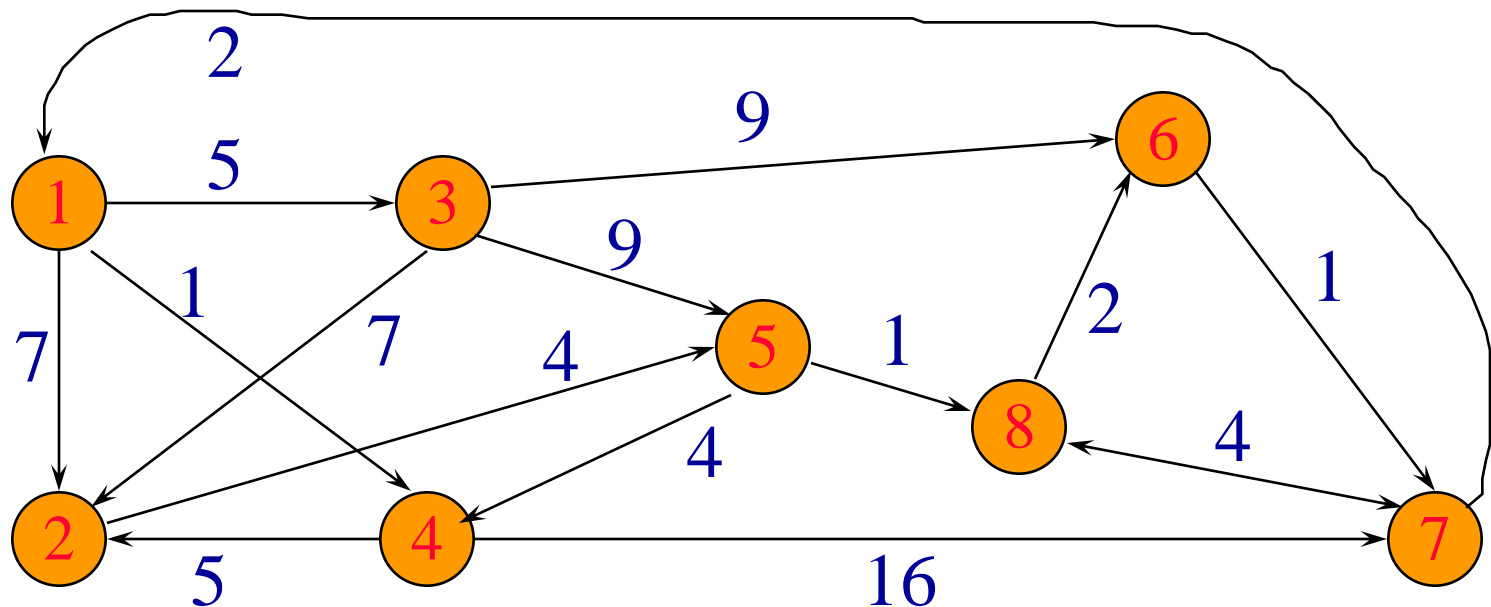


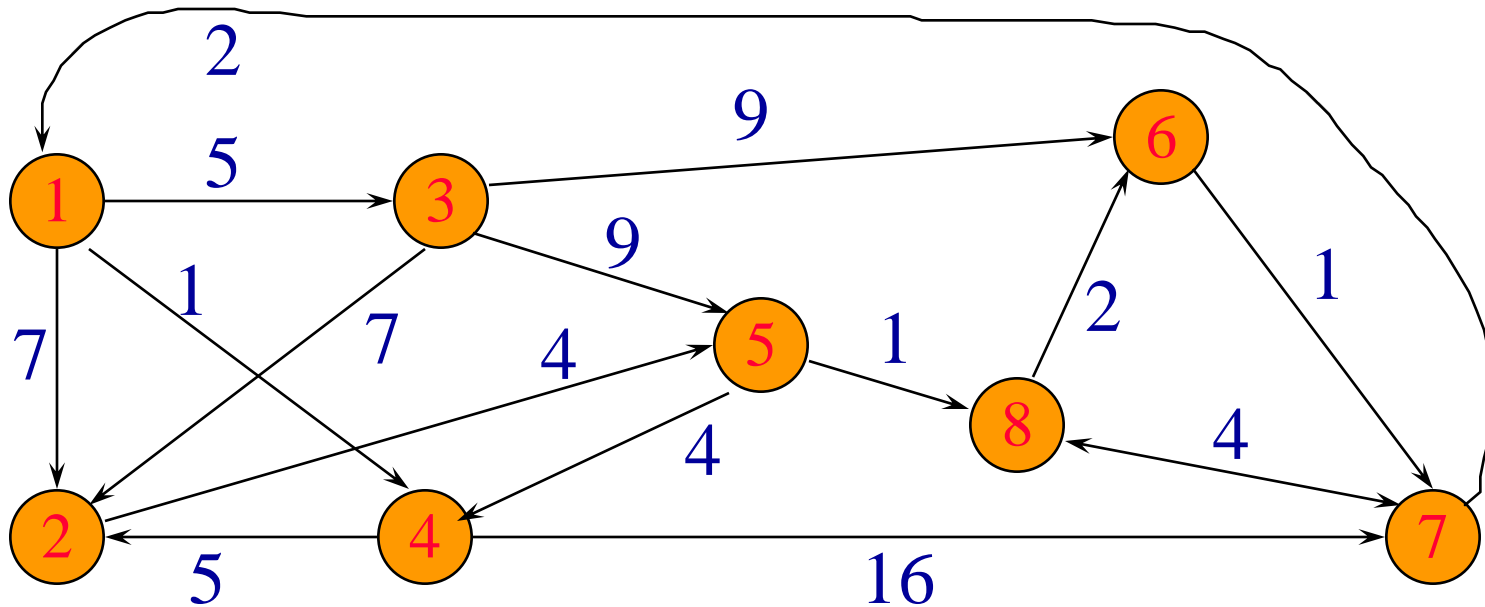
# • All-Pairs Shortest Paths •

- Given an  $n$ -vertex directed weighted graph, find a shortest path from vertex  $i$  to vertex  $j$  for each of the  $n^2$  vertex pairs  $(i,j)$ .

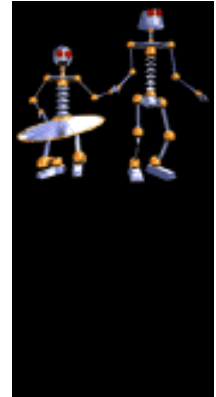


# Dijkstra's Single Source Algorithm

- Use Dijkstra's algorithm **n** times, once with each of the **n** vertices as the source vertex.



# Performance

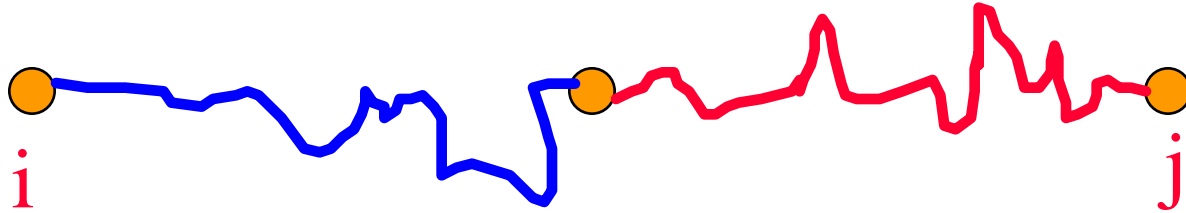


- Time complexity is  $O(n^3)$  time.
- Works only when no edge has a cost  $< 0$ .

# Floyd's Algorithm

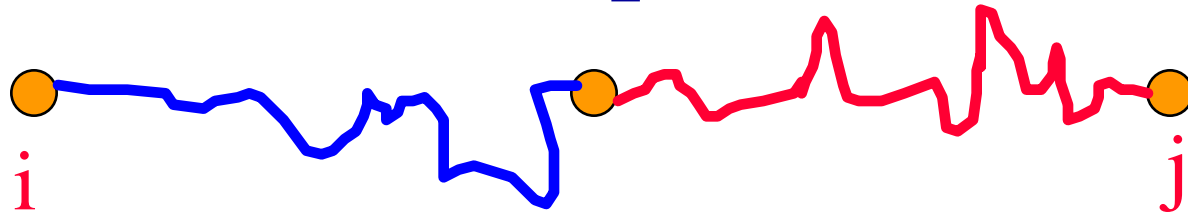
- Time complexity is  $\Theta(n^3)$  time.
- Works so long as there is no cycle whose length is  $< 0$ .
- When there is a cycle whose length is  $< 0$ , some shortest paths aren't finite.
  - If vertex **1** is on a cycle whose length is  $-2$ , each time you go around this cycle once you get a **1** to **1** path that is **2** units shorter than the previous one.
- Simpler to code, smaller overheads.

# Decision Sequence



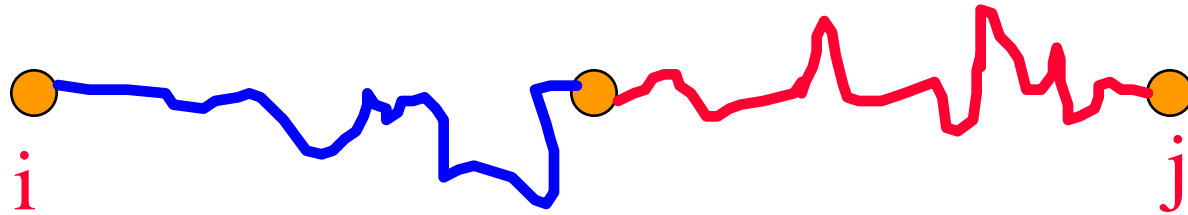
- First decide the highest intermediate vertex (i.e., largest vertex number) on the shortest path from **i** to **j**.
- If the shortest path is **i, 2, 6, 3, 8, 5, 7, j** the first decision is that vertex **8** is an intermediate vertex on the shortest path and no intermediate vertex is larger than **8**.
- Then decide the highest intermediate vertex on the path from **i** to **8**, and so on.

# A Triple



- $(i, j, k)$  denotes the problem of finding the shortest path from vertex  $i$  to vertex  $j$  that has no intermediate vertex larger than  $k$ .
- $(i, j, n)$  denotes the problem of finding the shortest path from vertex  $i$  to vertex  $j$  (with no restrictions on intermediate vertices).

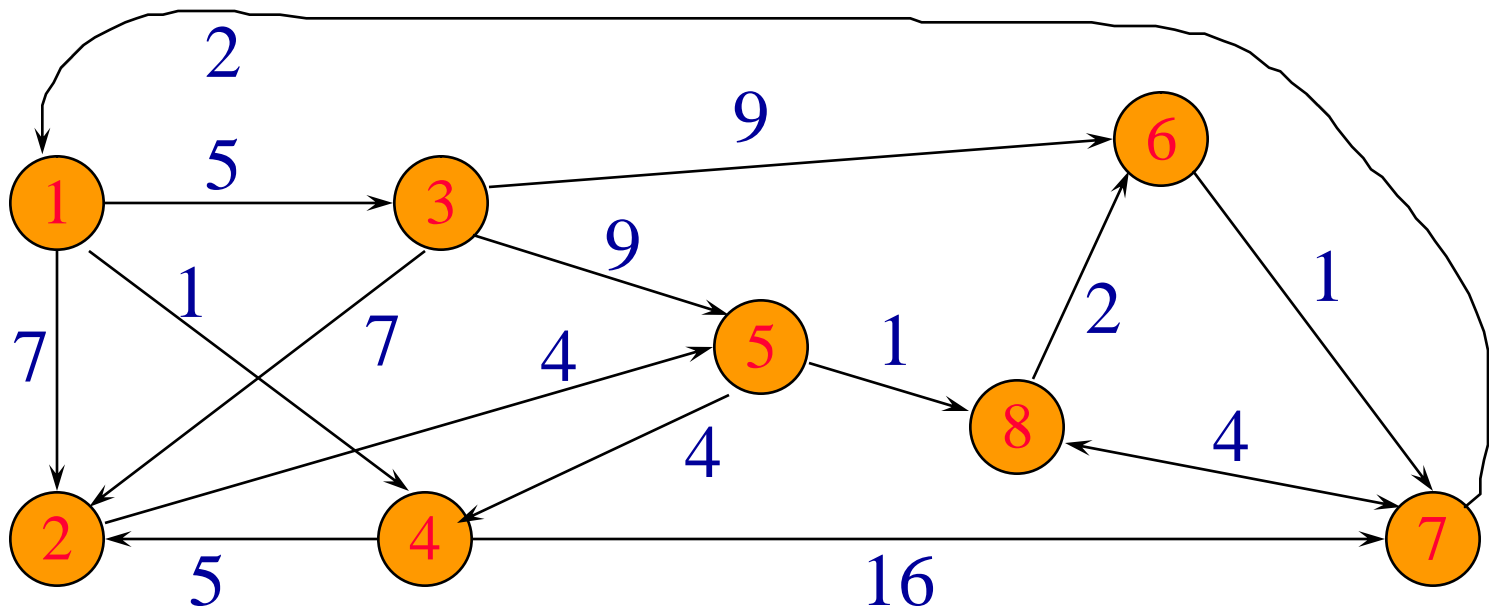
# Cost Function



- Let  $c(i,j,k)$  be the length of a shortest path from vertex  $i$  to vertex  $j$  that has no intermediate vertex larger than  $k$ .

# $c(i,j,n)$

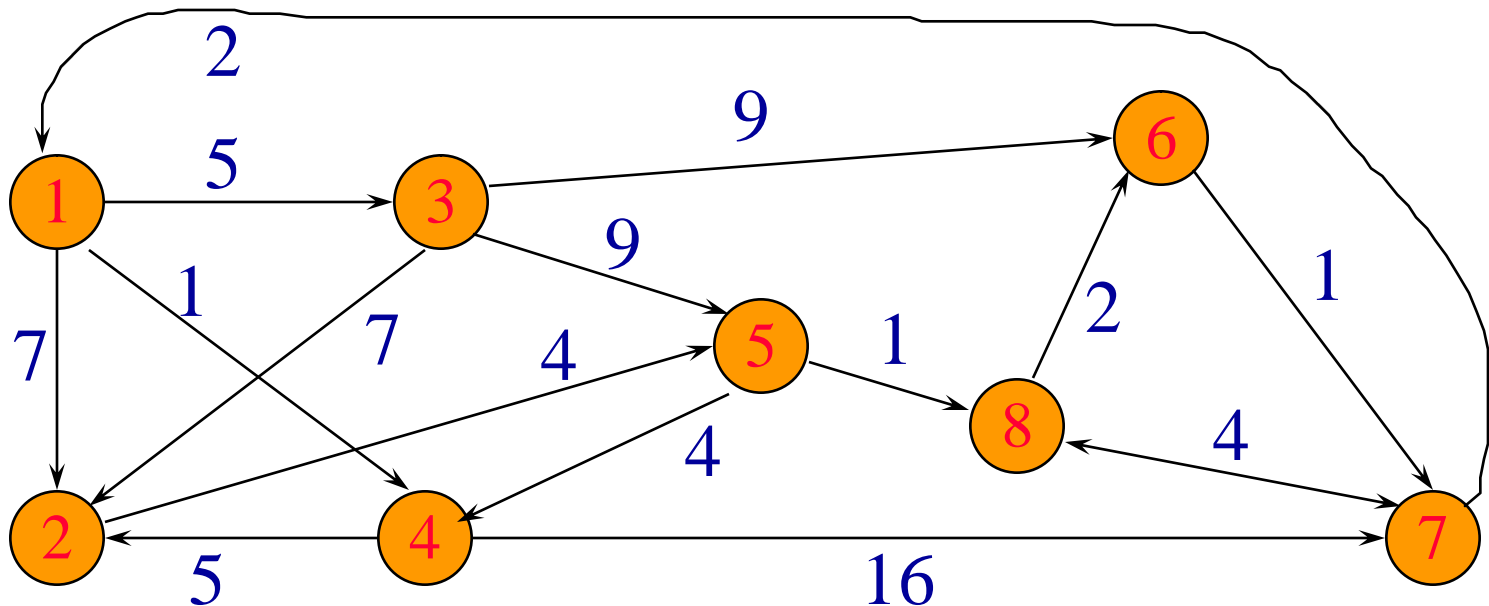
- $c(i,j,n)$  is the length of a shortest path from vertex  $i$  to vertex  $j$  that has no intermediate vertex larger than  $n$ .
- No vertex is larger than  $n$ .
- Therefore,  $c(i,j,n)$  is the length of a shortest path from vertex  $i$  to vertex  $j$ .





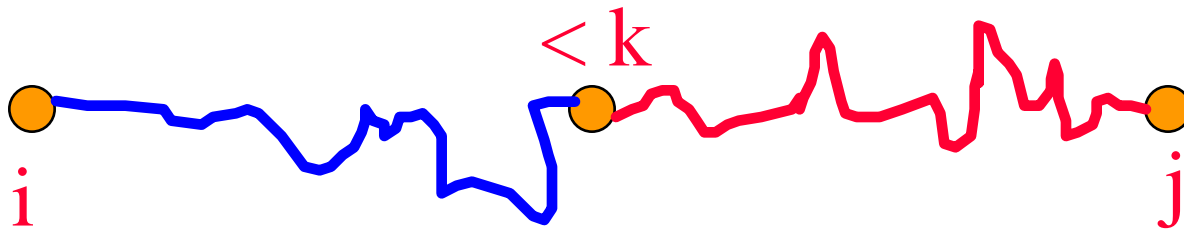
$$c(i,j,0)$$

- $c(i,j,0)$  is the length of a shortest path from vertex  $i$  to vertex  $j$  that has no intermediate vertex larger than  $0$ .
  - Every vertex is larger than  $0$ .
  - Therefore,  $c(i,j,0)$  is the length of a single-edge path from vertex  $i$  to vertex  $j$ .



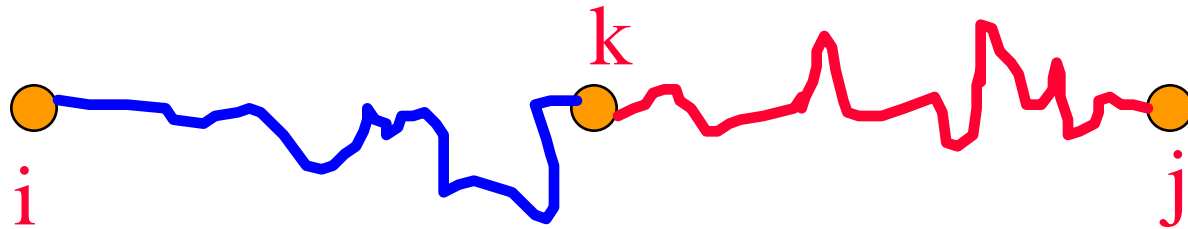
# Recurrence For $c(i,j,k)$ , $k > 0$

- The shortest path from vertex  $i$  to vertex  $j$  that has no intermediate vertex larger than  $k$  may or may not go through vertex  $k$ .
- If this shortest path does not go through vertex  $k$ , the largest permissible intermediate vertex is  $k-1$ . So the path length is  $c(i,j,k-1)$ .



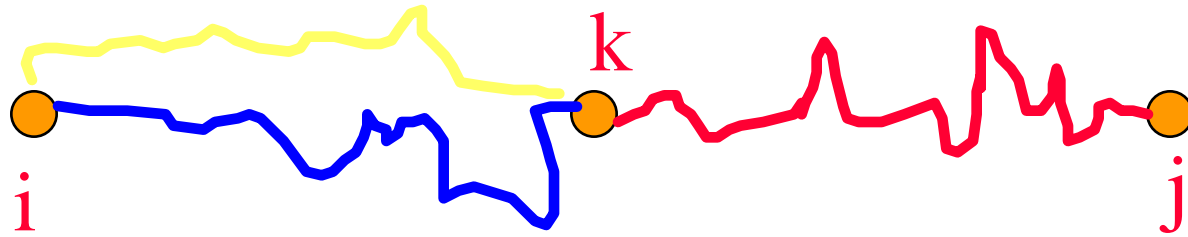
# Recurrence For $c(i,j,k)$ , $k > 0$

- Shortest path goes through vertex  $k$ .



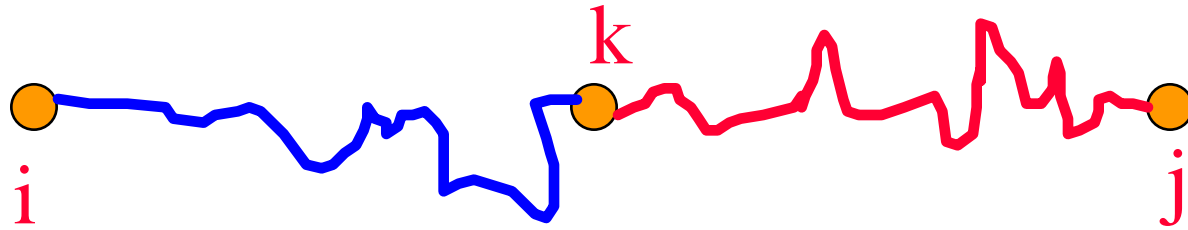
- We may assume that vertex  $k$  is not repeated because no cycle has negative length.
- Largest permissible intermediate vertex on  $i$  to  $k$  and  $k$  to  $j$  paths is  $k-1$ .

# Recurrence For $c(i,j,k)$ , $k > 0$



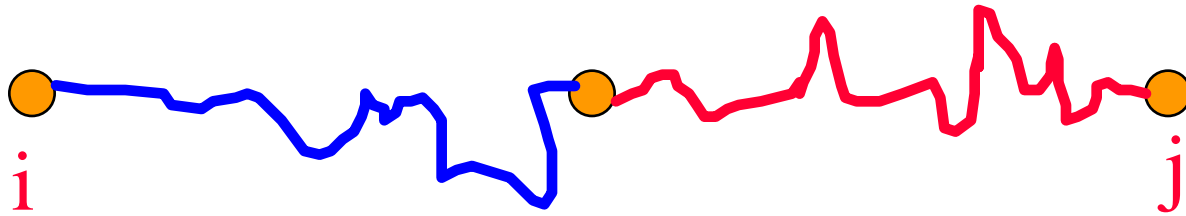
- $i$  to  $k$  path must be a shortest  $i$  to  $k$  path that goes through no vertex larger than  $k-1$ .
- If not, replace current  $i$  to  $k$  path with a shorter  $i$  to  $k$  path to get an even shorter  $i$  to  $j$  path.

# Recurrence For $c(i,j,k)$ , $k > 0$



- Similarly,  $k$  to  $j$  path must be a shortest  $k$  to  $j$  path that goes through no vertex larger than  $k-1$ .
- Therefore, length of  $i$  to  $k$  path is  $c(i,k,k-1)$ , and length of  $k$  to  $j$  path is  $c(k,j,k-1)$ .
- So,  $c(i,j,k) = c(i,k,k-1) + c(k,j,k-1)$ .

# Recurrence For $c(i,j,k)$ ), $k > 0$



- Combining the two equations for  $c(i,j,k)$ , we get  $c(i,j,k) = \min\{c(i,j,k-1), c(i,k,k-1) + c(k,j,k-1)\}$ .
- We may compute the  $c(i,j,k)$ s in the order  $k = 1, 2, 3, \dots, n$ .

# Floyd's Shortest Paths Algorithm

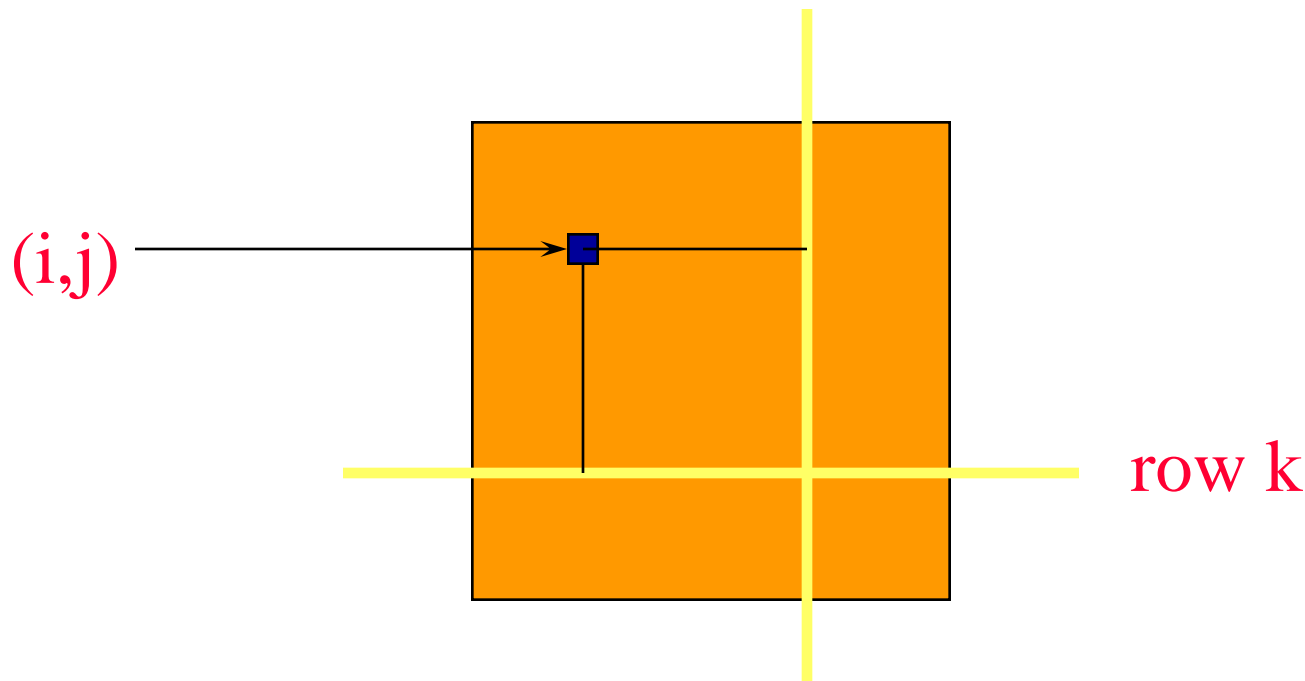
```
for (int k = 1; k <= n; k++)  
    for (int i = 1; i <= n; i++)  
        for (int j = 1; j <= n; j++)  
            c(i,j,k) = min{ c(i,j,k-1),  
                           c(i,k,k-1) + c(k,j,k-1) };
```

- Time complexity is  $O(n^3)$ .
- More precisely  $\Theta(n^3)$ .
- $\Theta(n^3)$  space is needed for  $c(*,*,*)$ .



# Space Reduction

- $c(i,j,k) = \min\{c(i,j,k-1), c(i,k,k-1) + c(k,j,k-1)\}$
- When neither  $i$  nor  $j$  equals  $k$ ,  $c(i,j,k-1)$  is used only in the computation of  $c(i,j,k)$ .  
column  $k$



- So  $c(i,j,k)$  can overwrite  $c(i,j,k-1)$ .



# Space Reduction

- $c(i,j,k) = \min\{c(i,j,k-1), c(i,k,k-1) + c(k,j,k-1)\}$
- When  $i$  equals  $k$ ,  $c(i,j,k-1)$  equals  $c(i,j,k)$ .
  - $c(k,j,k) = \min\{c(k,j,k-1), c(k,k,k-1) + c(k,j,k-1)\}$   
 $= \min\{c(k,j,k-1), 0 + c(k,j,k-1)\}$   
 $= c(k,j,k-1)$
- So, when  $i$  equals  $k$ ,  $c(i,j,k)$  can overwrite  $c(i,j,k-1)$ .
- Similarly when  $j$  equals  $k$ ,  $c(i,j,k)$  can overwrite  $c(i,j,k-1)$ .
- So, in all cases  $c(i,j,k)$  can overwrite  $c(i,j,k-1)$ .

# Floyd's Shortest Paths Algorithm

```
for (int k = 1; k <= n; k++)  
    for (int i = 1; i <= n; i++)  
        for (int j = 1; j <= n; j++)  
             $c(i,j) = \min\{c(i,j), c(i,k) + c(k,j)\};$ 
```

- Initially,  $c(i,j) = c(i,j,0)$ .
- Upon termination,  $c(i,j) = c(i,j,n)$ .
- Time complexity is  $\Theta(n^3)$ .
- $\Theta(n^2)$  space is needed for  $c(*,*)$ .

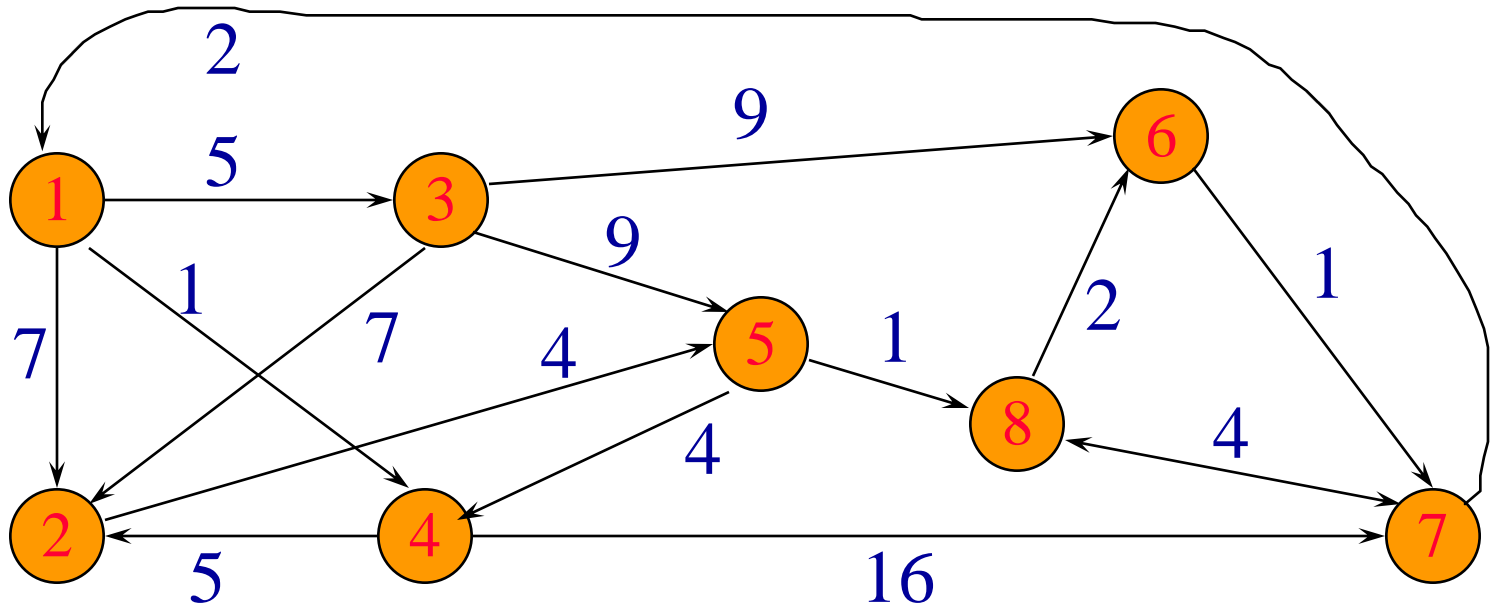


# Building The Shortest Paths

- Let  $kay(i,j)$  be the largest vertex on the shortest path from  $i$  to  $j$ .
- Initially,  $kay(i,j) = 0$  (shortest path has no intermediate vertex).

```
for (int k = 1; k <= n; k++)  
    for (int i = 1; i <= n; i++)  
        for (int j = 1; j <= n; j++)  
            if (c(i,j) > c(i,k) + c(k,j))  
                { kay(i,j) = k; c(i,j) = c(i,k) + c(k,j); }
```

# Example



-	7	5	1	-	-	-	-
-	-	-	-	4	-	-	-
-	7	-	-	9	9	-	-
-	5	-	-	-	-	16	-
-	-	-	4	-	-	-	1
-	-	-	-	-	-	1	-
2	-	-	-	-	-	-	4
-	-	-	-	-	2	4	-

Initial Cost Matrix

$$c(*,*) = c(*,*,0)$$

# Final Cost Matrix $c(*,*) = c(*,*,n)$

0	6	5	1	10	13	14	11
10	0	15	8	4	7	8	5
12	7	0	13	9	9	10	10
15	5	20	0	9	12	13	10
6	9	11	4	0	3	4	1
3	9	8	4	13	0	1	5
2	8	7	3	12	6	0	4
5	11	10	6	15	2	3	0

# kay Matrix

0 4 0 0 4 8 8 5

8 0 8 5 0 8 8 5

7 0 0 5 0 0 6 5

8 0 8 0 2 8 8 5

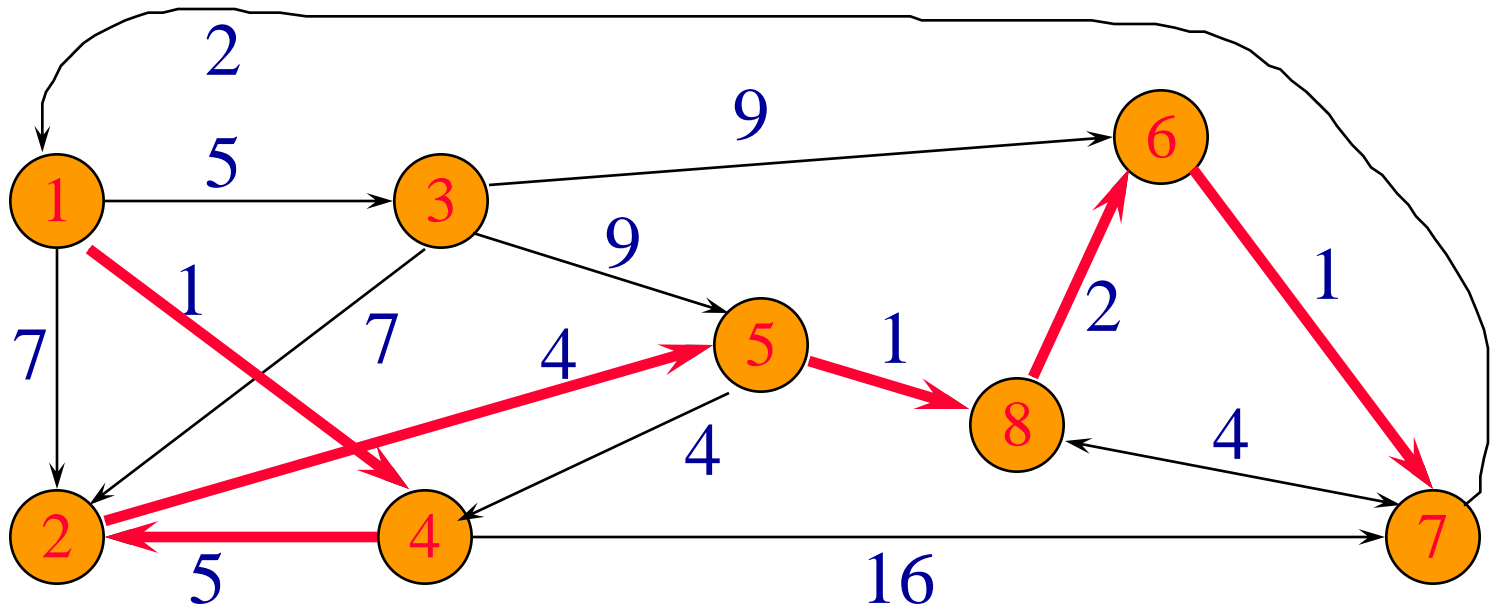
8 4 8 0 0 8 8 0

7 7 7 7 7 0 0 7

0 4 1 1 4 8 0 0

7 7 7 7 7 0 6 0

# Shortest Path



Shortest path from 1 to 7.

Path length is 14.

# Build A Shortest Path

0 4 0 0 4 8 8 5  
8 0 8 5 0 8 8 5  
7 0 0 5 0 0 6 5  
8 0 8 0 2 8 8 5  
8 4 8 0 0 8 8 0  
7 7 7 7 7 0 0 7  
0 4 1 1 4 8 0 0  
7 7 7 7 7 0 6 0

- The path is 1 4 2 5 8 6 7.

- $\text{kay}(1,7) = 8$

1  $\longrightarrow$  8  $\longrightarrow$  7

- $\text{kay}(1,8) = 5$

1  $\longrightarrow$  5  $\longrightarrow$  8  $\longrightarrow$  7

- $\text{kay}(1,5) = 4$

1  $\longrightarrow$  4  $\longrightarrow$  5  $\longrightarrow$  8  $\longrightarrow$  7



# Build A Shortest Path

0 4 0 0 4 8 8 5

8 0 8 5 0 8 8 5

7 0 0 5 0 0 6 5

8 0 8 0 2 8 8 5

8 4 8 0 0 8 8 0

7 7 7 7 7 0 0 7

0 4 1 1 4 8 0 0

7 7 7 7 7 0 6 0

- The path is 1 4 2 5 8 6 7.

1 → 4 → 5 → 8 → 7

- $\text{kay}(1,4) = 0$

1 4 → 5 → 8 → 7

- $\text{kay}(4,5) = 2$

1 4 → 2 → 5 → 8 → 7

- $\text{kay}(4,2) = 0$

1 4 2 → 5 → 8 → 7

# Build A Shortest Path

0 4 0 0 4 8 8 5

8 0 8 5 0 8 8 5

7 0 0 5 0 0 6 5

8 0 8 0 2 8 8 5

8 4 8 0 0 8 8 0

7 7 7 7 7 0 0 7

0 4 1 1 4 8 0 0

7 7 7 7 7 0 6 0

- The path is 1 4 2 5 8 6 7.

1 4 2  $\longrightarrow$  5  $\longrightarrow$  8  $\longrightarrow$  7

- $\text{kay}(2,5) = 0$

1 4 2 5  $\longrightarrow$  8  $\longrightarrow$  7

- $\text{kay}(5,8) = 0$

1 4 2 5 8  $\longrightarrow$  7

- $\text{kay}(8,7) = 6$

1 4 2 5 8  $\longrightarrow$  6  $\longrightarrow$  7

# Build A Shortest Path

0 4 0 0 4 8 8 5

8 0 8 5 0 8 8 5

7 0 0 5 0 0 6 5

8 0 8 0 2 8 8 5

8 4 8 0 0 8 8 0

7 7 7 7 7 0 0 7

0 4 1 1 4 8 0 0

7 7 7 7 7 0 6 0

- The path is 1 4 2 5 8 6 7.

1 4 2 5 8  $\rightarrow$  6  $\rightarrow$  7

- $\text{kay}(8,6) = 0$

1 4 2 5 8 6  $\rightarrow$  7

- $\text{kay}(6,7) = 0$

1 4 2 5 8 6 7

# Output A Shortest Path

```
void outputPath(int i, int j)
{ // does not output first vertex (i) on path
  if (i == j) return;
  if (kay[i][j] == 0) // no intermediate vertices on path
    cout << j << " ";
  else { // kay[i][j] is an intermediate vertex on the path
    outputPath(i, kay[i][j]);
    outputPath(kay[i][j], j);
  }
}
```

# Time Complexity Of outputPath



$O(\text{number of vertices on shortest path})$